

HW 1

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1. Suppose you want to approximate the function

$$f(t) = \begin{cases} -1 & \text{if } -1 \leq t < 0, \\ 0 & \text{if } t = 0, \\ 1 & \text{if } 0 < t \leq 1 \end{cases}$$

by a constant function  $\varphi(x) = c$ :

- (a) on  $[-1, 1]$  in the continuous  $L_1$  norm,
- (b) on  $\{t_1, t_2, \dots, t_N\}$  in the discrete  $L_1$  norm,
- (c) on  $[-1, 1]$  in the continuous  $L_2$  norm,
- (d) on  $\{t_1, t_2, \dots, t_N\}$  in the discrete  $L_2$  norm,
- (e) on  $[-1, 1]$  in the  $\infty$ -norm,
- (f) on  $\{t_1, t_2, \dots, t_N\}$  in the discrete  $\infty$ -norm.

The weighting in all norms is uniform (i.e.,  $w(t) \equiv 1$ ,  $w_i \equiv 1$ ) and  $t_i = -1 + \frac{2(i-1)}{N-1}$ ,  $i = 1, 2, \dots, N$ . Determine the best constant  $c$  (or constants  $c$ , if there is nonuniqueness) and the minimum error.

$$a) E[\epsilon] = \|f(t) - \varphi(t)\|_1 = \int_{-1}^1 |f(t) - c| dt$$

Then note we can set:

$$f(t) = c \rightarrow f'(c) = t.$$

Then we have:

$$E[\epsilon] = \int_{-1}^{f'(c)} (c - f(t)) dt + \int_{f'(c)}^1 (f(t) - c) dt$$

$$= \int_{-1}^{f'(c)} c dt - \int_{-1}^{f'(c)} f(t) dt + \int_{f'(c)}^1 f(t) dt - \int_{f'(c)}^1 c dt$$

$$= c f'(c) + c - c + c f'(c) - \int_{-1}^{f'(c)} f(t) dt + \int_{f'(c)}^1 f(t) dt.$$

$$= 2c f'(c) - \int_{-1}^{f'(c)} f(t) dt + \int_{f'(c)}^1 f(t) dt$$

$$\frac{d}{dc} [E[c]] = 2f'(c) + 2c \frac{d}{dc} [f'(c)] + 2 [f(f'(c)) \frac{d}{dc} [f'(c)]]$$

$$= 2f'(c) = 0 \rightarrow c = 0 \rightarrow E[\epsilon] = 1 - (-1) = 2$$

$$b) E[\epsilon] = \sum_{i=1}^N |f(t_i) - c|$$

Since the points are uniformly distributed.

Note that if  $N$  is even then we havehalf points have  $f(t)=1$  and other half have  $f(t)=-1$ If  $N$  is odd then we have one point has  $f(t)=0$ 

And others similar.

Thus choose  $c=0$  will balance the points on each side.Then  $E[\epsilon] = N$  if  $N$  is even $E[\epsilon] = N-1$  if  $N$  is odd

$$\begin{aligned} c) E[\epsilon] &= \left[ \int_{-1}^1 (f(t) - c)^2 dt \right]^{\frac{1}{2}} \\ &= \left[ \int_{-1}^0 (f(t) - c)^2 dt + \int_0^1 (f(t) - c)^2 dt \right]^{\frac{1}{2}} \\ &= \left[ (1-c)^2 t \Big|_0^1 + (1-c)^2 t \Big|_0^1 \right]^{\frac{1}{2}} \\ &= \left[ (1-c)^2 + (1-c)^2 \right]^{\frac{1}{2}} \\ &= \left[ 1+2c+c^2 + 1-2c+c^2 \right]^{\frac{1}{2}} = \left[ 2c^2 + 2 \right]^{\frac{1}{2}} \end{aligned}$$

Then note:

$$\frac{d}{dc} [E[\epsilon]] = \frac{1}{2} (2c^2 + 2)^{-\frac{1}{2}} \cdot 4c = 0$$

$$\Rightarrow 4c = 0 \rightarrow c = 0$$

$$E[\epsilon] = \sqrt{2}$$

Note this can't be 0.

$$d) E[e] = \left[ \sum_{1 \leq i \leq N} (f(t_i) - c)^2 \right]^{\frac{1}{2}}$$

Since the points are uniformly distributed

Note that if  $N$  is even then we have

half points have  $f(t_i) = 1$  and other half have  $f(t_i) = -1$

If  $N$  is odd than we have one point has  $f(t_i) = 0$

And others similar.

Thus choose  $c=0$  will balance the points on each side.

$$\text{Then } E[e] = \sqrt{N} \text{ if } N \text{ is even}$$

$$E[e] = \sqrt{N-1} \text{ if } N \text{ is odd}$$

$$e) E[e] = \max_{1 \leq i \leq N} |f(t_i) - c|$$

Note the only values for  $f(t_i)$  is:  $-1, 0, 1$

Then the constant that minimizes the maximum absolute difference

is the one halfway the extreme values.

$$\Rightarrow c = 0$$

$$E[e] = 1$$

$$f) E[e] = \max_{1 \leq i \leq N} |f(t_i) - c|$$

Since the points are uniformly distributed

Note that if  $N$  is even then we have

half points have  $f(t_i) = 1$  and other half have  $f(t_i) = -1$

If  $N$  is odd than we have one point has  $f(t_i) = 0$

And others similar.

Thus choose  $c=0$  will balance the points on each side.

$$E[e] = 1$$

2. Consider the data

$$f(t_i) = 1, \quad i = 1, 2, \dots, N-1; \quad f(t_N) = y \gg 1.$$

- (a) Determine the discrete  $L_\infty$  approximant to  $f$  by means of a constant  $c$  (polynomial of degree zero).
- (b) Do the same for discrete (equally weighted) least square approximation.
- (c) Compare and discuss the results, especially as  $N \rightarrow \infty$ .

a) Set  $e(x) = c$

Then we have:

$$E[e] = \|f(t) - c\|_\infty = \max_{1 \leq t \leq N} |f(t) - c|$$

Note since  $f(t_N) = y \gg 1$

Then note the value  $c$  that will minimize the maximum difference should be the halfway between two extreme values: 1 and  $y$

Thus  $c = \frac{1+y}{2}$

b) Set  $e(x) = c$

Then we have:

$$\begin{aligned} E[e] &= \|f(t) - c\|_2 = \left[ \sum_{i=1}^N (f(t_i) - c)^2 \right]^{\frac{1}{2}} \\ &= \left[ \sum_{i=1}^{N-1} (1-c)^2 + (y-c)^2 \right]^{\frac{1}{2}} \\ &= [(N-1)(1-c)^2 + (y-c)^2]^{\frac{1}{2}} \end{aligned}$$

$$2NC = 2y + 2N - 2$$

$$C = \frac{y+N-1}{N}$$

$$\begin{aligned} \frac{d}{dc} [E[e]^2] &= 2(N-1)(1-c) \cdot (-1) + 2(y-c) \cdot (-1) \\ &= -2N + 2 + 2NC - 2C - 2y + 2c \\ &= 2NC - 2N - 2y + 2 = 0 \end{aligned}$$

c). Note for  $L_\infty$  as  $N$  goes to infinity.

$C$  will stay the same.

Since  $L_\infty$  only cares about the maximum deviation.

Thus it only cares about the extreme scenario.

However this is less accurate when  $N \rightarrow \infty$ .

Then for  $L_2$  as  $N$  goes to infinity

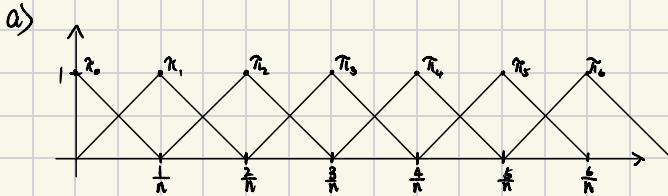
$C$  will converge to 1.

Which makes more sense since there will be only one outlier  $f(t_N) = y$ .

Thus in general it's more accurate.

13. Given an integer  $n \geq 1$ , consider the subdivision  $\Delta_n$  of the interval  $[0, 1]$  into  $n$  equal subintervals of length  $1/n$ . Let  $\pi_j(t)$ ,  $j = 0, 1, \dots, n$ , be the function having the value 1 at  $t = j/n$ , decreasing on either side linearly to zero at the neighboring subdivision points (if any), and being zero elsewhere.

- Draw a picture of these functions. Describe in words the meaning of a linear combination  $\pi(t) = \sum_{j=0}^n c_j \pi_j(t)$ .
- Determine  $\pi_j(k/n)$  for  $j, k = 0, 1, \dots, n$ .
- Show that the system  $\{\pi_j(t)\}_{j=0}^n$  is linearly independent on the interval  $0 \leq t \leq 1$ . Is it also linearly independent on the set of subdivision points  $0, \frac{1}{n}, \frac{2}{n}, \dots, \frac{n-1}{n}, 1$  of  $\Delta_n$ ? Explain.
- Compute the matrix of the normal equations for  $\{\pi_j\}$ , assuming  $d\lambda(t) = dt$  on  $[0, 1]$ . That is, compute the  $(n+1) \times (n+1)$  matrix  $A = [a_{ij}]$ , where  $a_{ij} = \int_0^1 \pi_i(t) \pi_j(t) dt$ .



The linear combination of  $\pi_j$ 's combines all the function  $\pi_j$ 's. Where each function's contribution is determined by the coefficient  $c_j$ . If  $c_j$  varies then it will create a bunch of triangles along  $[0, 1]$  with different heights.

b)  $\pi_j(k/n) = \begin{cases} 1 & \text{for } k=j \\ 0 & \text{otherwise} \end{cases}$

c) First note that  $\{\pi_j(t)\}_{j=0}^n$  is linearly independent if:

$$\sum_{j=0}^n c_j \pi_j(t) = 0 \text{ for } t \in [0, 1] \rightarrow c_j = 0 \text{ for } j \in \{0, 1, \dots, n\}$$

Then note  $\pi_j(\frac{k}{n}) = 1$  for  $j=k$  and  $\pi_j(\frac{k}{n}) = 0$  for  $j \neq k$

Then also note we have  $n+1$  sums:

$$S_0 = \sum_{j=0}^n c_j \pi_j(0) = \pi_0 = 0$$

$$S_{\frac{1}{n}} = \sum_{j=0}^n c_j \pi_j(\frac{1}{n}) = \pi_1 = 0$$

$$S_{\frac{2}{n}} = \sum_{j=0}^n c_j \pi_j(\frac{2}{n}) = \pi_2 = 0$$

$$\vdots$$

$$S_n = \sum_{j=0}^n c_j \pi_j(n) = \pi_n = 0$$

Thus  $\pi_0, \dots, \pi_n = 0$  if  $\sum_{j=0}^n c_j \pi_j(t) = 0$  for  $t \in [0, 1]$

Thus it is lin. indep. on  $t \in [0, 1]$   $\square$

Note it's not linearly independent on the Subintervals.

If we let  $k$  be a fix value

Then  $\sum_{j=0}^n c_j \pi_j(\frac{k}{n})$  would only require  $c_k = 0$

And  $c_1, \dots, c_{k-1}, c_{k+1}, \dots, c_n$  can be any value

Since  $\pi_j(\frac{k}{n}) = 0$ .

Thus not lin. indep.  $\square$

d)

$$A = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ 0 & 0 & \ddots & \vdots \\ \vdots & & \ddots & 1 \\ 0 & 0 & \cdots & 0 \end{bmatrix} = I^{n+1}$$

4. Using an orthogonal polynomial basis, find the best least squares polynomial approximation of degree 2 to the function  $f(t) = e^t$  on  $[0, 1]$ ; i.e., find  $p_2(t)$  that minimizes

$$\int_0^1 (e^t - p_2(t))^2 dt.$$

If the monomial basis is used, will the resulting polynomial be the same as the one obtained with the orthogonal basis? Explain.

First note a common choice for the orthogonal polynomial basis is the Legendre polynomial:

$$P_0^*(t) = 1$$

$$P_1^*(t) = t$$

$$P_2^*(t) = \frac{1}{2}(3t^2 - 1)$$

Then since we are focused on  $[0, 1]$  we have: (plug in  $2t-1$ )

$$P_0^*(t) = 1$$

$$P_1^*(t) = 2t - 1$$

$$P_2^*(t) = 6t^2 - 6t + 1$$

Then set:

$$p_2(t) = C_0 + C_1(2t-1) + C_2(6t^2 - 6t + 1)$$

Then we have:

$$E[P_2(t)] = \int_0^1 (e^t - P_2(t))^2 dt$$

$$\begin{aligned} \frac{\partial}{\partial C_1} [E[P_2(t)]] &= \int_0^1 2(e^t - P_2(t)) dt \\ &= 2(e^t \Big|_0^1 - C_1 t \Big|_0^1 - C_2 t^2 \Big|_0^1 + C_2 t \Big|_0^1 - 2C_2 t^3 \Big|_0^1 + 3C_2 t^2 \Big|_0^1 - C_2 t \Big|_0^1) \\ &= 2(e - 1 - C_1 - \cancel{C_2} + \cancel{C_2} - 2C_2 + 3(C_2 - \cancel{C_2})) \\ &= 2e - 2 - 2C_1 = 0 \rightarrow C_1 = e - 1 \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial C_2} [E[P_2(t)]] &= \int_0^1 2(e^t - P_2(t))(2t-1) dt \\ &= 2(3 - \frac{C_0+2e}{3}) = 0 \rightarrow C_2 = 9-3e \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial C_0} [E[P_2(t)]] &= \int_0^1 2(e^t - P_2(t))(6t^2 - 6t + 1) dt \\ &= 2 \left( -\frac{C_0-35e}{5} - 19 \right) = 0 \\ \Rightarrow C_0 &= -95 + 35e \end{aligned}$$

Note by definition we know.

Any monomial basis can be written as a linear combination of orthogonal polynomial basis.

Thus if we use monomial basis, the result will be the same.