

Features

- 3.3 and 5 VDC voltage supply option
- Absolute
- Bushing or servo mount
- Non-contacting magnetic technology
- Small size
- CMOS and TTL compatible

- Resolution: 1024 positions
- Long life
- High operating speed
- Highly repeatable
- Sealed option
- Magnetic technology

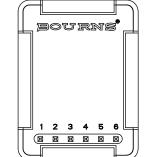
EMS22A - Non-Contacting Absolute Encoder

Electrical Characteristics	
Resolution	
Electrical Travel	
	5.0 VDC ±10 %, 3.3 VDC ±10 %
11,7	
Output Voltage	
	Vss+0.4 V maximum
•	Vdd-0.5 V minimum
Output Current	
	4 mA maximum
	500 ns maximum
• ,	
•	0.5 %
Accuracy	
	±0.7 ° or better
	±1.4 °
Output Transition Noise	
Environmental Characteristics	
Operating Temperature Range	40 °C to +125 °C (-40 °F to +257 °F)
	55 °C to +125 °C (-67 °F to +257 °F)
	MIL-STD-202, Method 103B, Condition B
•	
	50 G
Rotational Life	
· · · · · · · · · · · · · · · · · · ·	
•	IP 65
Mechanical Characteristics	
•	360 ° Continuous
Torque	
Starting	
Running	
Mounting Torque	203 N-cm (18 lbin.)
Shaft End Play	
•	
•	Axial, radial or ribbon cable
Soldering Condition	
Mariuai Soluetiily	370 °C (700 °F) max. for 3 seconds
Maya Caldarina	
vvave soldering	
Madamaa	260 °C (500 °F) max. for 10 seconds
•	Not recommended
HardwareOne lockwa	sher and one mounting nut supplied with each encoder, except on servo mount versions.

Pin Configuration

Output Type	Pin 1 (DI)	Pin 2 (CLK)	Pin 3	Pin 4 (DO)	Pin 5	Pin 6
Absolute	Digital Input	Clock	GND	Digital Output	VCC*	CS

Can be 5 or 3.3 VDC depending on the version.



^{*}RoHS Directive 2002/95/EC Jan. 27, 2003 including annex and RoHS Recast 2011/65/EU June 8, 2011. Specifications are subject to change without notice.

The device characteristics and parameters in this data sheet can and do vary in different applications and actual device performance may vary over time.
Users should verify actual device performance in their specific applications.

Applications

- Material handling equipment
- Brushless DC motor commutation
- Robotics
- Automotive
- Industrial automation
- Petroleum refinery

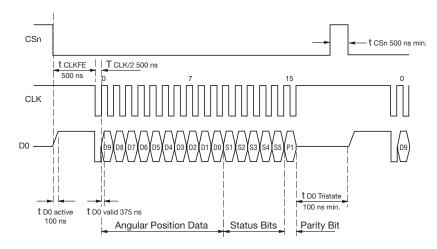
- Medical
- Office equipment
- Audio and broadcast equipment

EMS22A - Non-Contacting Absolute Encoder

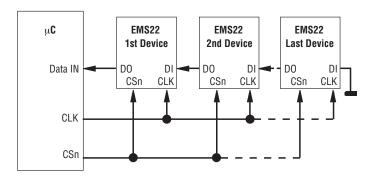
BOURNS

Output Type Waveform and Variant Table

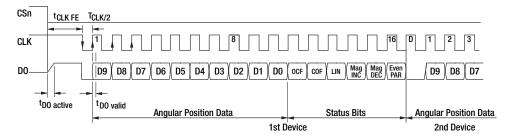
Absolute Output



Data Content	Description	
D9:D0	Absolute angular position data	
S1	End of offset compensation algorithm	
S2	Cordic overflow indicating an error in cordic part	
S3	Linearity alarm	
S4	Increase in magnitude	
S5	Decrease in magnitude	
P1	Even parity for detecting bits 1-15 transmission error	



Daisy Chain Hardware Configuration



Daisy Chain Mode Data Transfer

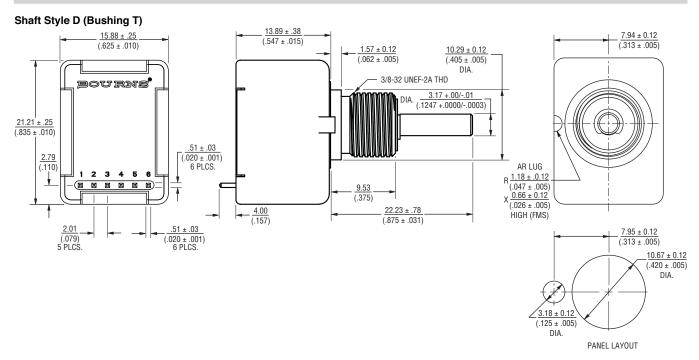
Consult factory for options not shown, including:

- Wire lead or cable options Special shaft/bushing sizes and features
- Connectors
- · Special performance characteristics
- · Non-standard resolutions
- · PCB mounting bracket

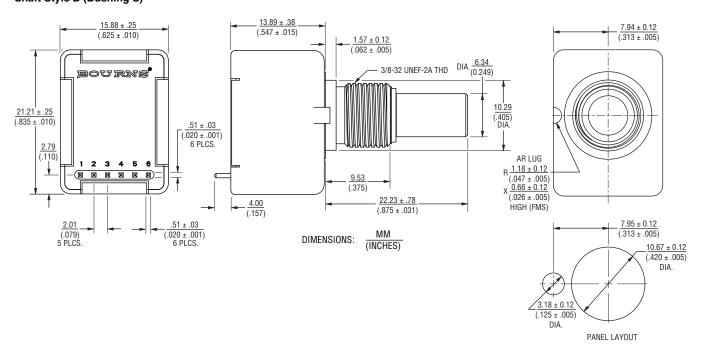
EMS22A - Non-Contacting Absolute Encoder

FOURNS®

Product Dimensions



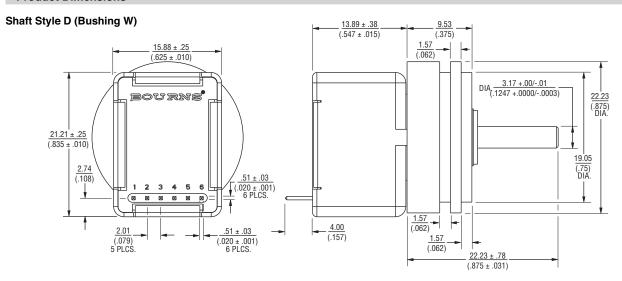
Shaft Style B (Bushing S)



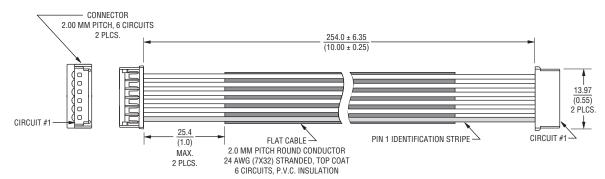
EMS22A - Non-Contacting Absolute Encoder

BOURNS

Product Dimensions



Cable Assembly

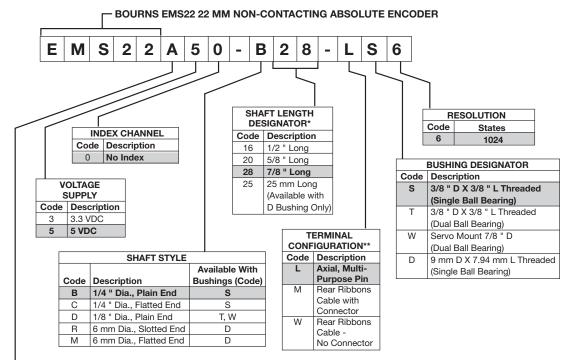


DIMENSIONS: $\frac{MM}{(INCHES)}$

EMS22A - Non-Contacting Absolute Encoder

BOURNS

How To Order



 OUTPUT TYPE

 Code
 Description
 Notes

 A
 CW Absolute
 See Note 1 below

 B
 CCW Absolute
 See Note 2 below

Note 1: (A) positions increase from 0 to 1024 with CW rotation of the shaft. Note 2: (B) positions increase from 0 to 1024 with CCW rotation of the shaft.

^{*} Shaft length measured from mounting surface.

^{**} Standard ribbon cable is 10 inches long. Consult factory for other lengths.

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Bourns:

<u>EMS22A50-C20-LS6</u> <u>EMS22A50-D16-LT6</u> <u>EMS22A30-C28-MS6</u> <u>EMS22A50-B28-LS6</u> <u>EMS22A50-D28-LT6</u> EMS22A50-M25-LD6 EMS22A30-C28-LS6