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Дисциплина: «Объектно-ориентированное программирование»

Лабораторная работа №6.
Тема: «Аллокация памяти»

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Цель работы

Целью лабораторной работы является:

- Закрепление навыков по работе с памятью в C++.
- Создание аллокаторов памяти для динамических структур данных.

Задание

Используя структуры данных, разработанные для предыдущей лабораторной работы спроектировать и разработать аллокатор памяти для динамической структуры данных.

Цель построения аллокатора – минимизация вызова операции **malloc**. Аллокатор должен выделять большие блоки памяти для хранения фигур и при создании новых фигур-объектов выделять место под объекты в этой памяти.

Алокатор должен хранить списки использованных/свободных блоков. Для хранения списка свободных блоков нужно применять динамическую структуру данных (контейнер 2-го уровня, согласно варианта задания).

Для вызова аллокатора должны быть переопределены оператор **new** и **delete** у классов-фигур.

Нельзя использовать:

- Стандартные контейнеры std.

Программа должна позволять:

- Вводить произвольное количество фигур и добавлять их в контейнер.
- Распечатывать содержимое контейнера.
- Удалять фигуры из контейнера.

Выводы

Листинг

```
queue_item_impl.cpp:
template <class T>
QueueItem<T>::QueueItem(const std::shared_ptr<T>& item)
{
    m_item = item;
}

template <class T>
void QueueItem<T>::setNext(std::shared_ptr<QueueItem<T>> next)
{
    m_next = next;
}

template <class T>
std::shared_ptr<QueueItem<T>> QueueItem<T>::getNext()
{
    return m_next;
}

template <class T>
std::shared_ptr<T> QueueItem<T>::getItem() const
{
    return m_item;
}

trapezoid.h:
#ifndef TRAPEZOID_H
```

```

#define TRAPEZOID_H

#include <iostream>
#include "figure.h"

class Trapezoid : public Figure
{
public:
    Trapezoid();
    Trapezoid(std::istream& is);

    void print() const override;
    double area() const override;

    Trapezoid& operator = (const Trapezoid& other);
    bool operator == (const Trapezoid& other) const;

    void* operator new (size_t size);
    void operator delete (void* p);

    friend std::ostream& operator << (std::ostream& os, const Trapezoid& trapezoid);
    friend std::istream& operator >> (std::istream& is, Trapezoid& trapezoid);

private:
    double m_sideA;
    double m_sideB;
    double m_height;
};

#endif

list_item.h:
#ifndef LIST_ITEM_H
#define LIST_ITEM_H

#include <memory>

template <class T>
class ListItem
{
public:
    ListItem(const std::shared_ptr<T>& item);

    void setPrev(std::shared_ptr<ListItem<T>> prev);
    void setNext(std::shared_ptr<ListItem<T>> next);
    std::shared_ptr<ListItem<T>> getPrev();
    std::shared_ptr<ListItem<T>> getNext();
    std::shared_ptr<T> getItem() const;

private:
    std::shared_ptr<T> m_item;
    std::shared_ptr<ListItem<T>> m_prev;
    std::shared_ptr<ListItem<T>> m_next;
};

#include "list_item_impl.cpp"

#endif

queue_item.h:
#ifndef QUEUE_ITEM_H
#define QUEUE_ITEM_H

```

```

#include <memory>

template <class T>
class QueueItem
{
public:
    QueueItem(const std::shared_ptr<T>& item);

    void setNext(std::shared_ptr<QueueItem<T>> next);
    std::shared_ptr<QueueItem<T>> getNext();
    std::shared_ptr<T> getItem() const;

private:
    std::shared_ptr<T> m_item;
    std::shared_ptr<QueueItem<T>> m_next;
};

#include "queue_item_impl.cpp"

#endif

list_impl.cpp:
template <class T>
List<T>::List()
{
    m_size = 0;
}

template <class T>
List<T>::~~List()
{
    while (size() > 0)
        erase(begin());
}

template <class T>
void List<T>::add(const std::shared_ptr<T>& item)
{
    std::shared_ptr<ListItem<T>> itemPtr = std::make_shared<ListItem<T>>(item);

    if (m_size == 0)
    {
        m_begin = itemPtr;
        m_end = m_begin;
    }
    else
    {
        itemPtr->setPrev(m_end);
        m_end->setNext(itemPtr);
        m_end = itemPtr;
    }

    ++m_size;
}

template <class T>
void List<T>::erase(const Iterator<ListItem<T>, T>& it)
{
    if (m_size == 1)
    {
        m_begin = nullptr;
        m_end = nullptr;
    }
}

```

```

else
{
    std::shared_ptr<ListItem<T>> left = it.getItem()->getPrev();
    std::shared_ptr<ListItem<T>> right = it.getItem()->getNext();
    std::shared_ptr<ListItem<T>> mid = it.getItem();

    mid->setPrev(nullptr);
    mid->setNext(nullptr);

    if (left != nullptr)
        left->setNext(right);
    else
        m_begin = right;

    if (right != nullptr)
        right->setPrev(left);
    else
        m_end = left;
}

--m_size;
}

template <class T>
unsigned int List<T>::size() const
{
    return m_size;
}

template <class T>
Iterator<ListItem<T>, T> List<T>::get(unsigned int index) const
{
    if (index >= size())
        return end();

    Iterator<ListItem<T>, T> it = begin();

    while (index > 0)
    {
        ++it;
        --index;
    }

    return it;
}

template <class T>
Iterator<ListItem<T>, T> List<T>::begin() const
{
    return Iterator<ListItem<T>, T>(m_begin);
}

template <class T>
Iterator<ListItem<T>, T> List<T>::end() const
{
    return Iterator<ListItem<T>, T>(nullptr);
}

template <class K>
std::ostream& operator << (std::ostream& os, const List<K>& list)
{
    if (list.size() == 0)
    {

```

```

        os << "=====" << std::endl;
        os << "List is empty" << std::endl;
    }
    else
        for (std::shared_ptr<K> item : list)
            item->print();

    return os;
}

```

square.h:

```

#ifndef SQUARE_H
#define SQUARE_H

```

```

#include <iostream>
#include "figure.h"

```

```

class Square : public Figure

```

```

{
public:

```

```

    Square();
    Square(std::istream& is);

```

```

    void print() const override;
    double area() const override;

```

```

    Square& operator = (const Square& other);
    bool operator == (const Square& other) const;

```

```

    void* operator new (size_t size);
    void operator delete (void* p);

```

```

    friend std::ostream& operator << (std::ostream& os, const Square& square);
    friend std::istream& operator >> (std::istream& is, Square& square);

```

```

private:

```

```

    double m_side;

```

```

};

```

```

#endif

```

trapezoid.cpp:

```

#include "trapezoid.h"

```

```

Trapezoid::Trapezoid()

```

```

{
    m_sideA = 0.0;
    m_sideB = 0.0;
    m_height = 0.0;
}

```

```

Trapezoid::Trapezoid(std::istream& is)

```

```

{
    is >> *this;
}

```

```

void Trapezoid::print() const

```

```

{
    std::cout << *this;
}

```

```

double Trapezoid::area() const

```

```

{

```

```

        return m_height * (m_sideA + m_sideB) / 2.0;
    }

Trapezoid& Trapezoid::operator = (const Trapezoid& other)
{
    if (&other == this)
        return *this;

    m_sideA = other.m_sideA;
    m_sideB = other.m_sideB;
    m_height = other.m_height;

    return *this;
}

bool Trapezoid::operator == (const Trapezoid& other) const
{
    return m_sideA == other.m_sideA && m_sideB == other.m_sideB && m_height == other.m_height;
}

void* Trapezoid::operator new (size_t size)
{
    return Figure::allocator.allocate();
}

void Trapezoid::operator delete (void* p)
{
    Figure::allocator.deallocate(p);
}

std::ostream& operator << (std::ostream& os, const Trapezoid& trapezoid)
{
    os << "=====" << std::endl;
    os << "Figure type: trapezoid" << std::endl;
    os << "Side A size: " << trapezoid.m_sideA << std::endl;
    os << "Side B size: " << trapezoid.m_sideB << std::endl;
    os << "Height: " << trapezoid.m_height << std::endl;

    return os;
}

std::istream& operator >> (std::istream& is, Trapezoid& trapezoid)
{
    std::cout << "=====" << std::endl;
    std::cout << "Enter side A: ";
    is >> trapezoid.m_sideA;
    std::cout << "Enter side B: ";
    is >> trapezoid.m_sideB;
    std::cout << "Enter height: ";
    is >> trapezoid.m_height;

    return is;
}

```

```

allocator.h:
#ifndef ALLOCATOR_H
#define ALLOCATOR_H

#include <cstdlib>
#include "list.h"

#define R_CAST(__ptr, __type) reinterpret_cast<__type>(__ptr)

```

```

class Allocator
{
public:
    Allocator(unsigned int blockSize, unsigned int count);
    ~Allocator();

    void* allocate();
    void deallocate(void* p);
    bool hasFreeBlocks() const;

private:
    void* m_memory;
    List<unsigned int> m_freeBlocks;
};

#endif

rectangle.h:
#ifndef RECTANGLE_H
#define RECTANGLE_H

#include <iostream>
#include "figure.h"

class Rectangle : public Figure
{
public:
    Rectangle();
    Rectangle(std::istream& is);

    void print() const override;
    double area() const override;

    Rectangle& operator = (const Rectangle& other);
    bool operator == (const Rectangle& other) const;

    void* operator new (size_t size);
    void operator delete (void* p);

    friend std::ostream& operator << (std::ostream& os, const Rectangle& rectangle);
    friend std::istream& operator >> (std::istream& is, Rectangle& rectangle);

private:
    double m_sideA;
    double m_sideB;
};

#endif

allocator.cpp:
#include "allocator.h"

Allocator::Allocator(unsigned int blockSize, unsigned int count)
{
    m_memory = malloc(blockSize * count);

    for (unsigned int i = 0; i < count; ++i)
        m_freeBlocks.add(std::make_shared<unsigned int>(i * blockSize));
}

Allocator::~~Allocator()
{
    free(m_memory);
}

```



```

}

void* Allocator::allocate()
{
    void* res = R_CAST(R_CAST(m_memory, char*) + **m_freeBlocks.get(0), void*);

    m_freeBlocks.erase(m_freeBlocks.begin());

    return res;
}

void Allocator::deallocate(void* p)
{
    unsigned int offset = R_CAST(p, char*) - R_CAST(m_memory, char*);

    m_freeBlocks.add(std::make_shared<unsigned int>(offset));
}

bool Allocator::hasFreeBlocks() const
{
    return m_freeBlocks.size() > 0;
}

queue_impl.cpp:
template <class T>
Queue<T>::Queue()
{
    m_size = 0;
}

template <class T>
Queue<T>::~~Queue()
{
    while (size() > 0)
        pop();
}

template <class T>
void Queue<T>::push(const std::shared_ptr<T>& item)
{
    std::shared_ptr<QueueItem<T>> itemPtr = std::make_shared<QueueItem<T>>(item);

    if (m_size == 0)
    {
        m_front = itemPtr;
        m_end = m_front;
    }
    else
    {
        m_end->setNext(itemPtr);
        m_end = itemPtr;
    }

    ++m_size;
}

template <class T>
void Queue<T>::pop()
{
    if (m_size == 1)
    {
        m_front = nullptr;
        m_end = nullptr;
    }
}

```

```

        }
        else
            m_front = m_front->getNext();

        --m_size;
    }

template <class T>
unsigned int Queue<T>::size() const
{
    return m_size;
}

template <class T>
std::shared_ptr<T> Queue<T>::front() const
{
    return m_front->getItem();
}

template <class T>
Iterator<QueueItem<T>, T> Queue<T>::begin() const
{
    return Iterator<QueueItem<T>, T>(m_front);
}

template <class T>
Iterator<QueueItem<T>, T> Queue<T>::end() const
{
    return Iterator<QueueItem<T>, T>(nullptr);
}

template <class K>
std::ostream& operator << (std::ostream& os, const Queue<K>& queue)
{
    if (queue.size() == 0)
    {
        os << "=====" << std::endl;
        os << "Queue is empty" << std::endl;
    }
    else
        for (std::shared_ptr<K> item : queue)
            item->print();

    return os;
}

list_item_impl.cpp:
template <class T>
ListItem<T>::ListItem(const std::shared_ptr<T>& item)
{
    m_item = item;
}

template <class T>
void ListItem<T>::setPrev(std::shared_ptr<ListItem<T>> prev)
{
    m_prev = prev;
}

template <class T>
void ListItem<T>::setNext(std::shared_ptr<ListItem<T>> next)
{
    m_next = next;
}

```

```

}

template <class T>
std::shared_ptr<ListItem<T>> ListItem<T>::getPrev()
{
    return m_prev;
}

template <class T>
std::shared_ptr<ListItem<T>> ListItem<T>::getNext()
{
    return m_next;
}

template <class T>
std::shared_ptr<T> ListItem<T>::getItem() const
{
    return m_item;
}

figure.h:
#ifndef FIGURE_H
#define FIGURE_H

#include "allocator.h"

class Figure
{
public:
    virtual ~Figure() {}
    virtual void print() const = 0;
    virtual double area() const = 0;

    static Allocator allocator;
};

#endif

iterator_impl.cpp:
template <class N, class T>
Iterator<N, T>::Iterator(const std::shared_ptr<N>& item)
{
    m_item = item;
}

template <class N, class T>
std::shared_ptr<N> Iterator<N, T>::getItem() const
{
    return m_item;
}

template <class N, class T>
std::shared_ptr<T> Iterator<N, T>::operator * ()
{
    return m_item->getItem();
}

template <class N, class T>
std::shared_ptr<T> Iterator<N, T>::operator -> ()
{
    return m_item->getItem();
}

```

```

template <class N, class T>
Iterator<N, T> Iterator<N, T>::operator ++ ()
{
    m_item = m_item->getNext();

    return *this;
}

template <class N, class T>
Iterator<N, T> Iterator<N, T>::operator ++ (int index)
{
    Iterator tmp(m_item);

    m_item = m_item->getNext();

    return tmp;
}

template <class N, class T>
bool Iterator<N, T>::operator == (const Iterator& other) const
{
    return m_item == other.m_item;
}

template <class N, class T>
bool Iterator<N, T>::operator != (const Iterator& other) const
{
    return !(*this == other);
}

```

queue.h:

```

#ifndef QUEUE_H
#define QUEUE_H

```

```

#include <iostream>
#include "queue_item.h"
#include "iterator.h"

```

```

template <class T>
class Queue
{
public:
    Queue();
    ~Queue();

    void push(const std::shared_ptr<T>& item);
    void pop();
    unsigned int size() const;
    std::shared_ptr<T> front() const;

    Iterator<QueueItem<T>, T> begin() const;
    Iterator<QueueItem<T>, T> end() const;

    template <class K>
    friend std::ostream& operator << (std::ostream& os, const Queue<K>& queue);

private:
    std::shared_ptr<QueueItem<T>> m_front;
    std::shared_ptr<QueueItem<T>> m_end;
    unsigned int m_size;
};

```

```

#include "queue_impl.cpp"

```

```

#endif

square.cpp:
#include "square.h"

Square::Square()
{
    m_side = 0.0;
}

Square::Square(std::istream& is)
{
    is >> *this;
}

void Square::print() const
{
    std::cout << *this;
}

double Square::area() const
{
    return m_side * m_side;
}

Square& Square::operator = (const Square& other)
{
    if (&other == this)
        return *this;

    m_side = other.m_side;

    return *this;
}

bool Square::operator == (const Square& other) const
{
    return m_side == other.m_side;
}

void* Square::operator new (size_t size)
{
    return Figure::allocator.allocate();
}

void Square::operator delete (void* p)
{
    Figure::allocator.deallocate(p);
}

std::ostream& operator << (std::ostream& os, const Square& square)
{
    os << "=====" << std::endl;
    os << "Figure type: square" << std::endl;
    os << "Side size: " << square.m_side << std::endl;

    return os;
}

std::istream& operator >> (std::istream& is, Square& square)
{
    std::cout << "=====" << std::endl;

```

```

        std::cout << "Enter side: ";
        is >> square.m_side;

        return is;
    }

list.h:
#ifndef LIST_H
#define LIST_H

#include <iostream>
#include "list_item.h"
#include "iterator.h"

template <class T>
class List
{
public:
    List();
    ~List();

    void add(const std::shared_ptr<T>& item);
    void erase(const Iterator<ListItem<T>, T>& it);
    unsigned int size() const;
    Iterator<ListItem<T>, T> get(unsigned int index) const;

    Iterator<ListItem<T>, T> begin() const;
    Iterator<ListItem<T>, T> end() const;

    template <class K>
    friend std::ostream& operator << (std::ostream& os, const List<K>& list);

private:
    std::shared_ptr<ListItem<T>> m_begin;
    std::shared_ptr<ListItem<T>> m_end;
    unsigned int m_size;
};

#include "list_impl.cpp"

#endif

makefile:
CC = g++
CFLAGS = -std=c++11 -Wall -Werror -Wno-sign-compare -Wno-unused-result
FILES = main.cpp square.cpp rectangle.cpp trapezoid.cpp figure.cpp allocator.cpp
PROG = lab6

all:
    $(CC) $(CFLAGS) -o $(PROG) $(FILES)

clean:
    rm $(PROG)

main.cpp:
#include "queue.h"
#include "square.h"
#include "rectangle.h"
#include "trapezoid.h"

int main()
{
    unsigned int action;

```

```
Queue<Figure> q;
```

```
while (true)
```

```
{
```

```
    std::cout << "=====" << std::endl;
```

```
    std::cout << "Menu:" << std::endl;
```

```
    std::cout << "1) Add figure" << std::endl;
```

```
    std::cout << "2) Delete figure" << std::endl;
```

```
    std::cout << "3) Print" << std::endl;
```

```
    std::cout << "0) Quit" << std::endl;
```

```
    std::cin >> action;
```

```
    if (action == 0)
```

```
        break;
```

```
    if (action > 3)
```

```
    {
```

```
        std::cout << "Error: invalid action" << std::endl;
```

```
        continue;
```

```
    }
```

```
    switch (action)
```

```
    {
```

```
        case 1:
```

```
        {
```

```
            if (!Figure::allocator.hasFreeBlocks())
```

```
                std::cout << "Error. No free blocks" << std::endl;
```

```
            else
```

```
            {
```

```
                unsigned int figureType;
```

```
                std::cout << "=====" << std::endl;
```

```
                std::cout << "1) Square" << std::endl;
```

```
                std::cout << "2) Rectangle" << std::endl;
```

```
                std::cout << "3) Trapezoid" << std::endl;
```

```
                std::cout << "0) Quit" << std::endl;
```

```
                std::cin >> figureType;
```

```
                if (figureType > 0)
```

```
                {
```

```
                    if (figureType > 3)
```

```
                    {
```

```
                        std::cout << "Error: invalid figure type" << std::endl;
```

```
                        continue;
```

```
                    }
```

```
                    switch (figureType)
```

```
                    {
```

```
                        case 1:
```

```
                        {
```

```
                            q.push(std::shared_ptr<Square>(new
```

```
Square(std::cin)));
```

```
                            break;
```

```
                        }
```

```
                        case 2:
```

```
                        {
```

```
                            q.push(std::shared_ptr<Rectangle>(new
```

```
Rectangle(std::cin)));
```

```

        break;
    }
    case 3:
    {
        q.push(std::shared_ptr<Trapezoid>(new
Trapezoid(std::cin)));
        break;
    }
}
}
}
break;
}
case 2:
{
    q.pop();
    break;
}
case 3:
{
    std::cout << q;
    break;
}
}
return 0;
}

```

rectangle.cpp:
#include "rectangle.h"

```

Rectangle::Rectangle()
{
    m_sideA = 0.0;
    m_sideB = 0.0;
}

```

```

Rectangle::Rectangle(std::istream& is)
{
    is >> *this;
}

```

```

void Rectangle::print() const
{
    std::cout << *this;
}

```

```

double Rectangle::area() const
{
    return m_sideA * m_sideB;
}

```

```

Rectangle& Rectangle::operator = (const Rectangle& other)
{
    if (&other == this)

```



```

        return *this;

        m_sideA = other.m_sideA;
        m_sideB = other.m_sideB;

        return *this;
}

bool Rectangle::operator == (const Rectangle& other) const
{
    return m_sideA == other.m_sideA && m_sideB == other.m_sideB;
}

void* Rectangle::operator new (size_t size)
{
    return Figure::allocator.allocate();
}

void Rectangle::operator delete (void* p)
{
    Figure::allocator.deallocate(p);
}

std::ostream& operator << (std::ostream& os, const Rectangle& rectangle)
{
    os << "=====" << std::endl;
    os << "Figure type: rectangle" << std::endl;
    os << "Side A size: " << rectangle.m_sideA << std::endl;
    os << "Side B size: " << rectangle.m_sideB << std::endl;

    return os;
}

std::istream& operator >> (std::istream& is, Rectangle& rectangle)
{
    std::cout << "=====" << std::endl;
    std::cout << "Enter side A: ";
    is >> rectangle.m_sideA;
    std::cout << "Enter side B: ";
    is >> rectangle.m_sideB;

    return is;
}

```

figure.cpp:
#include "figure.h"

Allocator Figure::allocator(32, 100);

iterator.h:
#ifndef ITERATOR_H
#define ITERATOR_H

```

template <class N, class T>
class Iterator
{
public:
    Iterator(const std::shared_ptr<N>& item);

    std::shared_ptr<N> getItem() const;

    std::shared_ptr<T> operator * ();
    std::shared_ptr<T> operator -> ();

```

```
Iterator operator ++ ();  
Iterator operator ++ (int index);  
bool operator == (const Iterator& other) const;  
bool operator != (const Iterator& other) const;
```

```
private:
```

```
    std::shared_ptr<N> m_item;
```

```
};
```

```
#include "iterator_impl.cpp"
```

```
#endif
```