

# MY457/MY557: Causal Inference for Observational and Experimental Studies

## Week 1: Causal Frameworks

Daniel de Kadt

Department of Methodology  
LSE

Winter Term 2024

# Lecture Roadmap

- 1 Potential outcomes
- 2 Causal estimands
- 3 Identification
- 4 Graphical Causal Framework
- 5 Assignment mechanisms
- 6 Summary

- 1 Potential outcomes
- 2 Causal estimands
- 3 Identification
- 4 Graphical Causal Framework
- 5 Assignment mechanisms
- 6 Summary

## A (Very) Simple Causal Model

***D***

# A (Very) Simple Causal Model

***D***

Causal variable

# A (Very) Simple Causal Model

***D***

Causal variable

***Y***

# A (Very) Simple Causal Model

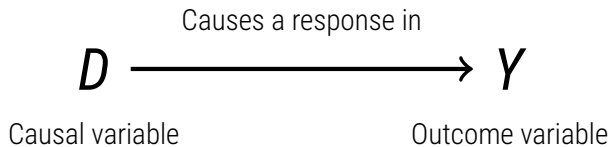
***D***

Causal variable

***Y***

Outcome variable

# A (Very) Simple Causal Model





# Effects of Causes

Causes and their effects have two properties: they are **successive** and can be reasoned about in **counterfactual** terms:

# Effects of Causes

Causes and their effects have two properties: they are **successive** and can be reasoned about in **counterfactual** terms:

*[...] We may define a **cause** to be an object **followed** by another, [...] where, **if** the first object had not been, the second never had existed.*

— Hume, 1748

# Effects of Causes

Causes and their effects have two properties: they are **successive** and can be reasoned about in **counterfactual** terms:

*[...] We may define a **cause** to be an object **followed** by another, [...] where, **if** the first object had not been, the second never had existed.*

— Hume, 1748

*[...] would not have died **if** he had not eaten of it, people would be apt to say that eating of that dish was the **cause** of his death.*

— Mill, 1843

# Effects of Causes

Causes and their effects have two properties: they are **successive** and can be reasoned about in **counterfactual** terms:

*[...] We may define a **cause** to be an object **followed** by another, [...] where, **if** the first object had not been, the second never had existed.*

— Hume, 1748

*[...] would not have died **if** he had not eaten of it, people would be apt to say that eating of that dish was the **cause** of his death.*

— Mill, 1843

One important implication is that causal variables must be **manipulable**:

# Effects of Causes

Causes and their effects have two properties: they are **successive** and can be reasoned about in **counterfactual** terms:

*[...] We may define a **cause** to be an object **followed** by another, [...] where, **if** the first object had not been, the second never had existed.*

– Hume, 1748

*[...] would not have died **if** he had not eaten of it, people would be apt to say that eating of that dish was the **cause** of his death.*

– Mill, 1843

One important implication is that causal variables must be **manipulable**:

*No causation without **manipulation**.*

– Holland, 1986

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making



# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes
  - Country of origin → political beliefs

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes
  - Country of origin → political beliefs
- Major global events?

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes
  - Country of origin → political beliefs
- Major global events?
  - Russian revolution → Karl Marx's intellectual popularity

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes
  - Country of origin → political beliefs
- Major global events?
  - Russian revolution → Karl Marx's intellectual popularity
  - 9/11 → Arab Spring

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes
  - Country of origin → political beliefs
- Major global events?
  - Russian revolution → Karl Marx's intellectual popularity
  - 9/11 → Arab Spring
- Non-successive chains?

# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes
  - Country of origin → political beliefs
- Major global events?
  - Russian revolution → Karl Marx's intellectual popularity
  - 9/11 → Arab Spring
- Non-successive chains?
  - Monthly expenditure → monthly savings

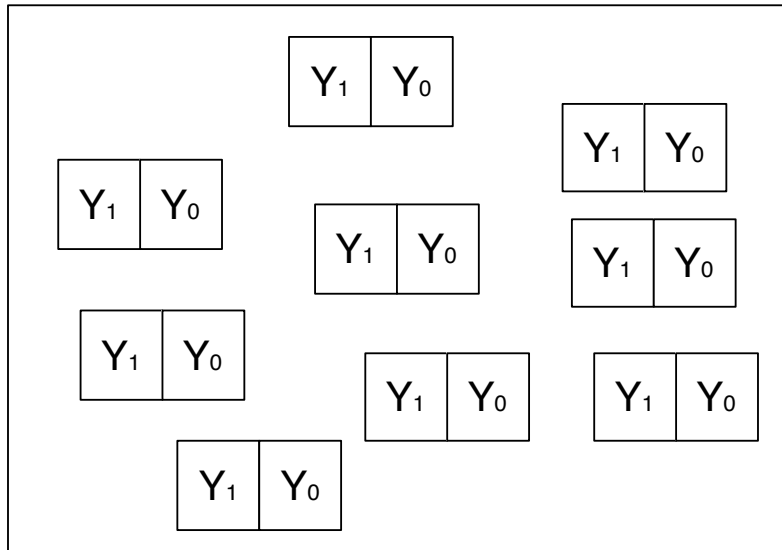
# Good Causal Questions

Manipulability means we must think very carefully about causal questions...

- (Largely) immutable characteristics?
  - Judges' sex assigned at birth → decision making
  - Race and ethnicity → employment outcomes
  - Country of origin → political beliefs
- Major global events?
  - Russian revolution → Karl Marx's intellectual popularity
  - 9/11 → Arab Spring
- Non-successive chains?
  - Monthly expenditure → monthly savings
  - Holocaust → modern AFD election support



# Neyman Urn Model



# Concepts: Treatment, Outcomes, and Potential Outcomes

## Definition (Treatment)

$D_i$ : Indicator of treatment intake for *unit i*

$$D_i = \begin{cases} 1 & \text{if unit } i \text{ received the treatment} \\ 0 & \text{otherwise.} \end{cases}$$

# Concepts: Treatment, Outcomes, and Potential Outcomes

## Definition (Treatment)

$D_i$ : Indicator of treatment intake for *unit i*

$$D_i = \begin{cases} 1 & \text{if unit } i \text{ received the treatment} \\ 0 & \text{otherwise.} \end{cases}$$

## Definition (Observed outcome)

$Y_i$ : Observed outcome variable of interest for unit *i*

# Concepts: Treatment, Outcomes, and Potential Outcomes

## Definition (Treatment)

$D_i$ : Indicator of treatment intake for *unit i*

$$D_i = \begin{cases} 1 & \text{if unit } i \text{ received the treatment} \\ 0 & \text{otherwise.} \end{cases}$$

## Definition (Observed outcome)

$Y_i$ : Observed outcome variable of interest for unit *i*

## Definition (Potential Outcome)

$Y_{0i}$  and  $Y_{1i}$ : Potential outcomes for unit *i*:

$Y_{1i}$  Outcome for unit *i* when  $D_i = 1$

$Y_{0i}$  Outcome for unit *i* when  $D_i = 0$

(Alternative notation:  $Y_i(d)$ ,  $Y_i^d$ , etc.)

# Concepts: Treatment, Outcomes, and Potential Outcomes

Under further assumptions ('SUTVA', more later), we can connect these three concepts mathematically:

$$Y_i = D_i \cdot Y_{1i} + (1 - D_i) \cdot Y_{0i}$$

# Concepts: Treatment, Outcomes, and Potential Outcomes

Under further assumptions ('SUTVA', more later), we can connect these three concepts mathematically:

$$Y_i = D_i \cdot Y_{1i} + (1 - D_i) \cdot Y_{0i}$$

i.e. 
$$Y_i = \begin{cases} Y_{1i} & \text{if } D_i = 1 \\ Y_{0i} & \text{if } D_i = 0 \end{cases}$$

# Concepts: Treatment, Outcomes, and Potential Outcomes

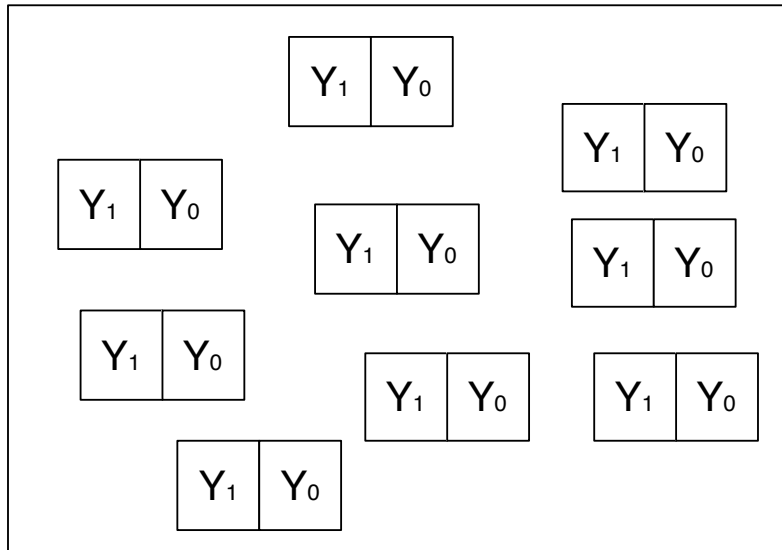
Under further assumptions ('SUTVA', more later), we can connect these three concepts mathematically:

$$Y_i = D_i \cdot Y_{1i} + (1 - D_i) \cdot Y_{0i}$$

i.e. 
$$Y_i = \begin{cases} Y_{1i} & \text{if } D_i = 1 \\ Y_{0i} & \text{if } D_i = 0 \end{cases}$$

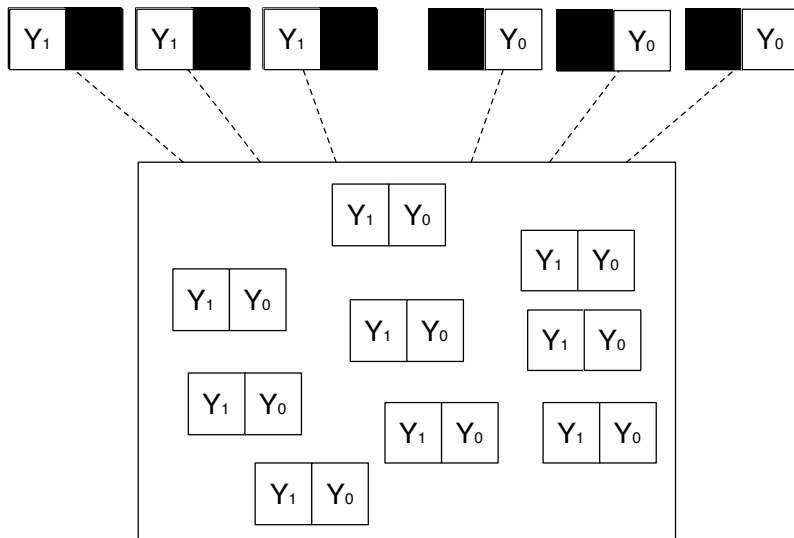
- *A priori* each potential outcome **could be observed** (manipulability!)
- After treatment assignment, one is observed, the other is **counterfactual**

# Neyman Urn Model





# Neyman Urn Model



# Stable Unit Treatment Value Assumption (SUTVA)

- Recall:  $Y_i = Y_{D_i i}$ , or equivalently  $Y_i = D_i Y_{1i} + (1 - D_i) Y_{0i}$
- This notation implicitly makes the following assumption:

# Stable Unit Treatment Value Assumption (SUTVA)

- Recall:  $Y_i = Y_{D_i i}$ , or equivalently  $Y_i = D_i Y_{1i} + (1 - D_i) Y_{0i}$
- This notation implicitly makes the following assumption:

## Assumption (SUTVA)

$$Y_{(D_1, D_2, \dots, D_N) i} = Y_{(D'_1, D'_2, \dots, D'_N) i} \quad \text{if} \quad D_i = D'_i$$

# Stable Unit Treatment Value Assumption (SUTVA)

- Recall:  $Y_i = Y_{D_i i}$ , or equivalently  $Y_i = D_i Y_{1i} + (1 - D_i) Y_{0i}$
- This notation implicitly makes the following assumption:

## Assumption (SUTVA)

$$Y_{(D_1, D_2, \dots, D_N) i} = Y_{(D'_1, D'_2, \dots, D'_N) i} \quad \text{if} \quad D_i = D'_i$$

SUTVA comprises two sub-assumptions:

- 1 No **interference** between units
  - Potential outcomes for a unit not affected by treatment status of other units
  - Violations: spill-over effects, contagion, dilution

# Stable Unit Treatment Value Assumption (SUTVA)

- Recall:  $Y_i = Y_{D_i i}$ , or equivalently  $Y_i = D_i Y_{1i} + (1 - D_i) Y_{0i}$
- This notation implicitly makes the following assumption:

## Assumption (SUTVA)

$$Y_{(D_1, D_2, \dots, D_N) i} = Y_{(D'_1, D'_2, \dots, D'_N) i} \quad \text{if} \quad D_i = D'_i$$

SUTVA comprises two sub-assumptions:

- 1 No **interference** between units
  - Potential outcomes for a unit not affected by treatment status of other units
  - Violations: spill-over effects, contagion, dilution
- 2 No **different versions** of treatment (stability, consistency)
  - Nominally identical treatments are in fact identical
  - Violations: variable levels of treatment, technical errors

## Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

## Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

## Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

How many potential outcomes for unit 1?



## Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

How many potential outcomes for unit 1?

$$Y_{(0,0)1}, Y_{(1,0)1}, Y_{(0,1)1}, Y_{(1,1)1}.$$

## Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

How many potential outcomes for unit 1?

$$Y_{(0,0)1}, Y_{(1,0)1}, Y_{(0,1)1}, Y_{(1,1)1}.$$

How many causal effects for unit 1?

## Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

How many potential outcomes for unit 1?

$$Y_{(0,0)1}, Y_{(1,0)1}, Y_{(0,1)1}, Y_{(1,1)1}.$$

How many causal effects for unit 1?

$$\begin{array}{ll} Y_{(1,1)1} - Y_{(0,0)1}, & Y_{(1,1)1} - Y_{(0,1)1}, \\ Y_{(1,0)1} - Y_{(0,0)1}, & Y_{(1,0)1} - Y_{(0,1)1}, \\ Y_{(1,1)1} - Y_{(1,0)1}, & Y_{(0,1)1} - Y_{(0,0)1}. \end{array}$$

# Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

How many potential outcomes for unit 1?

$$Y_{(0,0)1}, Y_{(1,0)1}, Y_{(0,1)1}, Y_{(1,1)1}.$$

How many causal effects for unit 1?

$$\begin{array}{ll} Y_{(1,1)1} - Y_{(0,0)1}, & Y_{(1,1)1} - Y_{(0,1)1}, \\ Y_{(1,0)1} - Y_{(0,0)1}, & Y_{(1,0)1} - Y_{(0,1)1}, \\ Y_{(1,1)1} - Y_{(1,0)1}, & Y_{(0,1)1} - Y_{(0,0)1}. \end{array}$$

How many observed outcomes for unit 1?

## Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

How many potential outcomes for unit 1?

$$Y_{(0,0)1}, Y_{(1,0)1}, Y_{(0,1)1}, Y_{(1,1)1}.$$

How many causal effects for unit 1?

$$\begin{aligned} Y_{(1,1)1} - Y_{(0,0)1}, & \quad Y_{(1,1)1} - Y_{(0,1)1}, \\ Y_{(1,0)1} - Y_{(0,0)1}, & \quad Y_{(1,0)1} - Y_{(0,1)1}, \\ Y_{(1,1)1} - Y_{(1,0)1}, & \quad Y_{(0,1)1} - Y_{(0,0)1}. \end{aligned}$$

How many observed outcomes for unit 1? Only one:  $Y_1 = Y_{(D_1, D_2)1}$

# Causal Inference Without SUTVA

Let  $\mathbf{D} = (D_1, D_2)$  be a vector of binary treatments for  $N = 2$ .

How many different values can  $\mathbf{D}$  possibly take?

$$(D_1, D_2) = (0, 0) \text{ or } (1, 0) \text{ or } (0, 1) \text{ or } (1, 1)$$

How many potential outcomes for unit 1?

$$Y_{(0,0)1}, Y_{(1,0)1}, Y_{(0,1)1}, Y_{(1,1)1}.$$

How many causal effects for unit 1?

$$\begin{array}{ll} Y_{(1,1)1} - Y_{(0,0)1}, & Y_{(1,1)1} - Y_{(0,1)1}, \\ Y_{(1,0)1} - Y_{(0,0)1}, & Y_{(1,0)1} - Y_{(0,1)1}, \\ Y_{(1,1)1} - Y_{(1,0)1}, & Y_{(0,1)1} - Y_{(0,0)1}. \end{array}$$

How many observed outcomes for unit 1? Only one:  $Y_1 = Y_{(D_1, D_2)1}$

Without SUTVA, causal inference is exponentially more difficult as  $n \uparrow$ .

# Causal Inference as a Missing Data Problem

# Causal Inference as a Missing Data Problem

Imagine a population with 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	0
2	1	1	1	1
3	0	0	1	0
4	0	1	1	1

- We take the values of both  $Y_{1i}$  and  $Y_{0i}$  to be real and fixed for all  $i$



# Causal Inference as a Missing Data Problem

Imagine a population with 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	0
2	1	1	1	1
3	0	0	1	0
4	0	1	1	1

- We take the values of both  $Y_{1i}$  and  $Y_{0i}$  to be real and fixed for all  $i$
- But we **can only observe** one of them for any  $i$  ...

# Causal Inference as a Missing Data Problem

Imagine a population with 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	0
2	1	1	1	1
3	0	0	1	0
4	0	1	1	1

- We take the values of both  $Y_{1i}$  and  $Y_{0i}$  to be real and fixed for all  $i$
- But we **can only observe** one of them for any  $i$  ...
- This is known as the **fundamental problem of causal inference** (FPCI)

# Causal Inference as a Missing Data Problem

... because of the FPCI we see only this:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	?
2	1	1	1	?
3	0	0	?	0
4	0	1	?	1

# Causal Inference as a Missing Data Problem

... because of the FPCI we see only this:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	?
2	1	1	1	?
3	0	0	?	0
4	0	1	?	1

Our goal:

# Causal Inference as a Missing Data Problem

... because of the FPCI we see only this:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	?
2	1	1	1	?
3	0	0	?	0
4	0	1	?	1

Our goal:

- define causal **estimands** in terms of potential outcomes (previous table)

# Causal Inference as a Missing Data Problem

... because of the FPCI we see only this:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	?
2	1	1	1	?
3	0	0	?	0
4	0	1	?	1

Our goal:

- define causal **estimands** in terms of potential outcomes (previous table)
- **estimate** them using observable data on this slide (previous table)

# Causal Inference as a Missing Data Problem

... because of the FPCI we see only this:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$
1	1	3	3	?
2	1	1	1	?
3	0	0	?	0
4	0	1	?	1

Our goal:

- define causal **estimands** in terms of potential outcomes (previous table)
- **estimate** them using observable data on this slide (previous table)
- essentially: fill in the missing counterfactuals as best as possible!

- 1 Potential outcomes
- 2 Causal estimands
- 3 Identification
- 4 Graphical Causal Framework
- 5 Assignment mechanisms
- 6 Summary



# Esti-what?

**Estimand:**

# Esti-what?

## **Estimand:**

↪ Unobserved population parameter or function.

# Esti-what?

## **Estimand:**

↪ Unobserved population parameter or function.

## **Estimator:**

# Esti-what?

## **Estimand:**

↪ Unobserved population parameter or function.

## **Estimator:**

↪ A function that can be applied to observed data.

# Esti-what?

## **Estimand:**

↪ Unobserved population parameter or function.

## **Estimator:**

↪ A function that can be applied to observed data.

## **Estimate:**

# Esti-what?

## **Estimand:**

↪ Unobserved population parameter or function.

## **Estimator:**

↪ A function that can be applied to observed data.

## **Estimate:**

↪ A specific output of said function.

# Unit-Level Causal Estimands

## Definition (Individual Treatment Effect)

Causal effect of the treatment on the outcome for unit  $i$ , defined by the comparison of two potential outcomes:

$$\tau_i = Y_{1i} - Y_{0i}$$

This **cannot be observed**, and is also very hard to estimate:

- We cannot observe both potential outcomes  $Y_{1i}$  and  $Y_{0i}$  for the same unit  $i$ .
- Hard to reliably fill in the missing potential outcome for any one unit  $i$ .

# Group-Level Causal Estimands

- Consider a fixed group (**population**) of units  $i = 1, \dots, N$
- Values of the potential outcomes for this population can be represented as two vectors:

$$\mathbf{Y}_1 = (Y_{11}, Y_{12}, \dots, Y_{1N})$$

$$\mathbf{Y}_0 = (Y_{01}, Y_{02}, \dots, Y_{0N})$$

- A population causal estimand is a comparison of  $\mathbf{Y}_1$  and  $\mathbf{Y}_0$
- A common choice is a difference of their expected values (means).



# Causal Estimand: The ATE

## Definition (Average treatment effect, ATE)

$$\tau_{ATE} = \frac{1}{N} \sum_{i=1}^N (Y_{1i} - Y_{0i})$$

or equivalently

$$\tau_{ATE} = \mathbb{E}[Y_{1i} - Y_{0i}]$$

- In the rest of this course, we will consider various assumptions under which  $\tau_{ATE}$  can be **identified** from observed information
- Note on notation: We represent the **estimand** as a greek letter (in this case  $\tau$ , but could be anything). We typically represent an **estimator** for that estimand as a greek letter with something on top (e.g.  $\tilde{\tau}$  or  $\hat{\tau}$ ). An **estimate** will be a realised number (interval, etc.).

# Causal Estimand: The ATT

Definition (Average treatment effect on the treated, ATT)

$$\tau_{ATT} = \frac{1}{N_1} \sum_{i=1}^N D_i (Y_{1i} - Y_{0i}) \quad \text{where} \quad N_1 = \sum_{i=1}^N D_i$$

or equivalently

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 1]$$

(Note: The mathematical symbol  $|$  means “conditional on”.)

# Causal Estimand: The ATT

## Definition (Average treatment effect on the treated, ATT)

$$\tau_{ATT} = \frac{1}{N_1} \sum_{i=1}^N D_i (Y_{1i} - Y_{0i}) \quad \text{where} \quad N_1 = \sum_{i=1}^N D_i$$

or equivalently

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 1]$$

(Note: The mathematical symbol  $|$  means “conditional on”.)

- In words,  $N_1$  equals

# Causal Estimand: The ATT

## Definition (Average treatment effect on the treated, ATT)

$$\tau_{ATT} = \frac{1}{N_1} \sum_{i=1}^N D_i (Y_{1i} - Y_{0i}) \quad \text{where} \quad N_1 = \sum_{i=1}^N D_i$$

or equivalently

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 1]$$

(Note: The mathematical symbol  $|$  means “conditional on”.)

- In words,  $N_1$  equals the number of treated units.

# Causal Estimand: The ATT

## Definition (Average treatment effect on the treated, ATT)

$$\tau_{ATT} = \frac{1}{N_1} \sum_{i=1}^N D_i (Y_{1i} - Y_{0i}) \quad \text{where} \quad N_1 = \sum_{i=1}^N D_i$$

or equivalently

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 1]$$

(Note: The mathematical symbol  $|$  means “conditional on”.)

- In words,  $N_1$  equals the number of treated units.
- When would  $\tau_{ATT} \neq \tau_{ATE}$ ?

# Causal Estimand: The ATT

## Definition (Average treatment effect on the treated, ATT)

$$\tau_{ATT} = \frac{1}{N_1} \sum_{i=1}^N D_i (Y_{1i} - Y_{0i}) \quad \text{where} \quad N_1 = \sum_{i=1}^N D_i$$

or equivalently

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 1]$$

(Note: The mathematical symbol  $|$  means “conditional on”.)

- In words,  $N_1$  equals the number of treated units.
- When would  $\tau_{ATT} \neq \tau_{ATE}$ ? When  $D_i$  and  $Y_{di}$  are associated.

# Causal Estimand: The ATT

## Definition (Average treatment effect on the treated, ATT)

$$\tau_{ATT} = \frac{1}{N_1} \sum_{i=1}^N D_i (Y_{1i} - Y_{0i}) \quad \text{where} \quad N_1 = \sum_{i=1}^N D_i$$

or equivalently

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 1]$$

(Note: The mathematical symbol  $|$  means “conditional on”.)

- In words,  $N_1$  equals the number of treated units.
- When would  $\tau_{ATT} \neq \tau_{ATE}$ ? When  $D_i$  and  $Y_{di}$  are associated.
- Exercise: Define  $\tau_{ATU}$ , ATE on the untreated (control) units, also called the ATU.

# Causal Estimand: The ATT

## Definition (Average treatment effect on the treated, ATT)

$$\tau_{ATT} = \frac{1}{N_1} \sum_{i=1}^N D_i (Y_{1i} - Y_{0i}) \quad \text{where} \quad N_1 = \sum_{i=1}^N D_i$$

or equivalently

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 1]$$

(Note: The mathematical symbol  $|$  means “conditional on”.)

- In words,  $N_1$  equals the number of treated units.
- When would  $\tau_{ATT} \neq \tau_{ATE}$ ? When  $D_i$  and  $Y_{di}$  are associated.
- Exercise: Define  $\tau_{ATU}$ , ATE on the untreated (control) units, also called the ATU.  
 $\tau_{ATU} = \mathbb{E}[Y_{1i} - Y_{0i} | D_i = 0]$



# Causal Estimand: The CATE

## Definition (Conditional average treatment effects, CATE)

$$\tau_{CATE}(\mathbf{x}) = \mathbb{E}[Y_{1i} - Y_{0i} | \mathbf{X}_i = \mathbf{x}]$$

where  $\mathbf{X}_i$  is a **pre-treatment covariate** for unit  $i$

- In words,  $\tau_{CATE}(\mathbf{x})$  is

# Causal Estimand: The CATE

## Definition (Conditional average treatment effects, CATE)

$$\tau_{CATE}(\mathbf{x}) = \mathbb{E}[Y_{1i} - Y_{0i} | \mathbf{X}_i = \mathbf{x}]$$

where  $\mathbf{X}_i$  is a **pre-treatment covariate** for unit  $i$

- In words,  $\tau_{CATE}(\mathbf{x})$  is a **subgroup effect**, treatment effect on units who have particular characteristics  $\mathbf{x}$ .

# Causal Estimand: The CATE

## Definition (Conditional average treatment effects, CATE)

$$\tau_{CATE}(\mathbf{x}) = \mathbb{E}[Y_{1i} - Y_{0i} | \mathbf{X}_i = \mathbf{x}]$$

where  $\mathbf{X}_i$  is a **pre-treatment covariate** for unit  $i$

- In words,  $\tau_{CATE}(\mathbf{x})$  is a **subgroup effect**, treatment effect on units who have particular characteristics  $\mathbf{x}$ .
- This estimand sometimes goes by other names (e.g. local average treatment effect or LATE).

# Causal Estimand: The CATE

## Definition (Conditional average treatment effects, CATE)

$$\tau_{CATE}(\mathbf{x}) = \mathbb{E}[Y_{1i} - Y_{0i} | \mathbf{X}_i = \mathbf{x}]$$

where  $\mathbf{X}_i$  is a **pre-treatment covariate** for unit  $i$

- In words,  $\tau_{CATE}(\mathbf{x})$  is a **subgroup effect**, treatment effect on units who have particular characteristics  $\mathbf{x}$ .
- This estimand sometimes goes by other names (e.g. local average treatment effect or LATE).
- This is an increasingly important area for causal inference (e.g. optimal policy targeting), and we will return to it later!

## Illustration: Average Treatment Effect

Let's return to our population of 4 units:

$i$	$D_i$	$Y_i$
1	1	3
2	1	1
3	0	0
4	0	1

What is  $\tau_{ATE} = \mathbb{E}[Y_{1i} - Y_{0i}]$ ?

## Illustration: Average Treatment Effect

Let's return to our population of 4 units:

$i$	$D_i$	$Y_i$
1	1	3
2	1	1
3	0	0
4	0	1
$\mathbb{E}[Y_i \mid D_i = 1]$		2
$\mathbb{E}[Y_i \mid D_i = 0]$		0.5
$\mathbb{E}[Y_i \mid D_i = 1] - \mathbb{E}[Y_i \mid D_i = 0]$		1.5

What is  $\tau_{ATE} = \mathbb{E}[Y_{1i} - Y_{0i}]$ ?

Naïve estimator:

$$\begin{aligned}\tilde{\tau} &= \mathbb{E}[Y_i \mid D_i = 1] - \mathbb{E}[Y_i \mid D_i = 0] \quad (\text{observed difference in means}) \\ &= \frac{3+1}{2} - \frac{0+1}{2} = 1.5 \quad \text{Could this be wrong?}\end{aligned}$$

# Illustration: Average Treatment Effect

Let's return to our population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	?	?
2	1	1	1	?	?
3	0	0	?	0	?
4	0	1	?	1	?

What is  $\tau_{ATE} = \mathbb{E}[Y_{1i} - Y_{0i}]$ ? We need potential outcomes that we do not observe!

## Illustration: Average Treatment Effect

Let's return to our population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	0	?
2	1	1	1	1	?
3	0	0	1	0	?
4	0	1	1	1	?

Suppose hypothetically:  $Y_{01} = 0, Y_{02} = Y_{13} = Y_{14} = 1$ .



## Illustration: Average Treatment Effect

Let's return to our population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	0	3
2	1	1	1	1	0
3	0	0	1	0	1
4	0	1	1	1	0
$\mathbb{E}[Y_{1i}]$			1.5		
$\mathbb{E}[Y_{0i}]$				0.5	
$\mathbb{E}[Y_{1i} - Y_{0i}]$					1

$$\tau_{ATE} = \mathbb{E}[Y_{1i} - Y_{0i}] = \mathbb{E}[\tau_i] = \frac{3 + 0 + 1 + 0}{4} = 1.$$

## Illustration: Average Treatment Effect

Let's return to our population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	0	3
2	1	1	1	1	0
3	0	0	1	0	1
4	0	1	1	1	0
$\mathbb{E}[Y_{1i}]$			1.5		
$\mathbb{E}[Y_{0i}]$				0.5	
$\mathbb{E}[Y_{1i} - Y_{0i}]$					1

$$\tau_{ATE} = \mathbb{E}[Y_{1i} - Y_{0i}] = \mathbb{E}[\tau_i] = \frac{3 + 0 + 1 + 0}{4} = 1.$$

Why does  $\tau_{ATE} \neq \tilde{\tau}$ ? When would they be equal?

# Illustration: Average Treatment Effect on the Treated

Again suppose we observe a population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	?	?
2	1	1	1	?	?
3	0	0	?	0	?
4	0	1	?	1	?

What is  $\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} \mid D_i = 1]$ ?

# Illustration: Average Treatment Effect on the Treated

Again suppose we observe a population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	0	3
2	1	1	1	1	0
3	0	0	1	0	1
4	0	1	1	1	0

What is  $\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} \mid D_i = 1]$ ?

## Illustration: Average Treatment Effect on the Treated

Again suppose we observe a population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	0	3
2	1	1	1	1	0
3	0	0	1	0	1
4	0	1	1	1	0
$\mathbb{E}[Y_{1i} \mid D_i = 1]$			2		
$\mathbb{E}[Y_{0i} \mid D_i = 1]$			0.5		
$\mathbb{E}[Y_{1i} - Y_{0i} \mid D_i = 1]$			1.5		

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} \mid D_i = 1] = \mathbb{E}[\tau_i \mid D_i = 1] = \frac{3 + 0}{2} = 1.5.$$

## Illustration: Average Treatment Effect on the Treated

Again suppose we observe a population of 4 units:

$i$	$D_i$	$Y_i$	$Y_{1i}$	$Y_{0i}$	$\tau_i$
1	1	3	3	0	3
2	1	1	1	1	0
3	0	0	1	0	1
4	0	1	1	1	0
$\mathbb{E}[Y_{1i} \mid D_i = 1]$			2		
$\mathbb{E}[Y_{0i} \mid D_i = 1]$			0.5		
$\mathbb{E}[Y_{1i} - Y_{0i} \mid D_i = 1]$			1.5		

$$\tau_{ATT} = \mathbb{E}[Y_{1i} - Y_{0i} \mid D_i = 1] = \mathbb{E}[\tau_i \mid D_i = 1] = \frac{3 + 0}{2} = 1.5.$$

# Average Treatment Effect on the Treated

Why does  $\tau_{ATT} \neq \tau_{ATE}$ ?

# Average Treatment Effect on the Treated

Why does  $\tau_{ATT} \neq \tau_{ATE}$ ?

Because  $\mathbb{E}[Y_{1i}] \neq \mathbb{E}[Y_{1i}|D_i = 1]$  (and likewise for  $\mathbb{E}[Y_{0i}]$ )



# Average Treatment Effect on the Treated

Why does  $\tau_{ATT} \neq \tau_{ATE}$ ?

Because  $\mathbb{E}[Y_{1i}] \neq \mathbb{E}[Y_{1i}|D_i = 1]$  (and likewise for  $\mathbb{E}[Y_{0i}]$ )

That is,  $D_i$  and  $Y_{di}$  are associated

# Internal and External Validity

- Note that when we talk about the 'population' in causal inference settings we often mean *only* to the  **$N$**  units for whom we have observed data (i.e. what we would typically call the 'sample')
- The estimands considered on this course are defined and estimated for this population (not for some super-population from which a sample was drawn)
- **Internal validity** refers to the validity of our estimates of these effects. This class is focused only on internal validity.

# Internal and External Validity

- **External validity** refers to the validity generalising our estimates of causal effects from the 'population' of  $N$  units to any other population (note, this could include generalising from a realised sample to a population)

# Internal and External Validity

- **External validity** refers to the validity generalising our estimates of causal effects from the 'population' of  $N$  units to any other population (note, this could include generalising from a realised sample to a population)
- If claimed, external validity has to be justified by different kinds of arguments, e.g.

# Internal and External Validity

- **External validity** refers to the validity generalising our estimates of causal effects from the 'population' of  **$N$**  units to any other population (note, this could include generalising from a realised sample to a population)
- If claimed, external validity has to be justified by different kinds of arguments, e.g.
  - Representative sampling (ideally probability sampling) of the  **$N$**  units from a larger population. This is a population inference task, as in survey research (see MY456).)

# Internal and External Validity

- **External validity** refers to the validity generalising our estimates of causal effects from the 'population' of  **$N$**  units to any other population (note, this could include generalising from a realised sample to a population)
- If claimed, external validity has to be justified by different kinds of arguments, e.g.
  - Representative sampling (ideally probability sampling) of the  **$N$**  units from a larger population. This is a population inference task, as in survey research (see MY456).)
  - Some re-weighting strategy designed to adjust the observed sample. Again, this is a population inference task.

# Internal and External Validity

- **External validity** refers to the validity generalising our estimates of causal effects from the 'population' of **N** units to any other population (note, this could include generalising from a realised sample to a population)
- If claimed, external validity has to be justified by different kinds of arguments, e.g.
  - Representative sampling (ideally probability sampling) of the **N** units from a larger population. This is a population inference task, as in survey research (see MY456).)
  - Some re-weighting strategy designed to adjust the observed sample. Again, this is a population inference task.
  - Substantive theory / assumptions / wishful thinking about why a causal effect for these **N** units would also apply elsewhere

- 1 Potential outcomes
- 2 Causal estimands
- 3 Identification**
- 4 Graphical Causal Framework
- 5 Assignment mechanisms
- 6 Summary



# Identification Problem for Causal Inference

- In statistics, an **estimand** (parameter) is **identified** if its value can be uniquely **estimated** based on the observed data

# Identification Problem for Causal Inference

- In statistics, an **estimand** (parameter) is **identified** if its value can be uniquely **estimated** based on the observed data and unidentified if not

# Identification Problem for Causal Inference

- In statistics, an **estimand** (parameter) is **identified** if its value can be uniquely **estimated** based on the observed data and unidentified if not
- Recall that in causal inference, estimands are population causal effects but the **FPCI** tells us that at least half of the potential outcomes are always missing

# Identification Problem for Causal Inference

- In statistics, an **estimand** (parameter) is **identified** if its value can be uniquely **estimated** based on the observed data and unidentified if not
- Recall that in causal inference, estimands are population causal effects but the **FPCI** tells us that at least half of the potential outcomes are always missing
- An **identification strategy** is a combination of data and assumptions which allows us to **identify** a causal estimand by estimating (“filling in”) the missing potential outcomes (usually at a group level)

# Selection Bias

Consider again the naïve difference of observed means in the treatment groups:

$$\underbrace{E(Y_i|D_i = 1) - E(Y_i|D_i = 0)}$$

Observed difference in average  
outcome measures

# Selection Bias

Consider again the naïve difference of observed means in the treatment groups:

$$\underbrace{E(Y_i|D_i = 1) - E(Y_i|D_i = 0)}_{\text{Observed difference in average outcome measures}} = E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 0)$$

Observed difference in average  
outcome measures

# Selection Bias

Consider again the naïve difference of observed means in the treatment groups:

$$\underbrace{E(Y_i|D_i = 1) - E(Y_i|D_i = 0)}_{\text{Observed difference in average outcome measures}} = E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 0)$$
$$= \underbrace{E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 1)}_{\text{ATT}}$$

# Selection Bias

Consider again the naïve difference of observed means in the treatment groups:

$$\begin{aligned} \underbrace{E(Y_i|D_i = 1) - E(Y_i|D_i = 0)}_{\text{Observed difference in average outcome measures}} &= E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 0) \\ = \underbrace{E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 1)}_{\text{ATT}} &+ \underbrace{E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)}_{\text{Selection bias}} \end{aligned}$$



# Selection Bias

Consider again the naïve difference of observed means in the treatment groups:

$$\underbrace{E(Y_i|D_i = 1) - E(Y_i|D_i = 0)}_{\substack{\text{Observed difference in average} \\ \text{outcome measures}}} = E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 0)$$
$$= \underbrace{E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 1)}_{\text{ATT}} + \underbrace{E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)}_{\text{Selection bias}}$$

- The same observed mean difference could be due to different combinations of the ATT (estimand!) and selection bias terms. We might say the causal effect of  $D$  on  $Y$  is **confounded**.
- Thus ATT is **not identified** from the naïve observed mean difference: it is not uniquely mapped from the observed data. We need more assumptions.

# Selection Bias

Consider again the naïve difference of observed means in the treatment groups:

$$\underbrace{E(Y_i|D_i = 1) - E(Y_i|D_i = 0)}_{\substack{\text{Observed difference in average} \\ \text{outcome measures}}} = E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 0)$$
$$= \underbrace{E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 1)}_{\text{ATT}} + \underbrace{E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)}_{\text{Selection bias}}$$

- The same observed mean difference could be due to different combinations of the ATT (estimand!) and selection bias terms. We might say the causal effect of  $D$  on  $Y$  is **confounded**.
- Thus ATT is **not identified** from the naïve observed mean difference: it is not uniquely mapped from the observed data. We need more assumptions.
- Correlation [association, here observed mean difference] is not necessarily causation.

# Selection Bias

$$\begin{aligned} & E(Y_i|D_i = 1) - E(Y_i|D_i = 0) \\ &= [E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 1)] + [E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)] \end{aligned}$$

# Selection Bias

$$\begin{aligned} E(Y_i|D_i = 1) - E(Y_i|D_i = 0) \\ = [E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 1)] + [E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)] \end{aligned}$$

- $E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)$  is referred to as **selection** bias because if it is not 0, it implies treatment and control groups are systematically different in potential outcome  $Y_{0i}$ .

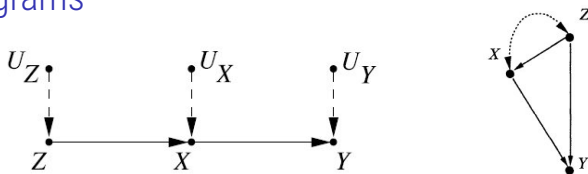
# Selection Bias

$$\begin{aligned} & E(Y_i|D_i = 1) - E(Y_i|D_i = 0) \\ &= [E(Y_{1i}|D_i = 1) - E(Y_{0i}|D_i = 1)] + [E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)] \end{aligned}$$

- $E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0)$  is referred to as **selection** bias because if it is not 0, it implies treatment and control groups are systematically different in potential outcome  $Y_{0i}$ .
- Canonical example: Job training program
  - participants are **self-selected** from a population of individuals in difficult labor situations
  - perhaps better resourced or more motivated individuals decide to take part
  - even in the absence of the program, post-training period earnings for those people would then have been higher than those for those who did not opt in ( $E[Y_0|D = 1] - E[Y_0|D = 0] > 0$ )

- 1 Potential outcomes
- 2 Causal estimands
- 3 Identification
- 4 Graphical Causal Framework**
- 5 Assignment mechanisms
- 6 Summary

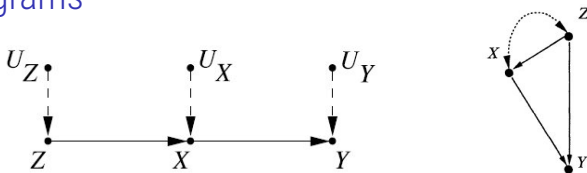
# Causal Diagrams



So far we have reasoned about causal effects using potential outcomes. An alternative (but intimately connected) framework is the **graphical** approach.

This uses **causal diagrams**, tools that allow us to:

# Causal Diagrams



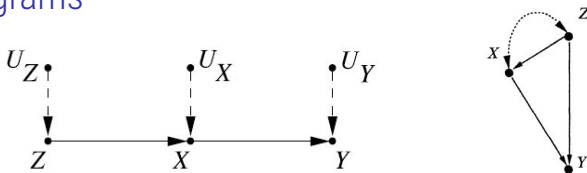
So far we have reasoned about causal effects using potential outcomes. An alternative (but intimately connected) framework is the **graphical** approach.

This uses **causal diagrams**, tools that allow us to:

1. Specify the variables (observed and unobserved) we care about



# Causal Diagrams

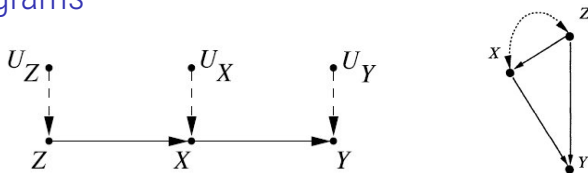


So far we have reasoned about causal effects using potential outcomes. An alternative (but intimately connected) framework is the **graphical** approach.

This uses **causal diagrams**, tools that allow us to:

1. Specify the variables (observed and unobserved) we care about
2. Specify how those variables are connected

# Causal Diagrams

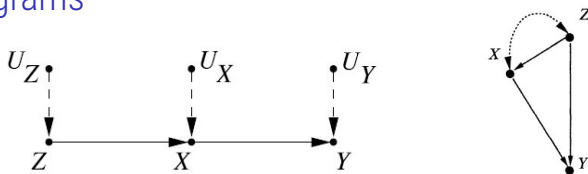


So far we have reasoned about causal effects using potential outcomes. An alternative (but intimately connected) framework is the **graphical** approach.

This uses **causal diagrams**, tools that allow us to:

1. Specify the variables (observed and unobserved) we care about
2. Specify how those variables are connected
3. See **what we can learn** about causal effects, and with **what assumptions**.

# Causal Diagrams



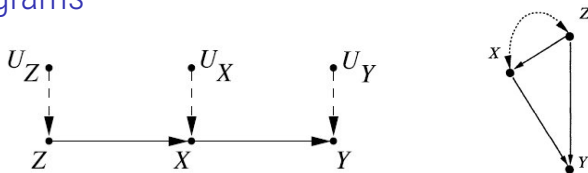
So far we have reasoned about causal effects using potential outcomes. An alternative (but intimately connected) framework is the **graphical** approach.

This uses **causal diagrams**, tools that allow us to:

1. Specify the variables (observed and unobserved) we care about
2. Specify how those variables are connected
3. See **what we can learn** about causal effects, and with **what assumptions**.

This can help us to:

# Causal Diagrams



So far we have reasoned about causal effects using potential outcomes. An alternative (but intimately connected) framework is the **graphical** approach.

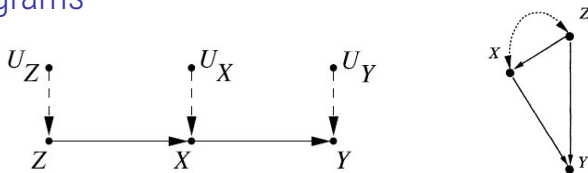
This uses **causal diagrams**, tools that allow us to:

1. Specify the variables (observed and unobserved) we care about
2. Specify how those variables are connected
3. See **what we can learn** about causal effects, and with **what assumptions**.

This can help us to:

1. Study how conditioning affects our research designs

# Causal Diagrams



So far we have reasoned about causal effects using potential outcomes. An alternative (but intimately connected) framework is the **graphical** approach.

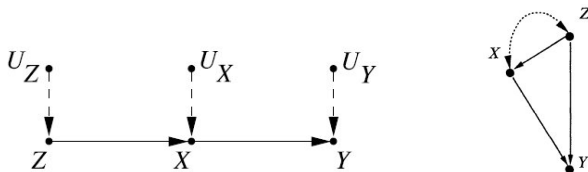
This uses **causal diagrams**, tools that allow us to:

1. Specify the variables (observed and unobserved) we care about
2. Specify how those variables are connected
3. See **what we can learn** about causal effects, and with **what assumptions**.

This can help us to:

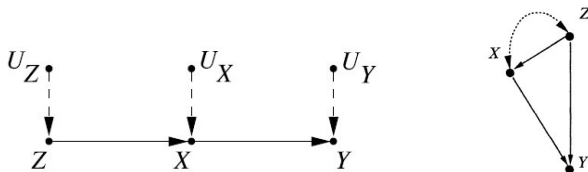
1. Study how conditioning affects our research designs
2. Create new research designs and methodologies.

# Causal Diagrams as Directed Acyclic Graphs



Components of a causal diagram as a Directed Acyclic Graphs (DAG):

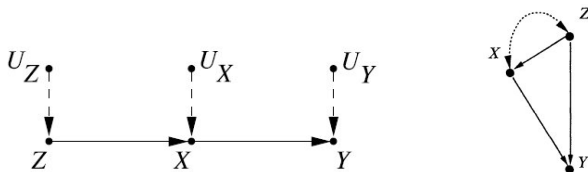
# Causal Diagrams as Directed Acyclic Graphs



Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes

# Causal Diagrams as Directed Acyclic Graphs

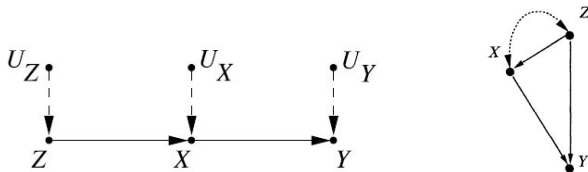


Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “variables” (also called vertices)



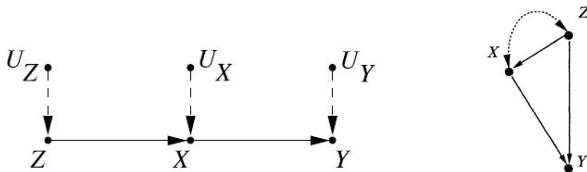
# Causal Diagrams as Directed Acyclic Graphs



Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “**variables**” (also called vertices)
- Directed Edges

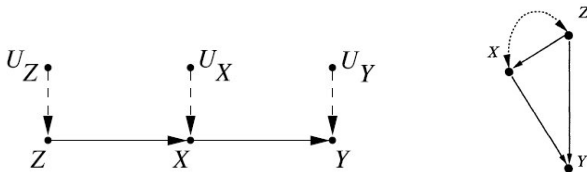
# Causal Diagrams as Directed Acyclic Graphs



Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “variables” (also called vertices)
- Directed Edges: Encoding one-way (causal) relationships

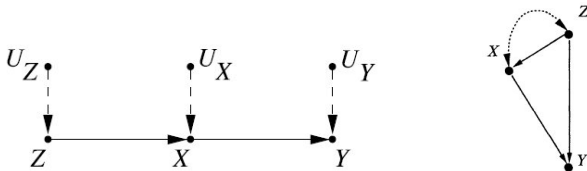
# Causal Diagrams as Directed Acyclic Graphs



Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “variables” (also called vertices)
- Directed Edges: Encoding one-way (causal) relationships  
→ This implies nodes are ordered (each pair: head and tail)

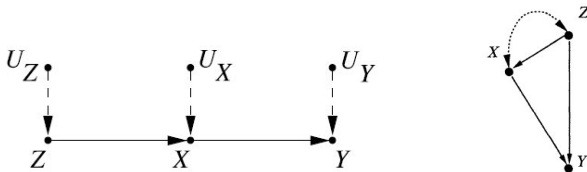
# Causal Diagrams as Directed Acyclic Graphs



Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “**variables**” (also called vertices)
- Directed Edges: Encoding one-way (causal) **relationships**
  - This implies nodes are **ordered** (each pair: head and tail)
  - These connections can be **observed** (solid) or **unobserved** (dashed)

# Causal Diagrams as Directed Acyclic Graphs



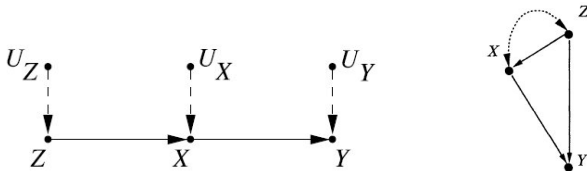
Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “variables” (also called vertices)
- Directed Edges: Encoding one-way (causal) relationships
  - This implies nodes are ordered (each pair: head and tail)
  - These connections can be observed (solid) or unobserved (dashed)

Features of a DAG:

- Acyclic

# Causal Diagrams as Directed Acyclic Graphs



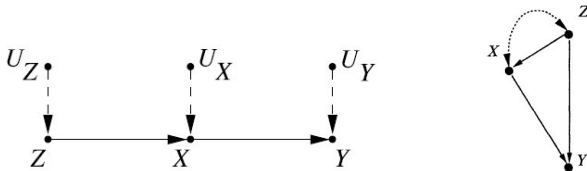
Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “variables” (also called vertices)
- Directed Edges: Encoding one-way (causal) relationships
  - This implies nodes are ordered (each pair: head and tail)
  - These connections can be observed (solid) or unobserved (dashed)

Features of a DAG:

- Acyclic: No directed cycles (e.g. A does not terminate A)

# Causal Diagrams as Directed Acyclic Graphs



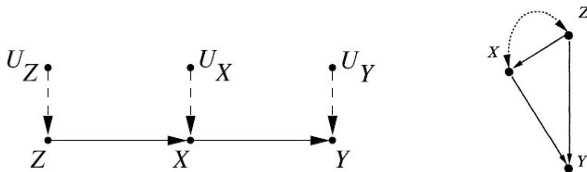
Components of a causal diagram as a Directed Acyclic Graphs (DAG):

- Nodes: Representing “variables” (also called vertices)
- Directed Edges: Encoding one-way (causal) relationships
  - This implies nodes are ordered (each pair: head and tail)
  - These connections can be observed (solid) or unobserved (dashed)

Features of a DAG:

- Acyclic: No directed cycles (e.g. A does not terminate A)
- Non-connections

# Causal Diagrams as Directed Acyclic Graphs



Components of a causal diagram as a Directed Acyclic Graphs (DAG):

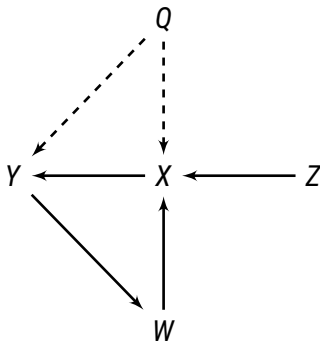
- Nodes: Representing “variables” (also called vertices)
- Directed Edges: Encoding one-way (causal) relationships
  - This implies nodes are ordered (each pair: head and tail)
  - These connections can be observed (solid) or unobserved (dashed)

Features of a DAG:

- Acyclic: No directed cycles (e.g. A does not terminate A)
- Non-connections: The absence of relationships between variables



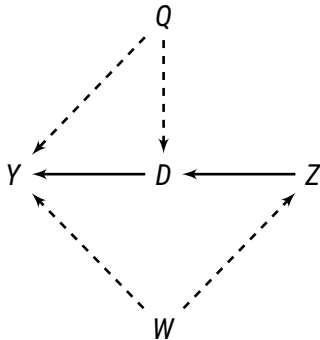
# Directed Acyclic Graphs: Example



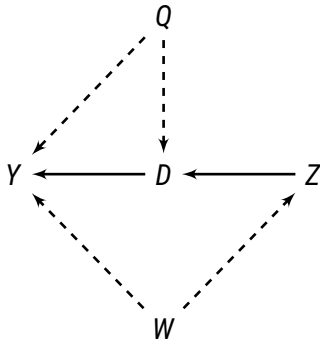


"These aren't the DAGs you're looking for"

## Directed Acyclic Graphs: Example

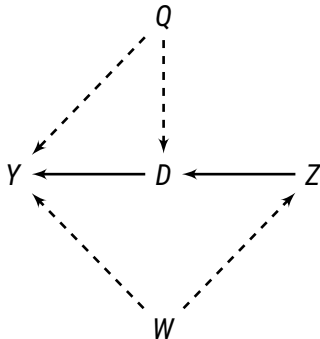


## Directed Acyclic Graphs: Example



What can we learn from this DAG?

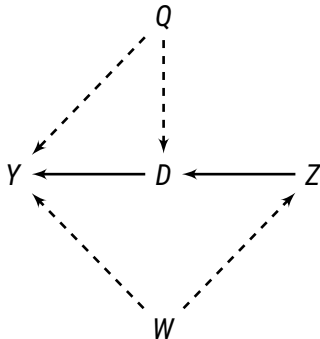
# Directed Acyclic Graphs: Example



What can we learn from this DAG?

- $Z \rightarrow Y$  is confounded by  $W$

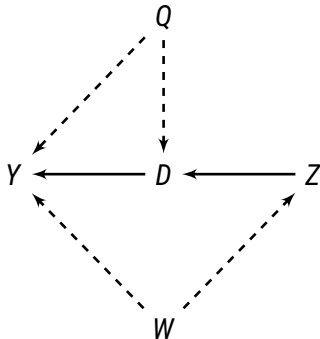
# Directed Acyclic Graphs: Example



What can we learn from this DAG?

- $Z \rightarrow Y$  is confounded by  $W$
- $D \rightarrow Y$  is confounded by  $Q$

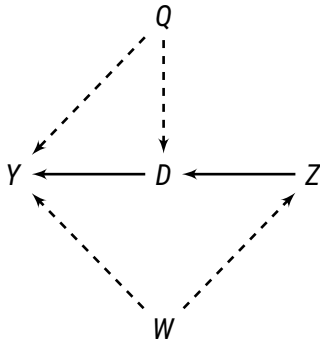
# Directed Acyclic Graphs: Example



What can we learn from this DAG?

- $Z \rightarrow Y$  is confounded by  $W$
- $D \rightarrow Y$  is confounded by  $Q$
- $Z \rightarrow D$  is identified

# Directed Acyclic Graphs: Example



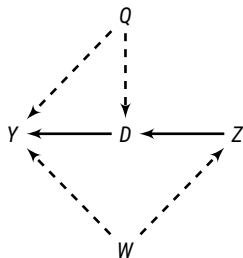
What can we learn from this DAG?

- $Z \rightarrow Y$  is confounded by  $W$
- $D \rightarrow Y$  is confounded by  $Q$
- $Z \rightarrow D$  is identified

But **only if our DAG is correct!**

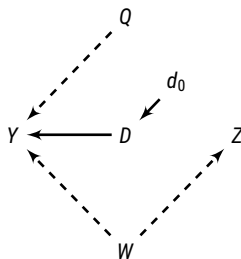


# Representing Interventions



Treatments (interventions) are represented by the **do()** operator.

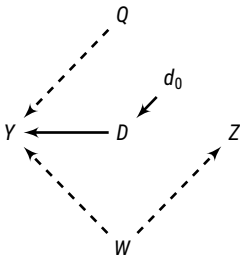
# Representing Interventions



Treatments (interventions) are represented by the ***do()*** operator.

For example, ***do***( $d_0$ ) holds  $D = d_0$  **exogenously**.

# Identification

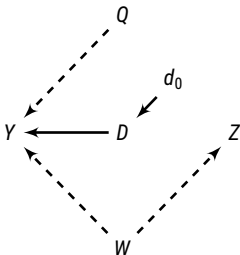


ATE of  $D$  on  $Y$  defined as the average difference in  $Y$  between two interventions:

$$\mathbb{E}[Y \mid do(d_1)] - \mathbb{E}[Y \mid do(d_0)]$$

**Problem:** Can this be estimated without an explicit intervention (identification)?

# Identification



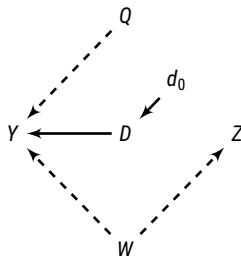
ATE of  $D$  on  $Y$  defined as the average difference in  $Y$  between two interventions:

$$\mathbb{E}[Y \mid \text{do}(d_1)] - \mathbb{E}[Y \mid \text{do}(d_0)]$$

**Problem:** Can this be estimated without an explicit intervention (identification)?

**Insight:** If the DAG is equivalent with and without  $\text{do}()$ , yes.

# Identification



ATE of  $D$  on  $Y$  defined as the average difference in  $Y$  between two interventions:

$$\mathbb{E}[Y \mid \text{do}(d_1)] - \mathbb{E}[Y \mid \text{do}(d_0)]$$

**Problem:** Can this be estimated without an explicit intervention (identification)?

**Insight:** If the DAG is equivalent with and without  $\text{do}()$ , yes.

**Generally:** We can identify the effect of  $D$  on  $Y$  if all **back-door paths** are **blocked**.

- 1 Potential outcomes
- 2 Causal estimands
- 3 Identification
- 4 Graphical Causal Framework
- 5 Assignment mechanisms**
- 6 Summary

# Assignment Mechanism

## Definition (Assignment Mechanism)

The assignment mechanism is the procedure that determines the treatment status of each unit.

# Assignment Mechanism

## Definition (Assignment Mechanism)

The assignment mechanism is the procedure that determines the treatment status of each unit.

- Most causal inference methods achieve identification by **restricting** the (assumed) assignment mechanism



# Assignment Mechanism

## Definition (Assignment Mechanism)

The assignment mechanism is the procedure that determines the treatment status of each unit.

- Most causal inference methods achieve identification by **restricting** the (assumed) assignment mechanism
- For example, if we are willing to assume that treatment assignment is independent of potential outcomes under no treatment, then:

$$E(Y_{0i}|D_i = 1) - E(Y_{0i}|D_i = 0) = 0$$

i.e. selection bias is zero and the observed mean difference is (in expectation) equal to ATT (and also ATE in that case)

# Different Assignment Mechanisms

Imbens and Rubin (2015, Ch. 3) present three **assumptions** about assignment mechanisms (for each unit) that provide the grounds for identification:

# Different Assignment Mechanisms

Imbens and Rubin (2015, Ch. 3) present three **assumptions** about assignment mechanisms (for each unit) that provide the grounds for identification:

1. *Individualistic*: Assignment does not depend on the covariates or potential outcomes for other units.

# Different Assignment Mechanisms

Imbens and Rubin (2015, Ch. 3) present three **assumptions** about assignment mechanisms (for each unit) that provide the grounds for identification:

1. *Individualistic*: Assignment does not depend on the covariates or potential outcomes for other units.
2. *Probabilistic*: There is a nonzero probability of each treatment value, for every unit.

# Different Assignment Mechanisms

Imbens and Rubin (2015, Ch. 3) present three **assumptions** about assignment mechanisms (for each unit) that provide the grounds for identification:

1. *Individualistic*: Assignment does not depend on the covariates or potential outcomes for other units.
2. *Probabilistic*: There is a nonzero probability of each treatment value, for every unit.
3. *Unconfounded*: Assignment does not depend on potential outcomes.

# Different Assignment Mechanisms

Imbens and Rubin (2015, Ch. 3) present three **assumptions** about assignment mechanisms (for each unit) that provide the grounds for identification:

1. *Individualistic*: Assignment does not depend on the covariates or potential outcomes for other units.
2. *Probabilistic*: There is a nonzero probability of each treatment value, for every unit.
3. *Unconfounded*: Assignment does not depend on potential outcomes.

Assuming the above, we can distinguish:

- **Experiments**: The assignment mechanism is both known and controlled by the researcher, and

# Different Assignment Mechanisms

Imbens and Rubin (2015, Ch. 3) present three **assumptions** about assignment mechanisms (for each unit) that provide the grounds for identification:

1. *Individualistic*: Assignment does not depend on the covariates or potential outcomes for other units.
2. *Probabilistic*: There is a nonzero probability of each treatment value, for every unit.
3. *Unconfounded*: Assignment does not depend on potential outcomes.

Assuming the above, we can distinguish:

- **Experiments**: The assignment mechanism is both known and controlled by the researcher, and
- **Observational studies**: The assignment mechanism is not known to, or not under the control of, the researcher

# Our Key Assignment Mechanisms

## Randomised Experiments:

- These come in many flavours, only a few of which we will discuss!
  - ~> Within designs, between designs
  - ~> Unit-randomized, cluster-randomized, dynamic randomization
  - ~> Crossover designs, stepped-wedge designs, etc. etc. etc.



# Our Key Assignment Mechanisms

## Randomised Experiments:

- These come in many flavours, only a few of which we will discuss!
  - ~> Within designs, between designs
  - ~> Unit-randomized, cluster-randomized, dynamic randomization
  - ~> Crossover designs, stepped-wedge designs, etc. etc. etc.

## Observational Studies:

- Adjustment: Selection on observables with regression, matching, etc.
- Temporal: Diff-in-diff, event studies, synthetic control methods
- Instrumental variables, shift-share designs, etc.
- Sharp and fuzzy regression discontinuity designs

# The Continuum of Credibility<sup>TM</sup>

**Least credible**

**Most credible**



# The Continuum of Credibility<sup>TM</sup>

**Least credible**

**Most credible**

Naïve  
comparison

Observational causal  
inference techniques

Controlled  
randomization

# The Continuum of Credibility<sup>TM</sup>

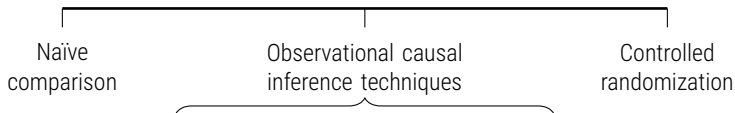
**Least credible**

**Most credible**

Naïve  
comparison

Observational causal  
inference techniques

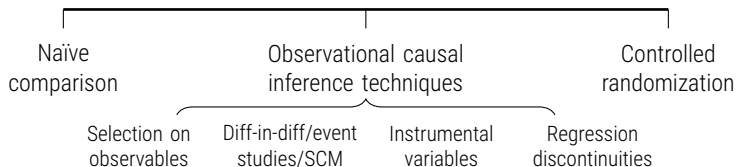
Controlled  
randomization



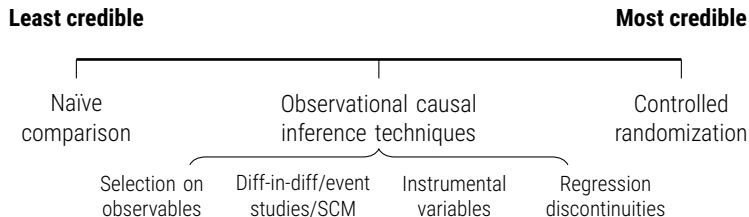
# The Continuum of Credibility<sup>TM</sup>

**Least credible**

**Most credible**

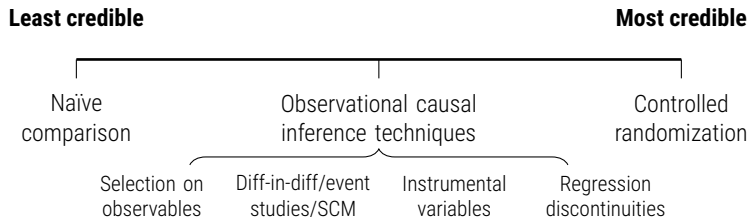


# The Continuum of Credibility™



Key point: The art (and science) of applied causal inference is **making defensible assumptions**.

# The Continuum of Credibility™



Key point: The art (and science) of applied causal inference is **making defensible assumptions**. There is no 'magic' solution to the fundamental problem of causal inference, only **assumptions all the way down!**

- 1 Potential outcomes
- 2 Causal estimands
- 3 Identification
- 4 Graphical Causal Framework
- 5 Assignment mechanisms
- 6 Summary



# Key ideas from this week

- Learned to think about causal effects in terms of **potential outcomes**, not realized (observed) outcomes
- Observed association is **neither necessary nor sufficient** for causality – focused on one big problem, selection bias
- Introduced an alternative framework for thinking about causal models – the **graphical** approach
- Learning about causal effects should start from **understanding the assignment mechanism** for treatment
- Evaluate the **plausibility of your assumptions** to understand the credibility of your conclusions