

✓ **Congratulations! You passed!**

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1. What do you think applying this filter to a grayscale image will do?

1 / 1 point

$$\begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 3 & 3 & 1 \\ -1 & -3 & -3 & -1 \\ 0 & -1 & -1 & 0 \end{bmatrix}$$

- ☐ Detect 45-degree edges.
- ☒ Detect horizontal edges.
- ☐ Detect vertical edges.
- ☐ Detecting image contrast.

↗ Expand

✓ **Correct**

Correct. There is a high difference between the values in the top part from those in the bottom part of the matrix. When convolving this filter on a grayscale image, the horizontal edges will be detected.

2. Suppose your input is a 300 by 300 color (RGB) image, and you are not using a convolutional network. If the first hidden layer has 100 neurons, each one fully connected to the input, how many parameters does this hidden layer have (including the bias parameters)?

1 / 1 point

- ☒ 27,000,100
- ☐ 9,000,100
- ☐ 9,000,001
- ☐ 27,000,001

↗ Expand

✓ **Correct**

Correct, the number of weights is $300 \times 300 \times 3 \times 100 = 27,000,000$, when you add the bias terms (one per neuron) you get 27,000,100.

3. Suppose your input is a 256 by 256 grayscale image, and you use a convolutional layer with 128 filters that are each 3×3 . How many parameters does this hidden layer have (including the bias parameters)?

1 / 1 point

- ☐ 3584
- ☐ 1152
- ☐ 75497600
- ☒ 1280

 Expand

 Correct

Yes, since the input volume has only one channel each filter has $3 \times 3 + 1$ weights including the bias, thus the total is $(3 \times 3 + 1) \times 128$.

4. You have an input volume that is $63 \times 63 \times 16$, and convolve it with 32 filters that are each 7×7 , using a stride of 2 and no padding. What is the output volume?

1 / 1 point

- ☐ $16 \times 16 \times 32$
- ☐ $16 \times 16 \times 16$
- ☒ $29 \times 29 \times 32$
- ☐ $29 \times 29 \times 16$

 Expand

 Correct

Yes, $\frac{63 - 7 + 0}{2} + 1 = 29$ and the number of channels should match the number of filters.

5. You have an input volume that is $61 \times 61 \times 32$, and pad it using "pad=3". What is the dimension of the resulting volume (after padding)?

1 / 1 point

- ☐ $64 \times 64 \times 35$
- ☐ $64 \times 64 \times 32$
- ☐ $61 \times 61 \times 35$
- ☒ $67 \times 67 \times 32$

 Expand

 Correct

Yes, if the padding is 3 you add 6 to the height dimension and 6 to the width dimension.

6. You have a volume that is $64 \times 64 \times 32$, and convolve it with 40 filters of 9×9 , and stride 1. You want to use a "same" convolution. What is the padding?

1 / 1 point

- ☐ 0
- ☐ 6
- ☐ 8
- ☒ 4

 Expand

 Correct

Yes, when using a padding of 4 the output volume has $n_H = \frac{121 - 9 + 2 \times 4}{1} + 1$.

7. You have an input volume that is $128 \times 128 \times 12$, and apply max pooling with a stride of 4 and a filter size of 4. What is the output volume?

0 / 1 point

- ☐ $128 \times 128 \times 3$
- ☐ $32 \times 32 \times 3$
- ☐ $32 \times 32 \times 12$
- ☒ $64 \times 64 \times 12$

[Expand](#)

 **Incorrect**

No, check that you apply the formula $n_H^{[l]} = \frac{n_H^{[l-1]} + 2 \times p - f}{s} + 1$ correctly.

8. Which of the following are hyperparameters of the pooling layers? (Choose all that apply)

1 / 1 point

- ☐ $W^{[l]}$ weights.
- ☐ $b^{[l]}$ bias.
- ☒ Stride

 **Correct**

Yes, although usually, we set $f = s$ this is one of the hyperparameters of a pooling layer.

- ☒ Whether it is max or average.

 **Correct**

Yes, these are the two types of pooling discussed in the lectures, and choosing which to use is considered a hyperparameter.

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 **Correct**

Great, you got all the right answers.

9. Which of the following are the **benefits of using convolutional layers**? (Check all that apply)


0 / 1 point

- ☒ Convolutional layers are good at capturing translation invariance.

 **Correct**


Yes, this is due in part to applying the same filter all over the image.

- ☒ It allows parameters learned for one task to be shared even for a different task (transfer learning).

 **This should not be selected**

No, transfer learning is not bound to ConvNets and can be used with other types of models as you've seen in Course 1-3.

- ☒ It reduces the computations in backpropagation since we omit the convolutional layers in the process.

 **This should not be selected**

No, we compute the derivatives with respect to the parameters of the filters of convolutional layers in backpropagation.

- ☒ It reduces the total number of parameters, thus reducing overfitting through parameter sharing.

 **Correct**

Yes, a convolutional layer uses parameters sharing and has usually a lot fewer parameters than a fully-connected layer.

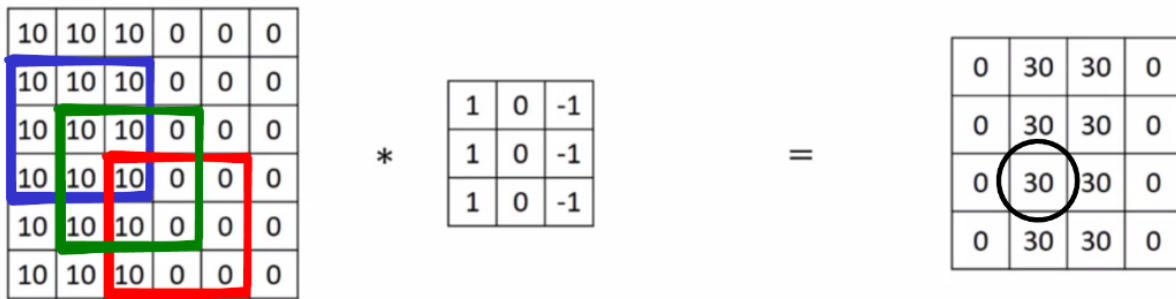
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 **Incorrect**

You chose the extra incorrect answers.

10. The following image depicts the result of a convolution at the right when using a stride of 1 and the filter is shown right next.

1 / 1 point



On which pixels does the circled pixel of the activation at the right depend?

- ☒ It depends on the pixels enclosed by the green square.
- ☐ It depends on the pixels enclosed by the red square.
- ☐ It depends on all the pixels of the image on the left.
- ☐ It depends on the pixels enclosed by the blue square.

[Expand](#)

✓ Correct

Yes, this is the position of the filter when we move it two pixels down and one to the right.