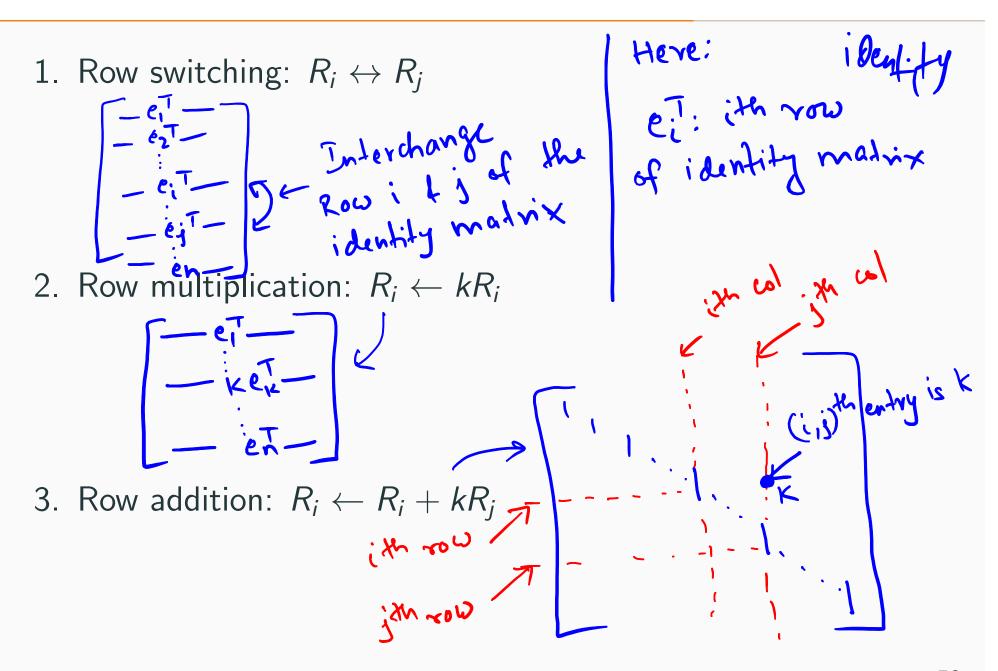
## **Elementary Row Operations**



### **Gauss Transforms**

What is  $\tau$ ?

$$egin{bmatrix} 1 & 0 \ - au & 1 \end{bmatrix} egin{bmatrix} v_1 \ v_2 \end{bmatrix} = egin{bmatrix} v_1 \ 0 \end{bmatrix}$$

More generally, which matrix to multiply on the left to create zeros below  $v_k$ ?

$$\begin{bmatrix} v_1 \\ \vdots \\ v_k \\ v_{k+1} \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} v_1 \\ \vdots \\ v_k \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

#### **Gauss Transforms**

Suppose  $v \in \mathbb{R}^n$  with  $v_k \neq 0$ . If

$$\tau^{T} = [0, \ldots, 0, \tau_{k+1}, \ldots, \tau_{n}], \quad \tau_{i} = \frac{v_{i}}{v_{k}}, \quad i = k+1:n,$$

Define:  $M_k = I_n - \tau e_k^T$ , then

$$M_{k}v = \begin{bmatrix} 1 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots & & \vdots & \vdots & \vdots \\ 0 & 1 & 0 & & 0 \\ 0 & & -\tau_{k+1} & 0 & & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & -\tau_{n} & 0 & \cdots & 1 \end{bmatrix} \begin{bmatrix} v_{1} \\ \vdots \\ v_{k} \\ v_{k+1} \\ \vdots \\ v_{n} \end{bmatrix} = \begin{bmatrix} v_{1} \\ \vdots \\ v_{k} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

### **Upper Triangularizing a Matrix**

$$A = \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 10 \end{bmatrix}$$

1. Make zeros below the diagonal of 1st column:

$$M_{1} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} \implies M_{1}A = \begin{bmatrix} 1 & 4 & 7 \\ 0 & -3 & -6 \\ 0 & -6 & -11 \end{bmatrix}$$

2. Make zeros below the diagonal of the above matrix

$$M_{2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \implies M_{2}M_{1}A = \begin{bmatrix} 1 & 4 & 7 \\ 0 & -3 & -6 \\ 0 & 0 & 1 \end{bmatrix}$$
here we have

### Remarks on upper triangularization

1. At the start of the kth loop we have a matrix

$$A^{(k-1)} = M_{k-1} \cdots M_1 A$$

that is upper triangular in columns 1 through k-1

2. The multipliers in the kth Gauss transform  $M_k$  are based on  $A^{(k-1)}(k+1:n,k)$  and  $a_{kk}^{(k-1)}$  must be non-zero in order to proceed

## Solving simultaneous linear systems: Matrix view

$$\begin{bmatrix} 3 & 5 \\ 6 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 9 \\ 4 \end{bmatrix}$$

Idea: Keep making zeros below the main diagonal. Then matrix becomes upper triangular, which can be solved using backward sweep.



### **Existence of LU factorization**

If no zero pivots are encountered, then Gauss transforms  $M_1, \ldots, M_{n-1}$  are generated such that

is upper triangular. This is 
$$2^{k}$$
 is upper triangular. This is  $2^{k}$  is upper triangular. This is  $2^{k}$  is only in sign.

If  $M_{k} = I_{n} \cap \tau^{(k)} e_{k}^{T}$ , then  $M_{k}^{-1} = I_{n} + \tau^{(k)} e_{k}^{T}$ , and  $M_{k} M_{k}^{T}$ 

$$A = LU, = \left( I_{n} - \tau^{k} e_{k}^{T} \right) \left( I_{n} + \tau^{k} e_{k}^{T} \right)$$

$$= I_{n} - \tau^{k} e_{k}^{T} + \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T}$$
where
$$L = M_{1}^{-1} \cdots M_{n-1}^{-1}$$

$$This is  $2^{k} e_{k}^{T}$ 

$$= I_{n} - \tau^{k} e_{k}^{T} + \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T}$$

$$= I_{n} - \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T}$$

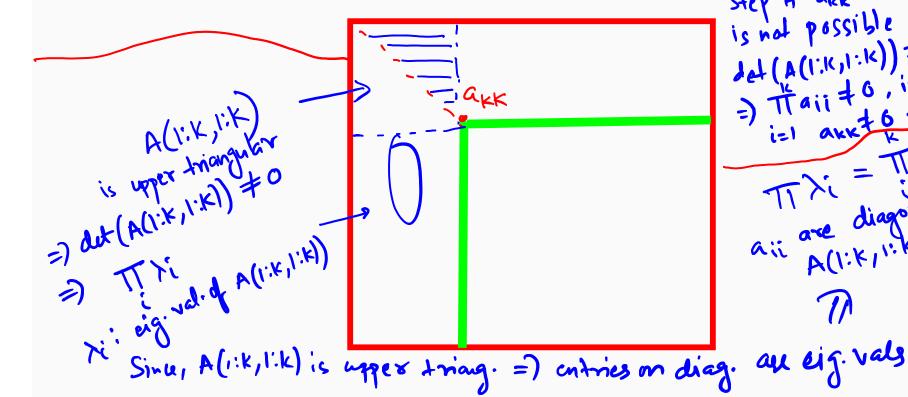
$$= I_{n} - \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T}$$

$$= I_{n} - \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T} \tau^{k} e_{k}^{T} e_$$$$

#### **LU Factorization**

If  $A \in \mathbb{R}^{n \times n}$  and  $\det(A(1:k,1:k)) \neq 0$  for k=1:n-1, then there exists a unit lower trianguar  $L \in \mathbb{R}^{n \times n}$  and an upper triangular  $U \in \mathbb{R}^{n \times n}$  such that A = LU. If this is the case and A is nonsingular, then the factorization is unique and

 $\det(A) = u_{11}u_{22}\cdots u_{nn}.$ 



Lu can't proceed after kth step if akk is zero, but this is not possible because =) Itaii + 6, in particular, aii are diagonal entries of A(1:K/1:K)

# Simplify L

$$L = M_1^{-1} \cdots M_{n-1}^{-1}$$

Construction of *L* is not complicated:

$$L = M_1^{-1} \cdots M_{n-1}^{-1}$$

$$= (I_n - \tau^{(1)} e_1^T)^{-1} \cdots (I_n - \tau^{(n-1)} e_{n-1}^T)^{-1}$$

$$= (I_n + \tau^{(1)} e_1^T) \cdots (I_n + \tau^{(n-1)} e_{n-1}^T)$$
Here  $\tau^k = [0, \cdots, 0, \tau^{k+1}, \cdots, \tau^n]^T$ .

L looks complicated but it is not.

Have a look at "mix" terms:

$$\tau^{(i)}e_i^T\tau^{(j)}e_j^T$$

# Simplify L

Does these "mix" terms:

survive? 
$$e_i^{T} = [o, o, ..., 1, o, ..., o]$$
,  $f(i) = [o, o, ..., o, \tau_{j+1}, \tau_{j+2}, ..., \tau_{n}]^{T}$ 

For  $j7$ ,  $e_i^{T} = 0$ 

Henu,  $L$  now becomes after removing the mixed terms, we get:

$$L = I_n + \sum_{k=1}^{n-1} \tau^{(k)} e_k^T, \quad L(k+1:n,k) = \tau^{(k)}(k+1:n)$$
This means =)
$$\begin{cases} L_{k+1} \\ L_{k+2} \\ L_{k+2} \end{cases} = \begin{bmatrix} \tau^{(k)}(k+1) \\ \tau^{(k+1)} \\ \tau^{(k)} \end{cases}$$