



Artificial & Computational Intelligence

DSE CLZG557

M5 : Probabilistic Representation & Reasoning

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BITS - CSIS

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Pilani Campus

- M1 Introduction to AI
- M2 Problem Solving Agent using Search
- M3 Game Playing, Constraint Satisfaction Problem
- M4 Knowledge Representation using Logics
- M5 Probabilistic Representation and Reasoning**
- M6 Reasoning over time, Reinforcement Learning

Module 5: Probabilistic Representation and Reasoning



A. Inference using full joint distribution

B. Bayesian Networks

I. Knowledge Representation

II. Conditional Independence

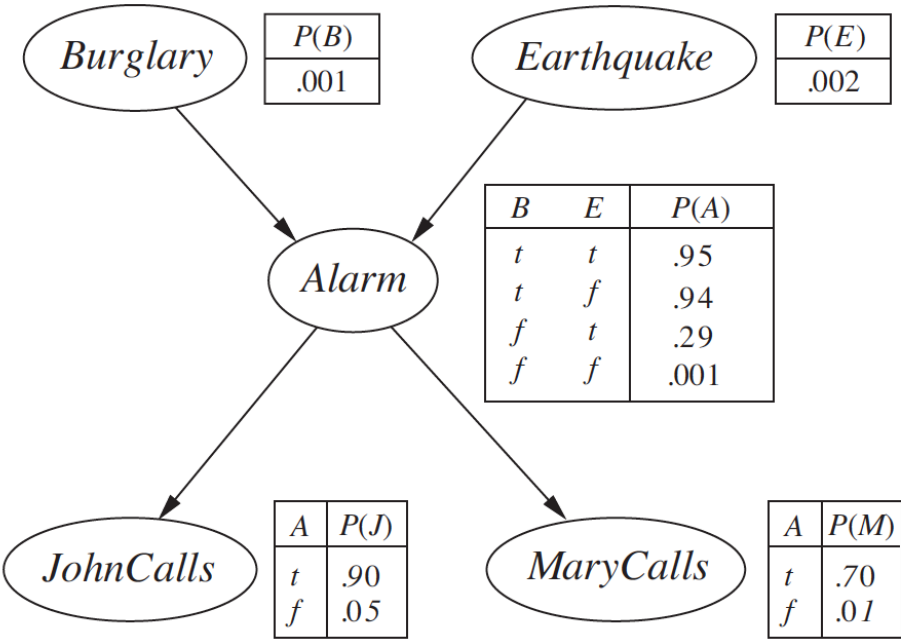
III. Exact Inference

IV. Introduction to Approximate Inference

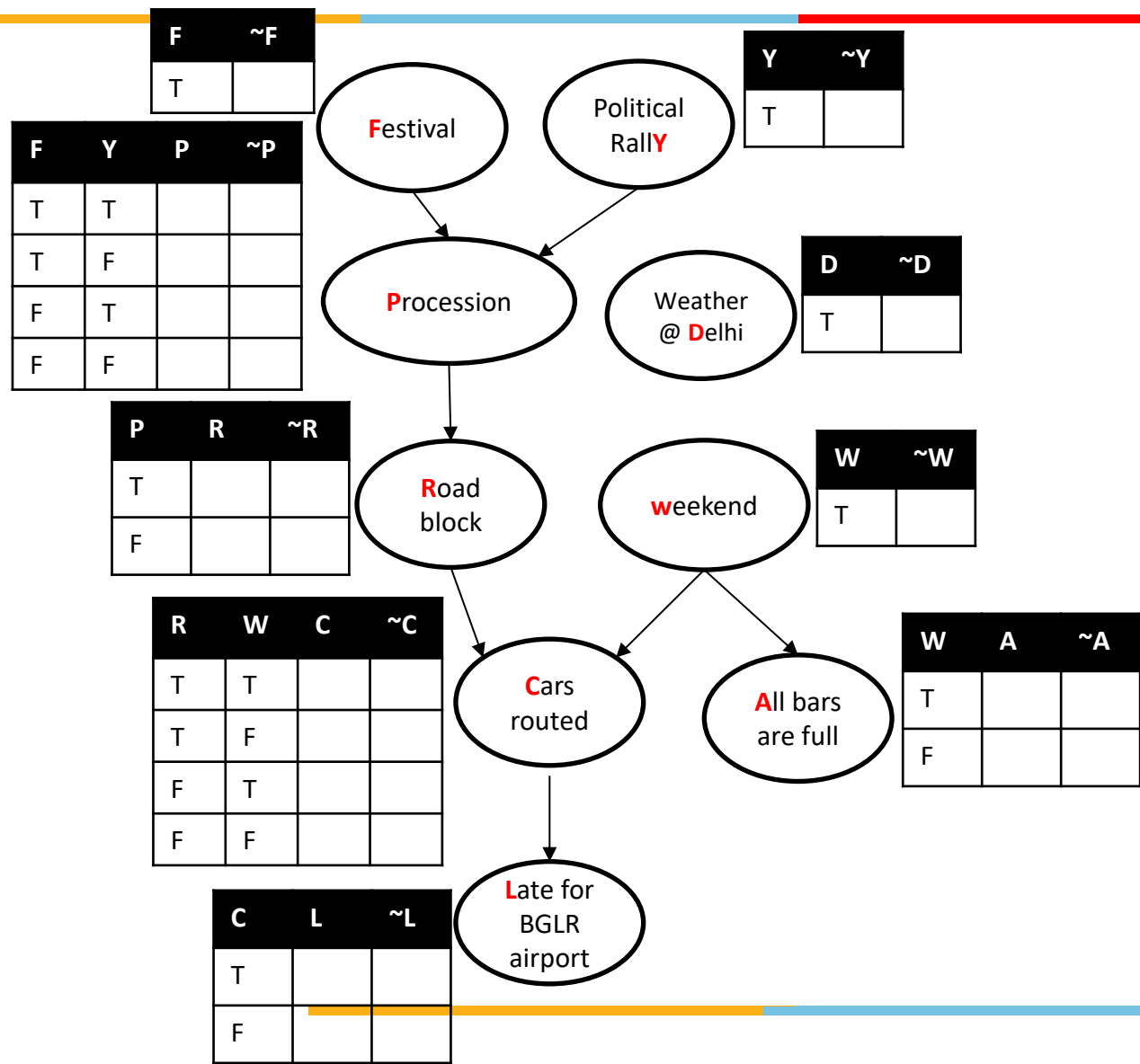
Reasoning under uncertainty

Building a Bayesian Network

Example Bayesian Net #2



Example Bayesian Net #3



Assumption Bayesian Nets

- A node is conditionally independent of its non-descendants given its parents
- A node is conditionally independent of all other nodes in the net , given its parents, children and children's parents.

Inferences in Bayesian Nets

Enumeration

Belief Nets



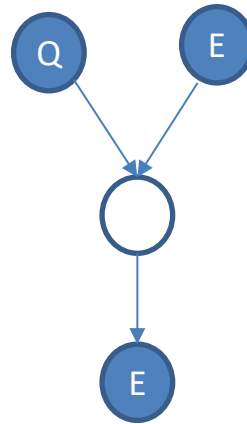
Diagnostic



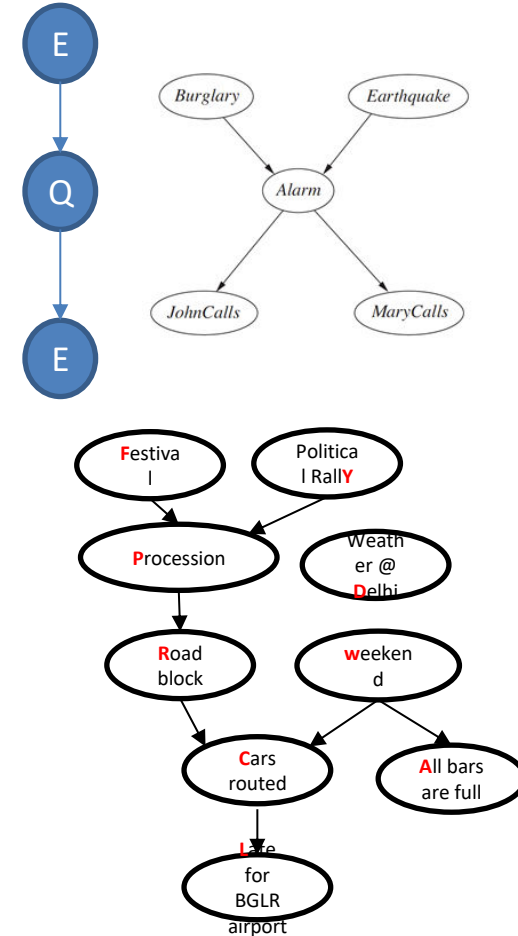
Causal



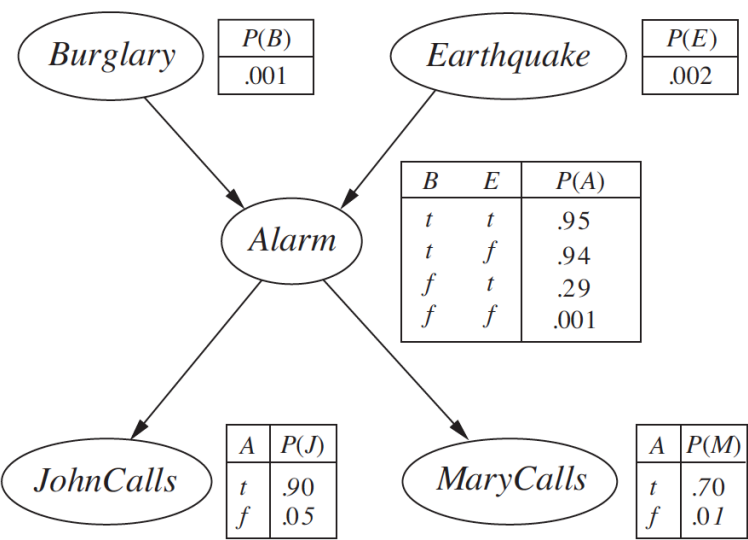
Inter-Casual



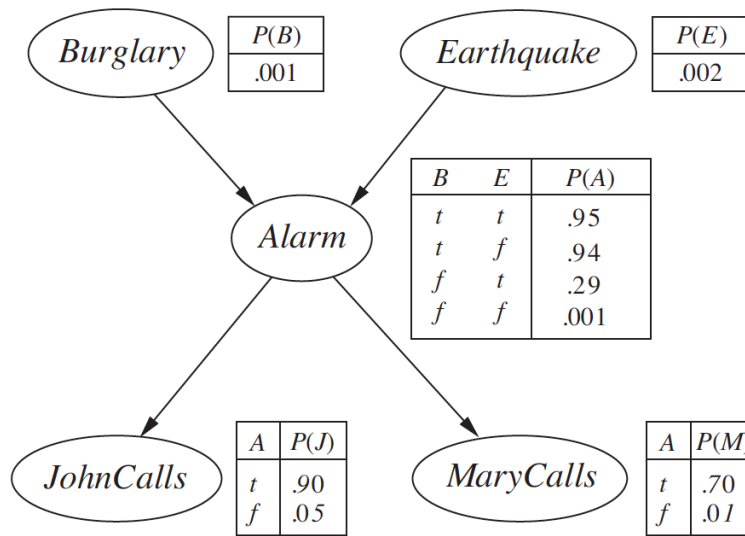
Mixed Inferences



Examples

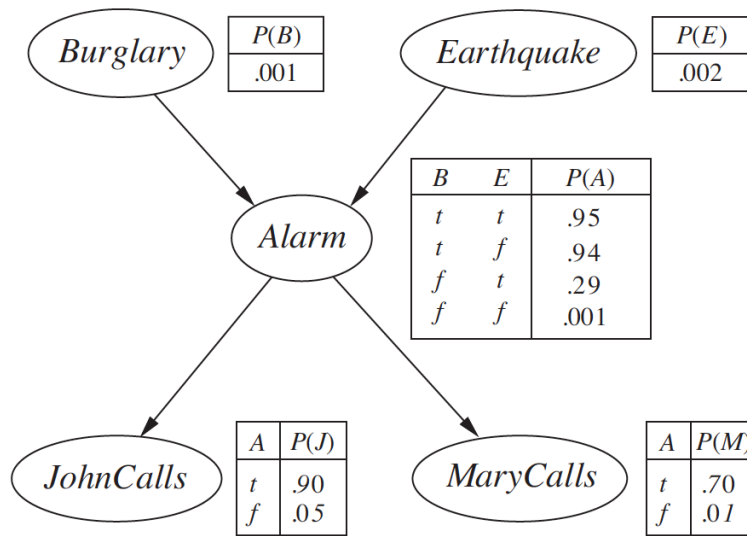


1. Calculate the probability that alarm has sounded, but neither burglary nor earthquake happened, and both John and Mary called
2. What is the probability that Burglary happened given John & Mary called the police
3. What is the probability that John calls given earthquake occurred?



1. Calculate the probability that alarm has sounded, but neither burglary nor earthquake happened, and both John and Mary called

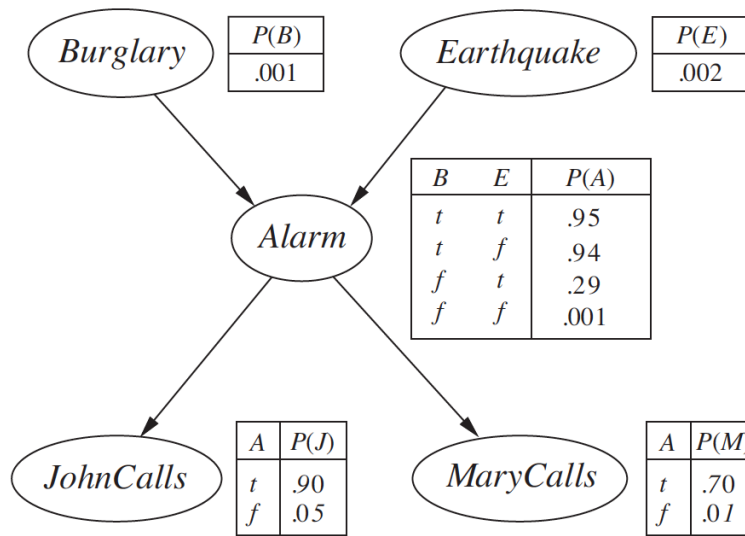
$$\begin{aligned}
 P(j, m, a, \neg b, \neg e) &= P(j | a)P(m | a)P(a | \neg b \wedge \neg e)P(\neg b)P(\neg e) \\
 &= 0.90 \times 0.70 \times 0.001 \times 0.999 \times 0.998 = 0.000628
 \end{aligned}$$



2. What is the probability that Burglary happened given John & Mary called the police

$$P(B | J, M) = \frac{P(B, J, M)}{P(J, M)}$$

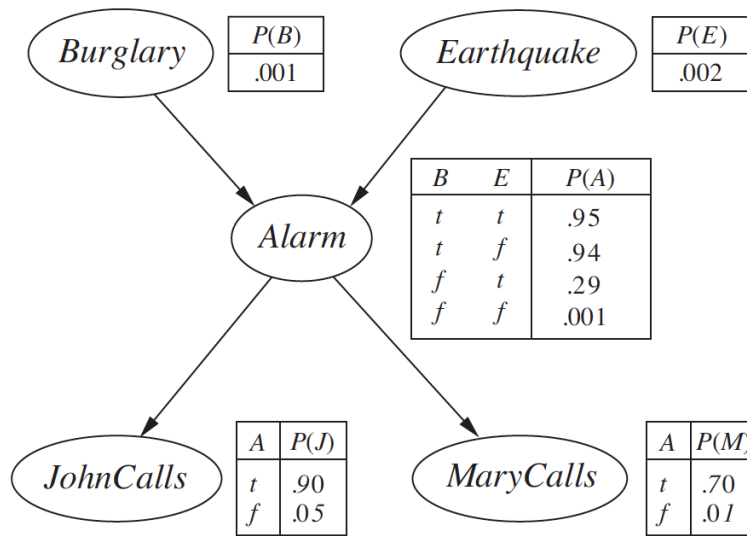
$$P(B | J, M) = \frac{\sum_{A, E} P(J, M, A, B, E)}{\sum_{A, B, E} P(J, M, A, B, E)}$$



2. What is the probability that Burglary happened given John & Mary called the police

$$P(B | J, M) = \frac{P(B, J, M)}{P(J, M)}$$

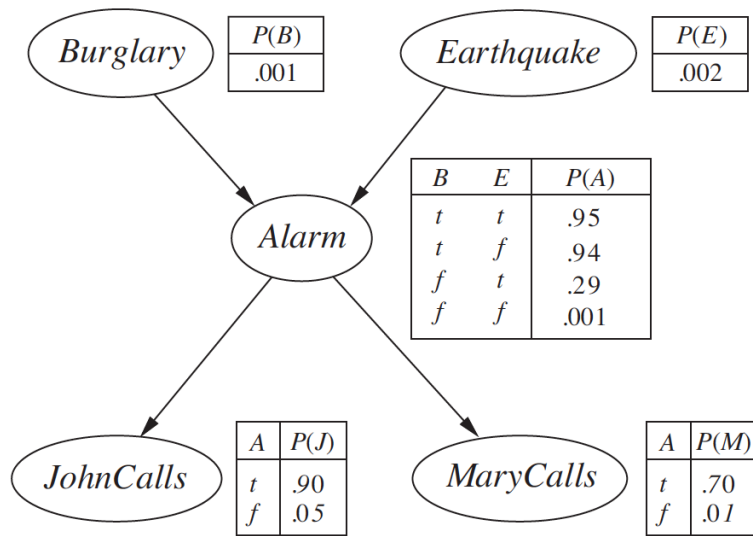
$$P(B | J, M) = \frac{\sum_{A, E} P(J, M, A, B, E)}{\sum_{A, B, E} P(J, M, A, B, E)}$$



2. What is the probability that Burglary happened given John & Mary called the police

$$P(B | J, M) = \frac{P(B, J, M)}{P(J, M)}$$

$$P(B | J, M) = \frac{\sum_{A, E} P(J, M, A, B, E)}{\sum_{A, B, E} P(J, M, A, B, E)}$$



3. What is the probability that John calls given earthquake occurred?

$$P(J | E) = \frac{P(J, E)}{P(E)}$$

$$P(J | E) = \frac{\sum_{M, A, B} P(J, M, A, B, E)}{\sum_{J, M, A, B} P(J, M, A, B, E)}$$

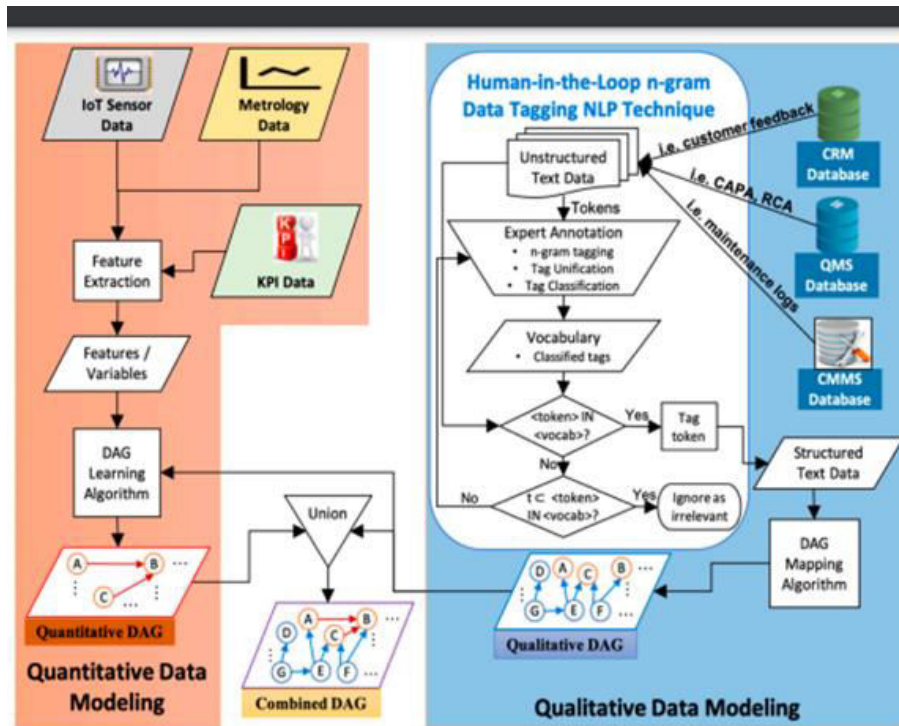
Bayesian Network

innovate

achieve

lead

Fault Diagnostic System

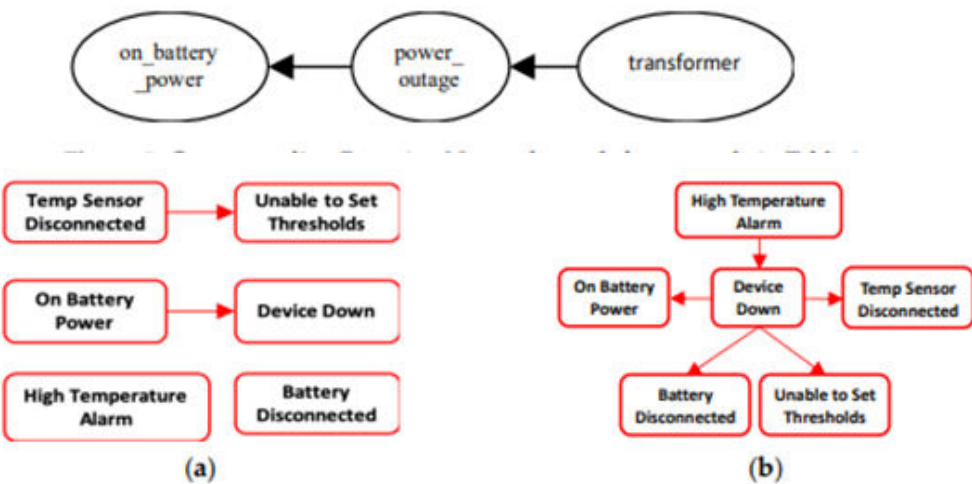


Source Credit : [Sensors 2021 : Fusion-Learning of Bayesian Network Models for Fault Diagnostics](#)

Bayesian Network

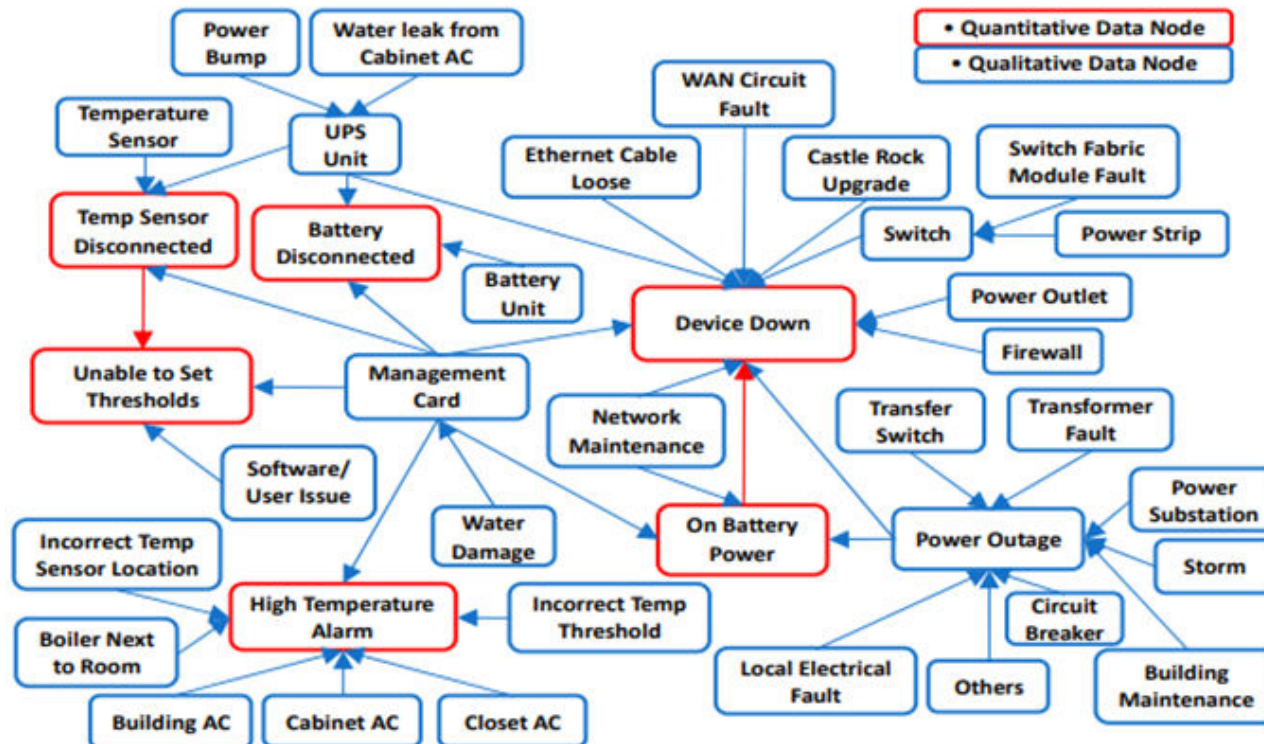
Fault Diagnostic System

Raw Data	Short Description		Resolution Notes			
	On battery power		Power outage due to transformer fire			
Classified Tags	Symptom		Cause(s)		Link	
	on_battery_power		power_outage, transformer_fire		due_to	
BN Mapping	Child Variable	Child State	Parent Variable	Parent State	Ancestor Variable	Ancestor State
	on_battery_power	yes	power_outage	yes	transformer	Fire



Source Credit : [Sensors 2021 : Fusion-Learning of Bayesian Network Models for Fault Diagnostics](#)

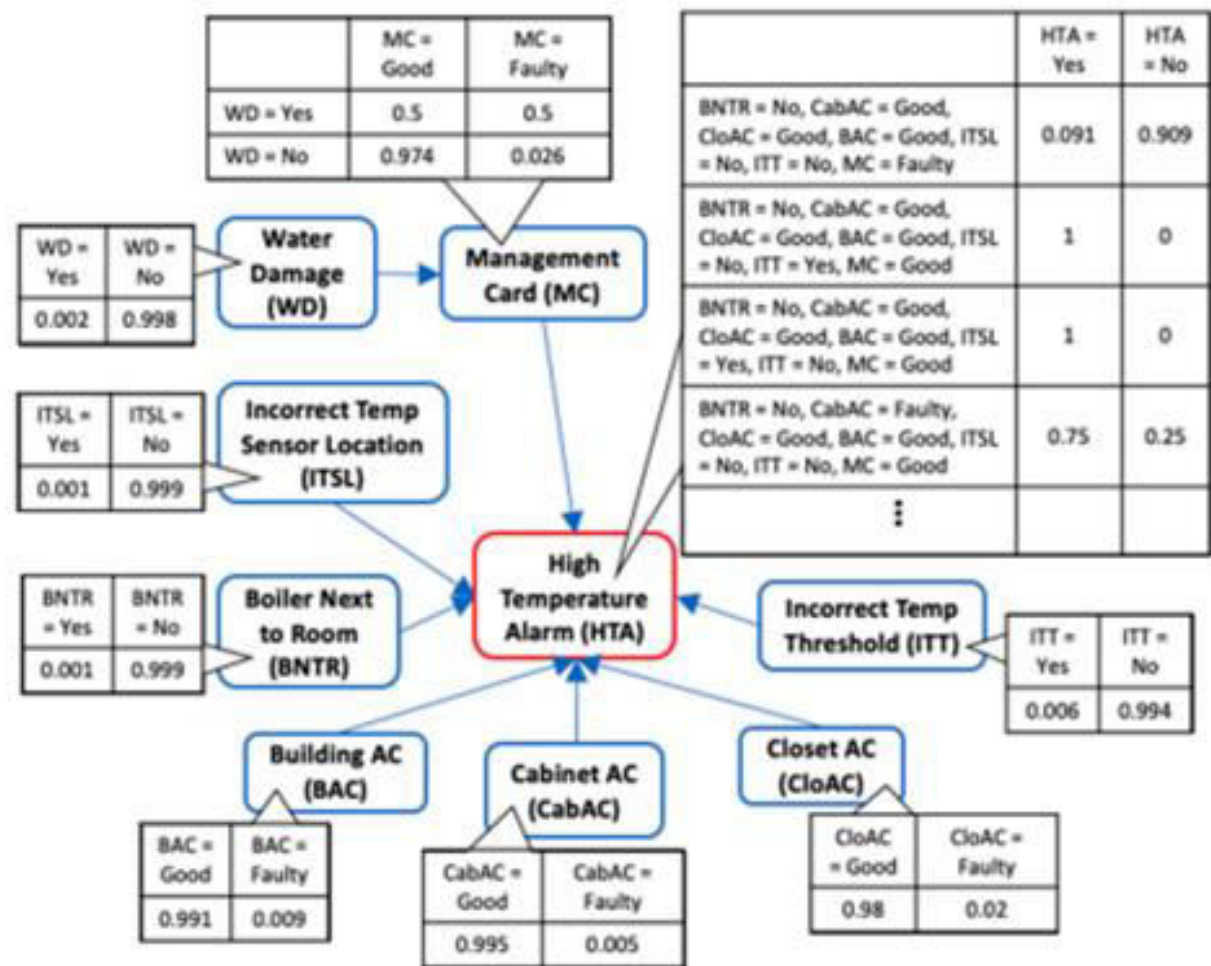
Fault Diagnostic System



Source Credit : [Sensors 2021 : Fusion-Learning of Bayesian Network Models for Fault Diagnostics](#)

Bayesian Network

Fault Diagnostic System

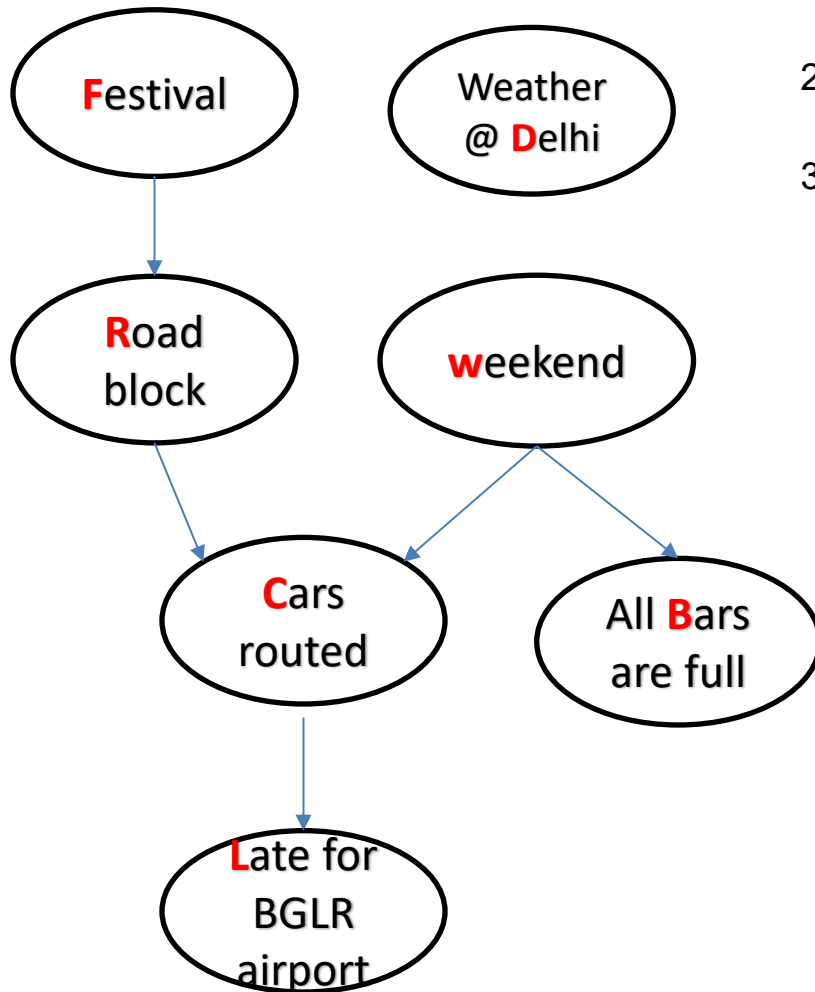


Source Credit : [Sensors 2021 : Fusion-Learning of Bayesian Network Models for Fault Diagnostics](#)

Inferences in Bayesian Nets

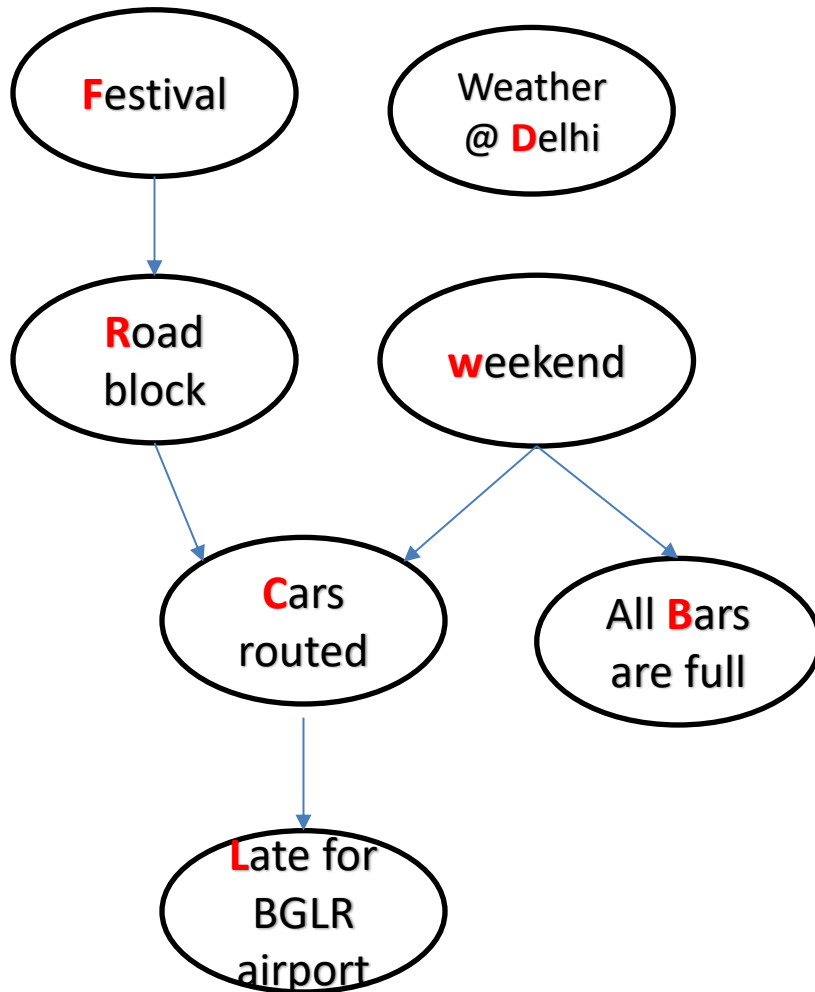
Reduce Guaranteed Independent nodes

D-Connectedness Vs D-Separation



1. Each variable is conditionally independent of its non-descendants, given its parents
2. Eliminate the hidden variables that is neither a query nor an evidence
3. **Two variables are d-separated if they are conditionally independent given evidences**

Try it & Test

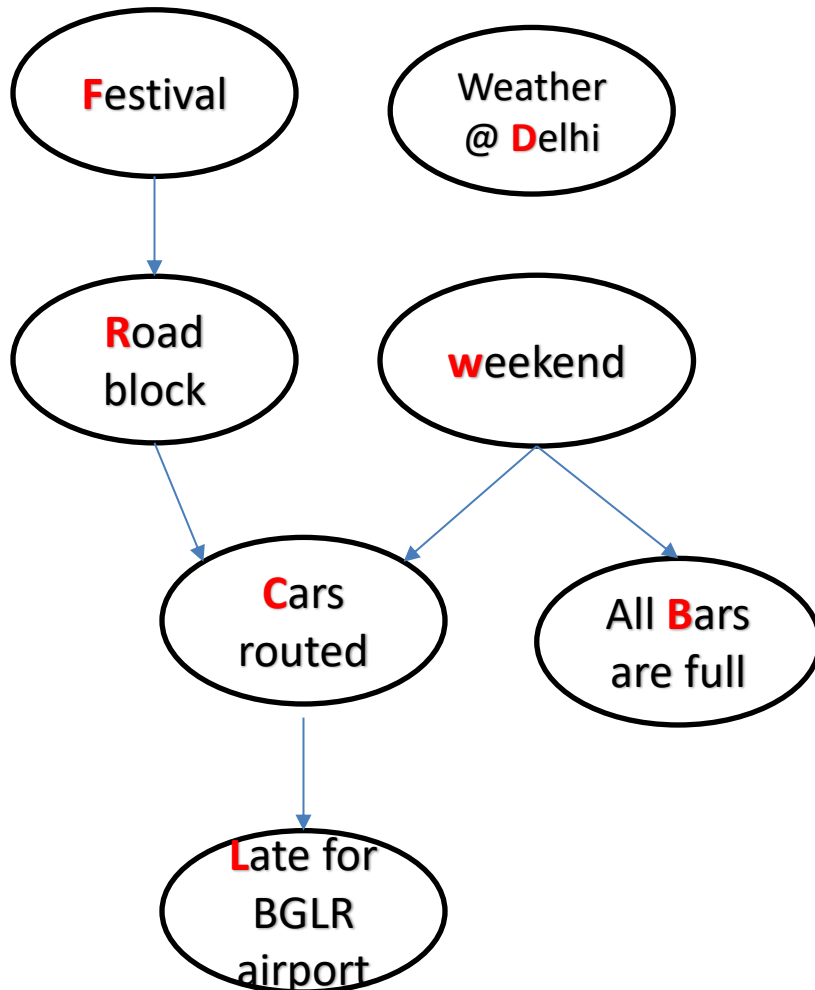


X	Y	Evidence Z	d-sep?
F	W	C	No
L	W	R	No
R	L	C	Yes
B	R	C	No

➤ $P(R | L, C) = P(R | L)$

R & L are d-separated i.e., conditionally independent given C

D-Separation in Inference

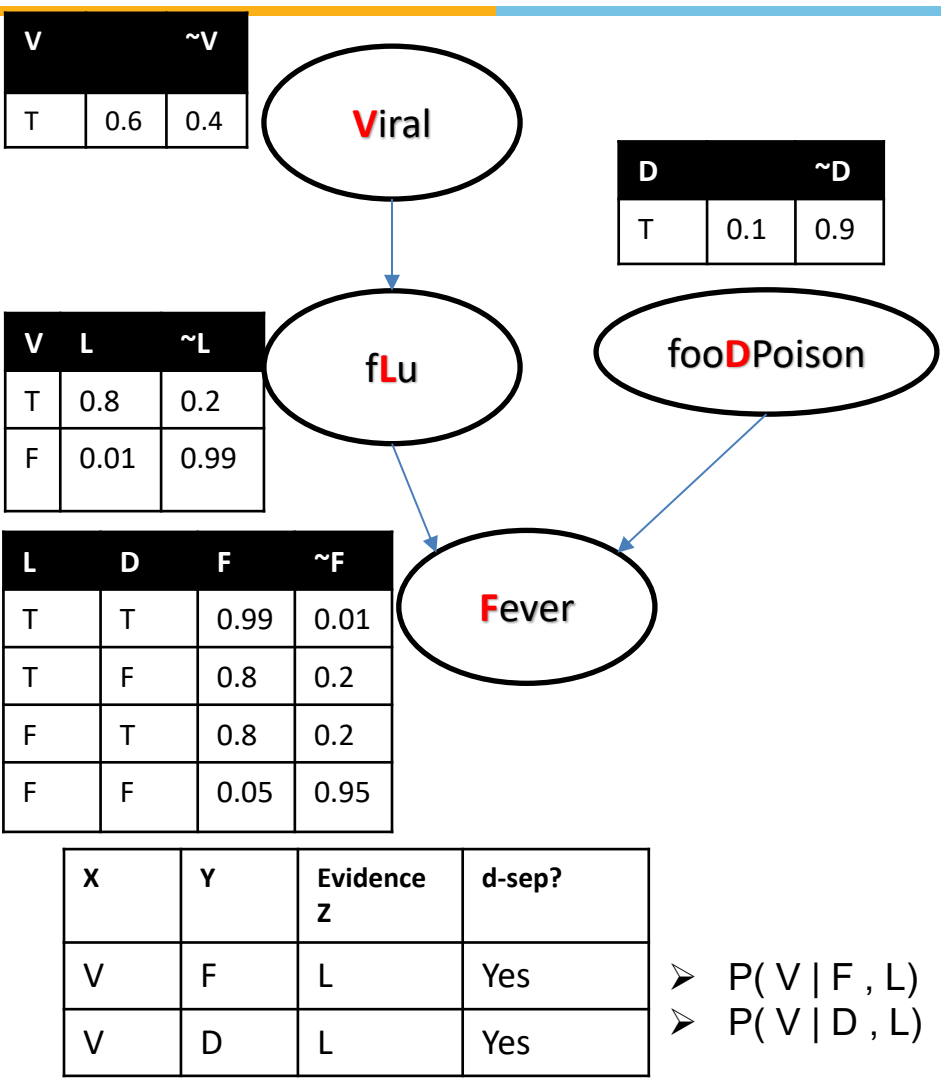


X	Y	Evidence Z	d-sep?
F	W	C	No
L	W	R	No
R	L	C	Yes
B	R	C	No

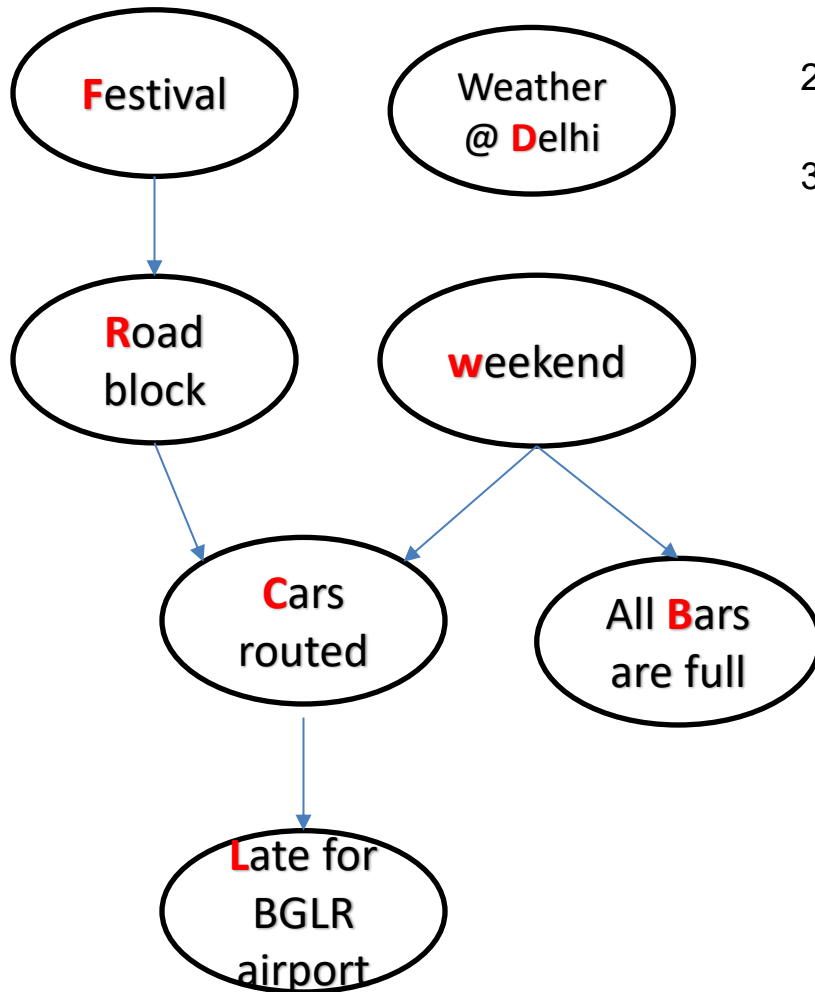
➤ $P(R | L, C) = P(R | L)$

R & L are d-separated ie., conditionally independent given C

D-Separation in Inference



Variable Elimination



1. Each variable is conditionally independent of its non-descendants, given its parents
2. **Eliminate the hidden variables that is neither a query nor evidence**
3. Two variables are d-separated if they are conditionally independent given evidences

$$\begin{aligned}
 \text{➤ } P(B) &= \sum_{L, B, W, R, F} P(L, C, B, W, R, F) \\
 &= \sum_L \sum_B P(L|C) \cdot P(B|W) \cdot \sum_W P(C|W, R) \cdot \sum_R P(R|F) \cdot \sum_F P(F) \\
 &= P(B|W)
 \end{aligned}$$

All other variables are hidden w.r.t to B as (L, C, R, F) are neither evidence nor query nor $(L, C, R, F) \in \text{Ancestors}(W, B)$

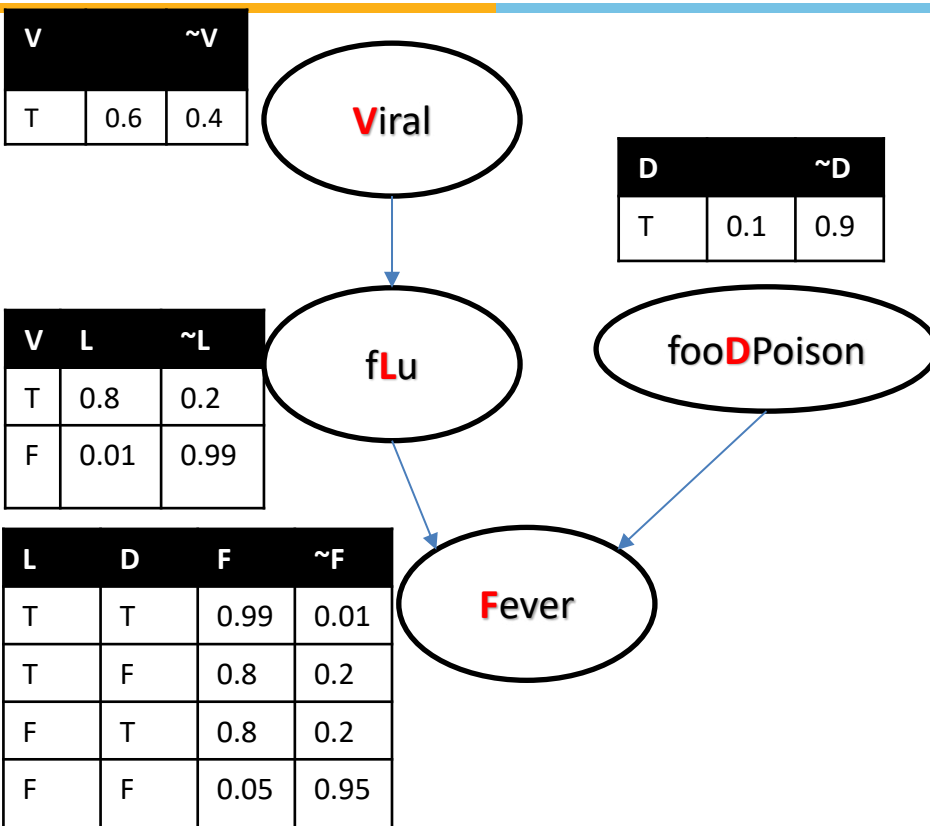
This is variable elimination example targeting irrelevant nodes

Approximate Inferences in Bayesian Nets

Introduction

Prior Sampling

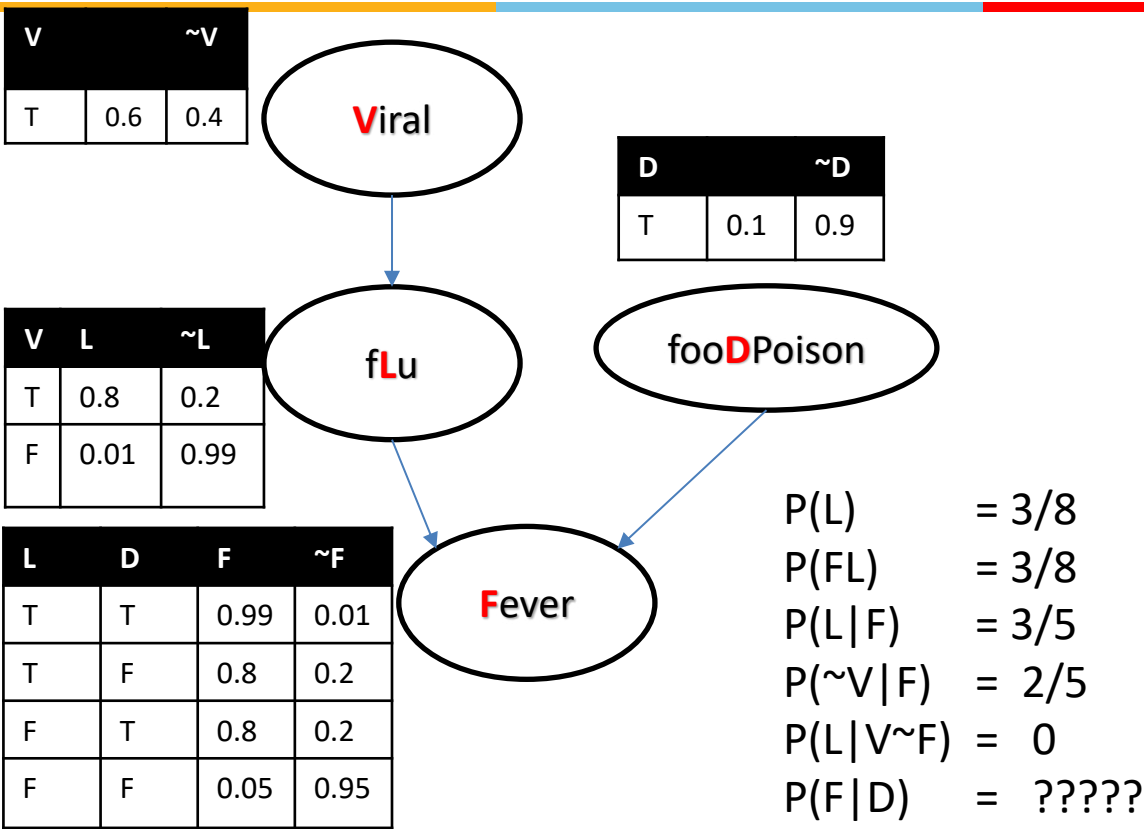
Sample Generation by Randomization



V	L	D	F
T	T	F	T
F	F	F	F
T	F	F	T
F	T	F	T
..			
.....			

0.3, 0.2, 0.6, 0.58, 0.73, 0.87, 0.15, 0.6, 0.57, 0.85, 0.12, 0.004, 0.93, 0.0002, 0.9, 0.55.....

Prior Sampling

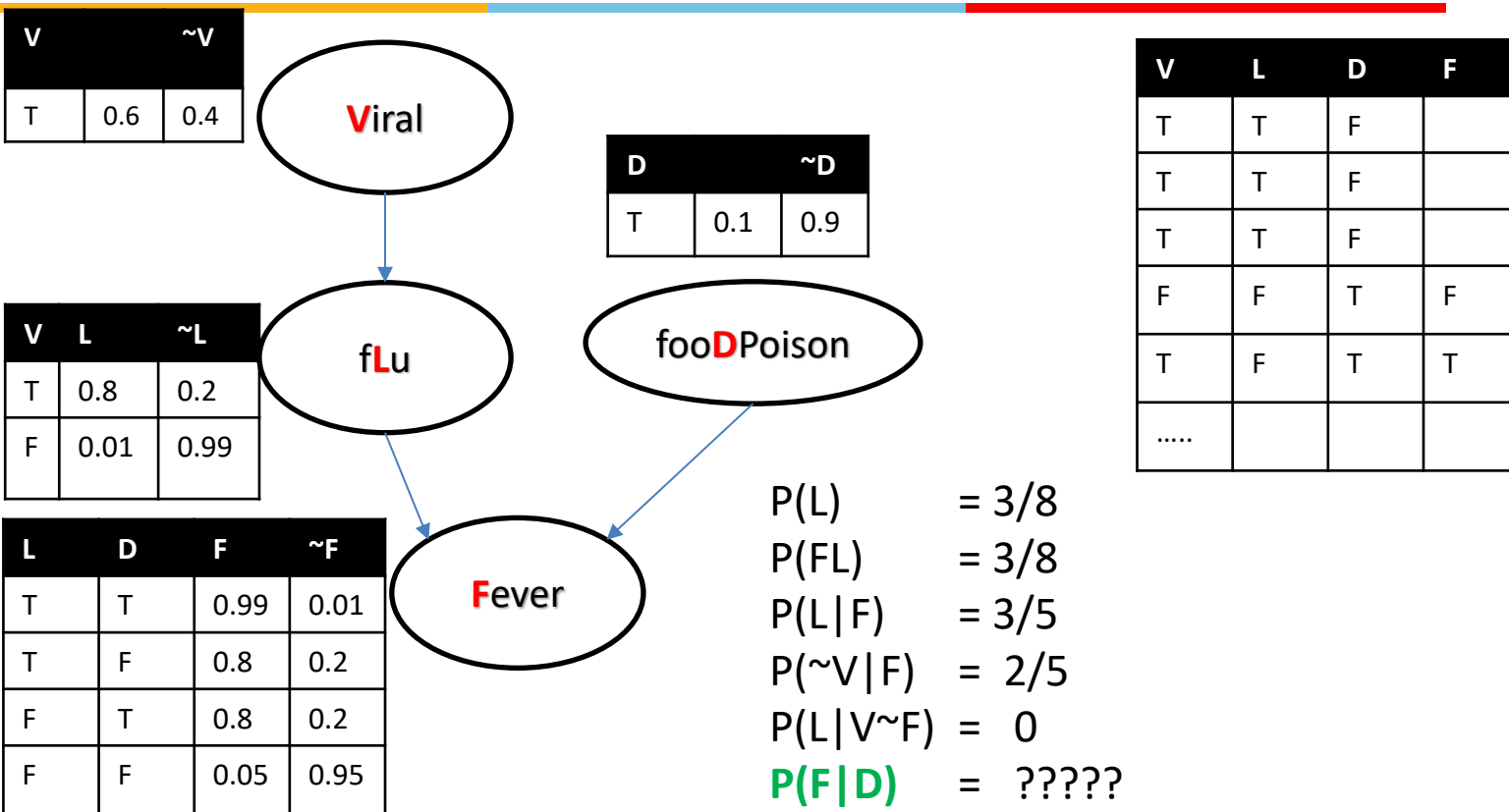


Inference

V	L	D	F
T	T	F	T
F	F	F	F
T	F	F	T
F	T	F	T
T	T	F	T
T	F	F	F
F	F	F	T
T	F	F	F

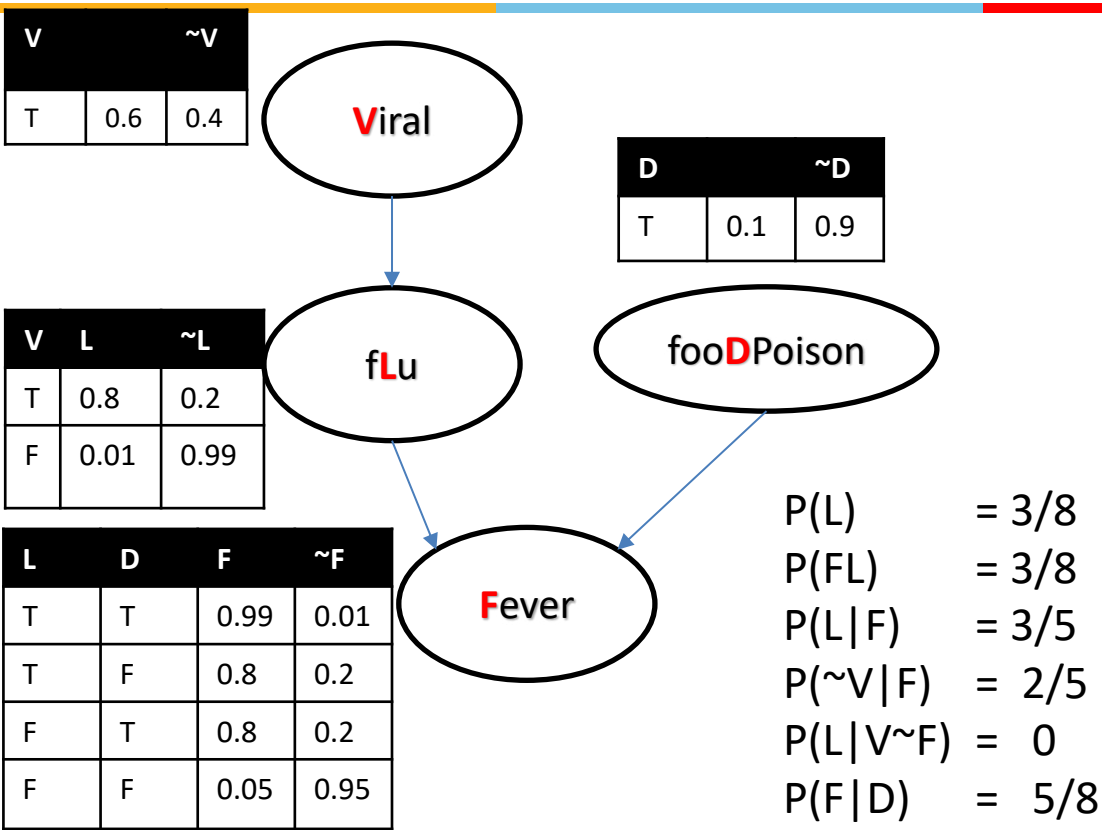
Rejection Sampling

Sample Generation by Randomization



0.3, 0.2, 0.6, 0.58, 0.73, 0.87, 0.15, 0.6, 0.57, 0.85, 0.12, 0.004, 0.93, 0.0002, 0.9, 0.555, 0.38.....

Rejection Sampling

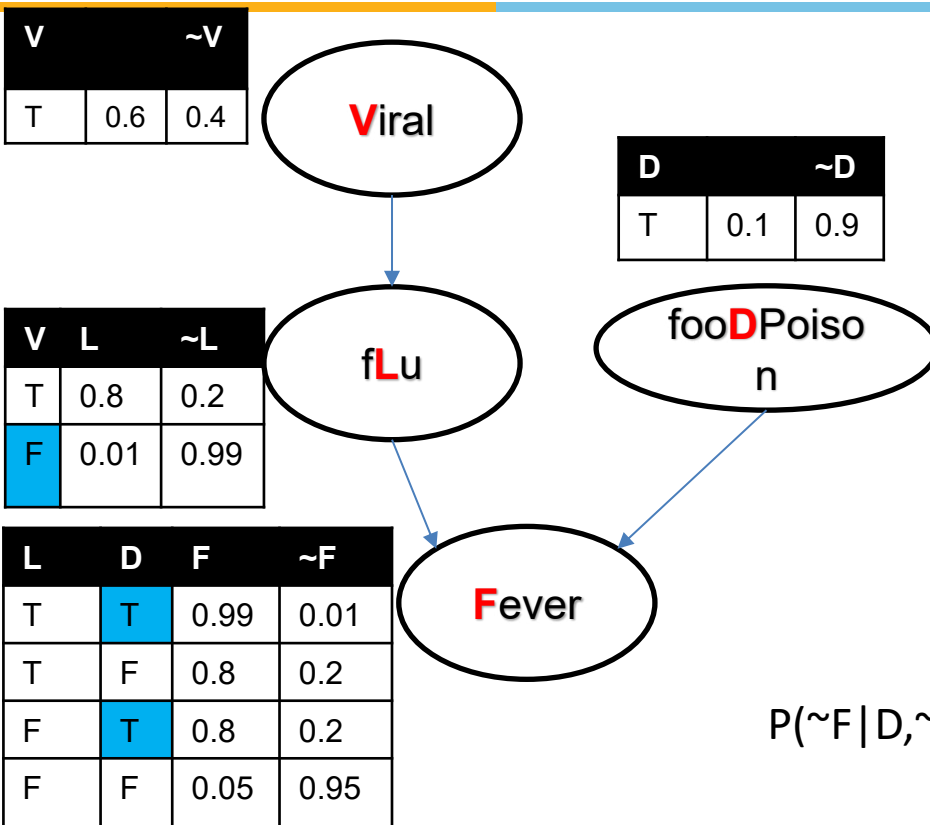


Inference

V	L	D	F
T	T	T	T
F	F	T	F
T	F	T	T
F	T	T	T
T	T	T	T
T	F	T	F
F	F	T	T
T	F	T	F

Likelihood Weighing

Sample Generation by Randomization



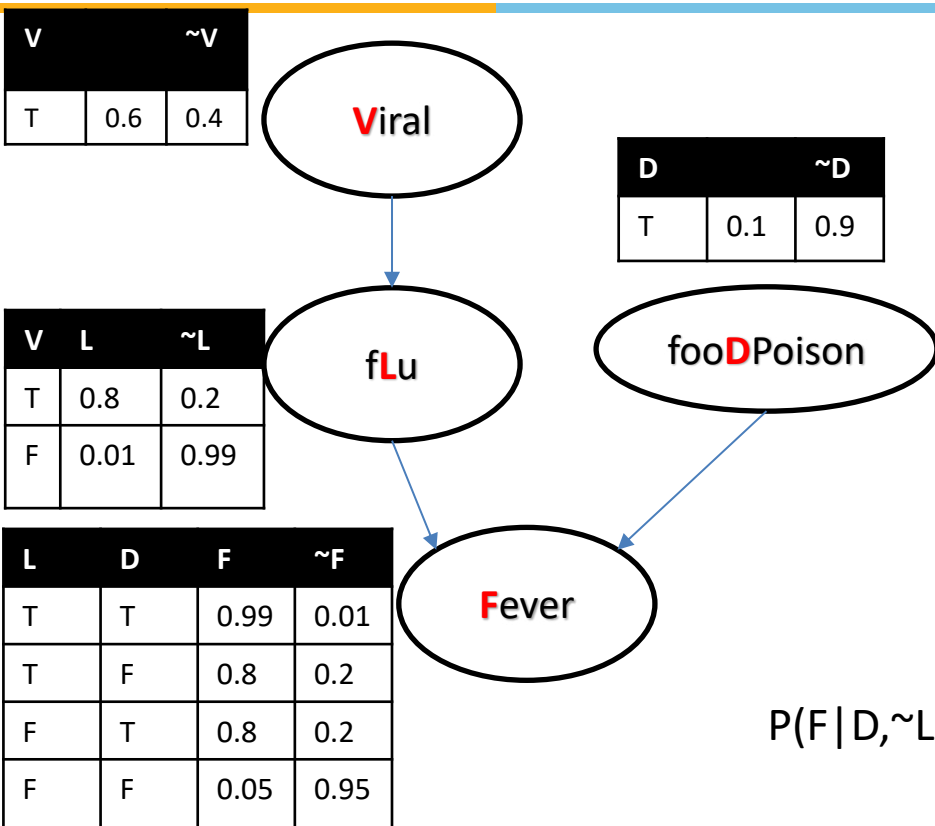
V	L	D	F	wgt
F	F	T	T	0.4*1*0.1*1=
F	F	T	T	
F	F	T	T	
F	F	T	T	
F	F	T	T	
F	T	T	T	
F	T	T	F	

$$P(\sim F | D, \sim V)$$

$$= 0.04 / 7 * 0.04$$

0.3, 0.2, 0.58, 0.73, 0.87, 0.15, 0.6, 0.57, 0.85, 0.12, 0.004, 0.93, 0.0002, 0.99,,.....

Likelihood Weighing



Inference

V	L	D	F	wgt
F	F	T	F	1*0.99* 0.1 *1=
F	F	T	T	1*0.99* 0.1 *1=
F	F	T	T	1*0.99* 0.1 *1=
T	F	T	F	1*0.2* 0.1 *1=

$$P(F|D, \sim L)$$

$$= 0.099+0.099 / (3*0.099 + 0.02)$$

Bayesian Network

Privacy Preserving Data Augmentation / Generation



$[0,4], [5,9], \dots, [95,99] \rightarrow (1,6,\dots,1) \text{ } n=100 \rightarrow (1,3,\dots,0) \text{ } n=93$
 Marginal Distribution(Sensitive Attribute) = $(1/93, 3/93, \dots, 0/93)$

Table 2. Example noisy marginal distributions for network \mathcal{N}_1 .

(a) Marginal distribution for 'age'		(b) Marginal distribution for 'age' and 'higrade'		
'age'	probability	'age' \ 'higrade'	01	02
[0, 4]	0.04	[0, 4]	0.02	0.02
[5, 9]	-0.1	[5, 9]	-0.1	0
...
[95, 99]	0.08	[95, 99]	0	0

Table 3. Processed noisy marginal distributions for network \mathcal{N}_1 .

(a) Marginal distribution for 'age'		(b) Marginal distribution for 'age' and 'higrade'		
'age'	probability	'age' \ 'higrade'	01	02
[0, 4]	0.05	[0, 4]	0.025	0.025
[5, 9]	0	[5, 9]	0	0
...
[95, 99]	0.1	[95, 99]	0	0

Table 4. Noisy marginal distributions for network \mathcal{N}_1 that are consistent on attribute 'age'.

(a) Marginal distribution for 'age'		(b) Marginal distribution for 'age' and 'higrade'		
'age'	probability	'age' \ 'higrade'	01	02
[0, 4]	0.05	[0, 4]	0.025	0.025
[5, 9]	0	[5, 9]	0	0
...
[95, 99]	0.067	[95, 99]	0.0335	0.0335

Source Credit : [TPDP 2020 : Synthetic Data Generation with Differential Privacy via Bayesian Networks](#)

Required Reading: AIMA - Chapter #13, #14.1, #14.2

Thank You for all your Attention

Note : Some of the slides are adopted from AIMA TB materials



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DSE CLZG557

M6 : Reasoning over time & Reinforcement Learning

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- M6 Reasoning over time

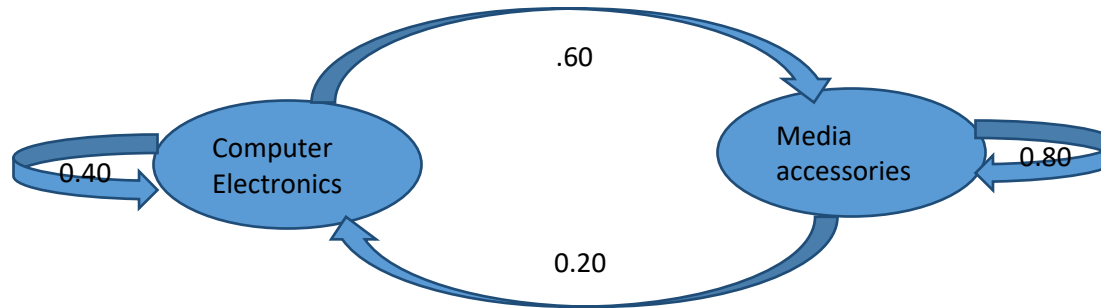
, Reinforcement Learning

Reasoning Over Time

Time & Uncertainty

$$\begin{aligned}
 & \begin{array}{cc} +ve & -ve \\ 0.25 & 0.7 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} * \begin{array}{cc} 0.4 & +ve \\ 0.6 & -ve \end{array} \\
 & \begin{array}{cc} +ve & -ve \\ 0.75 & 0.3 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} \\
 = & \begin{array}{cc} +ve & -ve \\ 0.25 & 0.7 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} * \begin{array}{cc} 0.52 & +ve \\ 0.48 & -ve \end{array} \\
 & \begin{array}{cc} +ve & -ve \\ 0.75 & 0.3 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} \\
 = & \begin{array}{cc} +ve & -ve \\ 0.25 & 0.7 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} * \begin{array}{cc} 0.466 & +ve \\ 0.534 & -ve \end{array} \\
 & \begin{array}{cc} +ve & -ve \\ 0.75 & 0.3 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} \\
 = & \begin{array}{cc} +ve & -ve \\ 0.25 & 0.7 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} * \begin{array}{cc} 0.4903 & +ve \\ 0.5097 & -ve \end{array} \\
 & \begin{array}{cc} +ve & -ve \\ 0.75 & 0.3 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} \\
 = & \begin{array}{cc} +ve & -ve \\ 0.25 & 0.7 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} * \begin{array}{cc} 0.4903 & +ve \\ 0.5097 & -ve \end{array} \\
 & \begin{array}{cc} +ve & -ve \\ 0.75 & 0.3 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} \\
 = & \begin{array}{cc} +ve & -ve \\ 0.25 & 0.7 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} * \begin{array}{cc} 0.48428575 & +ve \\ 0.51571425 & -ve \end{array} \\
 & \begin{array}{cc} +ve & -ve \\ 0.75 & 0.3 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} \\
 = & \begin{array}{cc} +ve & -ve \\ 0.25 & 0.7 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array} * \begin{array}{cc} 0.4820714125 & +ve \\ 0.5179285875 & -ve \end{array} \\
 & \begin{array}{cc} +ve & -ve \\ 0.75 & 0.3 \end{array} \begin{array}{c} \square \\ +ve \\ -ve \end{array}
 \end{aligned}$$

Morkov Model



Transition Model

C	M	
0.40	0.20	C
0.60	0.80	M

Next Session Plan :

- Hidden Markov Models
- Inferences in Temporal Models