## week-2-assignment-2203a51510

## February 5, 2024

[1]: from collections import deque
 def bfs(graph, start):
 visited = set()

```
queue = deque([start])
       visited.add(start)
       while queue:
         node = queue.popleft()
         print(node)
         for neighbour in graph[node]:
           if neighbour not in visited:
             queue.append(neighbour)
             visited.add(neighbour)
       return visited
     graph = {
       0: [1, 2],
       1: [0, 3, 4],
      2: [0, 5],
      3: [1],
       4: [1],
       5: [2]
     bfs(graph, 0)
    0
    1
    2
    3
    4
    5
[1]: {0, 1, 2, 3, 4, 5}
[2]: def dfs(g, start, visited=None):
         if visited is None:
             visited = set()
         visited.add(start)
         print(start)
```

```
for neighbor in g [start]:
        if neighbor not in visited:
            dfs(g, neighbor, visited)
g= {
  'A':['B','S'],
  'B':['A'],
  'S':['A','C','G'],
  'C':['D','E','F','S'],
  'D':['C'],
  'E':['C','H'],
  'F':['C','G'],
  'G':['S','F','H'],
  'H':['E','G']
}
starting_vertex = 'A'
dfs(g, starting_vertex)
```

```
B
S
C
D
E
H
G
F
```

Α

```
[3]: from copy import deepcopy
import numpy as np
import time

def bestsolution(state):
    bestsol = np.array([], int).reshape(-1, 9)
    count = len(state) - 1
    while count != -1:
        bestsol = np.insert(bestsol, 0, state[count]['puzzle'], 0)
        count = (state[count]['parent'])
    return bestsol.reshape(-1, 3, 3)
def all(checkarray):
```

```
set=[]
   for it in set:
       for checkarray in it:
            return 1
        else:
            return 0
def misplaced_tiles(puzzle,goal):
   mscost = np.sum(puzzle != goal) - 1
   return mscost if mscost > 0 else 0
def coordinates(puzzle):
   pos = np.array(range(9))
   for p, q in enumerate(puzzle):
       pos[q] = p
   return pos
def evaluvate_misplaced(puzzle, goal):
    steps = np.array([('up', [0, 1, 2], -3),('down', [6, 7, 8], 3),('left', __
 →[0, 3, 6], -1),('right', [2, 5, 8], 1)],
                dtype = [('move', str, 1),('position', list),('head', int)])
   dtstate = [('puzzle', list),('parent', int),('gn', int),('hn', int)]
   costg = coordinates(goal)
   parent = -1
   gn = 0
   hn = misplaced_tiles(coordinates(puzzle), costg)
   state = np.array([(puzzle, parent, gn, hn)], dtstate)
   dtpriority = [('position', int),('fn', int)]
   priority = np.array([(0, hn)], dtpriority)
   while 1:
       priority = np.sort(priority, kind='mergesort', order=['fn', 'position'])
       position, fn = priority[0]
       priority = np.delete(priority, 0, 0)
       puzzle, parent, gn, hn = state[position]
       puzzle = np.array(puzzle)
       blank = int(np.where(puzzle == 0)[0])
       gn = gn + 1
```

```
c = 1
        start_time = time.time()
        for s in steps:
            c = c + 1
            if blank not in s['position']:
                openstates = deepcopy(puzzle)
                openstates[blank], openstates[blank + s['head']] = ___
 →openstates[blank + s['head']], openstates[blank]
                if ~(np.all(list(state['puzzle']) == openstates, 1)).any():
                    end_time = time.time()
                    if (( end_time - start_time ) > 2):
                        print(" The 8 puzzle is unsolvable \n")
                        break
                    hn = misplaced_tiles(coordinates(openstates), costg)
                    q = np.array([(openstates, position, gn, hn)], dtstate)
                    state = np.append(state, q, 0)
                    fn = gn + hn
                    q = np.array([(len(state) - 1, fn)], dtpriority)
                    priority = np.append(priority, q, 0)
                    if np.array_equal(openstates, goal):
                        print(' The 8 puzzle is solvable \n')
                        return state, len(priority)
    return state, len(priority)
puzzle = []
puzzle.append(2)
puzzle.append(8)
puzzle.append(3)
puzzle.append(1)
puzzle.append(6)
puzzle.append(4)
puzzle.append(7)
puzzle.append(0)
puzzle.append(5)
goal = []
goal.append(1)
goal.append(2)
goal.append(3)
```

```
goal.append(8)
goal.append(0)
goal.append(4)
goal.append(7)
goal.append(6)
goal.append(5)

state, visited = evaluvate_misplaced(puzzle, goal)
bestpath = bestsolution(state)
print(str(bestpath).replace('[', ' ').replace(']', ''))
totalmoves = len(bestpath) - 1
print('\nSteps to reach goal:',totalmoves)
visit = len(state) - visited
print('Total nodes visited: ',visit, "\n")
```

## The 8 puzzle is solvable

```
2 8 3
1 6 4
7 0 5
2 8 3
1 0 4
7 6 5
2 0 3
1 8 4
7 6 5
0 2 3
1 8 4
7 6 5
1 2 3
0 8 4
7 6 5
1 2 3
8 0 4
7 6 5
```

Steps to reach goal: 5
Total nodes visited: 6