

ARTIFICIAL INTELLIGENCE LAB MANUAL

B.Tech (CSE) - R19 & R20

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VASIREDDY VENKATADRI INSTITUTE OF TECHNOLOGY

NAMBURU - GUNTUR DISTRICT - AP



VASIREDDY VENKATADRI INSTITUTE OF TECHNOLOGY

Permanently Affiliated to JNTU Kakinada, Approved by AICTE Accredited by NAAC with 'A' Grade, ISO 9001:2008 Certified Nambur, Pedakakani (M), Guntur (Dt) - 522508 DEPARTMENT OF COMPUTER SCIENCE & ENGINEERING

B.Tech Program is Accredited by NBA

Vision of the Department

To facilitate quality education by focusing on assimilation, generation and dissemination of knowledge in the area of Computer Science & Engineering to transform students into socially responsible engineers.

Mission of the Department

- Equip our graduates with the knowledge by student centric teaching-learning process and expertise to contribute significantly to the software industry and to continue to grow professionally.
- To train socially responsible, disciplined engineers who work with good leadership skills and can contribute for nation building.
- To make our graduates aware of cutting edge technologies and make them industry-ready engineers.
- To shape the department into a Centre of Academic and Research excellence.

	Program Educational Objectives		
	To provide the graduates with solid foundation in Computer Science and		
	Engineering along with the fundamentals of Mathematics and Sciences with		
PEO-1	a view to impart in them high quality technical skills like modelling,		
	analysing, designing, programming and implementation with global		
	competence and helps the graduates for life-long learning.		
	To prepare and motivate graduates with <i>recent technological developments</i>		
	related to core subjects like Programming, Databases, Design of Compilers		
PEO-2	and Network Security aspects and future technologies so as to contribute		
	effectively for Research & Development by participating in professional		
	activities like publishing and seeking copy rights.		
To train graduates to choose a decent career option either in high de			
PEO-3	employability/Entrepreneur or, in higher education by empowering students		
	with ethical administrative acumen, ability to handle critical situations and		
	training to excel in competitive examinations.		
	To train the graduates to have basic interpersonal skills and sense of social		
PEO-4	responsibility that paves them a way to become good team members and		
	leaders.		

Artificial Intelligence Lab Course details

Course : B.Tech
 Branch : CSE

3. Regulation : R19 & R20 4. Code : 20CS5L02

5. Lab Name : Artificial Intelligence Lab

6. Total Marks : 75 (Internal Lab marks 25 + External lab marks 50)

Course Objectives:

1. Study the concepts of Artificial Intelligence.

2. Learn the methods of solving problems using Artificial Intelligence.

3. Introduce the concepts of machine learning.

Course Outcomes:

At the end of the course, the students will be able to:

CO1: Identify problems that are amenable to solution by AI methods.

CO2: Recognize appropriate AI methods to solve a given problem.

CO3: Discuss a given problem in the framework of different AI methods.

CO4: Develop basic AI algorithms

Pre Requisites:

- Knowledge in Python programming
- Knowledge in Algorithms

Contents

S. No.	Experiment	P. No.
NO.		NO.
1.	Write a Program to Implement Tic-Tac-Toe game	
2.	Write a program to solve Water-Jug problem	
3.	Write a Program to Implement Breadth First Search	
4.	Write a Program to Implement Depth First Search	
5.	Write a Program to Implement 8-Puzzle problem	
6.	Implementation of Towers of Hanoi Problem	
7.	Write a Program to Implement Missionaries-Cannibals Problem	
8.	Write a Program to Implement Travelling Salesman Problem	
9.	Write a Program to Implement N-Queens Problem	

1. Write a Program to Implement Tic-Tac-Toe game

Tic-Tac-Toe Game Playing using Magic Square - Program 2 in AI

Assume,

Player 1 – uses X and

Player 2 – use O

So, a player who gets 3 consecutive marks first, the player will win the game.

Let's have a discussion about how a board's data structure looks and how the Tic Tac Toe algorithm works.

Magic Square

8	3	4
1	5	9
6	7	2

Here, we assign board positions to vector elements.

The Sum of all rows, columns, and diagonals must be 15.

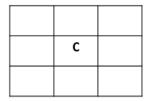
Algorithm – Tic-Tac-Toe Game Playing using Magic Square – Program 2 in AI The first machine will check, the chance to win,

• If the difference between 15 and the sum of the two squares, If this difference is not positive or if it is greater than 9, then the original two squares were not collinear and so can be ignored. or it will check the opponent of winning and block the chances of winning.

Here, the objective is machine will win the maximum number of matches.

Example:

Turn - Computer (C)



Turn - Computer (C)

Н		С
	С	

Turn - Human (H)

Н		
	С	

Turn - Human (H)

Н		С
	С	
Н		

Now, the computer will check its possibility of winning the game.

First, calculate the difference between the 15 and the sum of two positions.

Diff =
$$15 - (5+4) = 6$$

6 is not empty, hence Computer can't win the game.

Now, the computer checks the possibility of opponents winning the match. If the opponent is winning black it.

Diff =
$$15 - (8+6) = 1$$

1 is empty, hence the human can win the game.

Hence Computer Blocks it.

Computer - go to 1

Turn - Computer (C)

Н		С
С	С	
Н		

Now, it's Player Human Turn,

Turn - Human (H)

Н		С
С	С	
Н	Н	

Now, the computer will check its possibility of winning the game.

Diff =
$$15 - (5+4) = 6$$

6 is not empty, hence Computer can't win the game.

Diff =
$$15 - (1+4) = 10$$

10 is greater than 9, hence Computer can't win the game.

Diff =
$$15 - (1+5) = 9$$

9 is empty, hence Computer can win the game. Computer – go to 9

Turn - Computer (C)

Н		С
С	С	С
Н	Н	

2. Write a program to solve Water-Jug problem

A Water Jug Problem: You are given two jugs, a 4-gallon one and a 3-gallon one, a pump which has unlimited water which you can use to fill the jug, and the ground on which water may be poured. Neither jug has any measuring markings on it. How can you get exactly 2 gallons of water in the 4-gallon jug?

Here the initial state is (0, 0). The goal state is (2, n) for any value of n.

State Space Representation: we will represent a state of the problem as a tuple (x, y) where x represents the amount of water in the 4-gallon jug and y represents the amount of water in the 3-gallon jug. Note that $0 \le x \le 4$, and $0 \le y \le 3$.

To solve this we have to make some assumptions not mentioned in the problem. They are:

- We can fill a jug from the pump.
- We can pour water out of a jug to the ground.
- We can pour water from one jug to another.
- There is no measuring device available.

Operators — we must define a set of operators that will take us from one state to another.

Sr.	Current State	Next State	Descriptions
1	(x, y) if x < 4	(4, y)	Fill the 4 gallon jug
2	(x, y) if y < 3	(x, 3)	Fill the 3 gallon jug
3	(x, y) if x > 0	(x - d, y)	Pour some water out of the 4 gallon jug
4	(x, y) if y > 0	(x, y - d)	Pour some water out of the 3 gallon jug
5	(x, y) if y > 0	(0, y)	Empty the 4 gallon jug
6	(x, y) if y > 0	(x, 0)	Empty the 3 gallon jug on the ground
7	(x, y) if x + y >= 4 and y > 0	(4, y - (4 - x))	Pour water from the 3 gallon jug into the 4 gallon jug until the 4 gallon jug is full
8	(x, y) if x + y >= 3 and x > 0	(x - (3 - y), 3)	Pour water from the 4 gallon jug into the 3-gallon jug until the 3 gallon jug is full
9	(x, y) if x + y <= 4 and y > 0	(x + y, 0)	Pour all the water from the 3 gallon jug into the 4 gallon jug
10	(x, y) if x + y <=3 and x > 0	(0, x + y)	Pour all the water from the 4 gallon jug into the 3 gallon jug
11	(0, 2)	(2, 0)	Pour the 2 gallons from 3 gallon jug into the 4 gallon jug
12	(2, y)	(0, y)	Empty the 2 gallons in the 4 gallon jug on the ground

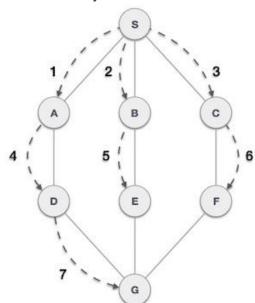
There are several sequences of operations that will solve the problem.

One of the possible solutions is given as:

Gallons in the 4-gallon jug	Gallons in the 3-gallon jug	Rule applied
0	0	2
0	3	9
3	0	2
3	3	7
4	2	5 or 12
0	2	9 or 11
2	0	

3. Write a Program to Implement Breadth First Search

Breadth First Search (BFS) algorithm traverses a graph in a breadthward motion and uses a queue to remember to get the next vertex to start a search, when a dead end occurs in any iteration.



As in the example given above, BFS algorithm traverses from A to B to E to F first then to C and G lastly to D. It employs the following rules.

- **Rule 1** Visit the adjacent unvisited vertex. Mark it as visited. Display it. Insert it in a queue.
- **Rule 2** If no adjacent vertex is found, remove the first vertex from the queue.
- **Rule 3** Repeat Rule 1 and Rule 2 until the queue is empty.

Step	Traversal	Description
1	A B C Queue	Initialize the queue.
2	A B C Queue	We start from visiting S (starting node), and mark it as visited.

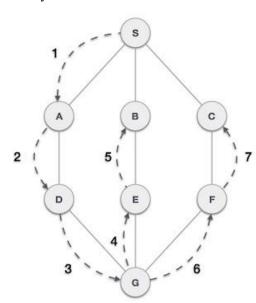
Step	Traversal	Description
3	A B C Queue	We then see an unvisited adjacent node from S . In this example, we have three nodes but alphabetically we choose A , mark it as visited and enqueue it.
4	B A Queue	Next, the unvisited adjacent node from S is B . We mark it as visited and enqueue it.
5	A B C C B A Queue	Next, the unvisited adjacent node from S is C . We mark it as visited and enqueue it.
6	A B C C B Queue	Now, S is left with no unvisited adjacent nodes. So, we dequeue and find A .

Step	Traversal	Description
7	A B C D C B Queue	From A we have D as unvisited adjacent node. We mark it as visited and enqueue it.

At this stage, we are left with no unmarked (unvisited) nodes. But as per the algorithm we keep on dequeuing in order to get all unvisited nodes. When the queue gets emptied, the program is over

4. Write a Program to Implement Depth First Search

Depth First Search (DFS) algorithm traverses a graph in a depthward motion and uses a stack to remember to get the next vertex to start a search, when a dead end occurs in any iteration.



As in the example given above, DFS algorithm traverses from S to A to D to G to E to B first, then to F and lastly to C. It employs the following rules.

- **Rule 1** Visit the adjacent unvisited vertex. Mark it as visited. Display it. Push it in a stack.
- Rule 2 If no adjacent vertex is found, pop up a vertex from the stack. (It will pop up all the vertices from the stack, which do not have adjacent vertices.)
- Rule 3 Repeat Rule 1 and Rule 2 until the stack is empty.

Step	Traversal	Description	
1	A B C Stack	Initialize the stack.	
2	A B C top→ S Stack	Mark S as visited and put it onto the stack. Explore any unvisited adjacent node from S . We have three nodes and we can pick any of them. For this example, we shall take the node in an alphabetical order.	
3	A B C top- A S Stack	Mark A as visited and put it onto the stack. Explore any unvisited adjacent node from A. Both S and D are adjacent to A but we are concerned for unvisited nodes only.	
4	A B C top+ D A S Stack	Visit D and mark it as visited and put onto the stack. Here, we have B and C nodes, which are adjacent to D and both are unvisited. However, we shall again choose in an alphabetical order.	

Step	Traversal	Description	
5	A B C top B D A S Stack	We choose B , mark it as visited and put onto the stack. Here B does not have any unvisited adjacent node. So, we pop B from the stack.	
6	A B C top+ D A S Stack	We check the stack top for return to the previous node and check if it has any unvisited nodes. Here, we find D to be on the top of the stack.	
7	A B C top+ C D A S Stack	Only unvisited adjacent node is from D is C now. So we visit C , mark it as visited and put it onto the stack.	

As C does not have any unvisited adjacent node so we keep popping the stack until we find a node that has an unvisited adjacent node. In this case, there's none and we keep popping until the stack is empty.

5. Write a Program to Implement 8-Puzzle problem

"It has set off a 3x3 board having 9 block spaces out of which 8 blocks having tiles bearing number from 1 to 8. One space is left blank. The tile adjacent to blank space can move into it. We have to arrange the tiles in a sequence for getting the goal state".

The 8-puzzle problem belongs to the category of "sliding block puzzle" type of problem. The 8-puzzle i s a square tray in which eight square tiles are placed. The

remaining ninth square is uncovered. Each tile in the tray has a number on it.

A tile that is adjacent to blank space can be slide into that space. The game consists of a starting position and a specified goal position. The goal is to transform the starting position into the goal position by sliding the tiles around.

Initial State			
1	2	3	
8		4	
7	6	5	

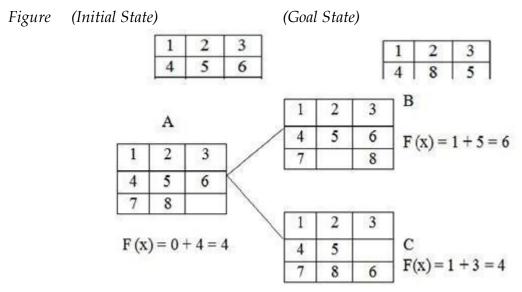
Goal State			
2	8	1	
	4	3	
7	6	5	

The control mechanisms for an 8-puzzle solver must keep track of the order in which operations are performed, so that the operations can be undone one at a time if necessary. The objective of the puzzles is to find a sequence of tile movements that leads from a starting configuration to a goal configuration such as two situations given. The state of 8-puzzle is the different permutation of tiles within the frame. The operations are the permissible moves up, down, left, right. Here at each step of the problem a function f(x) will be defined which is the combination of g(x) and h(x).

i.e. F(x)=g(x) + h(x)

Where, g(x): how many steps in the problem you have already done or the current state from the initial state, h(x): Number of ways through which you can reach at the goal state from the current state

h (x): is the heuristic estimator that compares the current state with the goal state note down how many states are displaced from the initial or the current state. After calculating the **f** value at each step finally take the smallest f (x) value at every step and choose that as the next current state to get the goal Let us take an example.



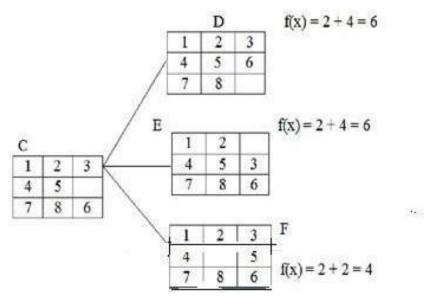
Step 1:

f(x) is the step required to reach at the goal state from the initial state. So in the trayeither 6 or 8 can change their portions to fill the empty position. So there will be two possible current states namely B and C. The f(x) value of B is 6 and that of C is 4. As 4 is the minimum, so take C as the current state to the next state.

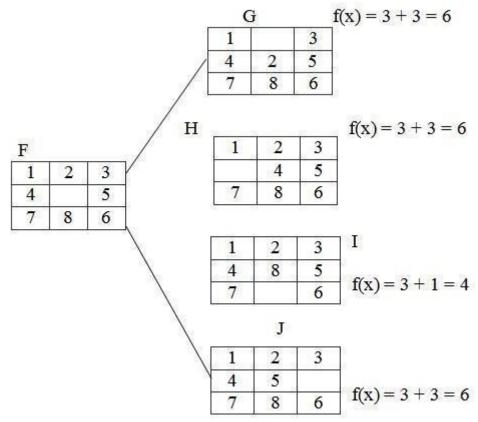
Step 2:

In this step, from the tray C three states can be drawn. The empty position will contain either 5 or 3 or 6. So for three different values three different states can be obtained. Then calculate each of their f (x) and take the minimum one.

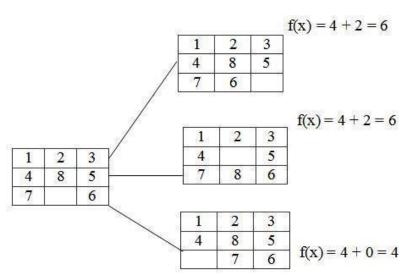
Here the state F has the minimum value i.e. 4 and hence take that as the next current state.



Step 3: The tray F can have 4 different states as the empty positions can be filled with b4 values i.e.2, 4, 5, 8.



Step 4: In the step-3 the tray I has the smallest f (n) value. The tray I can be implemented in 3 different states because the empty position can be filled by the members like 7, 8, 6. Hence, we reached at the goal state after few changes of tiles in different positions of the trays.



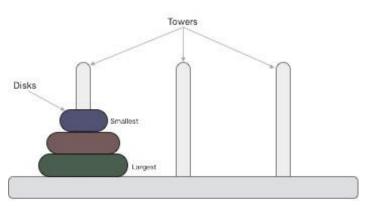
This problem requires a lot of space for saving the different trays. Time complexity is more than that of other problems.

The user has to be very careful about the shifting of tiles in the trays. Very complex puzzle games can be solved by this technique.

6. Implementation of Towers of Hanoi Problem

Tower of Hanoi, is a mathematical puzzle which consists of three towers (pegs) and more than one rings is as depicted –

These rings are of different sizes and stacked upon in an ascending order, i.e. the smaller one sits over the larger one. There are other variations of the puzzle where the number of disks increase, but the tower count remains the same.



Rules

The mission is to move all the disks to some another tower without violating the sequence of arrangement. A few rules to be followed for Tower of Hanoi are –

- Only one disk can be moved among the towers at any given time.
- Only the "top" disk can be removed.
- No large disk can sit over a small disk.

Following is an animated representation of solving a Tower of Hanoi puzzle with three disks.

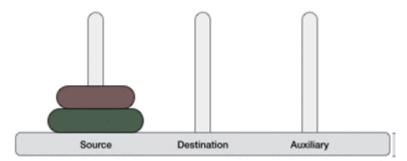


Tower of Hanoi puzzle with n disks can be solved in minimum 2^n-1 steps. This presentation shows that a puzzle with 3 disks has taken $2^3 - 1 = 7$ steps.

First its needed to learn how to solve this problem with lesser amount of disks, say \rightarrow 1 or 2. We mark three towers with name, **source**, **destination** and **aux** (only to help moving the disks). If there is only one disk, then it can easily be moved from source to destination peg.

If there are 2 disks -

- First, move the smaller (top) disk to aux peg.
- Then, move the larger (bottom) disk to destination peg.
- And finally, move the smaller disk from aux to destination peg.



We divide the stack of disks in two parts. The largest disk (nth disk) is in one part and all other (n-1) disks are in the second part.

Our ultimate aim is to move disk n from source to destination and then put all other (n1) disks onto it. We can imagine to apply the same in a recursive way for all given set of disks.

The steps to follow are –

Step 1 – Move n-1 disks from source to aux

Step 2 – Move nth disk from **source** to **dest**

Step 3 – Move n-1 disks from aux to dest

7. Write a Program to Implement Missionaries-Cannibals Problem

Missionaries and Cannibals problem is very famous in Artificial Intelligence because it was the subject of the first paper that approached problem formulation from an analytical viewpoint. The problem can be stated as follow.

Three missionaries and three cannibals are on one side of a river, along with a boat that can hold one or two people. Now we have to find a way to get everyone to the other side, without ever leaving a group of missionaries in one place outnumbered by the cannibals in another side. The above problem can be solved by a graph search method. Here I represent the problem as a set of states and operators. States are snapshots of the world and operators are those which transform one state into another state. States can be mapped to nodes of a graph and operators are the edges of the graph.

Explanation

Missionaries and Cannibals can be solved by using different search algorithms like Breadth first and Depth first search algorithm to find the solution. The node of the graph to be searched is represented by a state space. Each state space can be represent by

State(no_of_missionaries, no_of_cannibals, side_of_the_boat)

Where no_of_missonaries are the number of missionaries at left side of river, no_of_cannibals are the number of cannibals at the left side of river and side_of_the_boat is the side of the boat at particular state. For our case

Initial State => State(3, 3, 0) and Final State => State(0, 0, 1).

Where 0 represents left side and 1 represents right side of river. We should make a graph search which traverse the graph from initial state and find out the final state in fewest moves. There are many AI searches that search the graphs like Breadth first search, Depth first search, or iterative deepening search. Each of these different search methods has different properties such as whether a result is guaranteed, and how much time and space is needed to carry out the search. This project uses Breadth first and Depth first search.

Possible Moves

A move is characterized by the number of missionaries and the number of cannibals taken in the boat at one time. Since the boat can carry no more than two people at once, the only feasible combinations are:

```
Carry (2, 0).
Carry (1, 0).
Carry (1, 1).
```

Carry (0, 1).

Carry(0, 2).

Where Carry (M, C) means the boat will carry M missionaries and C cannibals on one trip.

Feasible Moves

Once we have found a possible move, we have to confirm that it is feasible. It is not a feasible to move more missionaries or more cannibals than that are present on one bank.

- When the state is state(M1, C1, left) and we try carry (M,C) then M <= M1 and C <= C1 must be true.
- When the state is state(M1, C1, right) and we try carry(M, C) then M + M1 <= 3 and C + C1 <= 3 must be true.

Legal Moves

Once we have found a feasible move, we must check that is legal i.e. no missionaries must be eaten.

```
Legal(X, X).
Legal(3, X).
Legal(0, X).
```

The only safe combinations are when there are equal numbers of missionaries and cannibals or all the missionaries are on one side. Generating the next state Above figure only shows valid states.

8. Write a Program to Implement Travelling Salesman Problem

A traveler needs to visit all the cities from a list, where distances between all the cities are known and each city should be visited just once. What is the shortest possible route that he visits each city exactly once and returns to the origin city?

Travelling salesman problem is the most notorious computational problem. We can use brute-force approach to evaluate every possible tour and select the best one. For $\bf n$ number of vertices in a graph, there are (n-1)! number of possibilities.

Instead of brute-force using dynamic programming approach, the solution can be obtained in lesser time, though there is no polynomial time algorithm.

Let us consider a graph G = (V, E), where V is a set of cities and E is a set of weighted edges. An edge e(u, v) represents that vertices u and v are connected. Distance between vertex u and v is d(u, v), which should be non-negative.

Suppose we have started at city 1 and after visiting some cities now we are in city j. Hence, this is a partial tour. We certainly need to know j, since this will determine which cities are most convenient to visit next. We also need to know all the cities visited so far, so that we don't repeat any of them. Hence, this is an appropriate sub-problem.

For a subset of cities $S \in \{1, 2, 3, ..., n\}$ that includes I, and $j \in S$, let C(S, j) be the length of the shortest path visiting each node in S exactly once, starting at I and ending at j.

When |S| > 1, we define $C(S, 1) = \infty$ since the path cannot start and end at 1.

Now, let express C(S, j) in terms of smaller sub-problems. We need to start at 1 and end at j. We should select the next city in such a way that

 $C(S,j)=\min C(S-\{j\},i)+d(i,j)$ where $i\in S$ and $i\neq j$ $i\in S$ and $i\neq S$ an

Algorithm: Traveling-Salesman-Problem

```
C ({1}, 1) = 0

for s = 2 to n do

for all subsets S \in {1, 2, 3, ..., n} of size s and containing 1

C (S, 1) = \infty

for all j \in S and j \neq 1

C (S, j) = min{C (S - {j}, i)+d(i, j) for i \in S and i \neq j}

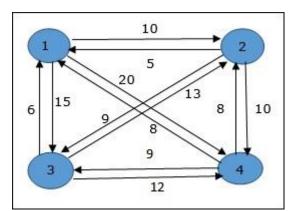
Return minj C ({1, 2, 3, ..., n}, j) + d(j, i)
```

Analysis

There are at the most 2^n .n sub-problems and each one takes linear time to solve. Therefore, the total running time is $O(2^n.n^2)$

Example

In the following example, we will illustrate the steps to solve the travelling salesman problem.



From the above graph, the following table is prepared.

	1	2	3	4
1	0	10	15	20
2	5	0	9	10
3	6	13	0	12
4	8	8	9	0

 $S = \Phi$

$$\begin{aligned} & \operatorname{Cost}(2,\Phi,1) = \operatorname{d}(2,1) = \operatorname{5Cost}(2,\Phi,1) = \operatorname{d}(2,1) = \operatorname{d}(2,1) = \operatorname{Cost}(2,\Phi,1) = \operatorname{Cost}(2,\Phi,1) = \operatorname{d}(2,1) = \operatorname{Cost}(2,\Phi,1) =$$

S = 1

$$\begin{split} & \operatorname{Cost}(i,s) = \min\{\operatorname{Cost}(j,s-(j)) + \operatorname{d}[i,j]\} \operatorname{Cost}(i,s) = \min\{\operatorname{Cost}(j,s)-(j)) + \operatorname{d}[i,j]\} \\ & \operatorname{Cost}(2,\{3\},1) = \operatorname{d}[2,3] + \operatorname{Cost}(3,\Phi,1) = 9 + 6 = 15 \operatorname{cost}(2,\{3\},1) = \operatorname{d}[2,3] + \operatorname{cost}(3,\Phi,1) = 9 + 6 = 15 \operatorname{Cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{Cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = 10 + 8 = 18 \operatorname{cost}(2,\{4\},1) = \operatorname{d}[2,4] + \operatorname{cost}(4,\Phi,1) = \operatorname{d}[2,$$

$$\begin{aligned} & \text{Cost}(3,\{2\},1) = \text{d}[3,2] + \text{Cost}(2,\Phi,1) = 13 + 5 = 18 \text{cost}(3,\{2\},1) = \text{d}[3,2] + \text{cost}(2,\Phi,1) = 13 + 5 = 18 \\ & \text{Cost}(3,\{4\},1) = \text{d}[3,4] + \text{Cost}(4,\Phi,1) = 12 + 8 = 20 \text{cost}(3,\{4\},1) = \text{d}[3,4] + \text{cost}(4,\Phi,1) = 12 + 8 = 20 \\ & \text{Cost}(4,\{3\},1) = \text{d}[4,3] + \text{Cost}(3,\Phi,1) = 9 + 6 = 15 \text{cost}(4,\{3\},1) = \text{d}[4,3] + \text{cost}(3,\Phi,1) = 9 + 6 = 15 \\ & \text{Cost}(4,\{2\},1) = \text{d}[4,2] + \text{Cost}(2,\Phi,1) = 8 + 5 = 13 \text{cost}(4,\{2\},1) = \text{d}[4,2] + \text{cost}(2,\Phi,1) = 8 + 5 = 13 \end{aligned}$$

S = 2

 $Cost(2,{3,4},1)=$

d[2,3]+Cost(3,{4},1)=9+20=29

d[2,4]+Cost(4,{3},1)=10+15=25=25 Cost(2,{3,4},1)

 ${d[2,3]+cost(3,{4},1)=9+20=29d[2,4]+Cost(4,{3},1)=10+15=25}$

=25

 $Cost(3,{2,4},1)=$

d[3,2]+Cost(2,{4},1)=13+18=31

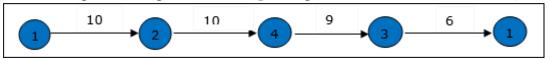
d[3,4]+Cost(4,{2},1)=12+13=25=25Cost(3,{2,4},1)

```
\{d[3,2]+\cos(2,\{4\},1)=13+18=31
d[3,4]+Cost(4,{2},1)=12+13=25
=25
Cost(4,{2,3},1)=
d[4,2]+Cost(2,{3},1)=8+15=23
d[4,3]+Cost(3,{2},1)=9+18=27=23Cost(4,{2,3},1)
{d[4,2]+cost(2,{3},1)=8+15=23}
d[4,3]+Cost(3,{2},1)=9+18=27
=23
S = 3
Cost(1,{2,3,4},1)=
d[1,2]+Cost(2,{3,4},1)=10+25=35
d[1,3]+Cost(3,{2,4},1)=15+25=40
d[1,4]+Cost(4,\{2,3\},1)=20+23=43=35cost(1,\{2,3,4\}),1)
d[1,2]+cost(2,{3,4},1)=10+25=35
d[1,3]+cost(3,{2,4},1)=15+25=40
d[1,4]+cost(4,\{2,3\},1)=20+23=43
=35
```

The minimum cost path is 35.

Start from cost $\{1, \{2, 3, 4\}, 1\}$, we get the minimum value for d[1, 2]. When s = 3, select the path from 1 to 2 (cost is 10) then go backwards. When s = 2, we get the minimum value for d[4, 2]. Select the path from 2 to 4 (cost is 10) then go backwards.

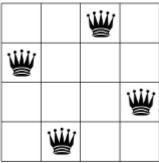
When $\mathbf{s} = \mathbf{1}$, we get the minimum value for $\mathbf{d} [\mathbf{4}, \mathbf{3}]$. Selecting path 4 to 3 (cost is 9), then we shall go to then go to $\mathbf{s} = \mathbf{\Phi}$ step. We get the min. value for $\mathbf{d} [\mathbf{3}, \mathbf{1}]$ (cost is 6).



9. Write a Program to Implement N-Queens Problem

In the following sections, we'll illustrate constraint programming (CP) by a combinatorial problem based on the game of chess. In chess, a queen can attack horizontally, vertically, and diagonally. The N-queens problem is how can N queens be placed on an NxN chessboard so that no two of them attack each other?

Below, you can see one possible solution to the N-queens problem for N = 4.



No two queens are on the same row, column, or diagonal.

Note that this isn't an optimization problem: we want to find all possible solutions, rather than one optimal solution, which makes it a natural candidate for constraint programming. The following sections describe the CP approach to the N-queens problem, and present Python programs that solve it using both the CP-SAT solver and the original CP solver.

CP approach to the N-queens problem

A <u>CP solver</u> works by systematically trying all possible assignments of values to the variables in a problem, to find the feasible solutions. In the 4-queens problem, the solver starts at the leftmost column and successively places one queen in each column, at a location that is not attacked by any previously placed queens.

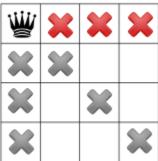
Propagation and backtracking

There are two key elements to a constraint programming search:

Propagation — Each time the solver assigns a value to a variable, the constraints add restrictions on the possible values of the unassigned variables. These restrictions *propagate* to future variable assignments. For example, in the 4-queens problem, each time the solver places a queen, it can't place any other queens on the row and diagonals the current queen is on. Propagation can speed up the search significantly by reducing the set of variable values the solver must explore.

Backtracking occurs when either the solver can't assign a value to the next variable, due to the constraints, or it finds a solution. In either case, the solver backtracks to a previous stage and changes the value of the variable at that stage to a value that hasn't already been tried. In the 4-queens example, this means moving a queen to a new square on the current column.

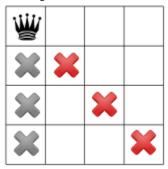
Next, you'll see how constraint programming uses propagation and backtracking to solve the 4-queens problem.



Let's suppose the solver starts by arbitrarily placing a queen in the upper left corner. That's a hypothesis of sorts; perhaps it will turn out that no solution exists with a queen in the upper left corner.

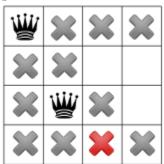
Given this hypothesis, what constraints can we propagate? One constraint is that there can be only one queen in a column (the gray Xs below), and another constraint prohibits

two queens on the same diagonal (the red Xs below).

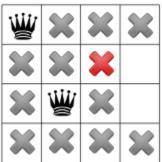


Our third constraint prohibits queens on the same row:

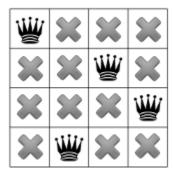
Our constraints propagated, we can test out another hypothesis, and place a second queen on one of the available remaining squares. Our solver might decide to place in it the first available square in the second column:



After propagating the diagonal constraint, we can see that it leaves no available squares in either the third column or last row:

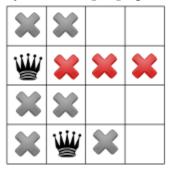


With no solutions possible at this stage, we need to backtrack. One option is for the solver to choose the other available square in the second column. However, constraint propagation then forces a queen into the second row of the third column, leaving no valid spots for the fourth queen:

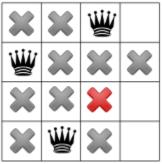


And so the solver must backtrack again, this time all the way back to the placement of the first queen. We have now shown that no solution to the queens problem will occupy a corner square.

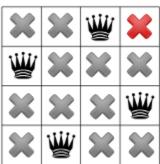
Since there can be no queen in the corner, the solver moves the first queen down by one, and propagates, leaving only one spot for the second queen:



Propagating again reveals only one spot left for the third queen:



And for the fourth and final queen:



We have our first solution! If we instructed our solver to stop after finding the first solution, it would end here. Otherwise, it would backtrack again and place the first queen in the third row of the first column.