

# MAST30013 – Techniques in Operations Research

## Semester 1 Tutorial 10

1. Consider the constrained nonlinear program

$$\begin{aligned} \min \quad & \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 - x_1 + x_2 \\ \text{subject to} \quad & x_1, x_2 \leq 0. \end{aligned}$$

- (a) Write down the log barrier penalty function  $P_k(\mathbf{x})$  with penalty parameter  $\alpha_k = k$ .
- (b) Write down  $\nabla P_k(\mathbf{x})$ , and solve  $\nabla P_k(\mathbf{x}) = \mathbf{0}$  to find any stationary points  $\mathbf{x}^k = (x_1^k, x_2^k)$  for  $P_k(\mathbf{x})$ .
- (c) Find all stationary points  $\mathbf{x}^k = (x_1^k, x_2^k)$  for  $P_k(\mathbf{x})$ , and find the limit  $\mathbf{x}^* = \lim_{k \rightarrow \infty} \mathbf{x}^k$ .
- (d) For each stationary point, write down an estimate  $\boldsymbol{\lambda}^k$  of the optimal Lagrange multiplier vector, and find the limit  $\boldsymbol{\lambda}^* = \lim_{k \rightarrow \infty} \boldsymbol{\lambda}^k$ .

2. Consider the constrained nonlinear program

$$\begin{aligned} \min \quad & x_1^2 + 2x_2^2 \\ \text{subject to} \quad & x_1^2 + x_2^2 \leq 1 \\ & x_1 + x_2 = 1. \end{aligned}$$

- (a) Find all KKT points and determine if any are minima.
- (b) Do the Lagrangian Saddle Point inequalities hold? That is, for feasible  $\mathbf{x}$  and  $\lambda \geq 0, \eta \in \mathbb{R}$ ,

$$L(\mathbf{x}^*, \lambda, \eta) \leq L(\mathbf{x}^*, \lambda^*, \eta^*) \leq L(\mathbf{x}, \lambda^*, \eta^*).$$

3. Consider the nonlinear program

$$\begin{aligned} \min \quad & \frac{1}{4}x_1^4 - \frac{1}{2}x_1^2 + x_2^2 \\ \text{subject to} \quad & x_1 \geq 0 \\ & x_2 \geq 2. \end{aligned}$$

- (i) Write down the log barrier penalty function  $P_k(\mathbf{x})$  with penalty parameter  $\alpha_k = k$ .
- (ii) Write down  $\nabla P_k(\mathbf{x})$ , and solve  $\nabla P_k(\mathbf{x}) = \mathbf{0}$  to find any stationary points  $\mathbf{x}^k = (x_1^k, x_2^k)$  for  $P_k(\mathbf{x})$ .
- (iii) Find the limit  $\mathbf{x}^* = \lim_{k \rightarrow \infty} \mathbf{x}^k$ .
- (iv) Find the limit  $\boldsymbol{\lambda}^* = \lim_{k \rightarrow \infty} \boldsymbol{\lambda}^k$ .