

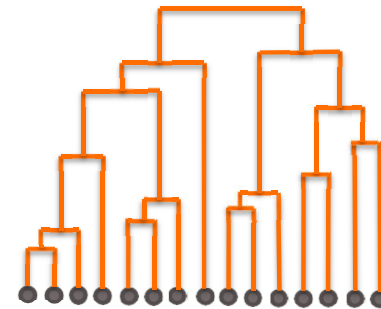


Clustering

Hierarchical Clustering
BRICH Clustering

Why hierarchical clustering?

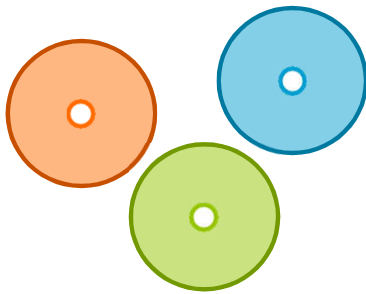
- Avoid choosing # clusters beforehand
- **Dendrograms** help visualize different clustering **granularities**
 - No need to rerun algorithm



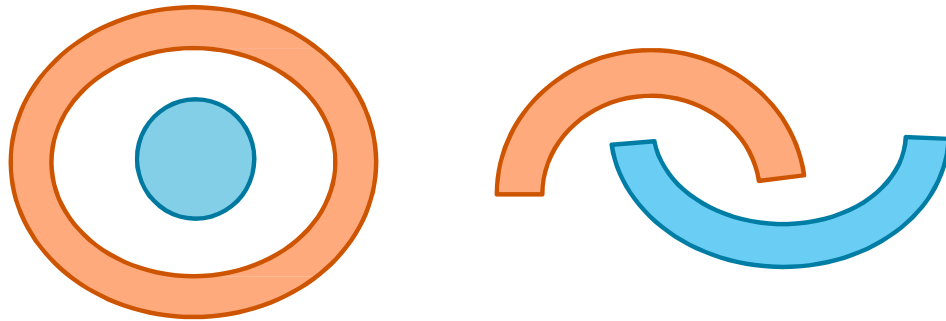
Why hierarchical clustering?

Can often find more **complex shapes** than k-means

k-means: spherical clusters



K-mean Clustering



Hierarchical Clustering

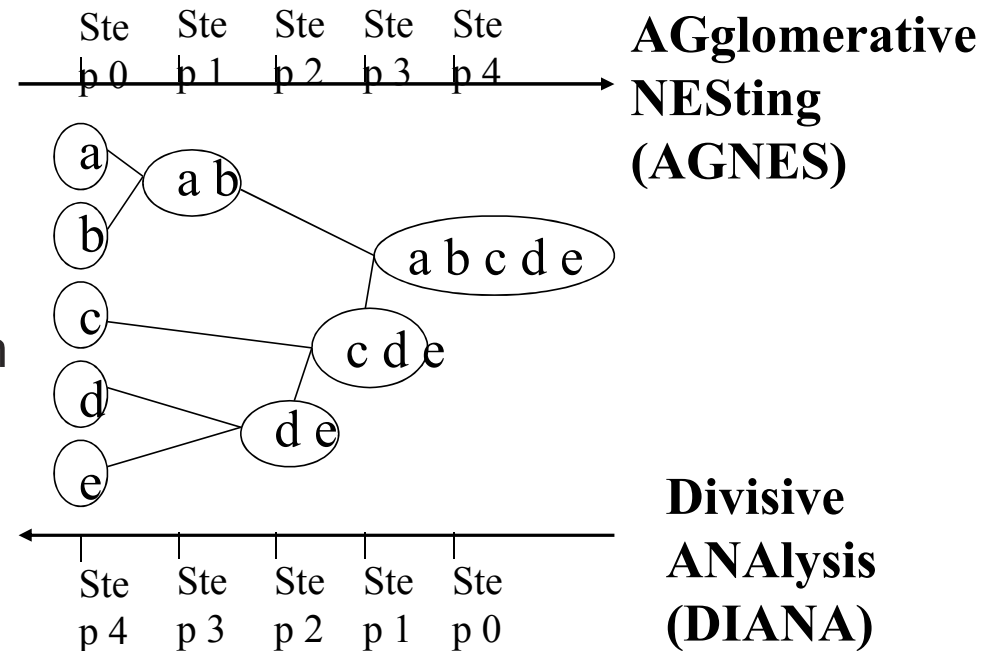
Two main types of algorithms

Divisive, *a.k.a top-down*: Start with all data in one big cluster and recursively split.

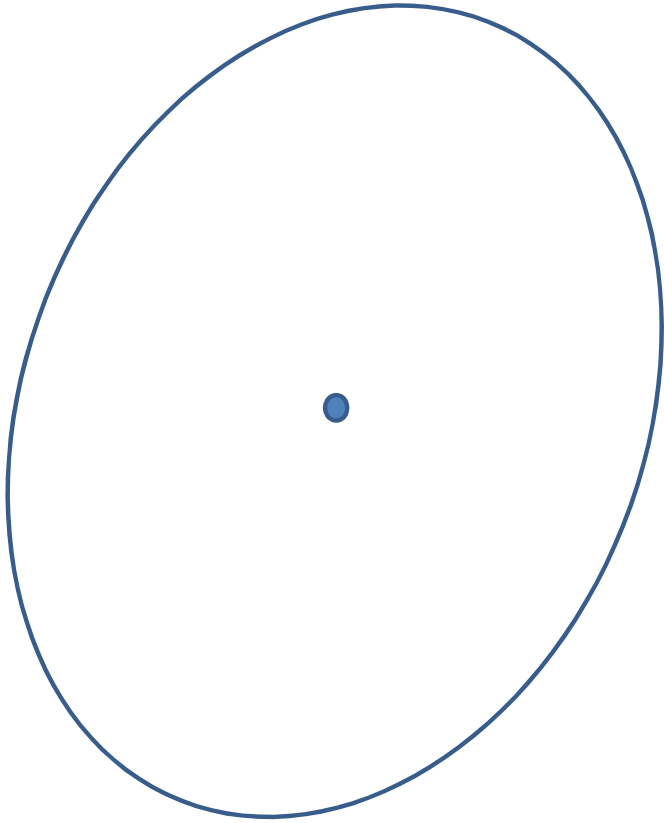
Example: **recursive k-means**

Agglomerative *a.k.a. bottom-up*: Start with each data point as its own cluster. Merge clusters until all points are in one big cluster.

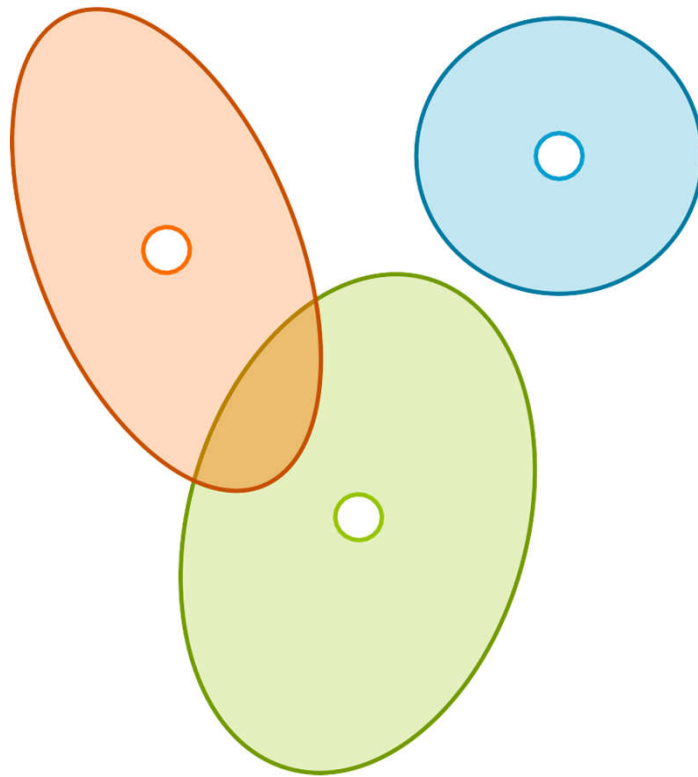
- Example: **Single linkage**
- **Complete linkage**
- **Average linkage**



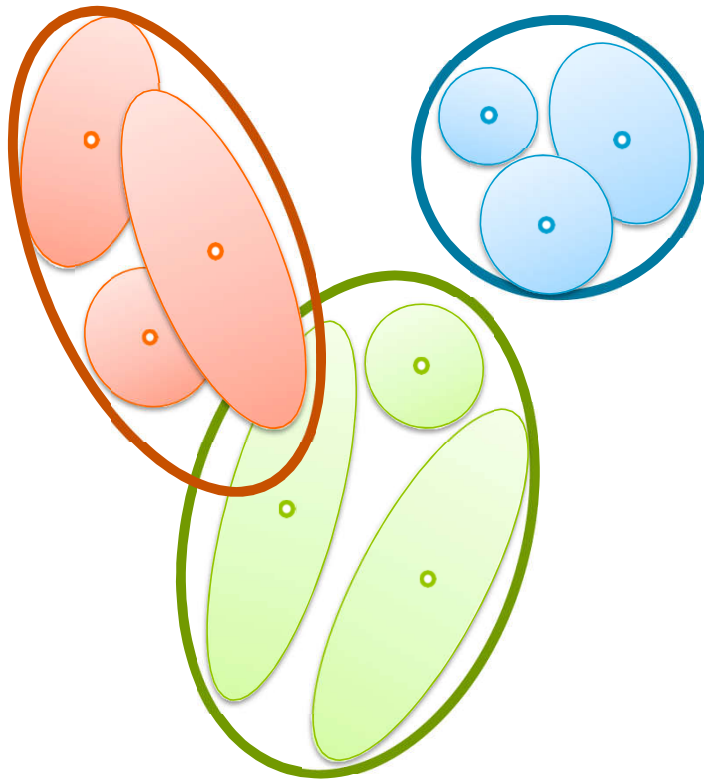
Divisive in pictures – level 1



Divisive in pictures – level 2



Divisive in pictures – level 3

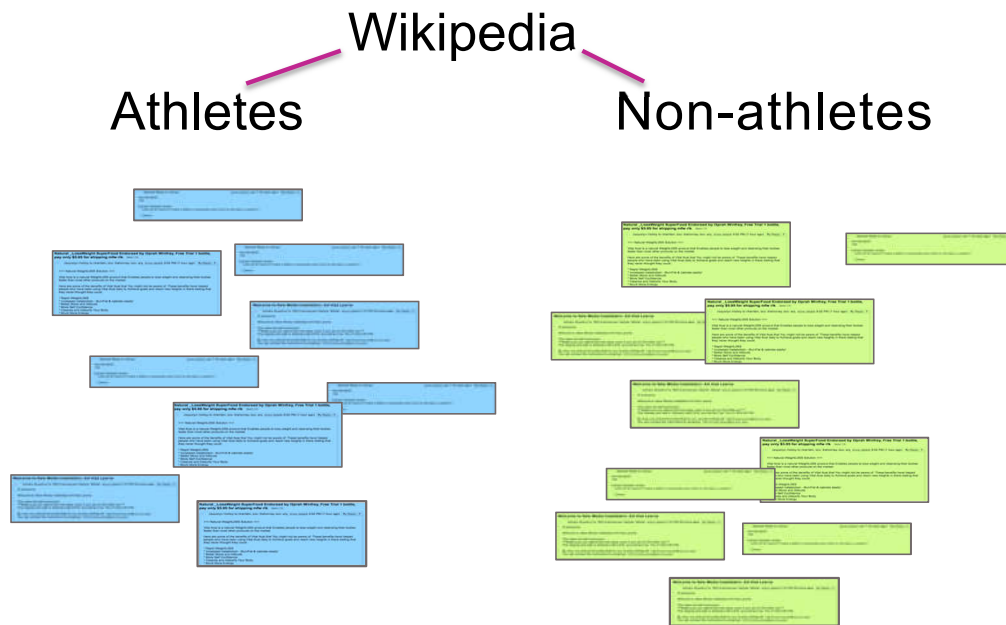


Divisive: Recursive k-means

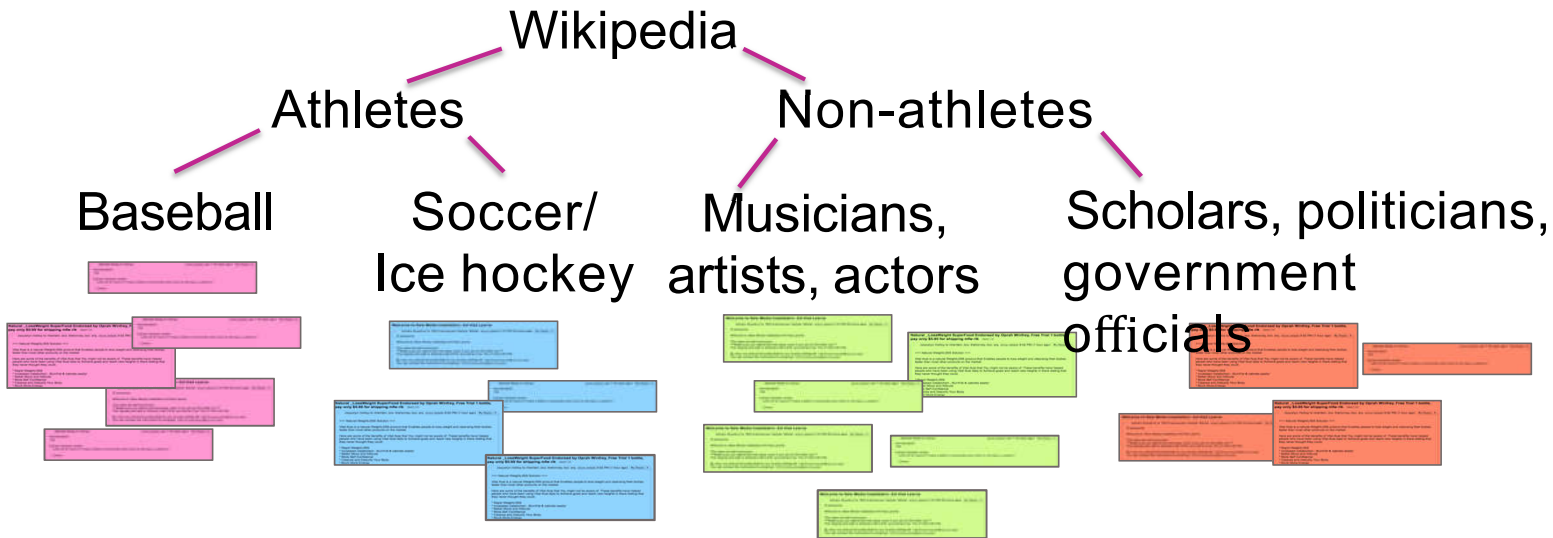
Wikipedia



Divisive: Recursive k-means



Divisive: Recursive k-means



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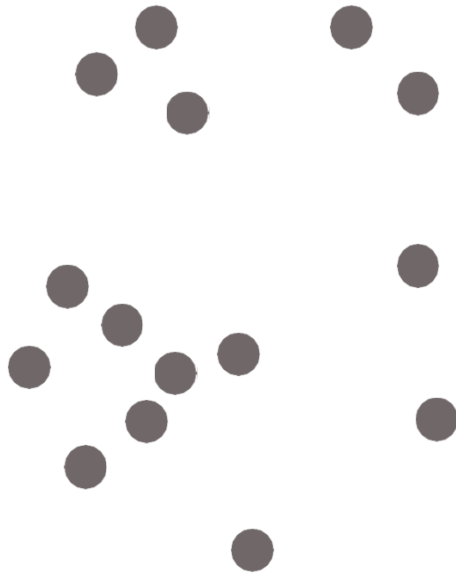


Divisive choices to be made

- Which algorithm to recurse
- How many clusters per split
- When to split vs. stop
 - Max cluster size:
number of points in cluster falls below threshold
 - Max cluster radius:
distance to furthest point falls below threshold
 - Specified # clusters:
split until pre-specified # clusters is reached

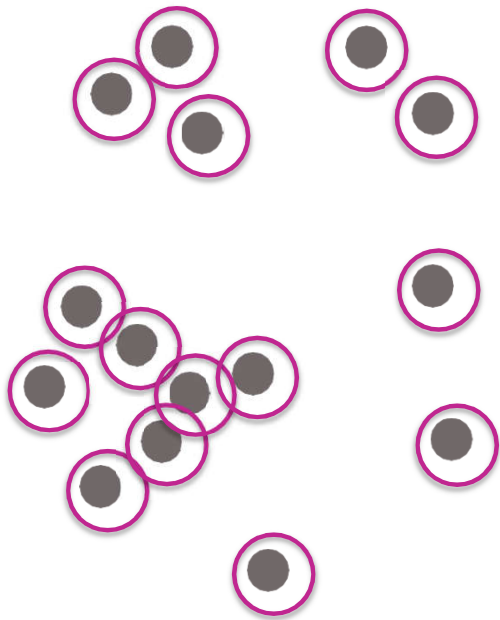
Agglomerative: Single linkage

1. Initialize each point to be its own cluster



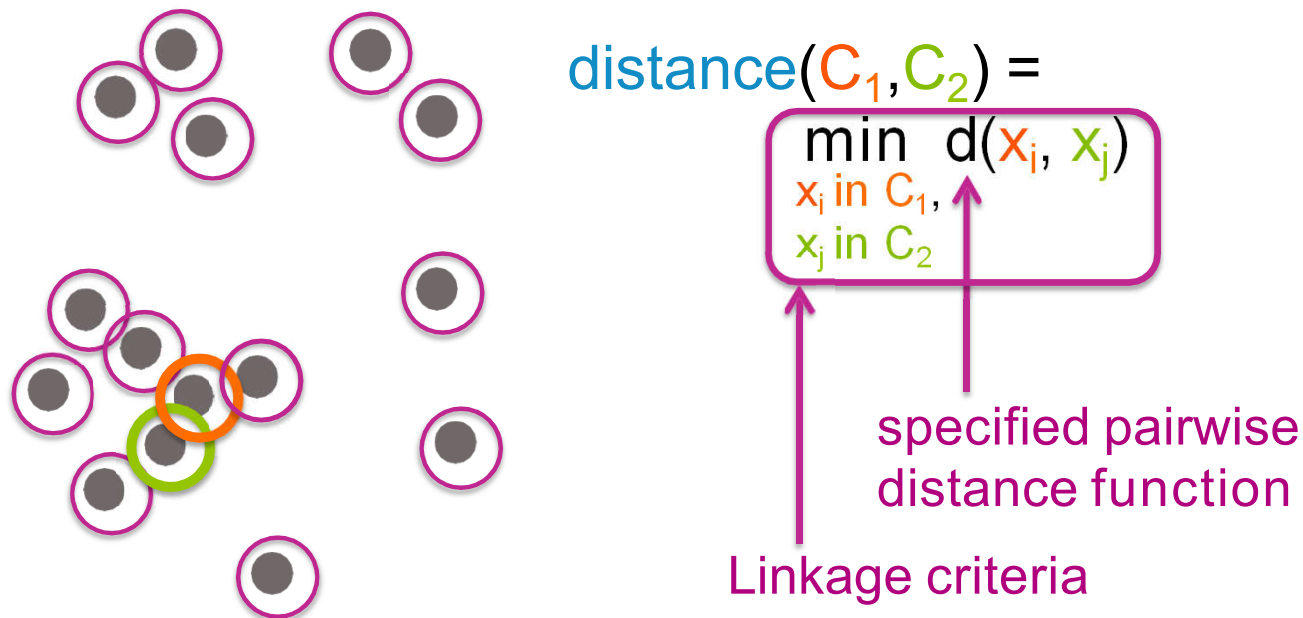
Agglomerative: Single linkage

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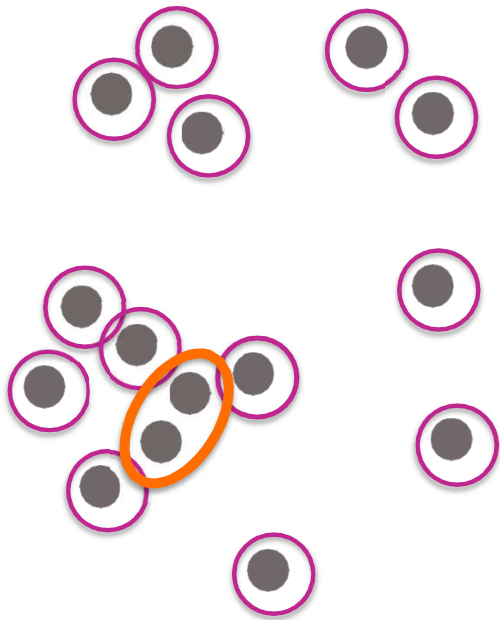
Agglomerative: Single linkage

2. Define distance between clusters to be:



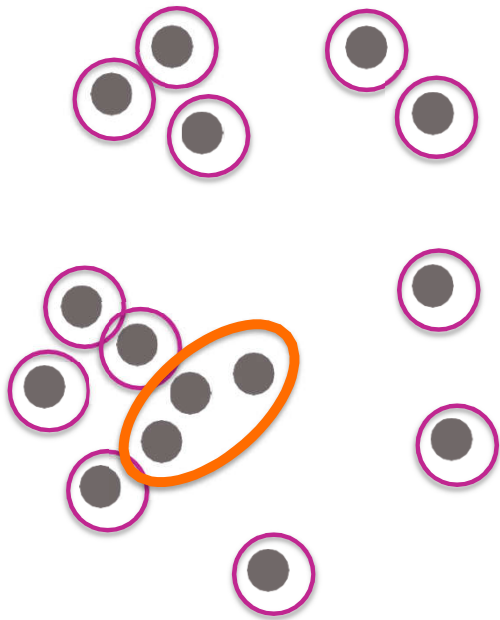
Agglomerative: Single linkage

3. Merge the two closest clusters



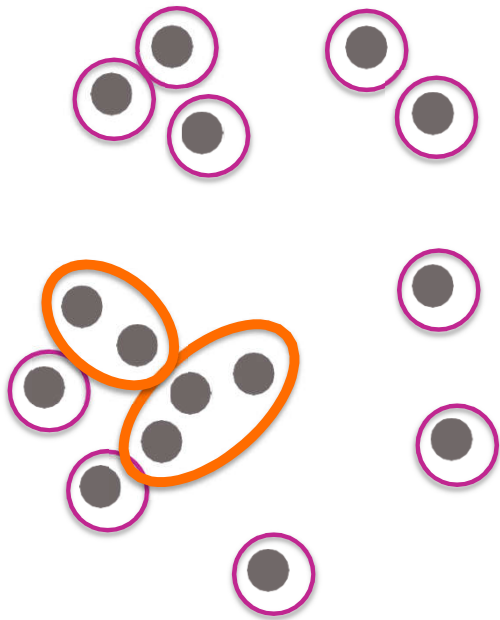
Agglomerative: Single linkage

4. Repeat step 3 until all points are in one cluster



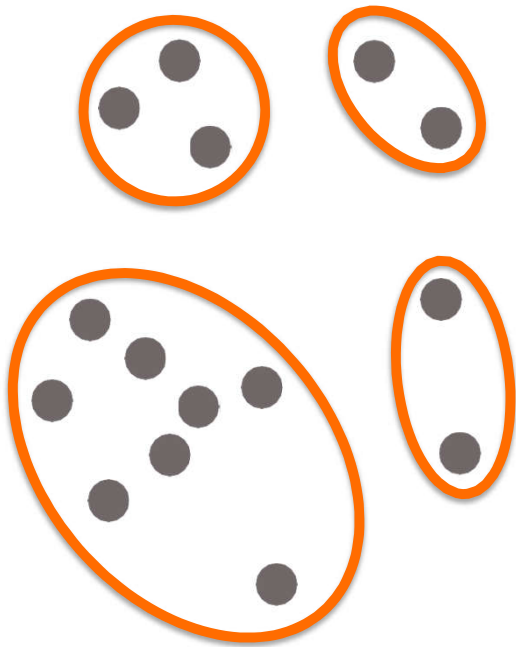
Agglomerative: Single linkage

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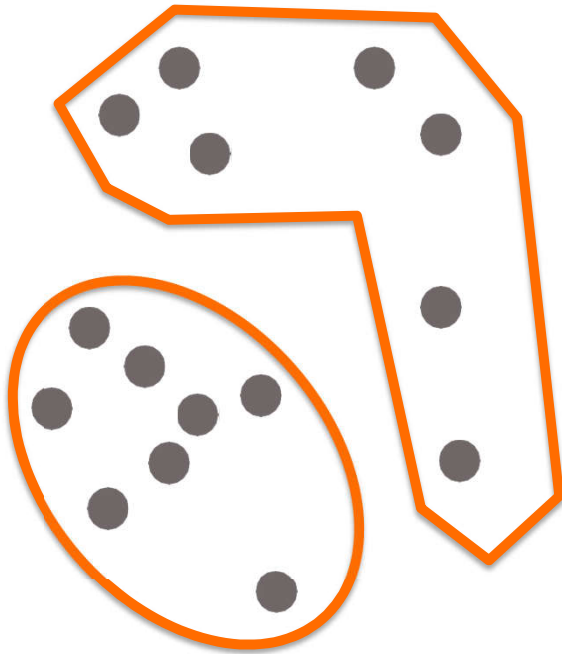
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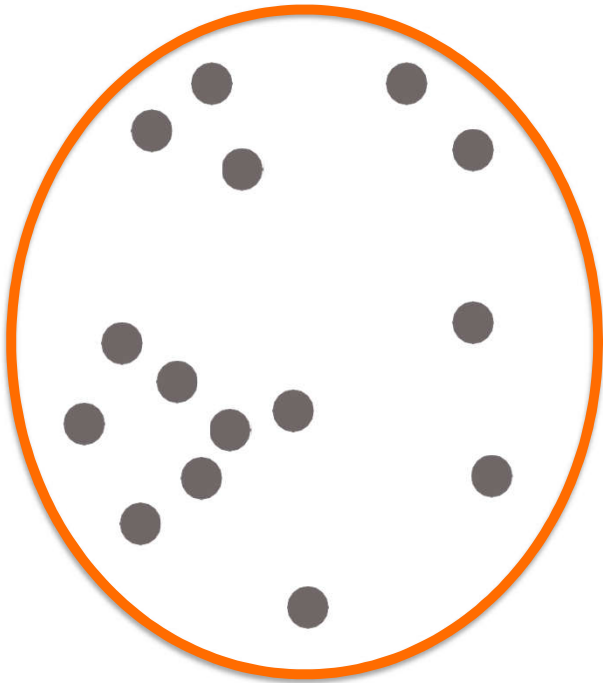
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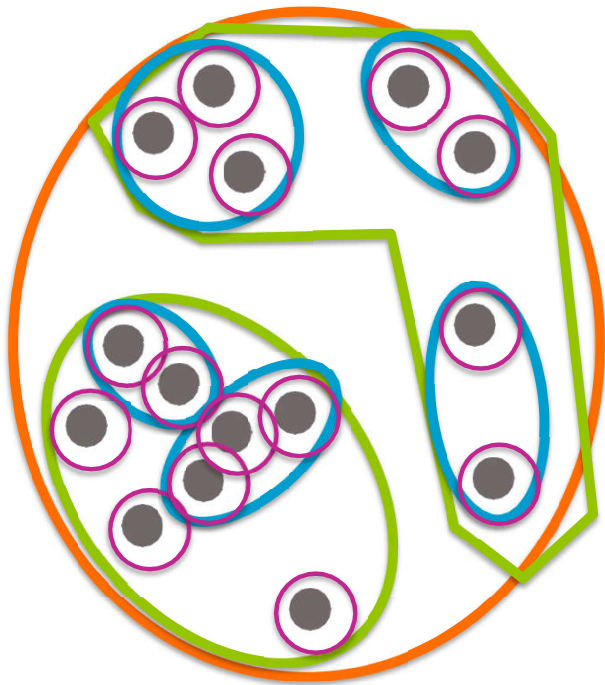
Agglomerative: Single linkage

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Clusters of clusters

Just like our picture for divisive clustering...



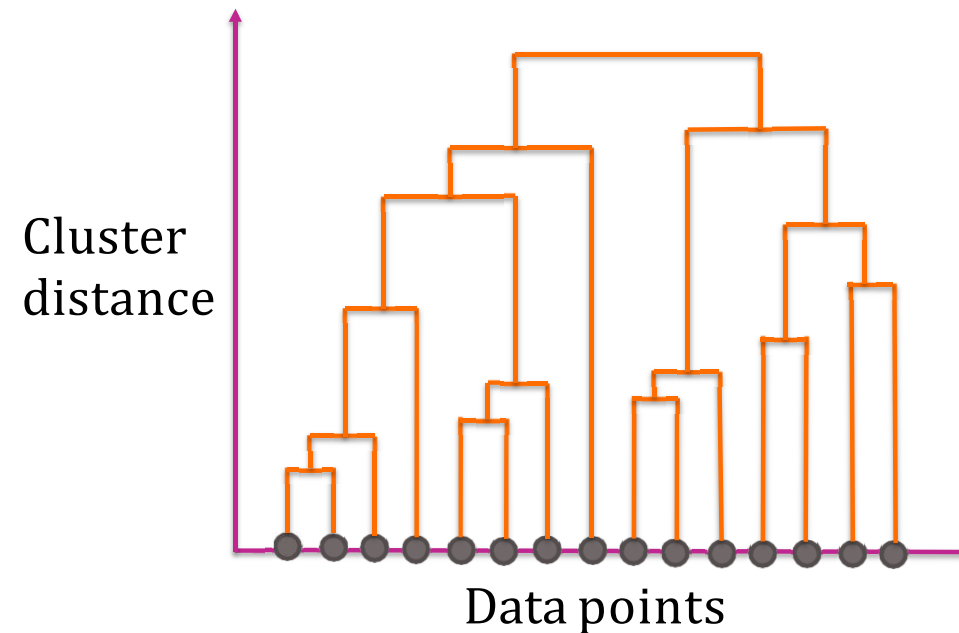


The dendrogram for
agglomerative clustering



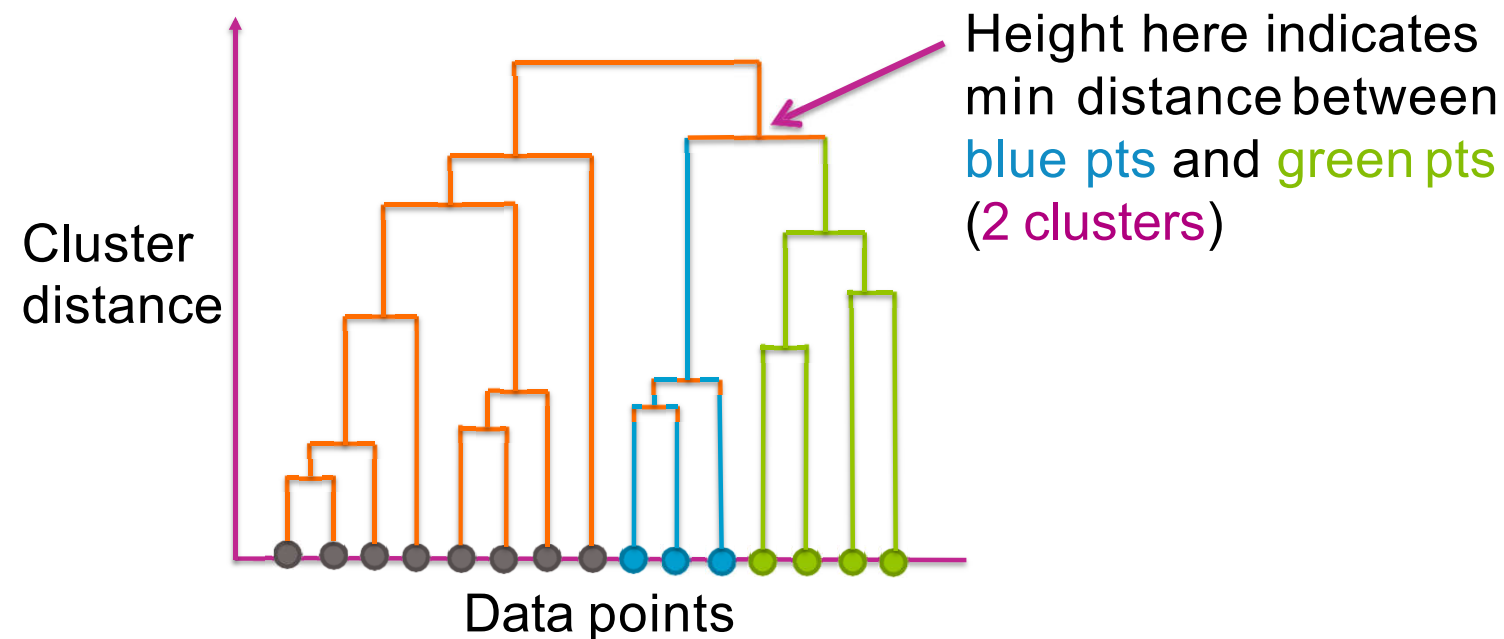
The dendrogram

- x axis shows data points (carefully ordered)
- y-axis shows distance between pair of clusters



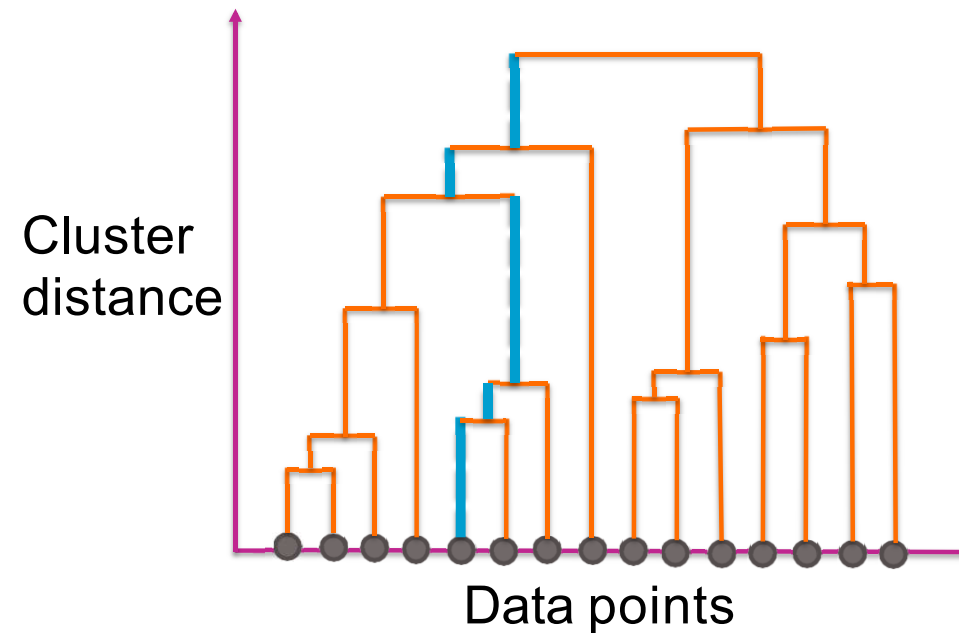
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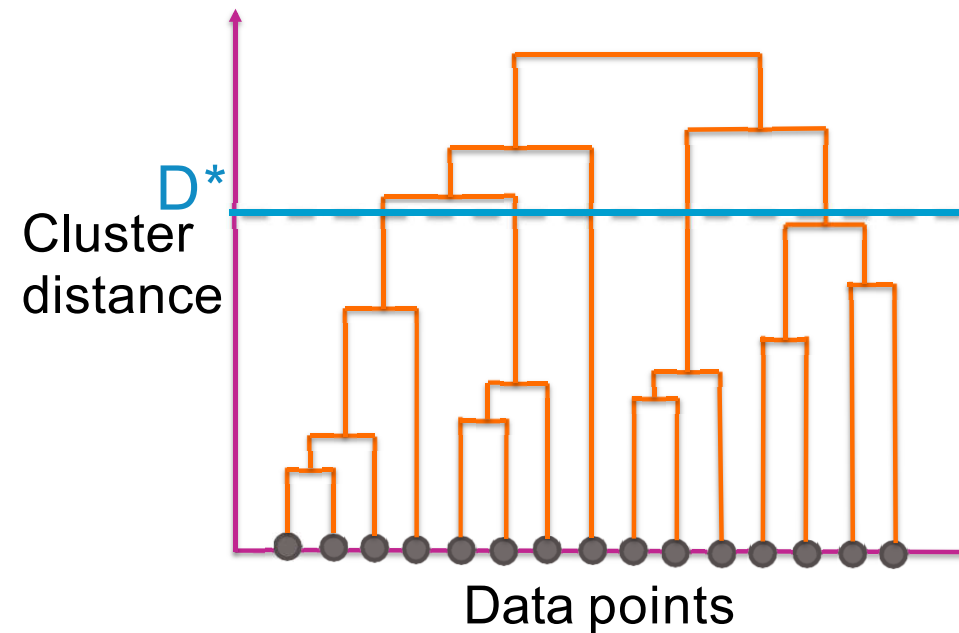
The dendrogram

Path shows all clusters to which a point belongs
and the order in which clusters merge



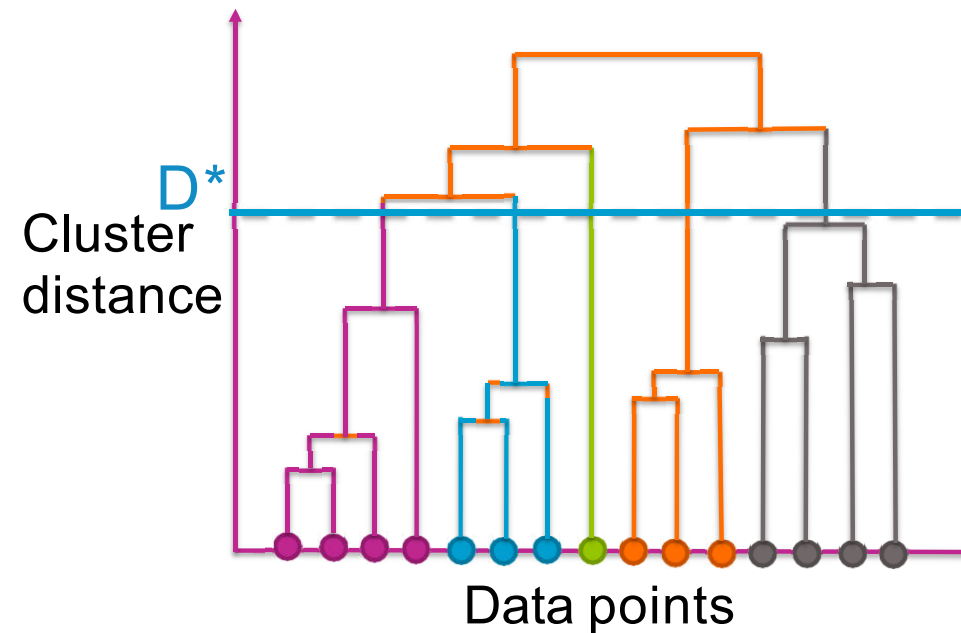
Extracting a partition

Choose a distance D^* at which to cut dendrogram



Extracting a partition

Every branch that crosses D^* becomes a separate cluster



Extracting a partition

Every branch that crosses D^* becomes a separate cluster





Extensions to Hierarchical Clustering

Major weakness of agglomerative clustering methods

Can never undo what was done previously

Do not scale well: time complexity of at least $O(n^2)$, where n is the number of total objects

Integration of hierarchical & distance-based clustering

BIRCH (1996): uses CF-tree and incrementally adjusts the quality of sub-clusters

CHAMELEON (1999): hierarchical clustering using dynamic modeling

BIRCH (Balanced Iterative Reducing and Clustering Using Hierarchies)

Incrementally construct a CF (Clustering Feature) tree, a hierarchical data structure for multiphase clustering

Phase 1 Building the CF tree

Phase 2: Clustering the subcluster

*It is also referred as **Two-Step Clustering***

A CF is a set of three summary statistics

Count: How many data values in the clusters.

Linear Sum: Sum the individual coordinates.

Squared Sum: Sum the squared coordinates.

Clustering Feature Vector in BIRCH

Clustering Feature (CF): $CF = (N, LS, SS)$

N : Number of data points

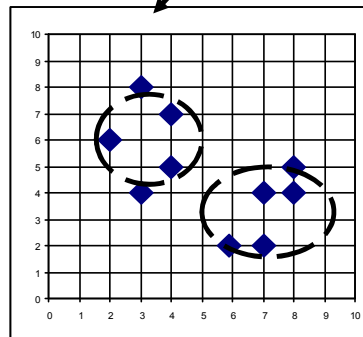
LS : linear sum of N points:

$$\sum_{i=1}^N x_i$$

SS : square sum of N points

$$\sum_{i=1}^N x_i^2$$

$CF = (5, (16,30),(54,190))$



(3,4)

(2,6)

(4,5)

(4,7)

(3,8)



CF-Tree in BIRCH

- A CF tree is a height-balanced tree that stores the clustering features for a hierarchical clustering

- A leaf node stores data points


- The nonleaf nodes store sums of the CFs of their children

A CF tree has three parameters

- Branching factor B:** max children allowed for a non-leaf node

- Threshold T:** Upper limit to the radius of a cluster in a leaf node

- Number of entries in a leaf node L**



Centroid, Radius

Centroid:

The “middle” of a cluster

$$\bar{x} = \frac{\sum x_i}{N}$$

Radius (R):

Average distance from member objects to the centroid

Square root of average distance from any point of the cluster to its centroid

$$R = \sqrt{\frac{\sum (x_i - \bar{x})^2}{N}}$$

$$R = \sqrt{\frac{SS - (LS)^2 / N}{N}}$$