# Computer System Final Project X-Part Toy-OS

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- **Buddy-system**
- System Call Table
- File Loader
- Shell
- Conclusions and Thoughts

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# **Background**

### Toy-OS

- Buddy-System
- Sys-call Table
- File Loader
- Shell



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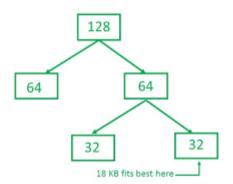
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What's Buddy-system?

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**Buddy-system** 



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How did I implement the buddy-system?

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How did I implement the buddy-system?

```
#define _BUDDY_H
uint64 ROUNDUP(uint64 num);
struct buddy
void init_buddy_system(void);
void *alloc_pages(int);
void free_pages(void *);
#endif
```

#### Details

```
void init_buddy_system(void)
   unsigned int *begin = (unsigned int *)(U64ADDR(_end));
   needPage += (U64ADDR(_end) - U64ADDR(text_start)) / PGSIZE;
```

#### **Details**

```
假设我们系统一共有8个可分配的页面,可分配的页面数需保证是2/n
memory:
| page 0 | page 1 | page 2 | page 3 | page 4 | page 5 | page 6 | page 7 |
+----+
buddy system将页面整理为 2^n 2^(n-1) ... 2^1 2^0 不同大小的块:
8 +---> 4 +---> 2 +---> 1
            +---> 1
       +---> 2 +---> 1
             +---> 1
 +---> 4 +---> 2 +---> 1
             +---> 1
       +---> 2 +---> 1
```

#### Details

```
#define P PAGE 0x1000
#define parent(x) (((x + 1) >> 1) - 1)
#define lson(x) (((x + 1) << 1) - 1)
#define rson(x) ((x + 1) << 1)
struct buddy buddy;
unsigned ins_bitmap[2 * P_PAGE - 1];
unsigned long page_offset = 0x80000000ul;
extern unsigned long *_end;
```

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### alloc\_pages

```
id *alloc_pages(int num)
}
```

```
oid *alloc_pages(int num)
```

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### free\_pages

```
free_pages(void *ptr)
```

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```
void free pages(void *ptr)
       if (buddy item.bitmap[nowIndex * 2 + 1] == nowSize && buddy item.bitmap[nowIndex * 2 + 2] == nowSize)
       nowSize *= 2:
```

### void \*kmalloc (size\_t size)

```
if (objindex >= NR_PARTIAL)
   p = alloc_pages((size - 1) / PAGE_SIZE + 1);
    set_page_attr(p, (size - 1) / PAGE_SIZE + 1, PAGE_BUDDY);
```

#### void kfree(void \*addr)

```
void kfree(const void *addr)
   struct page *page:
   page = ADDR_TO_PAGE(addr);
       clear_page_attr(ADDR_TO_PAGE(addr)->header);
```

#### get\_unmapped\_area

```
unsigned long get_unmapped_area(size_t length)
   unsigned long begin = 0:
    struct vm area struct *tmp = current->mm.vm area;
            if (begin < tmp->vm end && tmp->vm start < begin + length)
```

#### Do\_mmap

```
return (void *)t->vm_start;
    if (t->vm_start < begin->vm_end && begin->vm_start < t->vm_end)
```

#### Do\_mmap

```
t->vm_start = get_unmapped_area(length);
        t->vm_prev = prev;
t->vm_prev = prev;
```

#### mprotect

```
oid mprotect do(uint64 pagetable, uint64 va. size t len. int prot)
   struct PAGE *now = (struct PAGE *)pagetable;
       uint64 pte2, pte1, pte0;
```

### Some conclusion

- -fno-builtin
- -gdwarf-2
- -O2

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### Some conclusion

- -fno-builtin
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### sys-call Implemented in finished course

- sys-call 64: SYS\_WRITE (Lab4)
  - sys\_write(unsigned int fd, const char\* buf, size\_t count)
  - printout the string from user, is call by user-function printf

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### sys-call Implemented in finished course

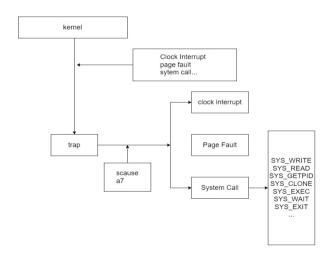
- sys-call 174: SYS\_GETPID (Lab4)
  - sys\_getpid
  - pick the pid of current process, pass it to user program with register a0

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### sys-call Implemented in finished course

- sys-call 220: SYS\_CLONE (Lab5)
  - sys\_clone(struct pt\_regs \*regs)
  - execute the fork process of current running process

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#### sys-call Implemented in finished course

- The former implemented three sys-calls build the framework of sys-call schema of a kernel, we could extend the sys-call of the kernel with a unified schema

```
lyoid trap handler(unsigned long scause, unsigned long sept. struct pt regs *regs) {
    if(timer interrupt)
        clock_set_next_event():
        do_timer():
    else
        if(Environment call from U-mode)
            if(SYS_GETPID) {...}
            else if(SYS_WRITE) {...}
            else if(SYS_CLONE) {...}
            else if(SYS_READ) {...}
            else if(SYS_WAIT) {...}
            else if(SYS_EXIT) {...}
        /*else if(Environment call from S-mode)
        ]*/
        else if(page fault handling)
            do_page_fault(regs);
```

sys-call Implemented in X-Part sys-call in buddy system

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sys-call Implemented in X-Part sys-call in buddy system

- sys\_mprotect
- sys munmap

sys-call Implemented in X-Part: In Buddy System (Referencing lab6)

- sys-call 226: SYS\_MPROTECT
  - change the memory access with specific content
  - int mprotect(void \_\_addr, size\_t \_len, int \_\_prot)

```
lint mprotect(void *_addr, size_t __len, int __prot)
{
    // imnput prot
    mprotect_do(current->mm.pgtbl, (uint64)__addr, __len, __prot);
    return 0;
}
```

sys-call Implemented in X-Part: In Buddy System (Referencing lab6)

- sys-call 215: SYS MUNMAP
  - cancel virtual memory mapping in specific memory area, if success return 0, else return -1
  - int munmap (void \*\_\_addr, size\_t \_\_len)

```
int munmap(void *start, size_t length)
{
    struct vm_area_struct *t = current->mm.vm_area;
    struct vm_area_struct *prev = NULL;
    while (t != NULL)
    {
        if (find memory area with input auguments)
        {
            free memory mapping;
            kfree(t);
            return 0;
        }
        continue searching in vma;
    }
    return -1;
```

sys-call Implemented in X-Part: In File system implementation and program loading (Referencing lab7)

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sys-call Implemented in X-Part: In File system implementation and program loading (Referencing lab7)

- sys-call 63: SYS\_READ
  - sys\_read(struct pt\_regs \*regs)
  - read the string input from user program(shell), store it in buffer

```
lint sys_read(struct pt_regs *regs){
    char* buf = regs->a1;
    int nbuf = regs->a2;

for(i from 0 to nbuf){
        scaning input to buf;
    }
    return length of reading string;
}
```

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sys-call Implemented in X-Part: In File system implementation and program loading (Referencing lab7)

- sys-call 260: SYS\_WAIT
  - We implement two states of process in OS kernel: TASK\_RUNNING and TASK\_WAITING, serving for process switch for user programs
  - int sys\_wait(struct pt\_regs \*regs)
  - set the current process(in running state) to pending state, the perform schedule(), switching to other program

```
jint sys_wait(struct pt_regs *regs) {
    set current task as pending;
    schedule to switch to another task;
}
```

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sys-call Implemented in X-Part: In File system implementation and program loading (Referencing lab7)

- · sys-call 93: SYS EXIT
  - void sys\_exit()
  - Exit current children process, return to parent process
  - The difference from SYS WAIT

```
void sys_exit() {
    while(1) {
        if( parent is pending )
            break;
        else
            schedule to give up cpu;
    }
    set parent as running state;
    schedule to give up cpu;
```

```
int proc_exec(struct task_struct *proc. const char *path) {
    memory preparing;
    for(for each segment in elf) {
        readi() read the program header(denoted as prog header) of each segment;
        check whether proq_header.type == LOAD;
        parse_ph_flags() parse the prog_header.flags to permissions;
        uvmalloc() allocate user pages, and set proper permissions;
        loadseg() copy the content of this segment to allocated memory space;
    allocate a page for user stack and update the newpotbl;
    set proc's sstatus, sscratch, and sepc like task init() in Lab5:
    set proc->pqtbl to newpqtbl;
```

#### Summary

 During these OS labs, we constructed a basic framework of systems call mechanism of a OS kernel.

#### Summary

- And implemented system call table with basic kernel function, which supports a toy-OS running
  - information input and output (SYS\_READ, SYS\_WRITE, SYS\_GETPID)
  - basic memory management (SYS\_MMAP, SYS\_MPROTECT)
  - process fork (SYS\_CLONE)
  - user program process management (SYS\_WAIT, SYS\_EXIT, SYS\_EXECVE)

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File system integrating into kernel.

We use a temporary file system: initramfs



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File system integrating into kernel.

- We use a temporary file system: initramfs
- The OS kernel will create a tmplfs file system to access the content

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We use a set of function serve as the file system interface of the Toy-OS: cpio, there are two major function in it

- struct inode \*namei(char\* path): receive the path of the file, return the loaction(node) in inittramfs
- int readi(struct inode \*ip, int user\_dst, void \*dst, uint off, uint n);

```
struct inode *namei(char *path) {//path文件名

struct inode *n = kalloc();

struct cpio_stat *stat = kalloc();

n->i_private = stat;

*stat = cpio_find_file(path);

return n;

struct cpio_stat *stat = ip->i_private;

void *base = stat->data;

memmove(dst, base + off, n);

return n;

struct inode *namei(char *path) {//path文件名

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*struct inode *n = kalloc();

neturn n;

*stat = cpio_find_file(path);

return n;

*stat = cpio_find_file(path);

*s
```

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- •In this section, we managed to load cpio into kernel with mapping it into memory, then the interaction between the Toy-OS and file system could be established
- •After a large amount of trial and analysis, we adjusted part of the file construction, make cpio integrated in our Toy-OS

```
run: all
gedo Launch the qemu .....
gqemu-system-riscv64 -nographic -machine virt -kernel vmlinux -bios default -initrd simple_fs.cpio

debug: all
gedo Launch the qemu for debug .....
gequu-system-riscv64 -nographic -machine virt -kernel vmlinux -bios default -initrd simple_fs.cpio -5 -s
```

```
C typesh

✓ lib

E built-in.a

M Makefile
C printf.c

E printf.o
C string.c

E string.o

✓ .gitignore

M Makefile

M Makefile
E simple_fs.cpio
E system.map
F vmlinux
```

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- •In this section, we managed to load cpio into kernel with mapping it into memory, then the interaction between the Toy-OS and file system could be established
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```
run: all

decho Launch the qemu .....

geqmu-system-riscv64 -nographic -machine virt -kernel vmlinux -bios default -initrd simple_fs.qpio

debug: all

gecho Launch the qemu for debug .....

geqmu-system-riscv64 -nographic -machine virt -kernel vmlinux -bios default -initrd simple_fs.qpio -5 -s
```

```
C types.h

> lib

= built-in.a

M Makefile

C printf.c

= printf.o

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o gittignore

M Makefile

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= simple_fs.cpio

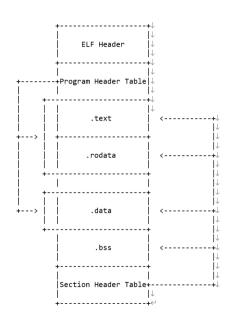
= system.map

= vmlinux
```

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- •Elf Loader: make program running on our kernel
- Overview of ELF header
  - main segment:
    - •.text
    - .rodata
    - .data and .bss
  - elf header and program header store basic infomation about elf file
    - including the offset of program header table and section header table

•Elf Loader



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The Implemation: function loadseg() and function system call exec, for the exec() is described before, this time we focus on loadseg().

- int loadseg(page\_table\_t pagetable, uint64 va, struct inode \*ip, uint offset, uint filesz);
- the function will walk through the pagetable, get the physical address of corresponding virtual address from given arguments
- when fetch the physical address, it will use readi() function, casting the content of the segment to memory physical address
- finally, turn to exec to execute the loaded program

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The Implemation: function loadseg() and function system call exec, for the exec() is described before, this time we focus on loadseg().

```
for(i = 0, ofs = elf->phoff: i < elf->phnum: i++, ofs += sizeof(struct proghdr)) {
   if(readi(ip, 0, prog, ofs, sizeof(struct proghdr)) != sizeof(struct proghdr)) {
        printk("load program error!\n"):
   if(prog->type != ELF PROG LOAD
    || prog->memsz < prog->filesz
    | prog->vaddr + prog->memsz < prog->vaddr) |
   void *segment=kalloc():
   create mapping(pgd, prog->vaddr, segment-PA2VA OFFSET,prog->filesz , (uint64)(prog->flags +8)); // PTE U 和 PTE X
   if(prog->vaddr % PGSIZE != 0) {
       printk("prog vadder is not aligned!\n");
   if(loadseg(pgd, prog->vaddr, ip, prog->off, prog->filesz) == -1) {
        printk("loadseg failed!\n");
```

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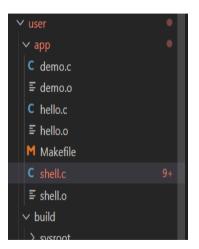
In lab7, the shell program is not provided, so wo implement a simple shell program to make user interact with the toy-os, to show the implementation of this program, we prepared two user programs: hello



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In lab7, the shell program is not provided, so wo implement a simple shell program to make user interact with the toy-os.

To show the implementation of this program, we prepared a user programs: hello



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Shell program introduction

mainly a simple endless loop, waiting for user input



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#### Shell program introduction

- mainly a simple endless loop, waiting for user input
- when receiving the user input, executing specific program
- the kernel will fork a children process for the application to execute
- the runcmd function will:
- load the specific program from file system to memory (unsing namei() and loadseg())
- · then execute the program



#### Shell program introduction

```
int main(void) { ↓
      char buf[100]; ↓
      int fd: ↓
      while(getcmd(buf,sizeof(buf)) >= 0) { ↓
        //printf("%s\n", buf); ↓
            if (strcmp(buf, "hello") == 0 ↓
                  || strcmp(buf, "demo") == 0) { \psi
                  int pid = fork(); ↓
                  printf("Get pid %d\n", pid); ↓
                  if(pid == 0) ↓
                        runcmd(buf); ↓
                  else if (pid > 0) { ↓
                        wait(); ↓
                  } ↓
                  else ↓
                        printf("panic fork"); ↓
            } ↓
            else { ↓
                  printf("Invalid command %s\n", buf); ↓
            } ↓
      } ↓
      exit(0); ↓
}←
void runcmd(char* cmd) { ↓
      exec(cmd); ↓
      printf("exec %s failed\n", cmd); ↓
      exit(0); ↓
}←
```

#### Shell program implementation

- The shell program is simple, but the procedure to load it is more complicated
- Need to call function elf\_loader to load shell program into memory
- The function is called in task\_init, after the idle process is inited



#### Shell program implementation

```
void task init(){
   task[1]->counter=1;
   task[1]->priority=rand();
   task[1]->thread.ra=& dummy;
   task[1] >thread.sp=(uint64)(task[1])+PGSIZE;
    task[1] -> thread info->kennel sp = task[1] -> thread.sp - PA2VA OFFSET;//PA
    elf loader(task[1], "shell")
```

#### Shell program execution

```
Build Finished OK
Launch the gemu .....
OpenSBI v0.9
Platform Name
                          : riscv-virtio.aemu
Platform Features
                          : timer, mfdeleg
Platform HART Count
...mm init done!
Current is: .
Current is: demo
Current is: flag
Current is: hello
Current is: shell
...proc init done!
[S-MODE] Hello RISC-V
[!] Switch from task 0[ffffffe007fbf000] to task 1[ffffffe007fbe000], prio: 1, counter: 1
$ hello
Get pid 2
[!] Switch from task 1[fffffe007fbe000] to task 2[ffffffe007fb0000], prio: 10, counter: 10
Get pid 0
Current is: .
Current is: demo
Current is: flag
Current is: hello
[User] pid: 2, sp is 0000003fffffffe0
 User] pid: 2, sp is 0000003fffffffe0
```

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# Conclusions and Thoughts

# Thanks!

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