

Lecture 05

Finite-Sample Properties of OLS

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The Yale logo, consisting of the word "Yale" in a blue, serif font.

Goals for today

1. Linear models assumptions
2. OLS Finite sample properties

LINEAR MODELS ASSUMPTIONS

I. Linearity

We observe a pair of random variables (y, X) , which have the following relationship for some random vector ϵ and fixed vector β :

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We assume that the following dimensions hold.

$$y \in \mathbb{R}^n$$

$$X \in \mathbb{R}^{n \times p}$$

$$\beta \in \mathbb{R}^p$$

$$\epsilon \in \mathbb{R}^n$$

II. Strict exogeneity

For all X , we have:

$$\mathbb{E}(\epsilon|X) = 0 \tag{1}$$

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Notice that this implies the weaker assumption we used with simple linear models:

$$\mathbb{E}(\epsilon) = \mathbb{E}\{\mathbb{E}(\epsilon|X)\} \quad (2)$$

$$= \mathbb{E}\{0\} \quad (3)$$

$$= 0 \quad (4)$$

III. No multicollinearity

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When broken, it is impossible to do inference on β without additional assumptions.

IV. Spherical errors

The variance of the errors is given by:

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We can break this assumption into two parts; the *homoscedasticity* assumption:

$$\mathbb{E}(\epsilon_i^2) = \sigma^2$$

and *no autocorrelation* assumption:

$$\mathbb{E}(\epsilon_i \epsilon_j) = 0 \quad i \neq j$$

V. Normality

The final, most restrictive assumption, is that the errors follow a multivariate normal distribution:

$$\epsilon \sim \mathcal{N}(0, \sigma^2 \mathbb{I}_n)$$

Classical linear model assumptions

I. Linearity $Y = X\beta + \epsilon$

II. Strict exogeneity $\mathbb{E}(\epsilon|X) = 0$

III. No multicollinearity $\mathbb{P}[\text{rank}(X) = p] = 1$

IV. Spherical errors $\mathbb{V}(\epsilon|X) = \sigma^2 \mathbb{I}_n$

V. Normality $\epsilon \sim \mathcal{N}(0, \sigma^2 \mathbb{I}_n)$

FINITE SAMPLE PROPERTIES

Ordinary least squares

We have already derived the ordinary least square estimator:

$$\hat{\beta} = (X^t X)^{-1} X^t y$$

If we define the following values:

$$S_{xx} = \frac{1}{n} X^t X$$
$$s_{xy} = \frac{1}{n} X^t y$$

The ordinary least squares estimator can also be written:

$$\hat{\beta} = S_{xx}^{-1} s_{xy}$$

A form that will be useful for large sample theory.

Special matrices

Last time we defined the following matrices:

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Today we have one more matrix A that does not have a direct geometric interpretation but is nonetheless very useful:

$$A = (X^tX)^{-1}X^t$$

$$Ay = \hat{\beta}$$

Last time we showed that:

$$P^2 = P^t = P$$

$$M^2 = M^t = M$$

$$PX = X$$

$$MX = 0$$

$$Py = X\beta$$

$$My = M\epsilon = r$$

The matrix A is not square, but the outer product has a nice property:

$$\begin{aligned} AA^t &= (X^tX)^{-1}X^tX(X^tX)^{-1} \\ &= (X^tX)^{-1} \end{aligned}$$

Two final definitions

The residuals and estimate of the σ^2 parameter are given as:

$$r = y - X\hat{\beta}$$

$$s^2 = \frac{1}{n - p} r^t r$$

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Under assumptions I-III:

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Under assumptions I-V:

(F) $\hat{\beta}$ achieves the Cramér–Rao lower bound

(A) Unbiased regression estimate $\hat{\beta}$

Notice that the error in our estimate can be re-written in terms of the matrix A :

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From here, we can derive the unbiased result easily:

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The formula for the variance of the ordinary least squares estimator can be derived from our assumptions and prior results.

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(E) Unbiased s^2

We have already established that $r^tr = \epsilon^t M \epsilon$, so all we need to do is show that $\mathbb{E}(\epsilon^t M \epsilon | X) = \sigma^2(n - p)$.

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We can write this expected value in terms of the trace of M :

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Plugging back into the original yields the result.