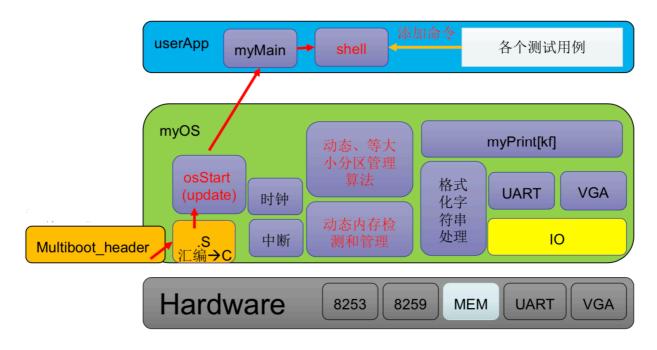
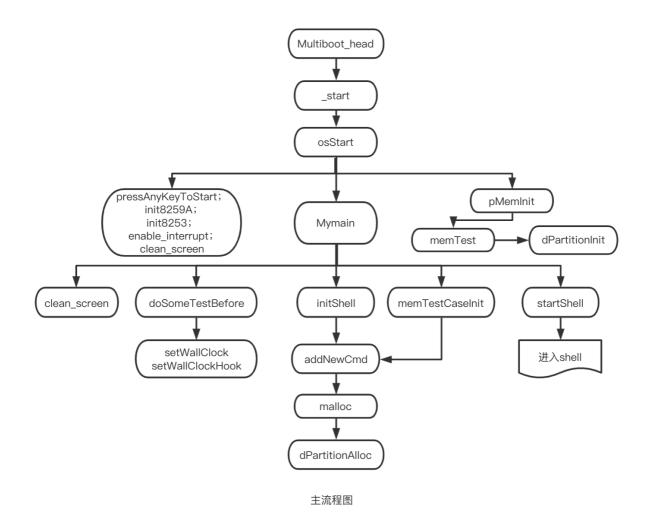
实验三 Memory Management

软件框架及概述



概述:从Multiboot_header进入入操作系统内核(myOS),为进入C程序准备好上下文,初始化操作系统。调用myMain进入userApp。userApp中实现了用户的shell功能,shell中可调用malloc/free动态注册新命令,malloc/free由OS内核中实现的内存管理算法封装得到。

主流程及其实现



主流程说明:multiboot_header.s调用_start入口,myOS中的Start32.s设置好中断处理,设置时钟中断(包括后续的tick维护、墙钟维护和显示),提供了osStart()入口,做好第一次调用C语言入口前的准备,进入osStart()后,先初始化操作系统,包括初始化i8259、i8253,并开中断,检测内存并初始化,再调用与userApp之间的接口myMain,进入myMain后,清屏、打开墙钟,初始化shell并和测试用例,再调用startshell()进入自定义shell,通过malloc动态注册新命令,malloc/free根据动态分区管理算法封装得到。

主要功能模块及其实现&源代码说明

实验4的基础来自助教提供的框架

模块一 内存检测和动态内存

6

```
检测start和grainSize
                     顺序检测每个
                                                                动态内存起点重
                                        的头或尾2个字节无效
 的取值是否合法
                     grainSize的内存
                                                                定位到_end之后
                                        时,停止并返回边界大小
   void memTest(unsigned long start, unsigned long grainSize){
                                                                 //内存检测
2
       int notFinished = 1;
3
      unsigned short *toTestAddr, *rearAddr;
      unsigned short temp;
4
5
```

if (start<0x100000) { //开始的地址要大于1M

检测到某个grainsize内

```
myPrintk(0x7,"???????? IN memTest: start is too small,
    should>=1MB ????????\n"); while(1);
8
       }
9
10
       if (grainSize<0x1000) { //默认规定grainsize要大于4kB
           myPrintk(0x7,"???????? IN memTest: grainSize is too small,
11
    should>=4KB ????????\n"); while(1);
12
       }
13
14
       pMemStart = start;
       toTestAddr = (unsigned short*) start; //unsigned short占用2个字节
15
16
       while(1){
17
           temp= *toTestAddr;
18
           *toTestAddr = 0xAA55; //通过先覆盖再读入的方法检测grainsize的
19
    头2个字节
           if(*toTestAddr!=0xAA55) notFinished=0;
20
21
22
           *toTestAddr = 0x55AA;
23
           if(*toTestAddr!=0x55AA) notFinished=0;
24
25
           *toTestAddr = temp;
                                         //恢复头2个字节
26
27
           rearAddr=toTestAddr+grainSize/sizeof(unsigned short)-1;
           temp= *rearAddr;
28
29
                                       //检测grainsize的尾2个字节
30
           *rearAddr = 0xAA55;
31
           if(*rearAddr!=0xAA55) notFinished=0;
32
           *rearAddr = 0x55AA;
33
34
           if(*rearAddr!=0x55AA) notFinished=0;
35
                                         //恢复尾2个字节
36
           *rearAddr = temp;
37
38
           if(notFinished) break;
39
           toTestAddr += grainSize/sizeof(unsigned short); //检测下一块内存
40
41
        }
42
43
       pMemSize = (unsigned long)toTestAddr - start;
44
45
       myPrintk(0x7,"MemStart: %x \n",pMemStart);
       myPrintk(0x7,"MemSize: %x \n",pMemSize);
46
47
48
49
   extern unsigned long _end;
                                                          //初始化,包括确定动
50
   void pMemInit(void){
    态内存
51
       unsigned long _end_addr = (unsigned long) &_end;
```

```
52
        memTest(0x100000,0x1000);
53
        myPrintk(0x7,"_end: %x \n", _end_addr);
        if (pMemStart <= end addr) {</pre>
54
            pMemSize -= _end_addr - pMemStart; //1M到_end的部分不计入动态
55
    内存
           pMemStart = _end_addr;
56
57
58
        pMemHandler = dPartitionInit(pMemStart,pMemSize);
59
    }
```

模块二 等大小分区管理算法

对每块空闲的内存创建⁾ 一个结构体EEB,将所 有空闲内存串起来

```
#define OVERHEAD EFP (sizeof(struct eFPartition))
   unsigned long eFPartitionInit(unsigned long start, unsigned long perSize,
    unsigned long n){
                                                                         11
    初始化内存
       struct EEB * nextEEB;
 3
       unsigned long nextStart = start + OVERHEAD EFP;
 4
 5
       unsigned long actualSize = ((perSize + 3) >> 2) << 2; // aligned up
    to 4
 6
      struct eFPartition * theEFP = (struct eFPartition*)start;
 7
                                                      //创建一个eFPartition记
 8
       the EFP->total n;
    录整个内存的结构
9
                         = actualSize;
       theEFP->perSize
10
        theEFP->firstFree = nextStart;
11
       for(int i=0; i<n; i++) {
                                                      //对每块内存创建一个EEB
12
13
            nextEEB = (struct EEB *)nextStart;
14
           nextStart += perSize;
15
           nextEEB->next start = nextStart;
16
        }
17
18
        nextEEB->next start = 0;
19
       return start;
20
   }
```

计算整块内存的合理大小:

分配内存:

```
unsigned long eFPartitionAlloc(unsigned long EFPHandler) { //分配内存 struct eFPartition * theEFP = (struct eFPartition*)EFPHandler; unsigned long addr = theEFP->firstFree; if (addr!=0) //分配第一块空闲的内存 theEFP->firstFree = ((struct EEB*)(addr))->next_start; return addr; }
```

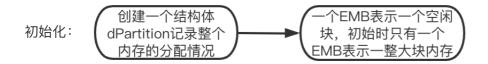
释放内存:

```
unsigned long eFPartitionFree(unsigned long EFPHandler, unsigned long
    mbStart){ //释放内存
 2
      struct eFPartition * theEFP;
 3
       struct EEB* newFree;
4
 5
       theEFP = (struct eFPartition*)EFPHandler;
 6
 7
       newFree = (struct EEB*)mbStart;
8
       newFree->next_start = theEFP->firstFree; //更新EBB组成的链表
       theEFP->firstFree = mbStart; //mbstart成为第一个空闲块
9
10
11
       return 1;
12
   }
```

查看内存分配情况:

```
void eFPartitionWalkByAddr(unsigned long efpHandler){
                                                                   //杳看
   内存分配结构
2
       struct eFPartition * theEFP = (struct eFPartition*)efpHandler;
                                   //打印eFPartiiton结构体的信息
3
       showeFPartition(theEFP);
       unsigned long addr = theEFP->firstFree;
4
5
       struct EEB* eeb;
6
       while(addr!=0){
                                            //遍历每一个EEB, 打印出他们的地址以
   及下一个EEB的地址
7
           eeb=(struct EEB*)(addr);
           showEEB(eeb);
8
           addr = eeb->next start;
9
10
       }
11 }
```

模块三 动态分区管理算法



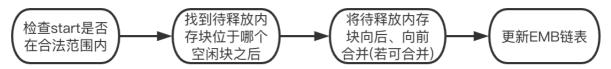
```
#define MINI DP SIZE (sizeof(struct EMB)+sizeof(struct dPartition))
1
   unsigned long dPartitionInit(unsigned long start, unsigned long totalSize)
    { //初始化内存
      struct dPartition * theDP;
3
       struct EMB *firstEMB;
4
5
       if (totalSize < MINI_DP_SIZE) return 0; //totalSize至少要容纳一个EMB和一
    个dP
7
8
       theDP = (struct dPartition*)start; //theDP结构体表示整个数据结构
9
       theDP->size = totalSize;
10
       theDP->firstFreeStart = start+sizeof(struct dPartition);
11
       firstEMB = (struct EMB*)(theDP->firstFreeStart); //一整块的EMB被分
12
    配,在内存中紧紧跟在dP后面
       firstEMB->size = totalSize-sizeof(struct dPartition);
14
       firstEMB->nextStart = 0;  //for the end of List
15
16
       return start;
17
   }
```

```
size修改为合适大小,保留对记
内存块大小的记录并对齐4字节
大型第一块大小
足够的空闲块
大型第一块大小
个EMB,则增加一个EMB;
否则将整个空闲块分配出去
```

```
#define OVERHEAD EMB (sizeof(struct EMB)-sizeof(struct EMB*))
                                                                     //记录内存块
    大小所需内存
    #define MINI EMB SIZE sizeof(struct EMB)
    unsigned long dPartitionAllocFirstFit(unsigned long dp, unsigned long
    size) { //使用firstfit算法分配内存块
        struct dPartition *theDP;
 4
 5
        unsigned long curr, prev=0, next, rear;
        unsigned long actualSize = size + OVERHEAD EMB;
 6
 7
        unsigned long sizeLeft;
 8
        int notfind=1;
 9
        actualSize = ((actualSize+3)>>2)<<2;  //align up to 4</pre>
10
        if (actualSize<MINI_EMB_SIZE) actualSize = MINI_EMB SIZE;</pre>
11
12
13
        // find the first fit
14
        theDP = (struct dPartition*)dp;
15
        curr = theDP->firstFreeStart;
16
17
        while (notfind) {
            if (curr == 0) {
18
19
                notfind = 1;
                break; // not find, &finish
20
2.1
            }
22
23
            if (actualSize<=((struct EMB*)curr)->size) {
2.4
                notfind=0;
                break; // find, &finish
25
26
            }
27
            //next loop
28
29
            prev = curr;
30
            curr = ((struct EMB*)prev)->nextStart;
31
        }
32
33
        if(notfind)
34
            return 0;
        else { //find
35
            sizeLeft = ((struct EMB*)curr)->size - actualSize;
36
            if (sizeLeft >= MINI EMB SIZE) {
37
                //need cut, return curr, insert rear
38
39
                rear = curr + actualSize;
40
                ((struct EMB*)rear)->size = ((struct EMB*)curr)->size -
    actualSize;
```

```
((struct EMB*)rear)->nextStart = ((struct EMB*)curr)-
    >nextStart;
42
                if(prev) ((struct EMB*)prev)->nextStart = rear;
43
                else theDP->firstFreeStart = rear;
44
                ((struct EMB*)curr)->size = actualSize;
45
            } else { // do not cut
46
47
                if(prev) ((struct EMB*)prev)->nextStart = ((struct EMB*)curr)-
    >nextStart;
                else theDP->firstFreeStart = ((struct EMB*)curr)->nextStart;
48
49
            }
50
            return curr+OVERHEAD EMB;
52
        }
53
    }
```

释放内存:



```
unsigned long dPartitionFreeFirstFit(unsigned long dp, unsigned long
    start){ //释放内存
 2
        unsigned long curr = start-OVERHEAD EMB;
        unsigned long prev=0, next;
 3
        struct dPartition *theDP;
 4
 5
        int notfind=1;
        theDP = (struct dPartition*)dp;
 6
 7
        next = theDP->firstFreeStart;
        prev = 0;
 8
 9
        //检查start是否在dp范围内
10
11
        if(curr<dp+sizeof(struct dPartition)||curr>=dp+theDP->size)
12
            return 0;
13
14
        //find position in freelist
15
        while(notfind){
16
            if ((next == 0)||(next > curr)) { // insert curr before next
17
                notfind = 0;
18
                if (prev == 0) // the first
19
                    theDP->firstFreeStart = curr;
20
21
                else ((struct EMB*)prev)->nextStart = curr;
2.2
23
                ((struct EMB*)curr)->nextStart = next;
24
                                                                             //
25
                if(next&&next==curr+((struct EMB*)curr)->size){
    向后合并
```

```
26
                     ((struct EMB*)curr)->nextStart = ((struct EMB*)next)-
    >nextStart;
27
                     ((struct EMB*)curr)->size += ((struct EMB*)next)->size;
28
                }
                                                                              //
29
                if(prev&&curr==prev+((struct EMB*)prev)->size){
    向前合并
3.0
                     ((struct EMB*)prev)->nextStart = ((struct EMB*)curr)-
    >nextStart;
31
                     ((struct EMB*)prev)->size += ((struct EMB*)curr)->size;
32
33
                break;
34
            }
35
            prev = next;
36
            next = ((struct EMB*)next)->nextStart;
37
        }
38
        return 1;
39
```

查看内存分配情况:

```
void dPartitionWalkByAddr(unsigned long dp){
                                                  //查看内存分配结构
       struct dPartition * theDP = (struct dPartition *) dp;
2
                                                     //先印dP的信息
3
       showdPartition(theDP);
4
       unsigned long addr = theDP->firstFreeStart;
5
       struct EMB* emb;
       while(addr!=0){
                                   //遍历EMB并打印其地址,大小和以及下一个EEB的地址
6
7
           emb=(struct EMB*)(addr);
           showEMB(emb);
           addr = emb->nextStart;
9
10
        }
11
```

模块四 malloc/free接口实现, shell新增命令

malloc/free接口:

```
unsigned long malloc(unsigned long size){
   dPartitionAlloc(pMemHandler,size);
}
unsigned long free(unsigned long start){
   dPartitionFree(pMemHandler,start);
}
```

Kmalloc/free接口简单实现(包含在kmalloc.h中):

```
#define kmalloc(size) dPartitionAlloc(pMemHandler,size)
#define kfree(start) dPartitionFree(pMemHandler,start)
```

shell动态注册新命令:

```
void addNewCmd( unsigned char *cmd,
 2
            int (*func)(int argc, unsigned char **argv),
 3
            void (*help_func)(void),
 4
            unsigned char* description) {
                                          //动态注册新命令
        struct cmd *f = (struct cmd *)malloc(sizeof(struct cmd)); //创建一个
 5
    cmd的结构体
                                                   //命令名
 6
        strncpy(cmd,f->cmd,20);
 7
       f->func=func;
                                                   //命令入口
                                                   //命令的help入口
        f->help func=help func;
8
9
        strncpy(description, f->description, 100);
                                                   //该命令的描述
        f->nextCmd=ourCmds;
                                                   //维护cmd的链表
1.0
11
        ourCmds=f;
12
    }
```

自测一个新命令exit,当在命令行输入exit时会退出shell。修改了startshell的部分代码帮助实现exit功能:

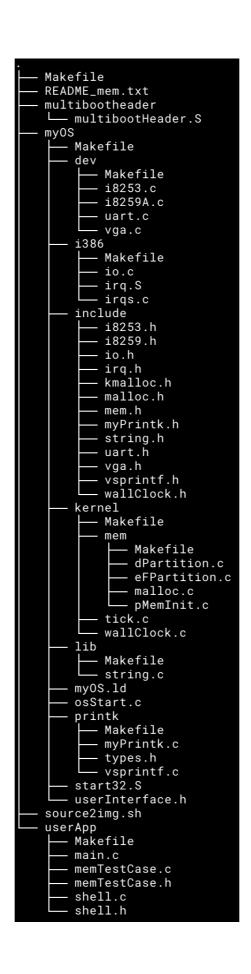
```
1
    int exit_terminal(int argc, unsigned char **argv){
                                                            //exit命令入口
 2
        if (argc>1) return 1;
        return -1; //返回-1时, startshell接收到-1会直接return
 3
 4
    }
 5
 6
    void initShell(void){
        /*......其他命令......*/
 7
        addNewCmd("exit\0",exit terminal,NULL,"exit the terminal\0");
8
9
    }
10
11
    void startShell(void){
12
        unsigned char *argv[10]; //max 10
13
        int argc;
14
        struct cmd *tmpCmd;
        //myPrintf(0x7,"StartShell:\n");
15
16
17
        while(1) {
18
            myPrintf(0x3, "rbzhang >: ");
            getCmdline(&cmdline[0],100);
19
20
            myPrintf(0x7,cmdline);
2.1
            argc = split2Words(cmdline,&argv[0],10);
2.2
            if (argc == 0) continue;
2.3
24
2.5
            tmpCmd = findCmd(argv[0]);
26
            if (tmpCmd)
```

```
27
                int rv=(tmpCmd->func(argc, argv)); //记录命令返回值
28
                if(rv==-1)
                                                 //退出shell
29
                   return;
30
               else if(rv==1)
31
                   myPrintf(0x7,"UNKOWN parameter of %s\n",cmdline); //参数不
    匹配
32
            }
33
            else
34
               myPrintf(0x7,"UNKOWN command: %s\n",argv[0]);
35
36
   }
```

自测kmalloc/kfree:

```
1
    #include "../myOS/include/kmalloc.h"
    #include "../myOS/include/myPrintk.h"
 2
 3
    int test_kmalloc(int argc, unsigned char **argv){
        4
        char*buf1 = (char*)kmalloc(19);
 5
        char*buf2 = (char*)kmalloc(24);
 6
 7
 8
        for(int i=0; i<17; i++) *(buf1+i) = '*';
9
        *(buf1+17) = '\n';
10
        *(buf1+18) = ' \000';
11
        for(int i=0; i<22; i++) *(buf2+i) = '#';
12
        *(buf2+22) = '\n';
13
        *(buf2+23) = '\000';
14
15
16
        myPrintk(0x5, "We allocated 2 buffers.\n");
        myPrintk(0x5, "BUF1(size=19, addr=0x%x) filled with 17(*): ",(unsigned
17
    long)buf1);
18
        myPrintk(0x7,buf1);
19
        myPrintk(0x5, "BUF2(size=24, addr=0x%x) filled with 22(#): ",
    (unsigned long)buf2);
20
        myPrintk(0x7,buf2);
21
22
       myPrintk(0x7,"\n");
23
24
        kfree((unsigned long)buf1);
25
        kfree((unsigned long)buf2);
26
27
       return 0;
28
    }
    void memTestCaseInit(void){
29
        /*......其他命令.....*/
30
31
        addNewCmd("testKmalloc\0", test_kmalloc, NULL, "Kmalloc, write and
    read.\0");
32
    }
```

目录组织



Makefile组织

关键规则:

```
output/myOS.elf: ${OS OBJS} ${MULTI BOOT HEADER}
2
        ${CROSS_COMPILE}ld -n -T myOS/myOS.ld ${MULTI_BOOT_HEADER} ${OS_OBJS}
    -o output/myOS.elf
    output/%.o:%.S #所有的.s生成.o
4
5
        @mkdir -p $(dir $@)
        @${CROSS COMPILE}gcc ${ASM FLAGS} -c -o $@ $<</pre>
6
7
   output/%.o:%.c
                        #所有的.c生成.o
8
9
        @mkdir -p $(dir $@)
10
        @${CROSS COMPILE}gcc ${C FLAGS} -c -o $@ $<</pre>
```

先由各级子目录下的.c 和.s文件生成.o文件,再将.o文件作为依赖文件,按照myOS.ld规则链接成终极目标文件myOS.elf。

代码布局说明

首先定位到内存中1M地址处。可执行文件的.text段从此处开始。先存放.multiboot_header段[12字节],往后对齐8字节后,再存放所有输入文件的.text段。往后对齐16字节,开始存放可执行文件的.data段,即为所有输入文件的.data段。往后对齐16字节,接着存放可执行文件的.bss段,包括所有输入文件中未初始化的全局变量。bss段结束后再向后对齐16字节,此处以_end作为结束标记。往后对齐512字节。

编译过程说明

直接在终端运行./source2run.sh即可。具体过程是先按照makefile内容进行编译链接,编译成功后再执行命令

```
qemu-system-i386 -kernel output/myOS.elf -serial pty &
```

将串口重定向到伪终端、运行时会告知具体是哪个、据此输入

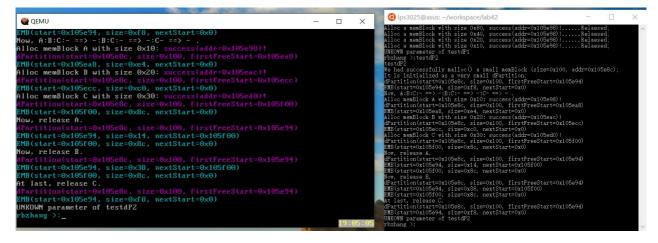
```
1 sudo screen /dev/pts/0 #假设是/dev/pts/0
```

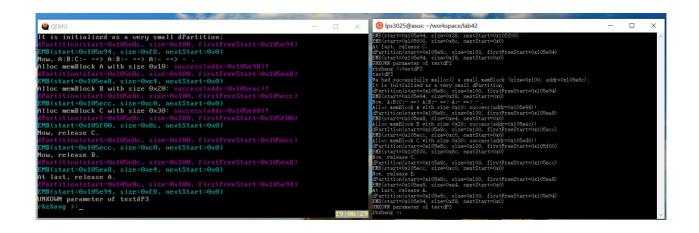
接着就可以通过伪终端输入命令。

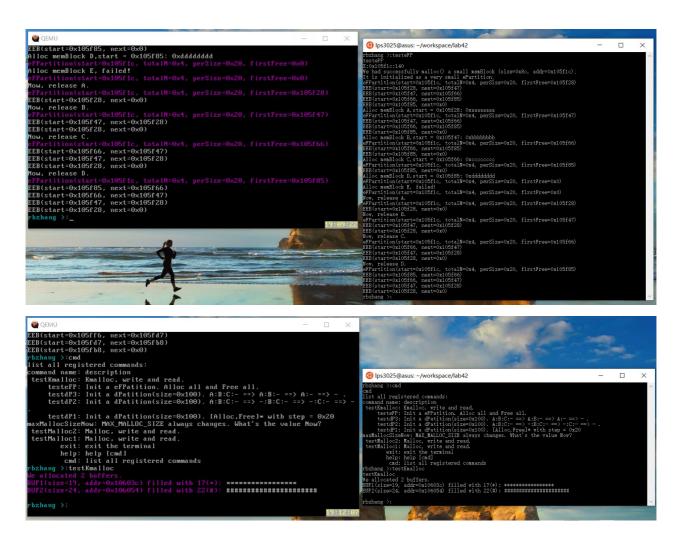
运行和运行结果说明

运行结果如下:

```
| Command name: description | Commands: | Command name: description | Command name: de
```







说明:分别在命令行输入cmd, maxMallocSizeNow, testMalloc1, testMalloc2, maxMallocSizeNow, testdP1,t estdP2, testdP3, testeFP,最后输入kmalloc/free的自编测试命令testKmalloc。

遇到的问题和解决方案说明

使用动态分区管理算法释放内存时,需要知道被分配的内存大小。因此需要在分配空闲块的时候, 就将该处EMB的size信息保留下来,即从内存中size存储位置的后面开始分配所需大小的内存。