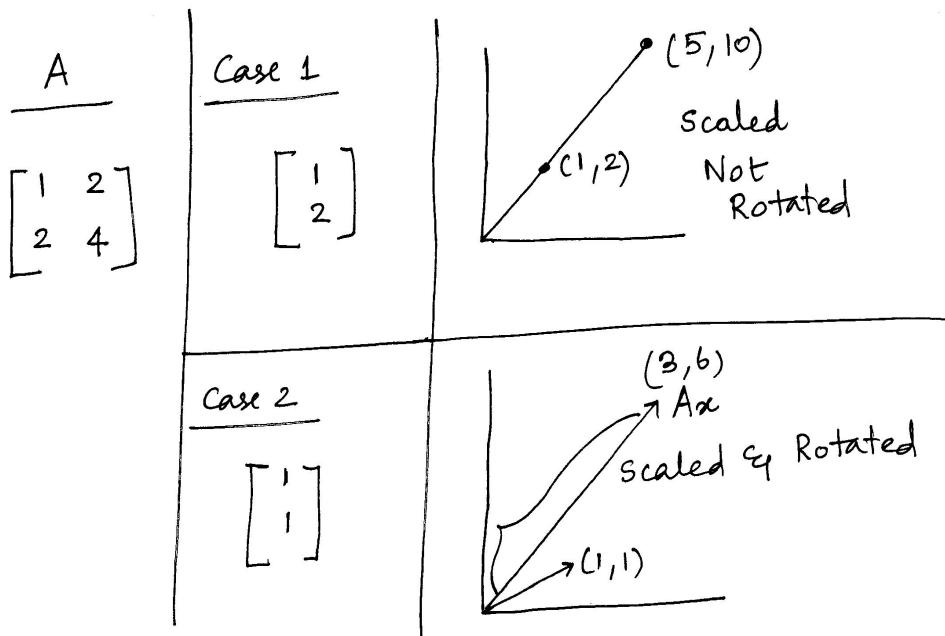


## EIGEN VALUE & EIGEN VECTORS [defined for square matrices]

Product of matrix A & vector  $x = Ax$



A vector that undergoes pure scaling without rotation is known as EIGEN VECTOR.

Scaling factor / Stretch Ratio is known as EIGEN VALUE

$$Ax = \begin{bmatrix} 5 \\ 10 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$Ax = \underset{\substack{\text{scalar}}}{{\circledcirc}} x$$

Eigen value / characteristic eqn  $\boxed{Ax = \lambda x}$  where  
 $x$  is eigen vector &  $\lambda$  is eigen value.

Applications of Eigen Value -> 1) Solve system of Linear differential equations

- 2) describe natural frequencies of vibrations
- 3) distinguish states of energy.

1) Eigen Vectors must be NON TRIVIAL (they cannot be zero vector)

2) A matrix is SINGULAR if and only if it has ZERO EIGEN VALUE

3) Trace of Matrix  $\text{tr}(A)$  = Sum of elements on  
(defined only for main diagonal  
square matrix)

$$\boxed{\text{tr}(A) = \lambda_1 + \lambda_2 + \dots + \lambda_n} = \sum_{j=1}^n \lambda_j \quad \text{Sum of}$$

eigenvalues of a matrix

$$\begin{bmatrix} 2 & -5 & 5 \\ 0 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix}$$

$$\text{tr } A = 2 + 3 + 3 = 8$$

4)  $\boxed{\det(\text{matrix}) = \lambda_1 \lambda_2 \dots \lambda_n = \text{Product of Eigenvalues of Matrix}}$

$$= \prod_{j=1}^n \lambda_j$$

5) The eigenvalues of an upper (lower) triangular matrix are elements on the main diagonal.

6) If  $\lambda$  is Eigenvalue of  $A$  and  $A$  is invertible then

$\frac{1}{\lambda}$  is an Eigenvalue of  $A^{-1}$

7) Eigenvalues of  $A = A^T$  Eigenvalues

8) Square matrix  $A_{n \times n}$  can have Multiple Eigenvalues

but no more than its Number of Rows / Number of columns)

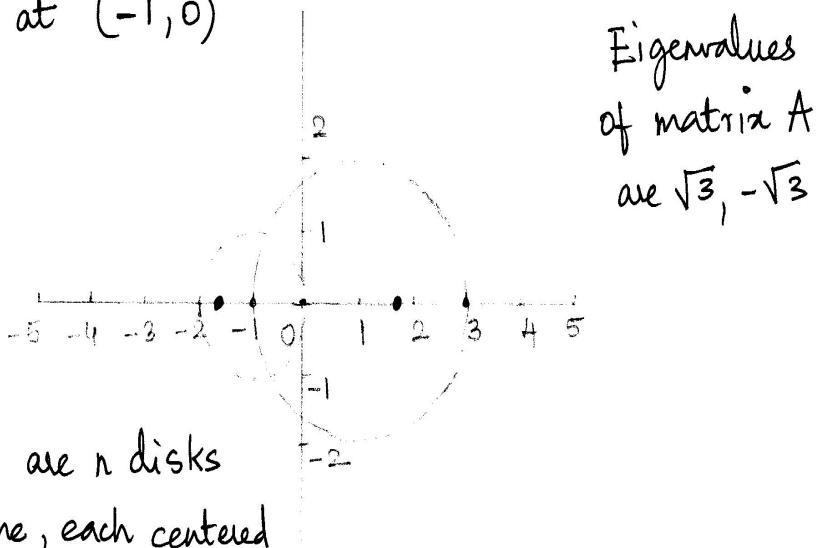
9) Eigenvalues of Real Symmetric matrix are Real.

10) Eigenvalues of Orthogonal matrix have  $|\lambda| = 1$

GERSCHGORIN THEOREM - Range of Eigenvalues defined by union of all discs

$$A = \begin{bmatrix} 1 & 2 \\ 1 & -1 \end{bmatrix}$$

From the rows of matrix A we get a disc with radius 2 centered at  $(1, 0)$  and a disc of radius 1 centered at  $(-1, 0)$



For  $A_{nn}$  there are  $n$  disks in complex plane, each centered on one of the diagonal entries of the matrix

Every Eigenvalue must lie within one of these discs  
 ✗ Thm does not state each disk has one eigenvalue  
 Using Gerschgorin Theorem

- Range for Eigenvalues can be found
- Especially useful for LARGE MATRICES when calculating Eigenvalues can be impractical.

## Inner Product / dot Product

$$\mathbf{a} \cdot \mathbf{b} = \begin{bmatrix} a_1 & a_2 & \dots & a_n \end{bmatrix} \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

Row vector    Column vector

$$\mathbf{a} \cdot \mathbf{b} = \sum_{l=1}^n a_l b_l = a_1 b_1 + \dots + a_n b_n$$

Eg)  $\mathbf{a} = \begin{bmatrix} 4 & -1 & 5 \end{bmatrix}$   $\mathbf{b} = \begin{bmatrix} 2 & 5 & 8 \end{bmatrix}^\top$

$$\mathbf{a} \cdot \mathbf{b} = \begin{bmatrix} 4 & -1 & 5 \end{bmatrix} \begin{bmatrix} 2 \\ 5 \\ 8 \end{bmatrix} = 4 \cdot 2 + (-1) \cdot 5 + 5 \cdot 8 = \underline{\underline{43}}$$

ORTHOGONAL - Two vectors are orthogonal if they are perpendicular to each other, dot product of two vectors is ZERO

Note :- If the length of vector is ONE, we say vector is

NORMALIZED

ORTHONORMAL SET - A set of Orthogonal and Normalized vectors

↓  
orthogonal unit vectors.

Eg:- Set of vectors  $\{v_1, v_2, v_3\}$  where  $v_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$

$v_2 = \begin{bmatrix} 1 \\ \sqrt{2} \\ 1 \end{bmatrix}$   $v_3 = \begin{bmatrix} 1 \\ -\sqrt{2} \\ 1 \end{bmatrix}$  is set of orthogonal vectors

dot product of each two vectors is zero

$$v_1 \cdot v_2 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ \sqrt{2} \\ 1 \end{bmatrix} = 1 - 1 = 0.$$

$$v_1 \cdot v_3 = 0 \quad \& \quad v_2 \cdot v_3 = 0.$$

To normalize each vector, calculate Magnitude and divide each vector by magnitude

$$|v_1| = \sqrt{1+1} = \sqrt{2} \Rightarrow \text{Normalized vector } \frac{1}{|v_1|} v_1 = \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}$$

$$|v_2| = \sqrt{1+2+1} = 2 \Rightarrow \text{Normalized vector } \frac{1}{|v_2|} v_2 = \begin{bmatrix} 1/2 \\ \sqrt{2}/2 \\ -1/2 \end{bmatrix}$$

$$|v_3| = \sqrt{1+2+1} = 2 \Rightarrow \text{Normalized vector } \frac{1}{|v_3|} v_3 = \begin{bmatrix} 1/2 \\ -\sqrt{2}/2 \\ 1/2 \end{bmatrix}$$

Orthonormal set is  $\left\{ \frac{1}{|v_1|} v_1, \frac{1}{|v_2|} v_2, \frac{1}{|v_3|} v_3 \right\}$

$$= \left\{ \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \end{bmatrix}, \begin{bmatrix} 1/2 \\ \sqrt{2}/2 \\ -1/2 \end{bmatrix}, \begin{bmatrix} 1/2 \\ -\sqrt{2}/2 \\ 1/2 \end{bmatrix} \right\}$$

vector  
has  
length 10

$\Rightarrow$   
Process of  
Normalization

This vector has  
a length of 1.

Take vector of any  
length, keeping it pointing in  
same direction change its  
length to 1. (unit vector)

### QUADRATIC FORM

A homogeneous polynomial of second degree in any number of variables

$$\text{eq i) } ax^2 + 2hxy + by^2$$

$$\text{ii) } ax^2 + by^2 + cz^2 + 2hxy + 2gyz + 2fzx \text{ and}$$

$$\text{iii) } ax^2 + by^2 + cz^2 + dw^2 + 2hxy + 2gyz + 2fzx \\ + 2lxw + 2myw + 2nzw.$$

are quadratic forms in two, three and four variables.

Writing quadratic form in matrix form:-

$$ax^2 + 2hxy + by^2 = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & h \\ h & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Quadratic Form given by

$$Q = \underline{x^T A x} = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j$$

Coefficient matrix  $A$  is Real Symmetric, therefore has  $n$  linearly independent orthonormal set of eigenvectors corresponding to  $n$  eigenvalues.

$$Q = \underline{x^T A x} = \underline{y^T D y} \rightarrow \begin{array}{l} \text{Canonical form / Sum of} \\ \text{Squares form / Principal Axes} \end{array} \text{form.}$$

Transformation of Quadratic Form to Principal Axes

Conic Sections

$$\text{Pbm 20) } 4x_1^2 + 12x_1x_2 + 13x_2^2 = 16.$$

$$Q = \underline{x^T A x}.$$

