

CSI 2103: Data Structures

Trees (Ch 8)

Yonsei University

Spring 2022

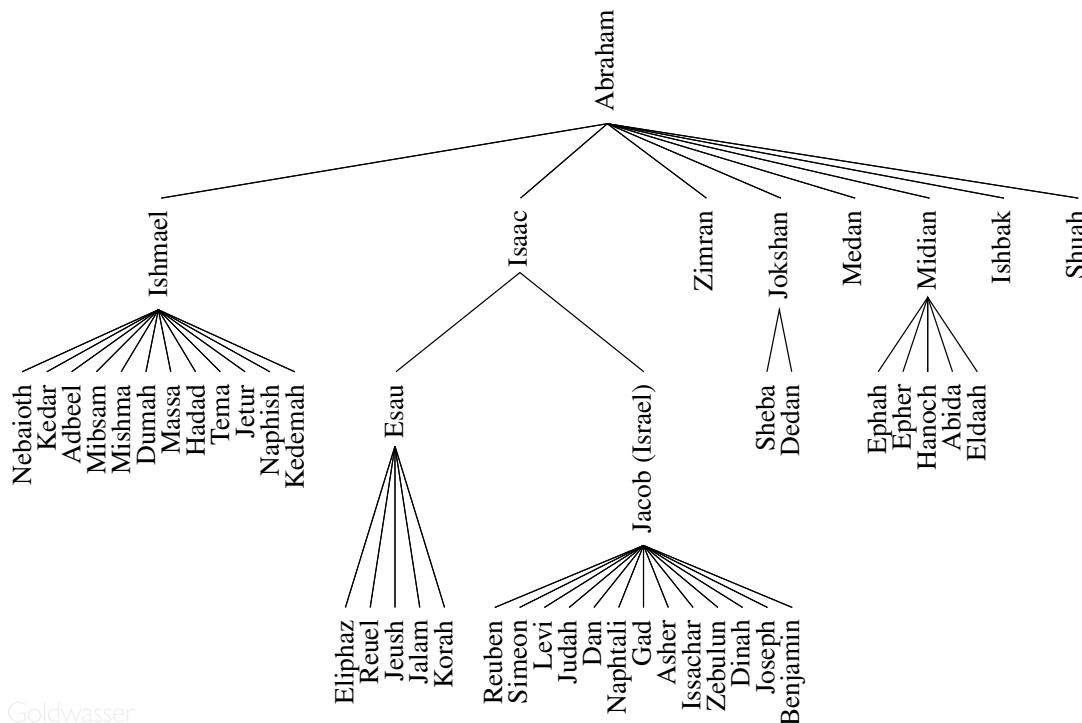
Seong Jae Hwang

Aims

- Tree: first nonlinear data structure we study
- Binary Tree
- How to implement trees
 - linked structure
 - array-based
- How to traverse through trees
- Application of binary tree for binary search

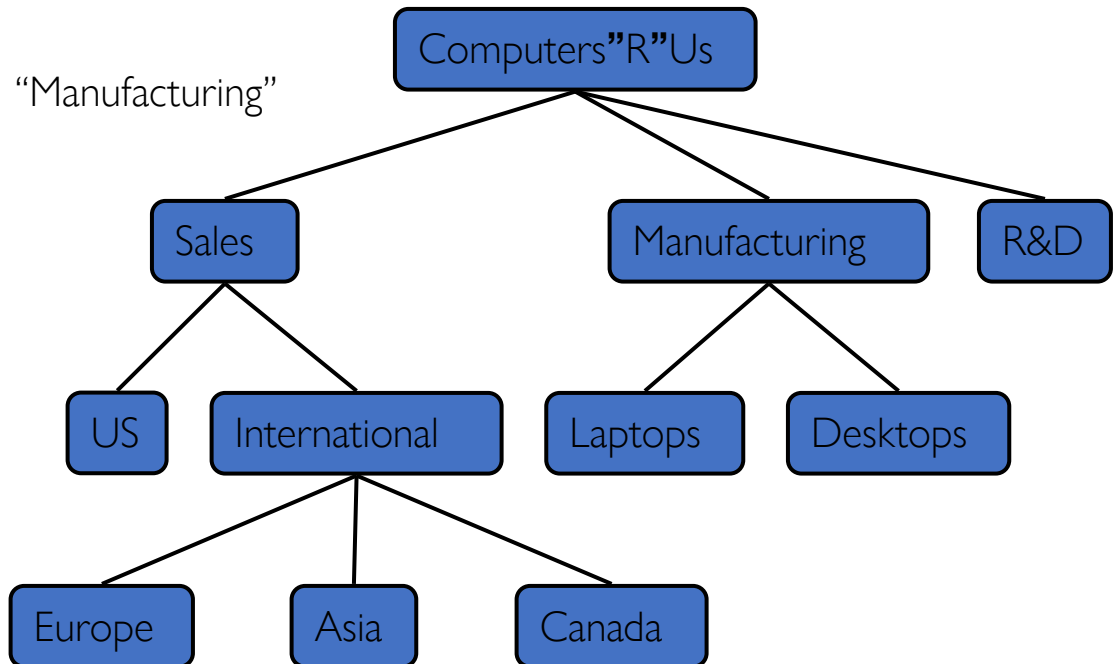
Trees!

- One of the most important **nonlinear** data structures
 - More than just “before” and “after” relationships
 - **hierarchical** relationships: “above” and “below” others
- Many algorithms become much faster with trees compared to linear data structures such as array or linked lists



Definitions and Properties

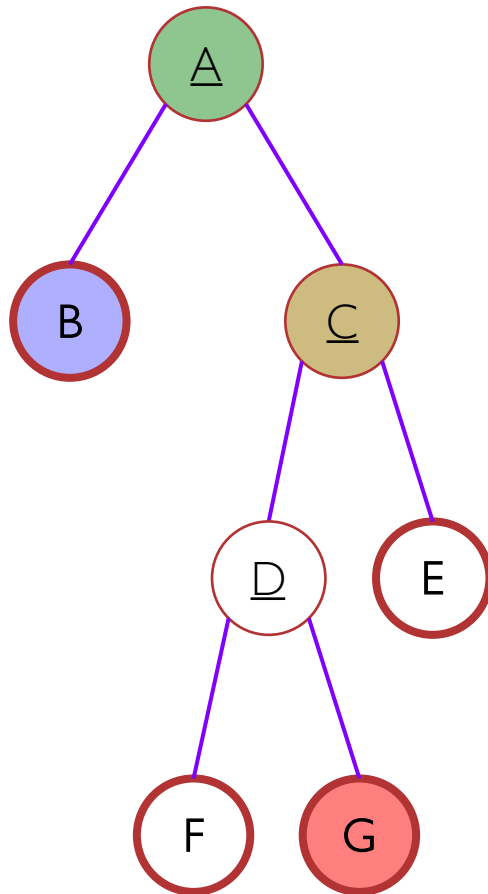
- ADT that stores elements hierarchically
- Each element (except the very top element) has a **parent** and zero or more **children** elements
 - **root**: top/highest element
- Notice that the elements at the same “level” are not necessarily of the same characteristics
 - ex: children of “Sales” and “Manufacturing”



Formal Tree Definition

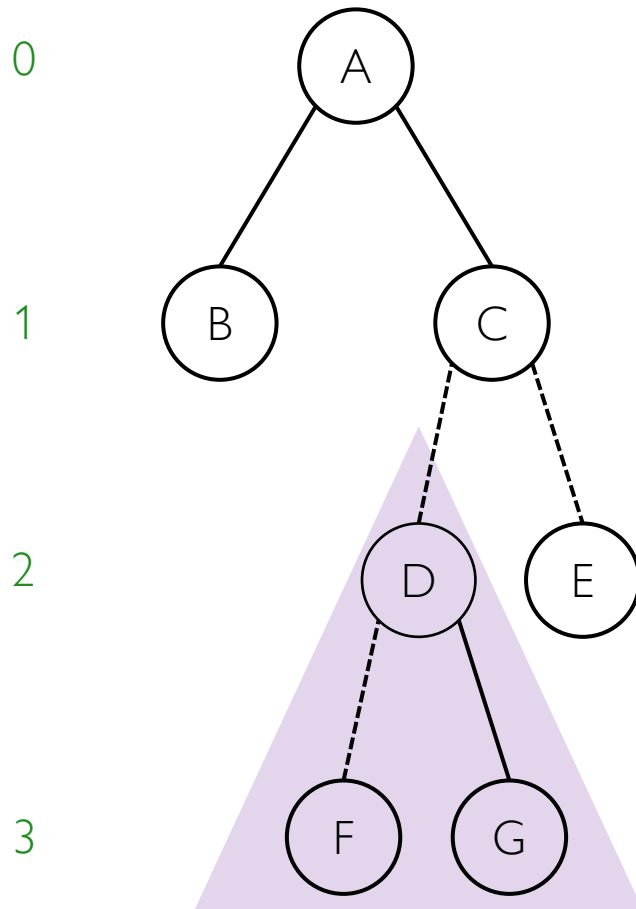
- Formally, a **tree** T is a set of **nodes** storing elements such that the nodes have a **parent-child** relationship that satisfies:
 - If T is nonempty, it has the **root** of T that has **no parent**
 - Each node v of T (except for the root) has a unique **parent** node w ; every node with parent w is a **child** of w
- Technically, a tree can be
 - of only one node (i.e., root) with (possibly empty) subtrees
 - or even empty

Tree Terminology



- *Nodes*
- *Edges* connect two nodes
- *A* is the *root* of the tree
- *B* is a *child* of *A*
- *A* is the *parent* of *B*
- *C* is a *sibling* of *B*
- *G* is a *descendant* of *C*
- *C* is an *ancestor* of *G*
- *Leaves* do not have children; *internal nodes* do

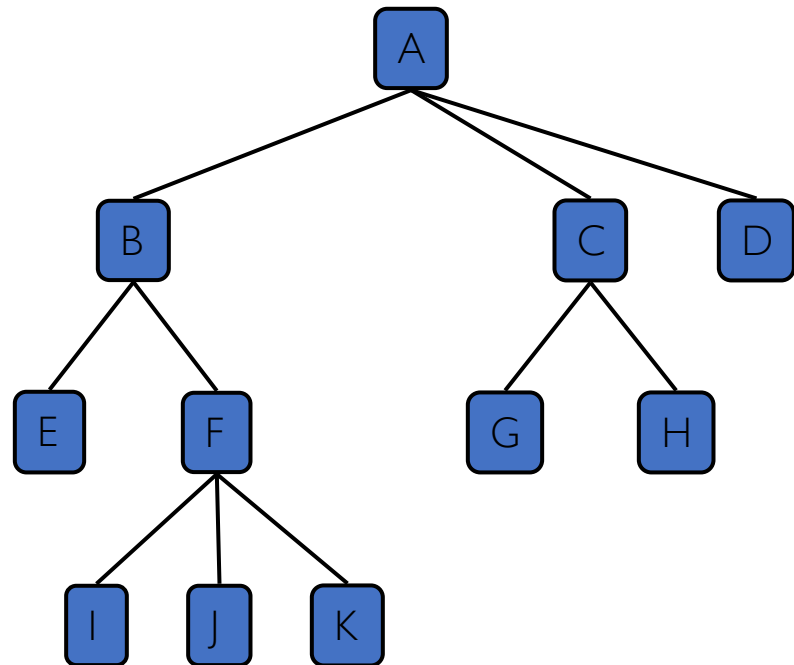
Tree Terminology



- The *subtree rooted at* D contains 3 nodes
- The *degree* of a node is the number of its children
- A *path* connects two nodes; there exists a unique (simple) *path* between any pair of nodes
- The *level** of a node is the length of the unique path from the root to the vertex
- The *height* of a tree is the maximum level of a node

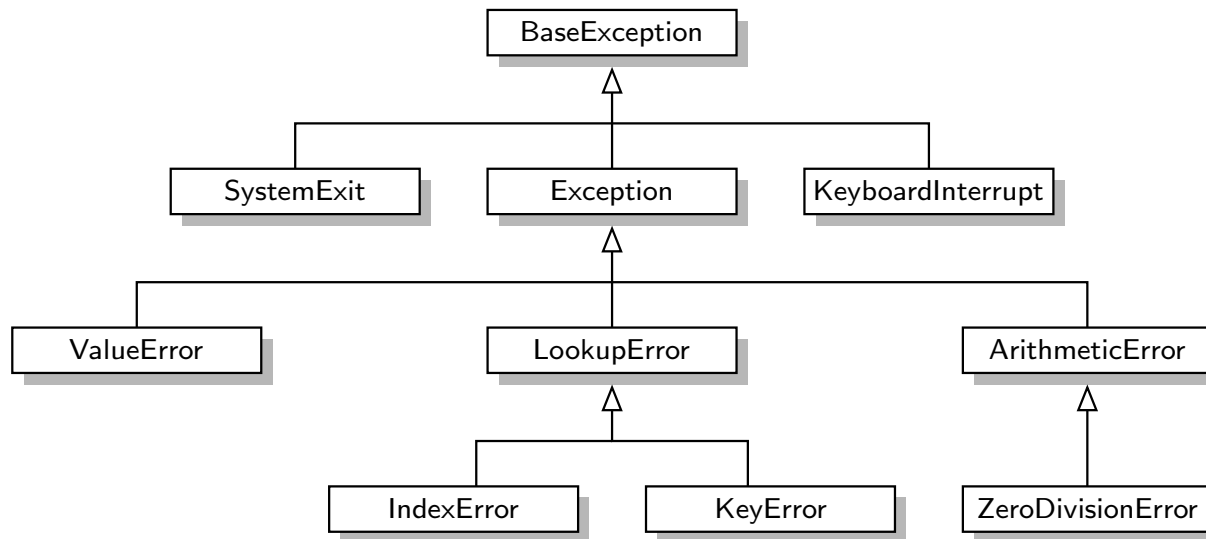
Example

- Root: A
- Internal node: A, B, C, F
- Leaves: E, I, J, K, G, H, D
- Ancestors of K: F, B, A
- Level of J: 3
- Level of C: 1
- Height: 3
- Descendants of B: F, I, J, K
- One subtree: F and its children
- Path from J to G: J, F, B, A, C, G



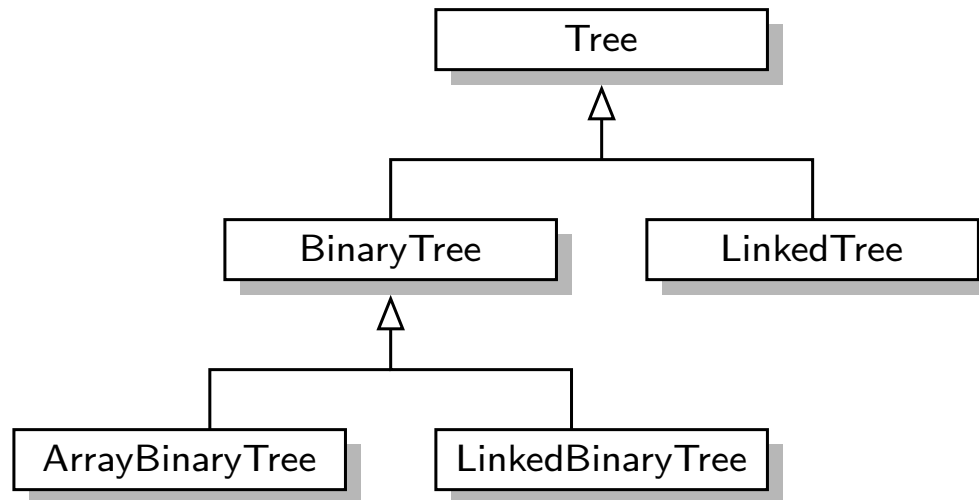
Example

- The hierarchy for Python's exception types
- *BaseException* is the root
- All user-defined exception classes conventionally declared as descendants of *Exception* class



Example

- The inheritance hierarchy for various tree data structures we will cover in this chapter
 - BinaryTree is a type of Tree
 - ArrayBinaryTree is a type of BinaryTree

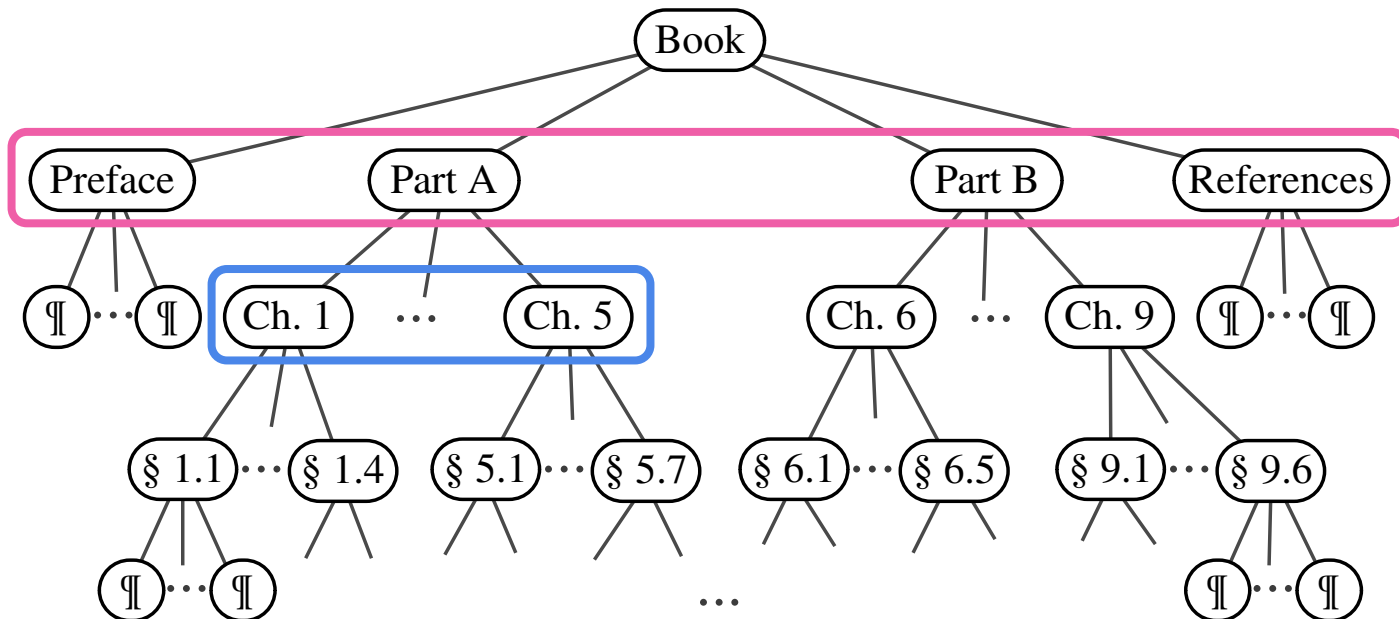


Quick Question: what is data structure?

- Let us realize that data structures are not just ways to use large datasets efficiently in terms of speed and space
- Information to be store often have **inherent relationships**
- Appropriate data structures help us to **capture those relationships**
 - Not only for efficiency
 - But also for understanding the underlying relationship of our data

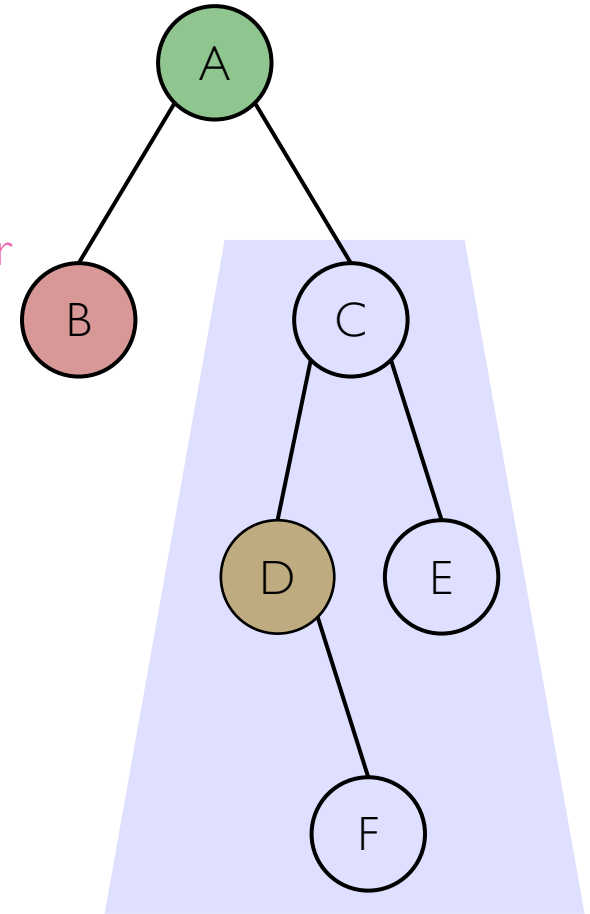
Can We “Order” Trees?

- A tree is **ordered** if there is a meaningful linear order among the children of each node
 - Visually, ordered from left to right
- Hierarchical *and* linear relationships



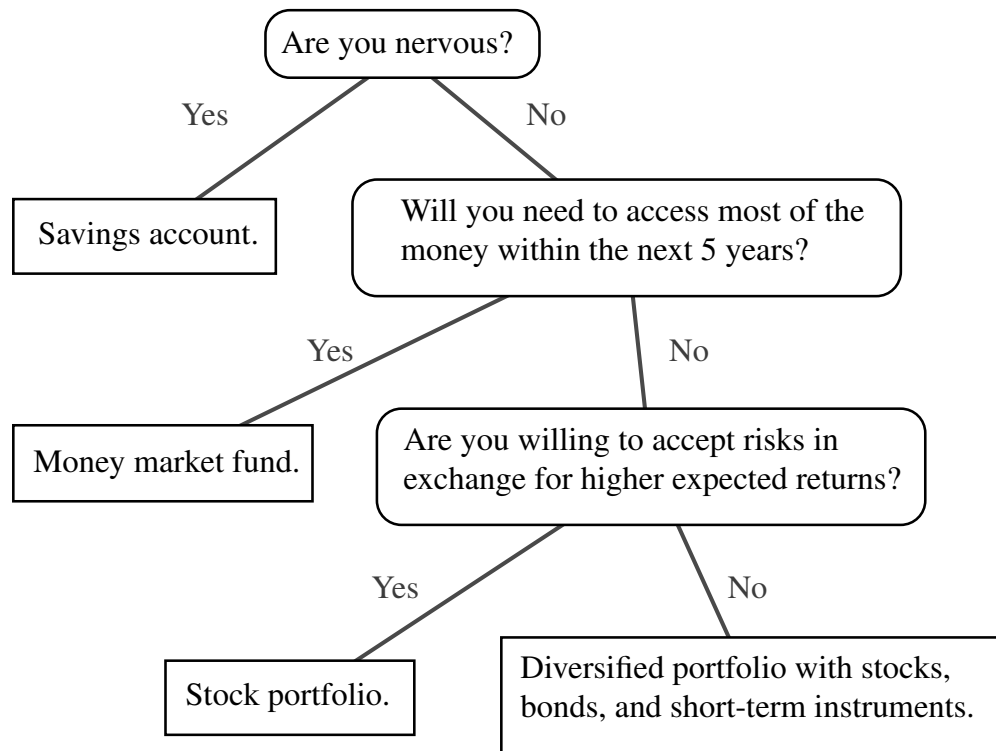
Binary Trees

- A binary tree is an **ordered tree** which
 - Every node has at most two children
 - When all nodes have exactly zero or two children, the binary tree is **proper**
 - If not proper, then the binary tree is **improper**
 - a **left child** or a **right child**
 - The children of a node are **ordered**
- **B** is the left child of **A**
- The **subtree rooted at C** is the right subtree of **A**
- **D** has the right child only



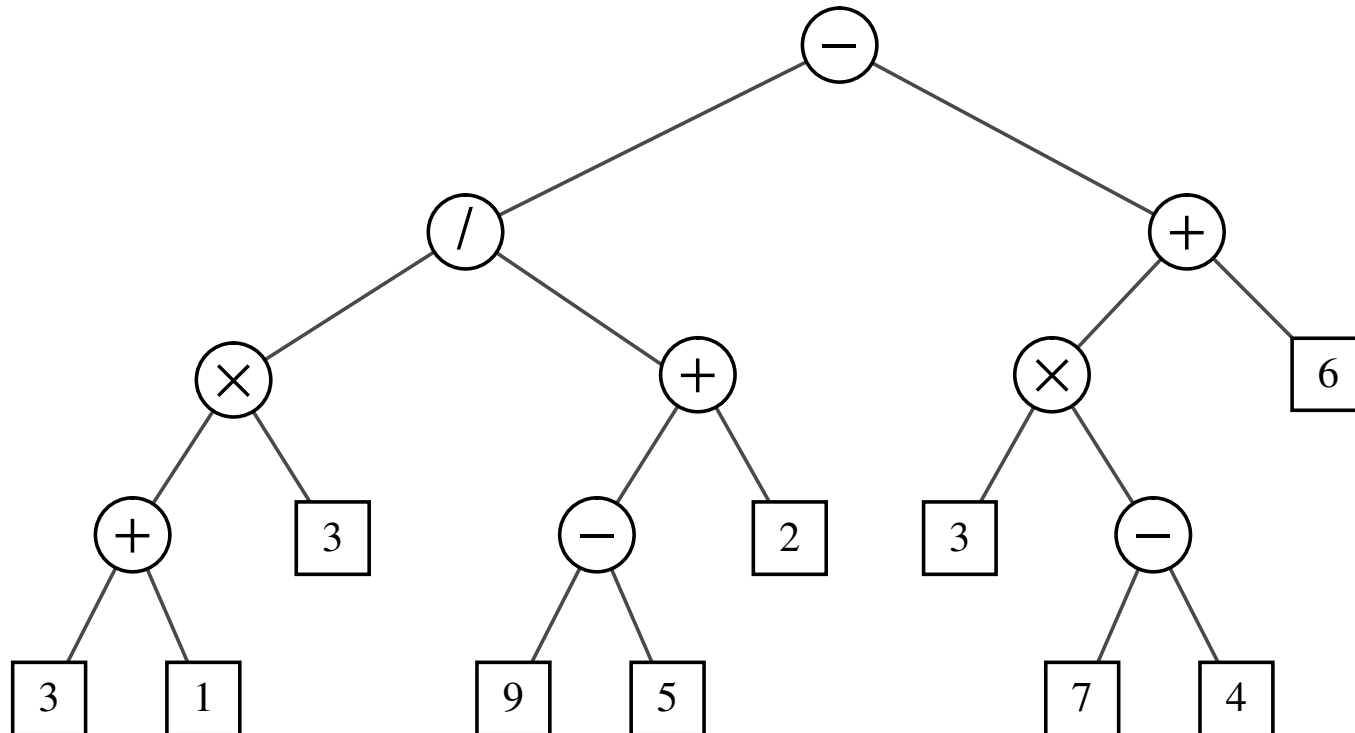
Example

- Decision trees: ask questions and take a step depending on your answer
 - Yes: go to the left child
 - No: go to the right child



Example

- Arithmetic expression
 - Internal nodes: operators (+, -, ×, /)
 - Leaves (external nodes): variables or constants
- $((((3 + 1) \times 3) / (9 - 5) + 2)) - ((3 \times (7 - 4)) + 6))$



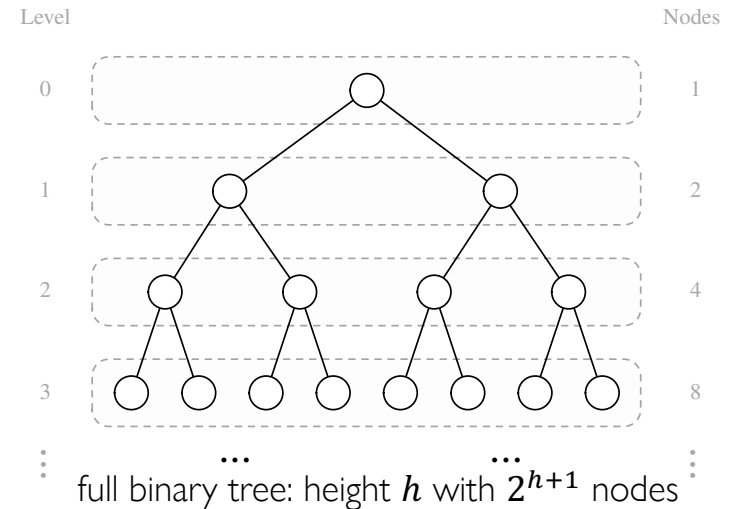
Properties of Binary Trees

- Because of such strict structures, binary trees have interesting properties based on

- n : # of nodes
- n_E : # of external nodes (leaves)
- n_I : # of internal nodes
- h : height

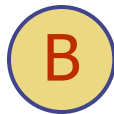
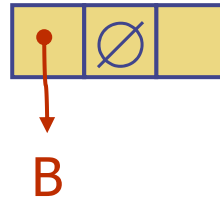
- For a nonempty binary tree T ,

- $h + 1 \leq n \leq 2^{h+1} - 1$
 - $h + 1$: T with only one child
 - $2^{h+1} - 1$: max possible # of nodes of a binary tree with height h
- $1 \leq n_E \leq 2^h$
 - 1: T with root
 - 2^h : max possible # of leaves at level h
- $h \leq n_I \leq 2^h - 1$
 - h : T with only one child (note h starts from 0)
 - $2^h - 1$: max possible # of nodes except for level h
- $\log(n + 1) - 1 \leq h \leq n - 1$
 - $\log(n + 1) - 1$: height of a **full binary tree** built from n nodes
 - $n - 1$: height of a one-child binary tree built from n nodes



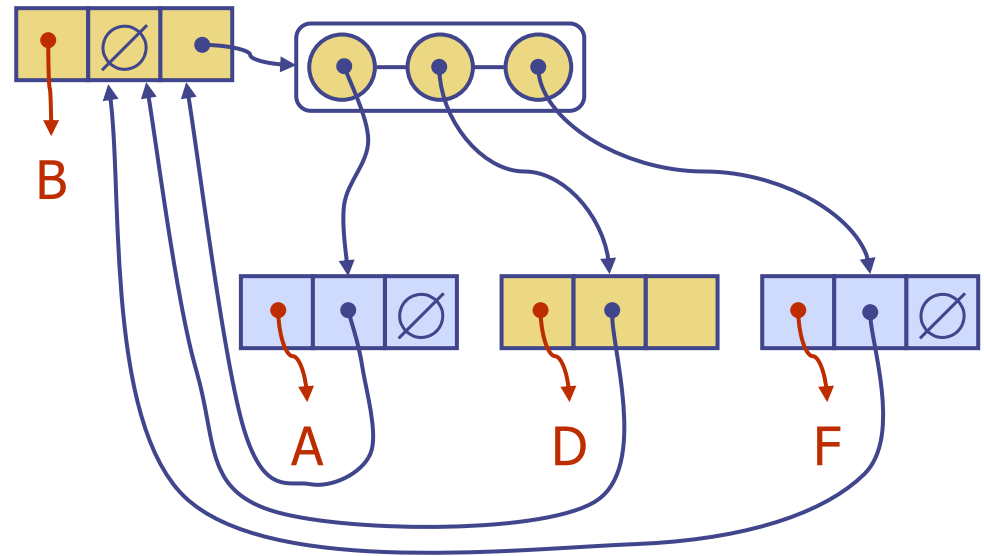
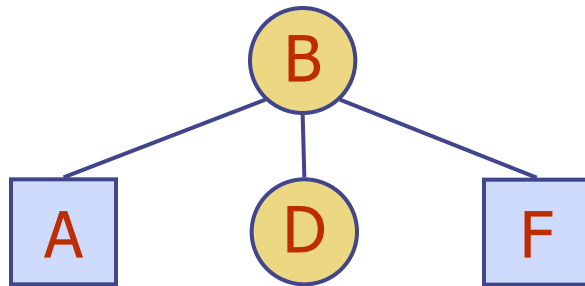
Implementing Trees

- Linked Structures
- A node as an object storing
 - element
 - parent node
 - sequence of children nodes



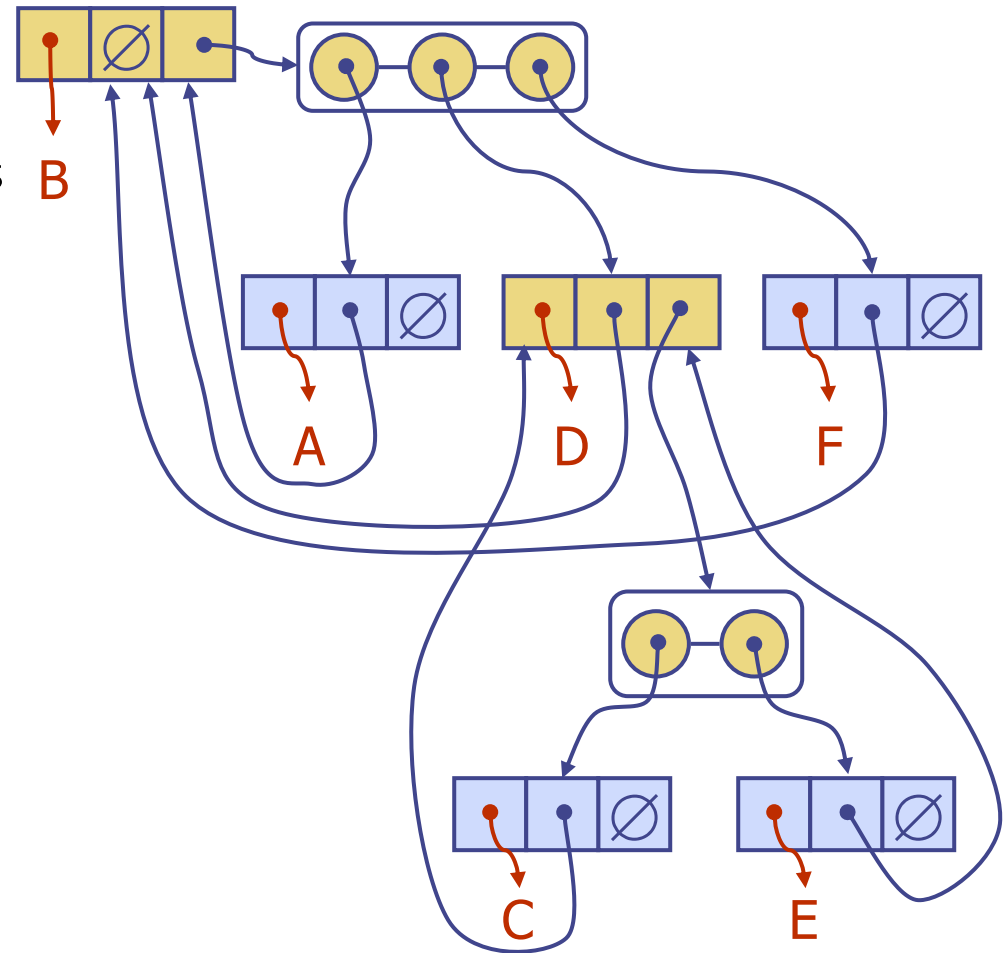
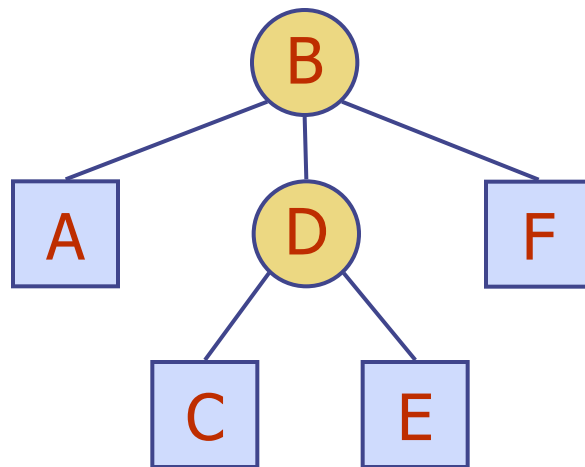
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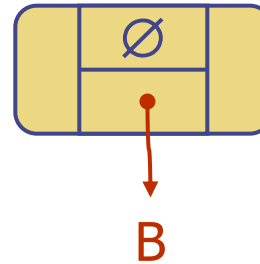
Implementing Trees

- Linked Structures
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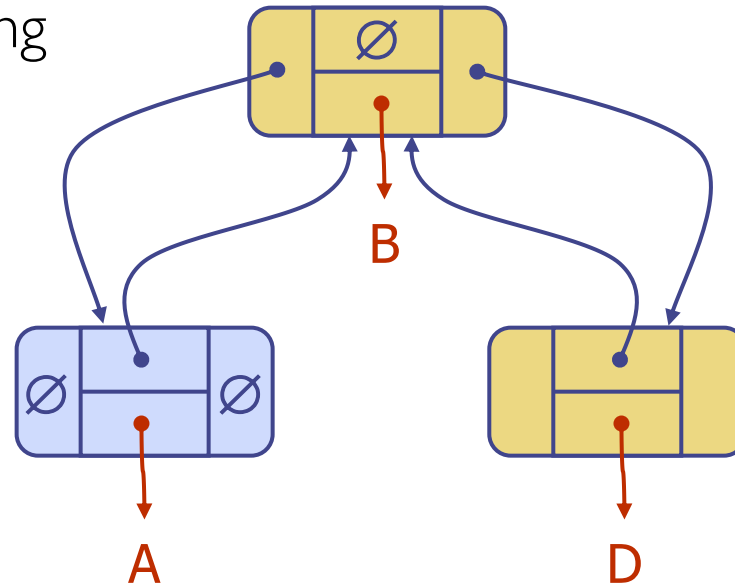
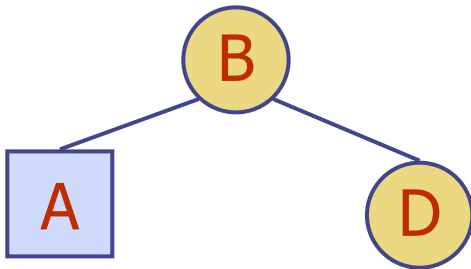
Implementing Binary Trees

- Again, Linked Structures
- A node as an object storing
 - element
 - parent node
 - left child node
 - right child node



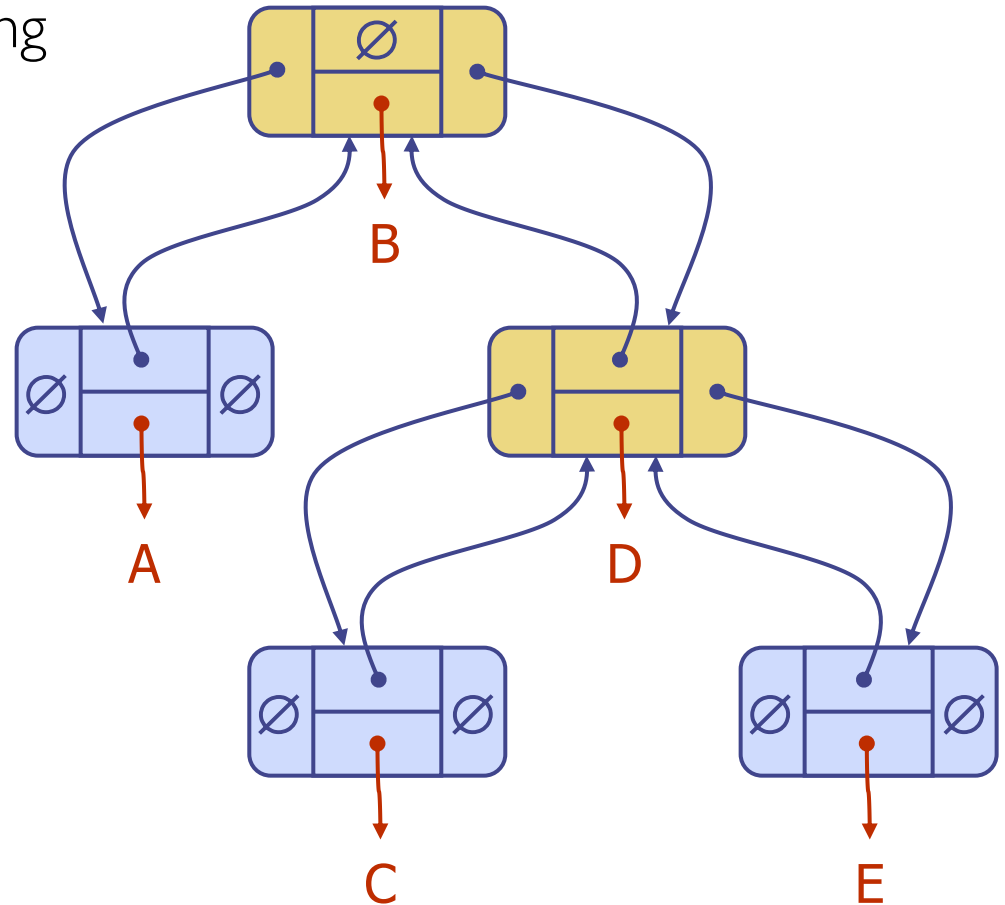
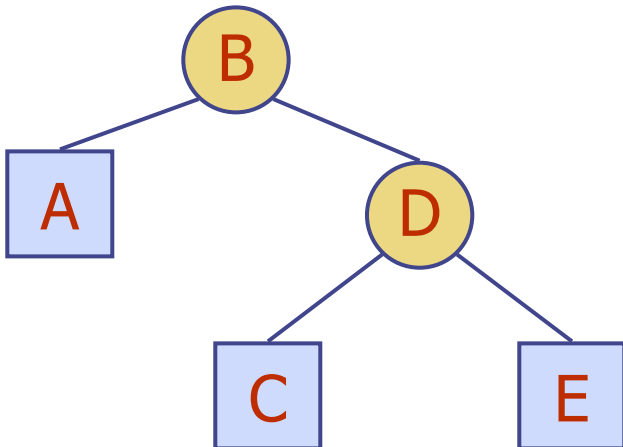
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Implementing Binary Trees

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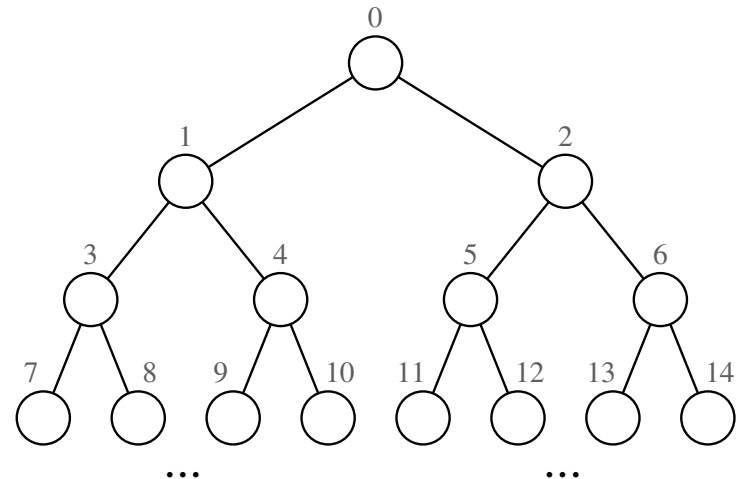
Time Complexity of Binary Tree

- Linked binary tree
- Most operations require a constant number of node relinking
- height needs to check all nodes to find the maximum depth

Operation	Running Time
len, is_empty	$O(1)$
root, parent, left, right, sibling, children, num_children	$O(1)$
is_root, is_leaf	$O(1)$
depth(p)	$O(d_p + 1)$
height	$O(n)$
add_root, add_left, add_right, replace, delete, attach	$O(1)$

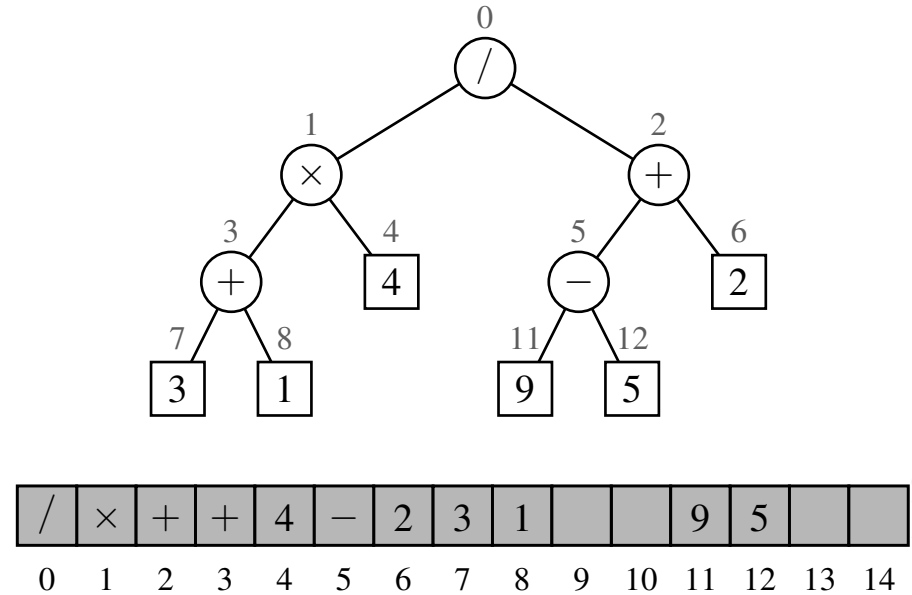
Implementing Binary Trees

- Array-Based
 - Can we actually do this with a simple array?
 - Yes! Assign an index to each node based on its level: **level numbering**
- For every position p of T , the index/rank $f(p)$ is
 - If p is the root of T , then $f(p) = 0$
 - If p is the left child of position q , then $f(p) = 2f(q) + 1$
 - If p is the right child of position q , then $f(p) = 2f(q) + 2$
- Parent of p ? (what is $f(q)$ given p ?)
 - left child: $f(q) = \frac{f(p)-1}{2}$
 - right child: $f(q) = \frac{f(p)-2}{2}$
 - left or right child: $f(q) = \left\lfloor \frac{f(p)-1}{2} \right\rfloor$



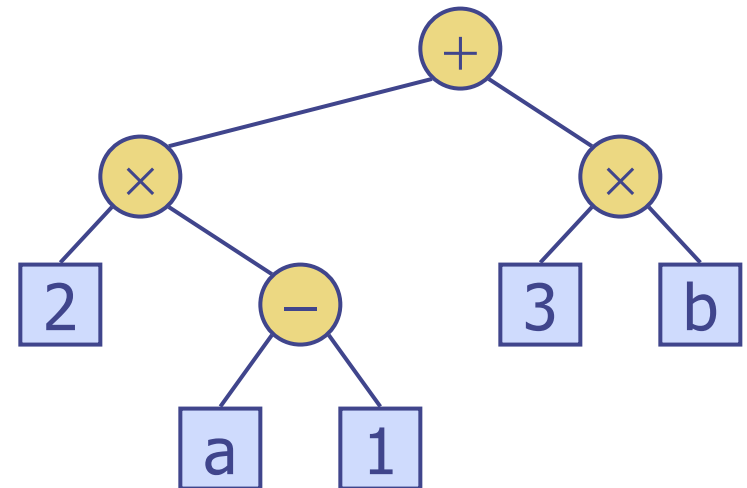
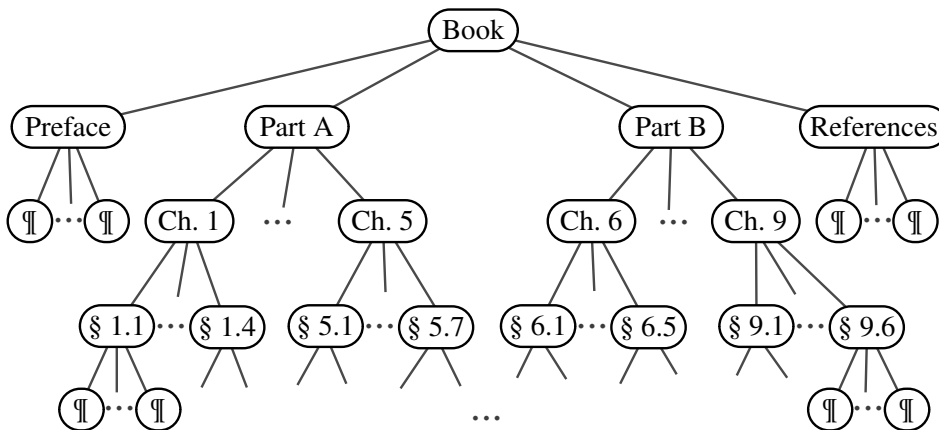
Implementing Binary Trees

- Indices are based on full binary tree
regardless of your tree shape
- Advantage:
 - position (element) p can be expressed by a single integer
 - parent, left, and right of p can all be arithmetically computed
- Disadvantage:
 - Size of the array depends on the $\max f(p)$
 - what is the most extreme example?
right-child-only tree
 - For each new level, how much does the array size grow? doubles!
 - Updating (add or delete) a node is cannot be done efficiently
 - what is the time complexity? $O(n)$



In what order do we access the nodes?

- From a node, we have two options: visit the sibling, or visit the children
- How do we systematically or algorithmically access the nodes such that
 - a book is structured in the correct order?
 - returning the node elements gives $(2 \times (a - 1) + (3 \times b))$?
- Depends on the application!



Tree Traversal 1: Preorder Traversal

- In a **preorder traversal**, a node is visited *before* its descendants

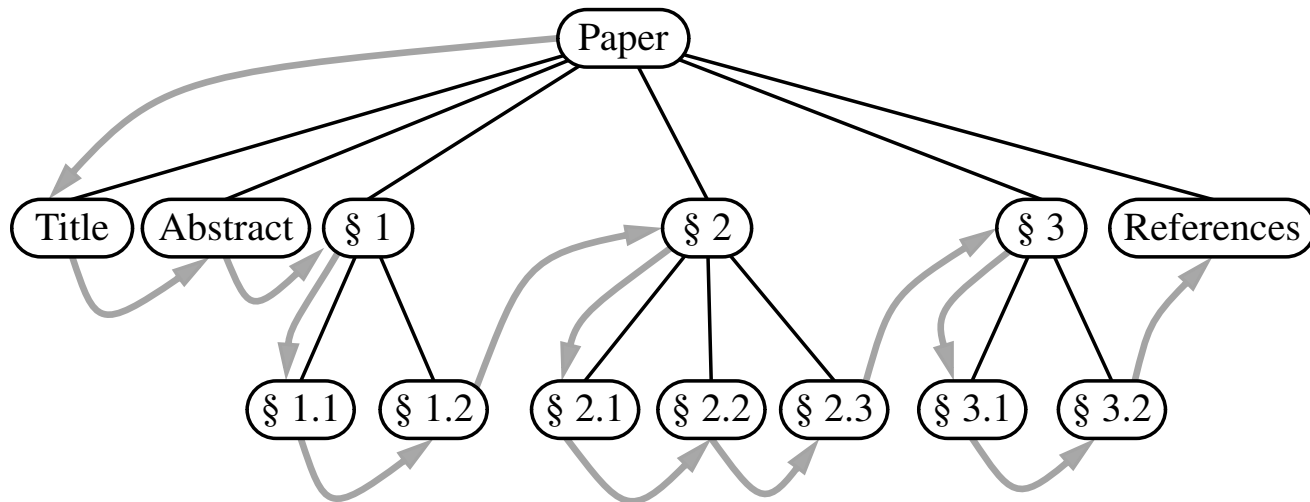
Algorithm preorder(T, p):

perform the “visit” action for position p

for each child c in $T.children(p)$ **do**

preorder(T, c)

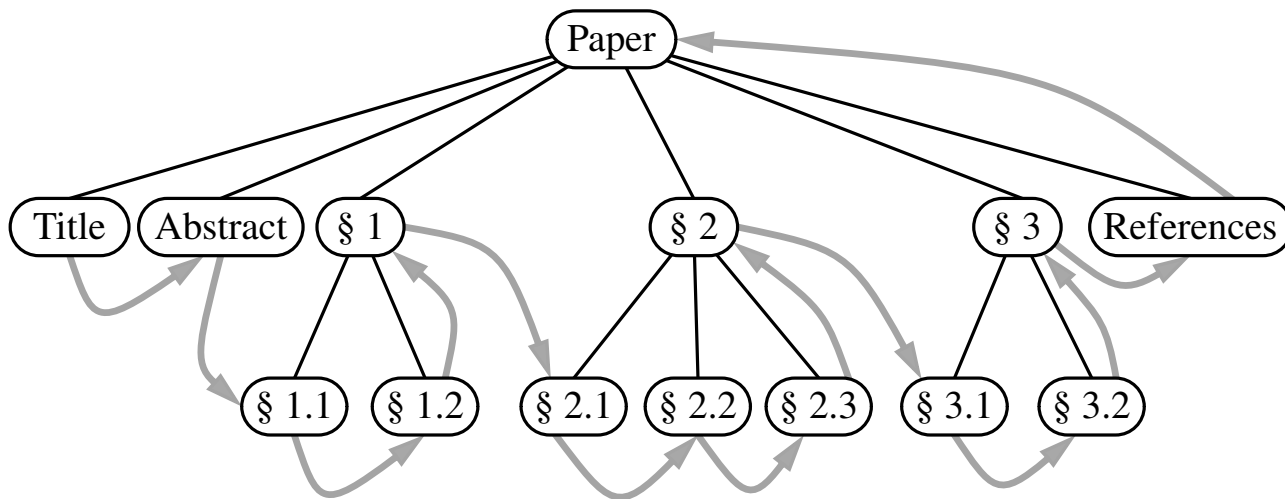
{recursively traverse the subtree rooted at c }



Tree Traversal 2: Postorder Traversal

- In a **postorder traversal**, a node is visited *after* its descendants

Algorithm postorder(T, p):
 for each child c in $T.children(p)$ do
 postorder(T, c) {recursively traverse the subtree rooted at c }
 perform the “visit” action for position p



Breath-First Tree Traversal

- Preorder and postorder traversals are recursive
- **Breath-First Search**: visit all the nodes in each level before checking the nodes at the next level
 - Example: a **game tree** to check all the moves possible by a player
 - Check all possible moves for the next ***h*** moves (where ***h*** is as much as the computer can compute)
- How do we implement this non-recursive traversal? Use **queue**!

Algorithm breadthfirst(T):

Initialize queue Q to contain T.root()

while Q not empty **do**

 p = Q.dequeue()

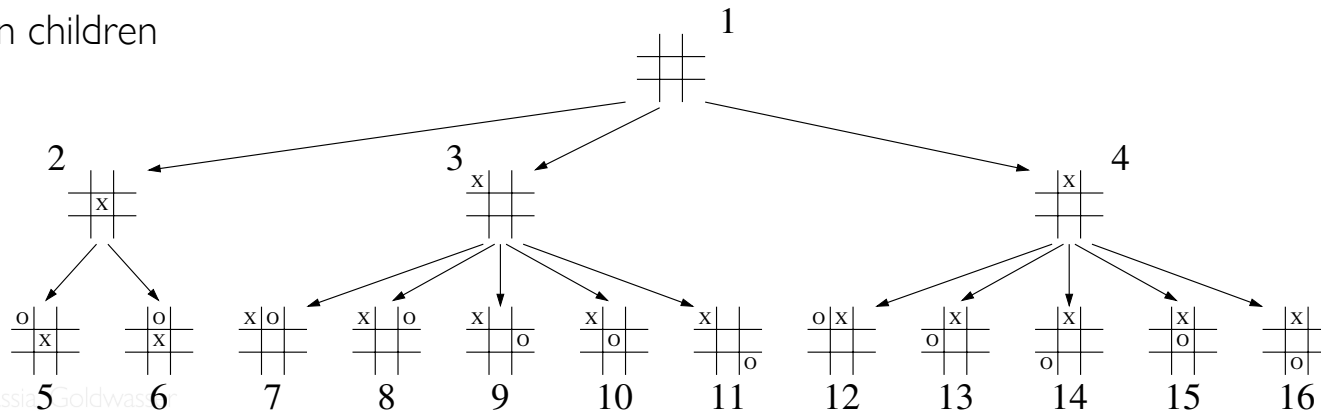
{p is the oldest entry in the queue}

 perform the “visit” action for position p

for each child c in T.children(p) **do**

 → Q.enqueue(c) {add p’s children to the end of the queue for later visits}

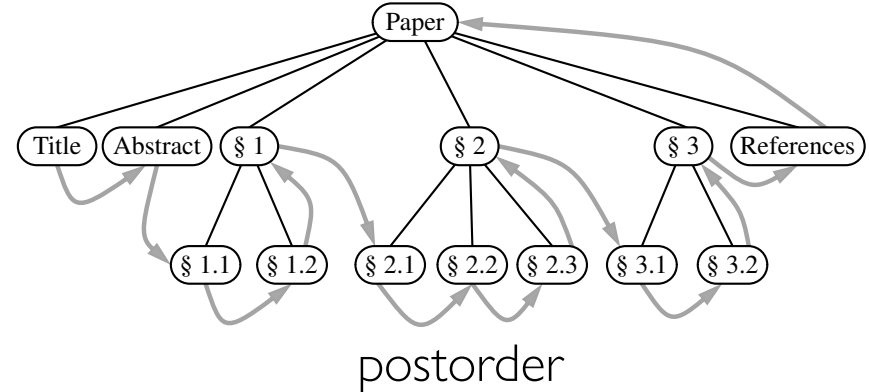
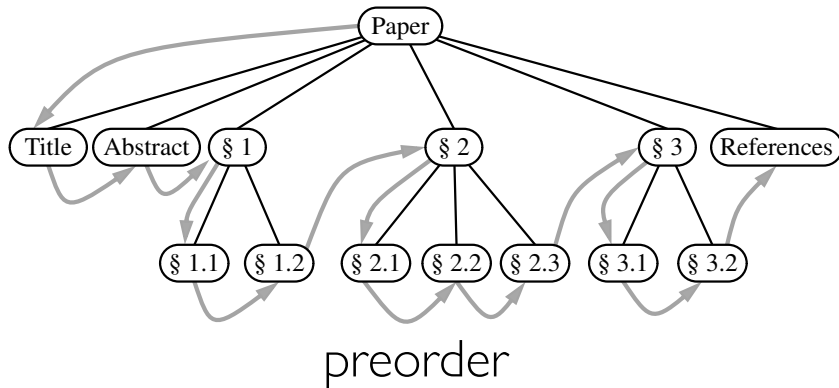
enqueue the children to
ensure they are visited
before their own children



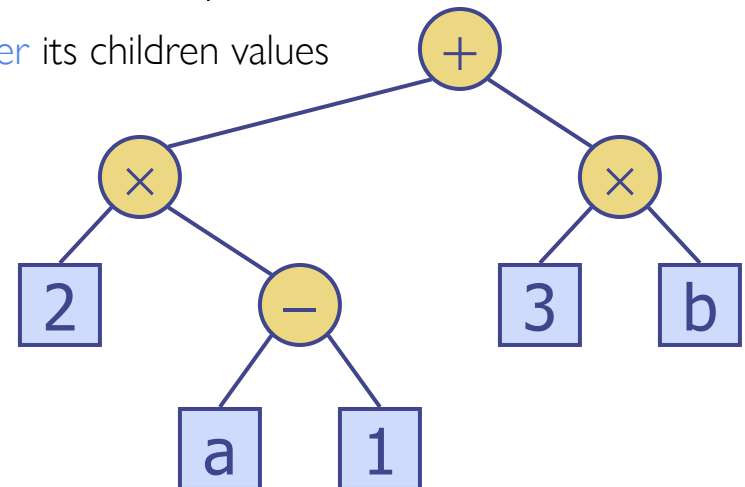
Example

- Preorder (left) or postorder (right) to structure the document?
 - preorder – parent node element needs to appear **before** its children

Paper
Title
Abstract
§1
§1.1
§1.2
§2
§2.1
...



- Preorder or postorder to compute the arithmetic expression tree
 - postorder – parent node operator is applied **after** its children values
- How about to print the arithmetic tree?



Binary Tree Traversal: Inorder Traversal

- For binary tree:
 - Preorder: root \rightarrow left subtree \rightarrow right subtree
 - Postorder: left subtree \rightarrow right subtree \rightarrow root
 - Inorder**: left subtree \rightarrow root \rightarrow right subtree
- $3 + 1 \times 3 / 9 - 5 + 2 - 3 \times 7 - 4 + 6$
 - Missing the parenthesis

Algorithm inorder(p):

if p has a left child lc **then**

inorder(lc)

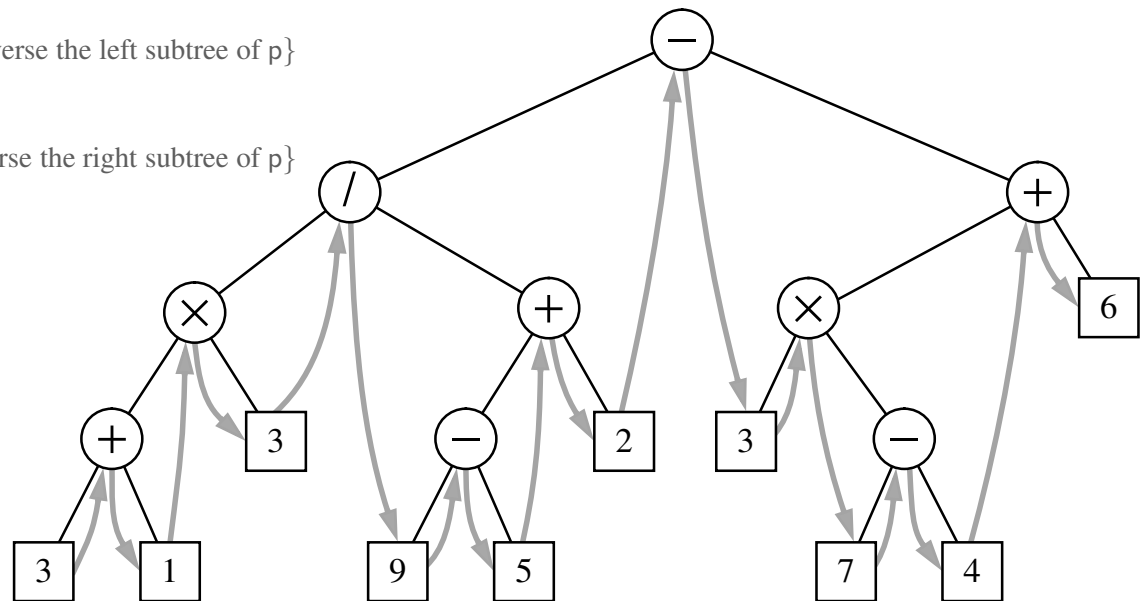
{recursively traverse the left subtree of p}

perform the “visit” action for position p

if p has a right child rc **then**

inorder(rc)

{recursively traverse the right subtree of p}

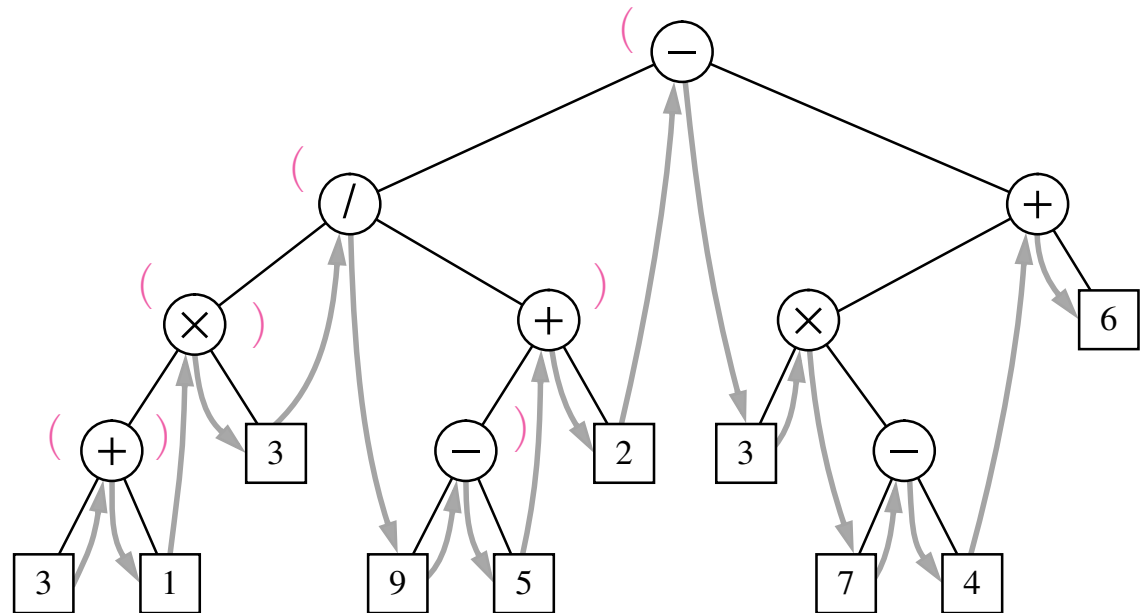


Example

- Print arithmetic expressions
 - print "(" before traversing left subtree
 - print ")" after traversing right subtree
- $((((3 + 1) \times 3) / ((9 - 5) + 2) - \dots$

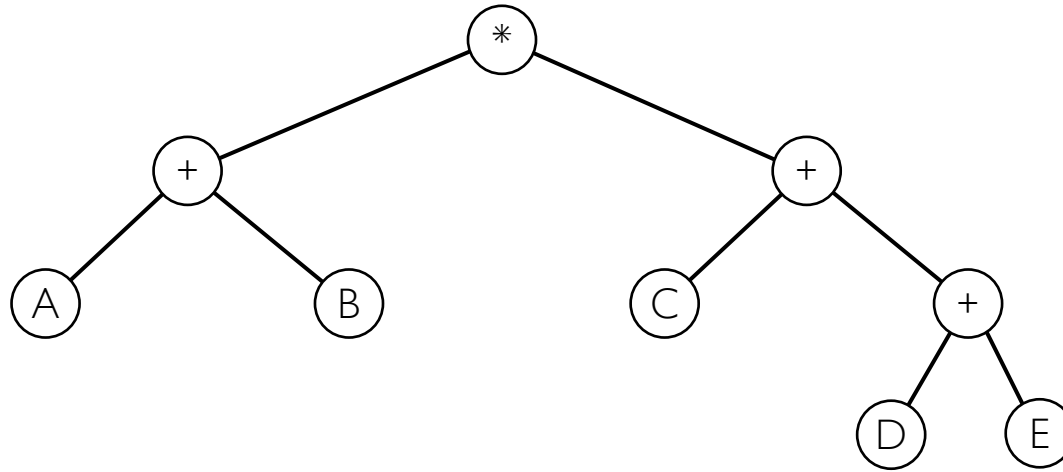
```

Algorithm printExpression(v)
    if left(v) ≠ null
        print("(")
        inorder (left(v))
        print(v.element ())
    if right(v) ≠ null
        inorder (right(v))
        print(")")
    
```



Example

- If we simply “output” the data of each node...



- $(A+B)*(C+(D+E))$
- Preorder traversal: $*+AB+C+DE$
- Inorder traversal: $A+B*C+D+E$
- Postorder traversal: $AB+CDE++*$

Consider a Binary Search

10

3	9	10	13	19	20	23
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Consider a Binary Search

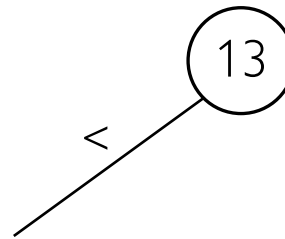
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3	9	10	13	19	20	23
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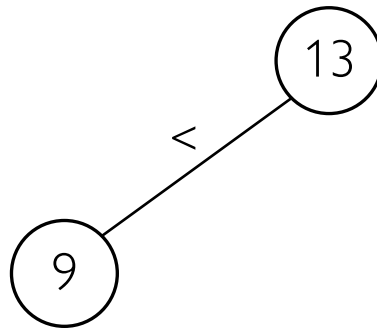
Consider a Binary Search

10



Consider a Binary Search

10



Consider a Binary Search

10

3

9

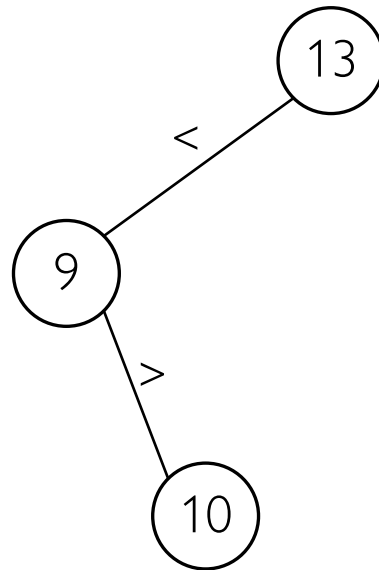
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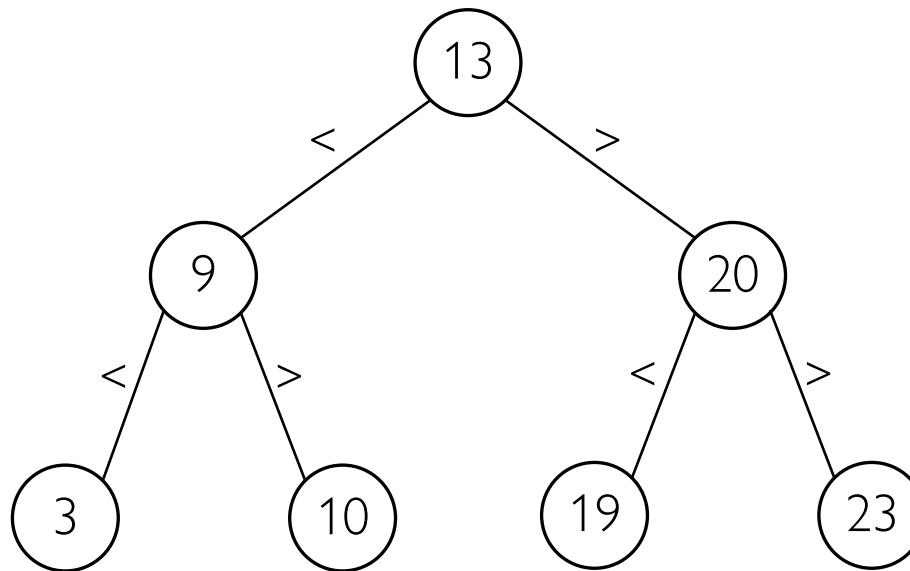
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23



Consider a Binary Search

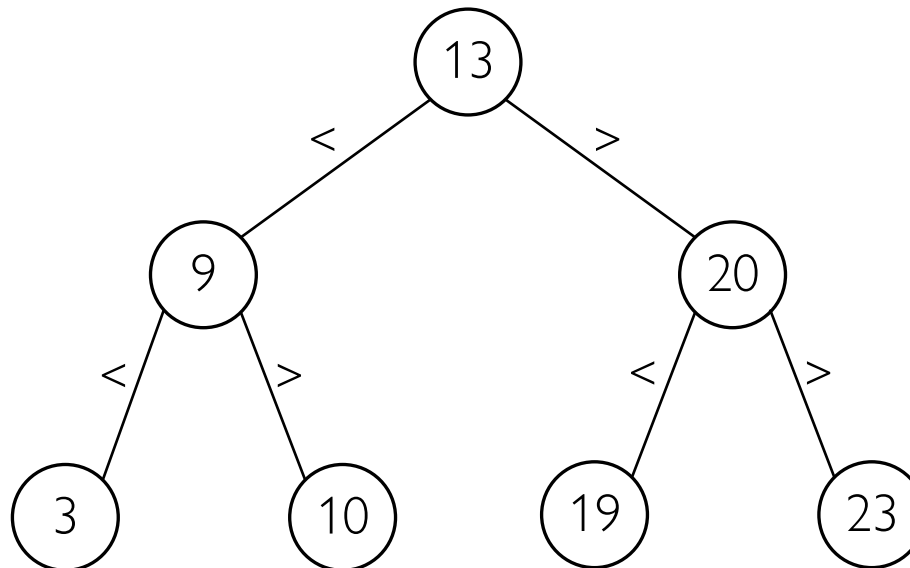
3 9 10 13 19 20 23



The entire binary search can be stored and processed in a binary tree

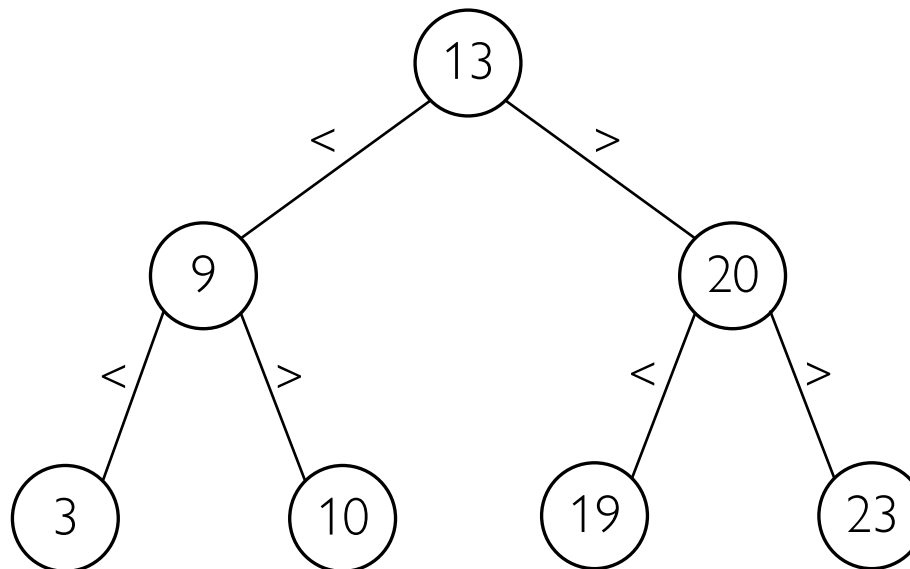
Binary Search Tree

- A **binary search tree**
 - an empty tree or
 - a binary tree such that
 - root has an element
 - left subtree elements are smaller than the root element
 - right subtree elements are greater than the root element
- Inorder traversal of a BST gives an ordered sequence of elements
- Why use this over a sorted array?



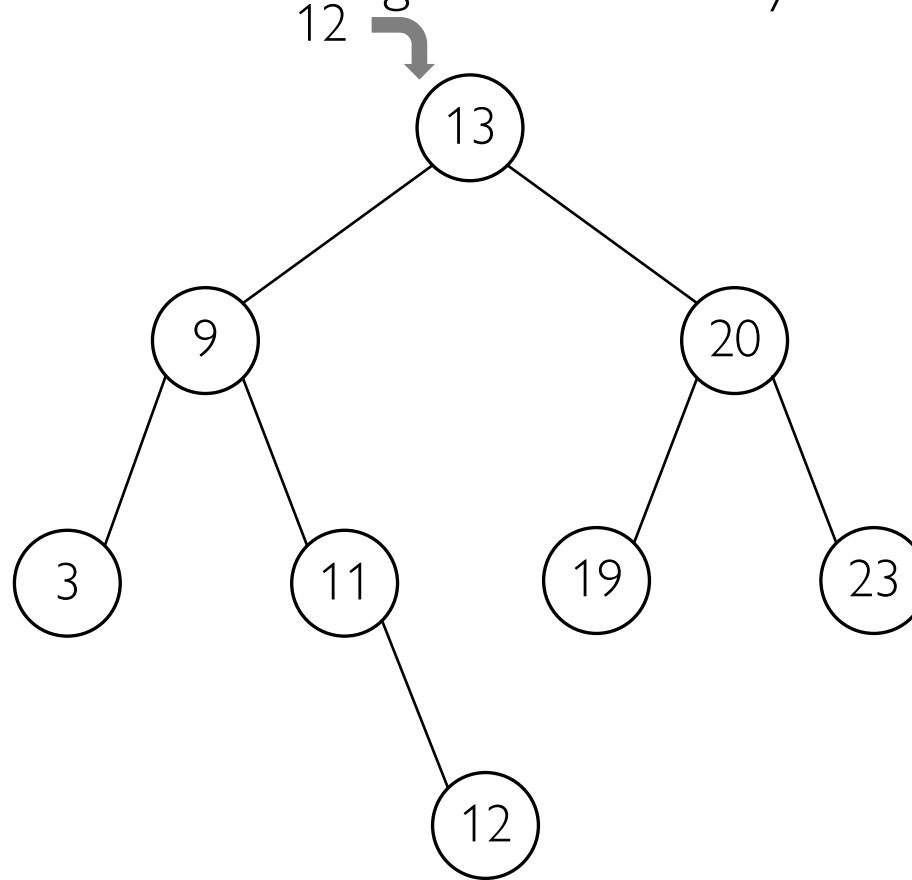
Binary Search Tree

- Insertion:
 - Array: $O(n)$ to find and insert
 - BST: ?



Binary Search Tree

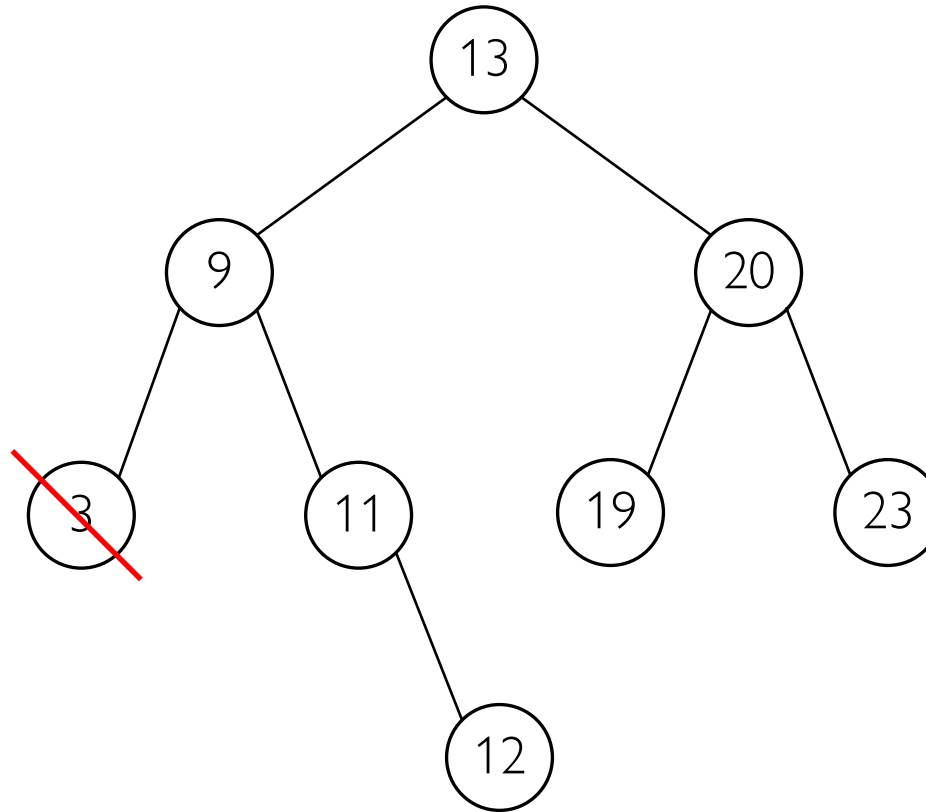
- $O(h)$ time, where h is the height of the binary search tree



Binary Search Tree

- Deleting a leaf

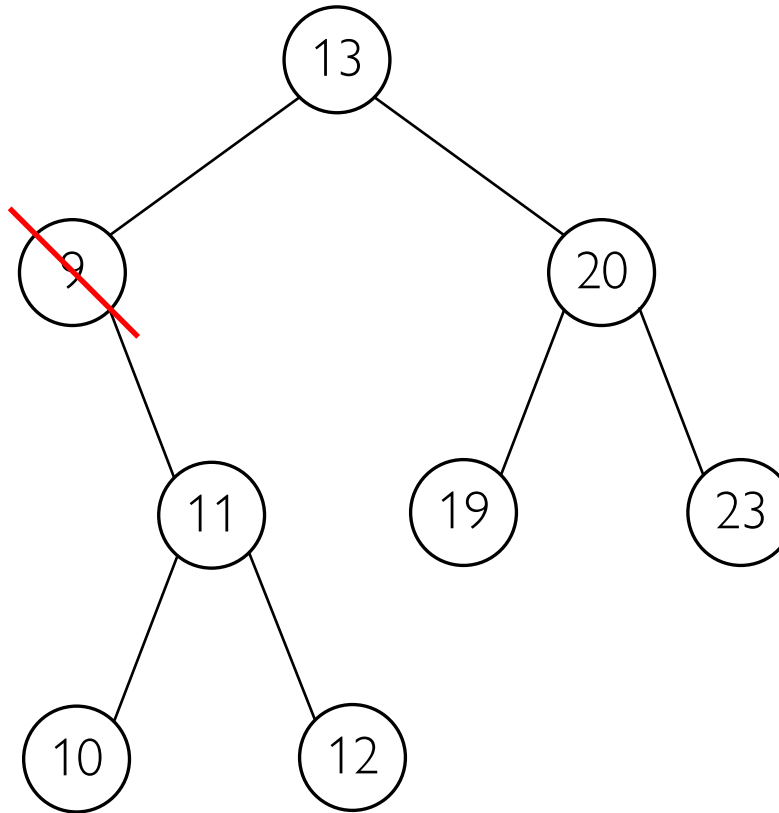
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Binary Search Tree

- Deleting a node with a single child

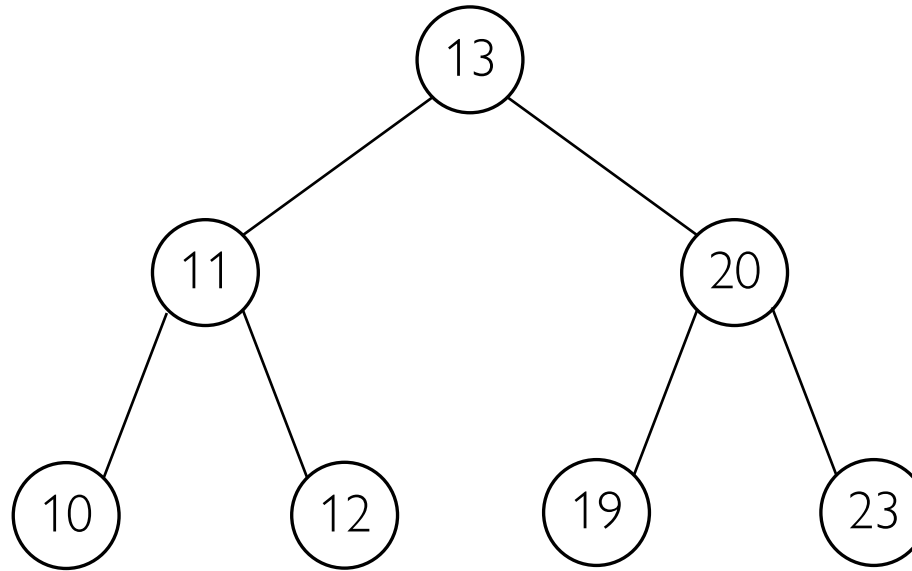
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Binary Search Tree

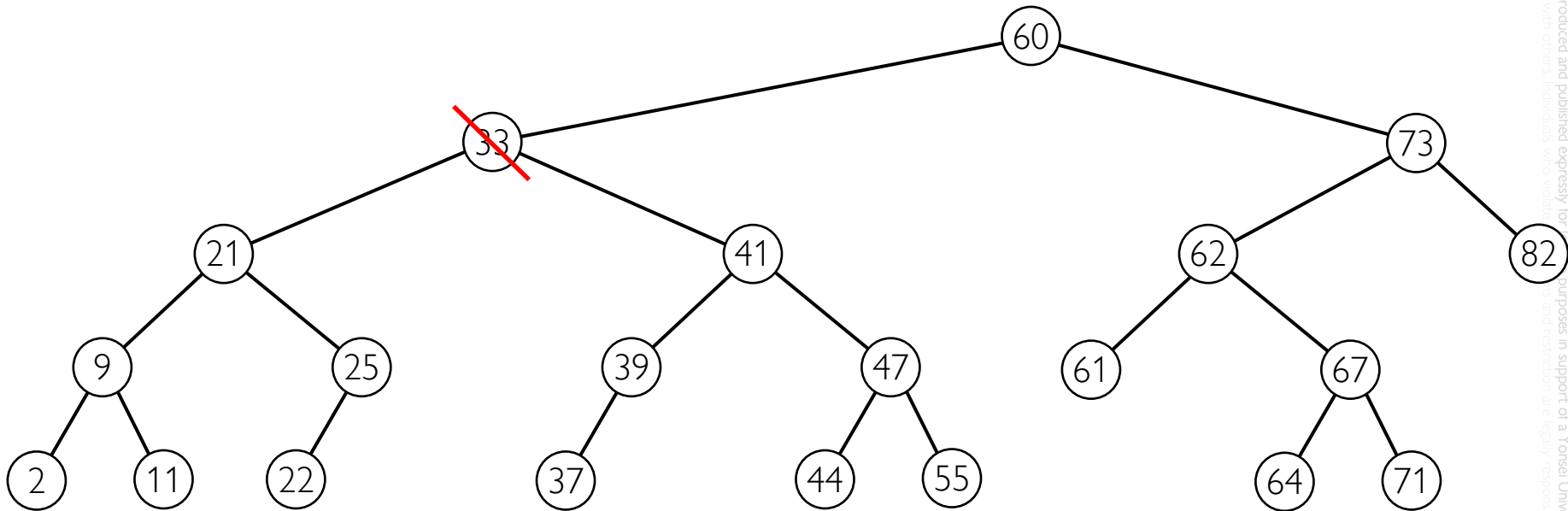
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9



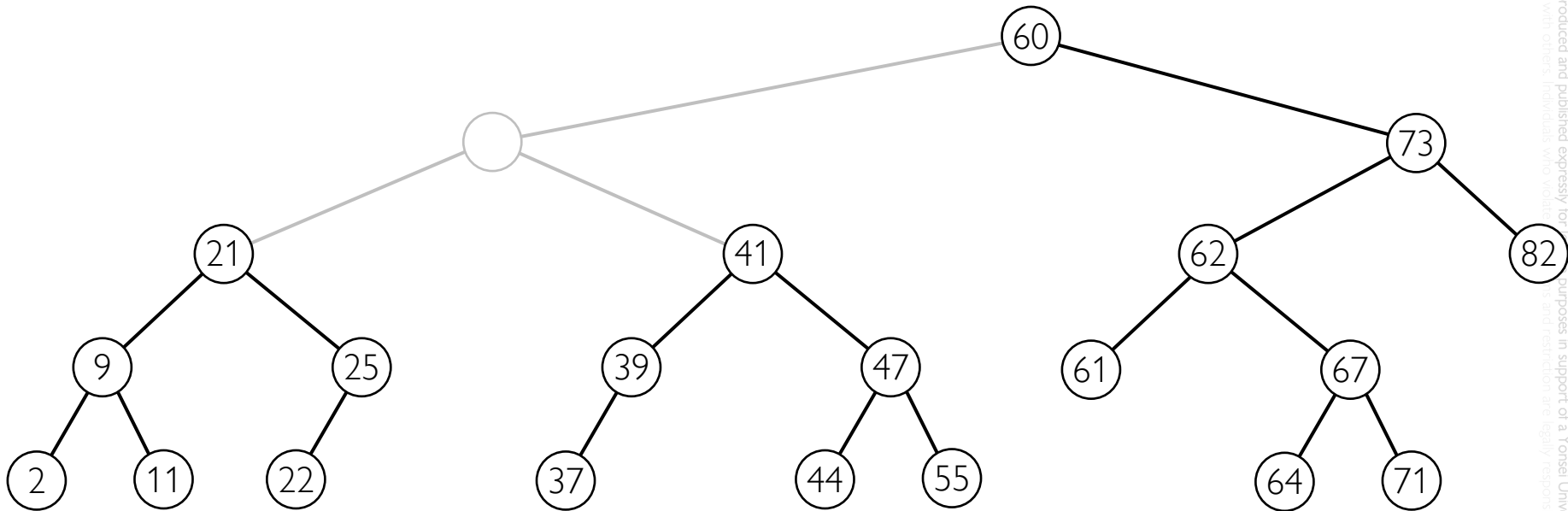
Binary Search Tree

- Deleting a node with a two children



Binary Search Tree

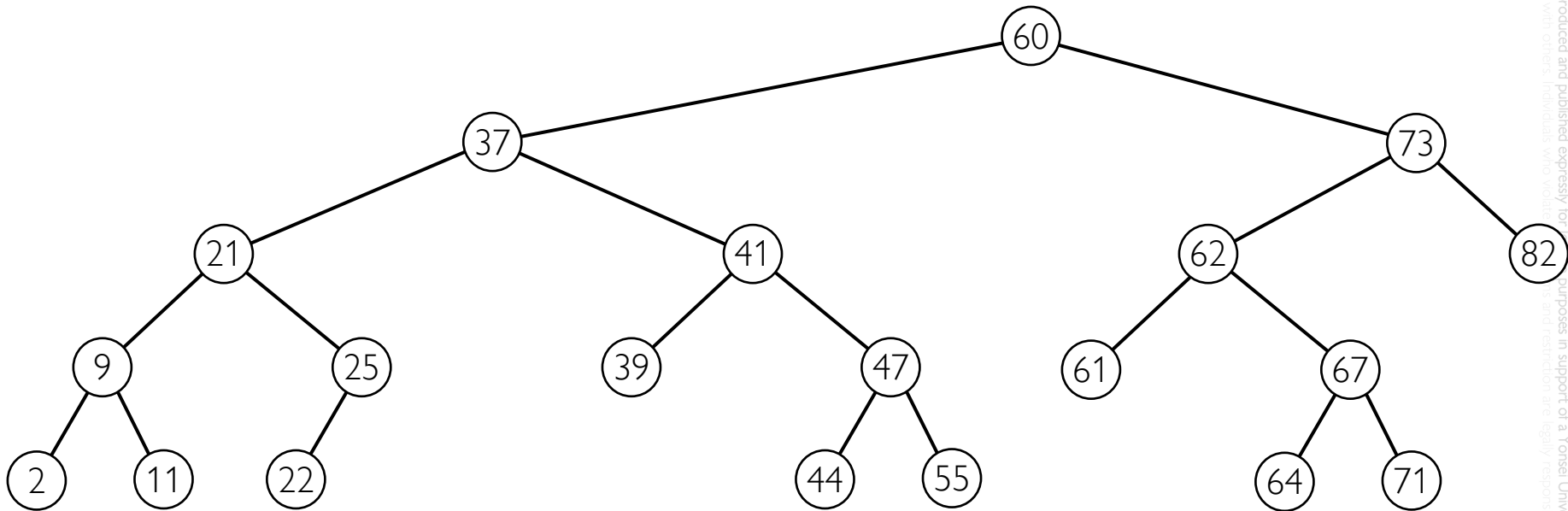
- Deleting a node with a two children



- Replace with max of left subtree or min of right subtree
 - Question: How to find them?

Binary Search Tree

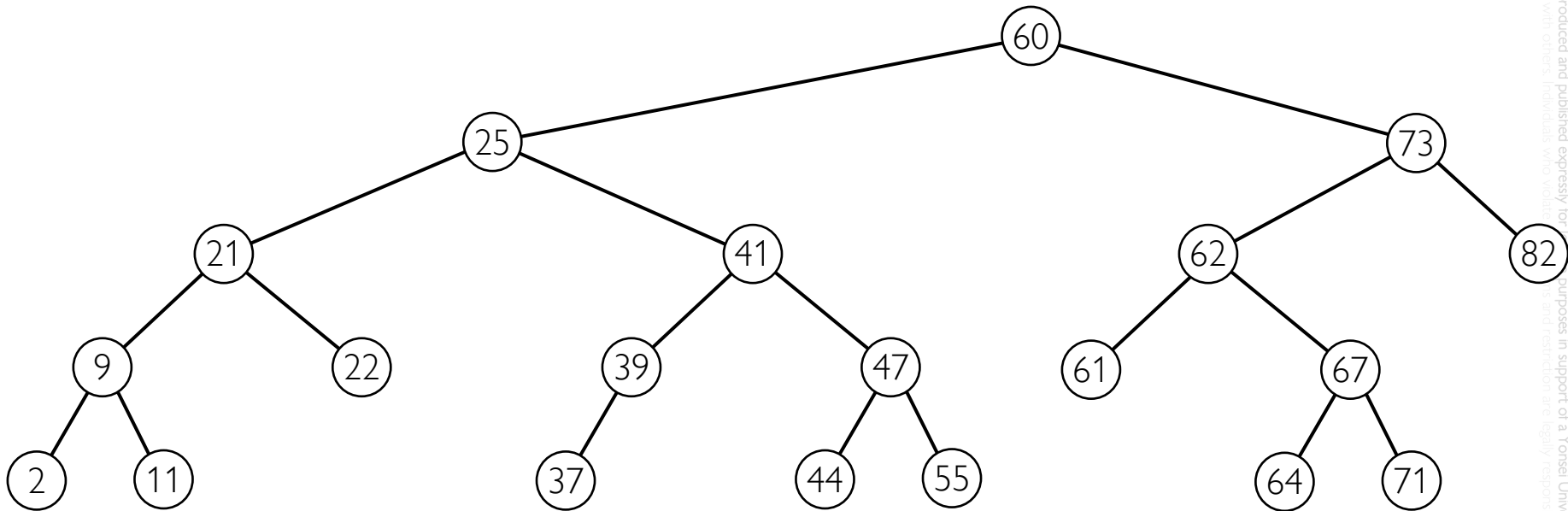
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Binary Search Tree

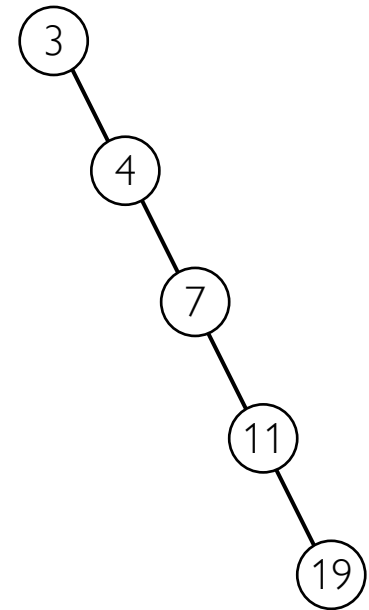
- Deleting a node with a two children



- Replace with **max of left subtree** or min of right subtree
 - Question: How to find them?

Time Complexity

- Sorted array
 - $O(\log n)$ search
 - $O(n)$ insertion
 - $O(n)$ deletion
- Binary search tree
 - $O(h)$ search
 - $O(h)$ insertion
 - $O(h)$ deletion
- but $\log(n + 1) - 1 \leq h \leq n - 1$ for n nodes
- Need to balance the tree to have small height
 - Will get back to this in Chapter 11



Summary

- Tree is a nonlinear data structure
- Allows nonlinear hierarchical relationship + linear relationship
- General trees
- Binary trees
 - linked vs. array
- Traversals
 - preorder, postorder, breath-first, inorder (binary tree only)
- Binary search tree (BST)
 - another natural way to store ordered elements
- Next: see how binary tree becomes the basis of another data structure