

# Runmao Yao

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## Education

<b>Tsinghua University</b> , B.Eng. in Software Engineering	Sept 2021 – Jun 2025
• GPA: 3.84/4.00 (93.14/100)	
– Freshman: 3.55/4.00	Sophomore: 3.90/4.00
– Junior: 3.98/4.00	Senior: 4.00/4.00

## Publications

[1] <b>AnchoredDream: Zero-Shot 360° Indoor Scene Synthesis from a Single View via Geometric Grounding</b> (OpenReview <a href="#">🔗</a> )	Submitted to NeurIPS 2025
<i>Runmao Yao</i> , Junsheng Zhou, Yu-Shen Liu	
[2] <b>AirRoom: Objects Matter in Room Reidentification</b> (arXiv <a href="#">🔗</a> )	CVPR 2025
<i>Runmao Yao</i> , Yi Du, Zhuoqun Chen, Haoze Zheng, Chen Wang	
[3] <b>SuperPC: A Single Diffusion Model for Point Cloud Completion, Upsampling, Denoising, and Colorization</b> (arXiv <a href="#">🔗</a> )	CVPR 2025
Yi Du, Zhipeng Zhao, Shaoshu Su, Sharath Golluri, Haoze Zheng, <i>Runmao Yao</i> , Chen Wang	

## Research Experiences

<b>Single-View Indoor Scene Synthesis (3D Computer Vision)</b>	<i>Tsinghua University</i>
Supervisor: Prof. Yu-Shen Liu <a href="#">🔗</a>	Dec 2024 – Jun 2025

- **Task:** Generate a complete 360° indoor scene from a single-view input image.
- Proposed AnchoredDream, a novel pipeline that grounds scene appearance generation on high-quality geometry for single-view indoor scene synthesis with full 360° capability.
- Introduced an appearance-geometry mutual boosting mechanism and designed a novel Grouting Block to seamlessly blend the boundary between the input view and the synthesized scene, enhancing the consistency between scene appearances and geometry.
- Extensive experiments show that AnchoredDream, without any training or fine-tuning, outperforms existing methods in both appearance consistency and geometric plausibility.

<b>Room Reidentification (Computer Vision for Robotics)</b>	<i>University at Buffalo</i>
Supervisor: Prof. Chen Wang <a href="#">🔗</a>	Jul 2024 – Feb 2025

- **Task:** Retrieve the most similar room image from a large database given a query room image.
- Curated four comprehensive room reidentification datasets (MPReID, HMReID, GibsonReID, and ReplicaReID) with over 35000 images across diverse environments.
- Proposed AirRoom, an object-aware, coarse-to-fine pipeline integrating multi-level object information, from global context to object patches, segmentation, and keypoints.
- Extensive experiments demonstrated that AirRoom outperformed state-of-the-art models by 6% to 80% across nearly all evaluation metrics and exhibited robust performance under diverse viewpoint variations.

<b>Skill Discovery (Reinforcement Learning)</b>	<i>Tsinghua University</i>
Supervisor: Prof. Yi Wu <a href="#">🔗</a>	Mar 2024 – Aug 2024

- **Task:** Enable agents to learn diverse skills, where each skill corresponds to a distinct behavior.
- Reproduced key results from previous works, including LSD, CSD, and METRA.
- Proposed a novel approach by designing rewards based on trajectory segments rather than individual states.
- Developed an on-the-fly trajectory predictor and evaluator leveraging FLD.

## Awards and Honors

<b>Second Prize Scholarship for Incoming Students</b> , Tsinghua University	Dec 2021
<b>Third Prize in the Software Competition</b> , Tsinghua University	Jan 2022, Jun 2023
<b>Outstanding Admission Volunteer</b> , Tsinghua University	Jul 2022
<b>Sports Excellence Award</b> , Tsinghua University	Sep 2022
<b>Comprehensive Excellence Award</b> , Tsinghua University (Top 5%)	Sep 2023, Sep 2024

## Skills

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**Programming:** C, C++, Python, Java, HTML, CSS, JavaScript

**Techniques:** Pytorch, Mujoco, Docker, Git

**Languages:** English(Proficient), Chinese(Native)