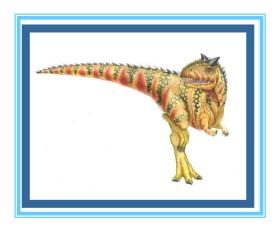
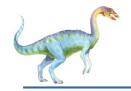
Threads Day5: March 2022

Kiran Waghmare





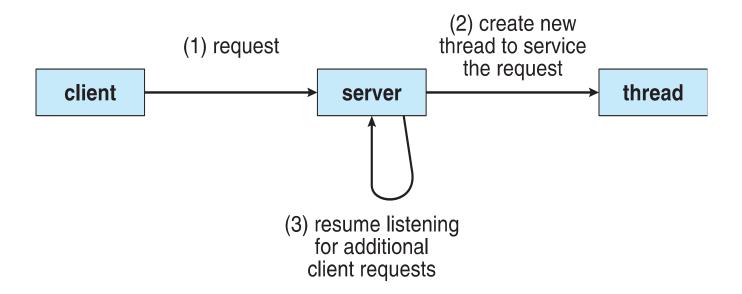
Threads

- Overview
- Multicore Programming
- Multithreading Models
- Thread Libraries





Multithreaded Server Architecture







Benefits

- Responsiveness may allow continued execution if part of process is blocked, especially important for user interfaces
- Resource Sharing threads share resources of process, easier than shared memory or message passing
- Economy cheaper than process creation, thread switching lower overhead than context switching
- Scalability process can take advantage of multiprocessor architectures





Multicore Programming

- Multicore or multiprocessor systems putting pressure on programmers, challenges include:
 - Dividing activities
 - Balance
 - Data splitting
 - Data dependency
 - Testing and debugging
- Parallelism implies a system can perform more than one task simultaneously
- **Concurrency** supports more than one task making progress
 - Single processor / core, scheduler providing concurrency





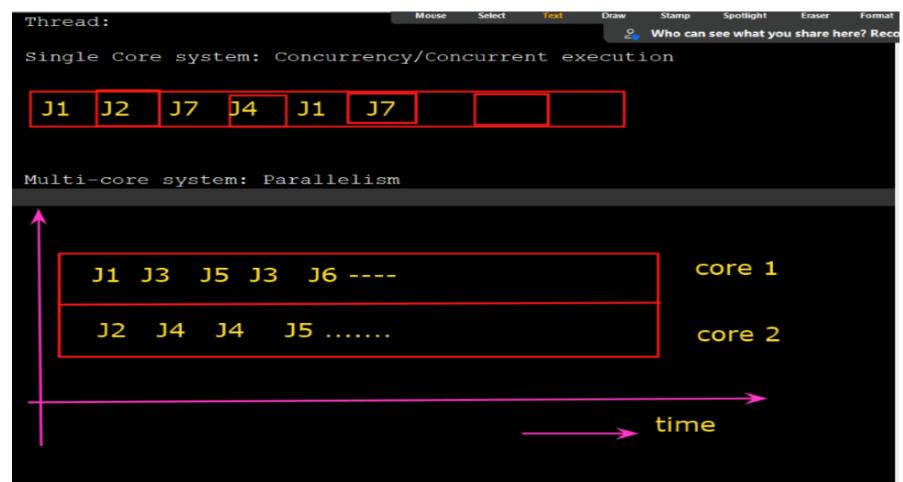
Multicore Programming (Cont.)

- Types of parallelism
 - Data parallelism distributes subsets of the same data across multiple cores, same operation on each
 - Task parallelism distributing threads across cores, each thread performing unique operation
- As # of threads grows, so does architectural support for threading
 - CPUs have cores as well as hardware threads
 - Consider Oracle SPARC T4 with 8 cores, and 8 hardware threads per core





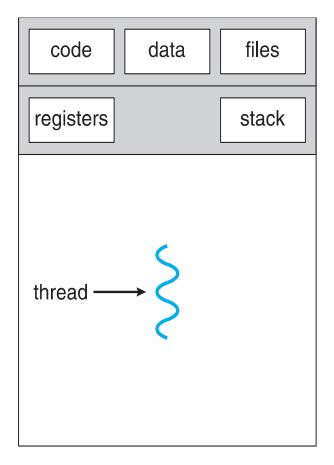
Concurrency vs. Parallelism



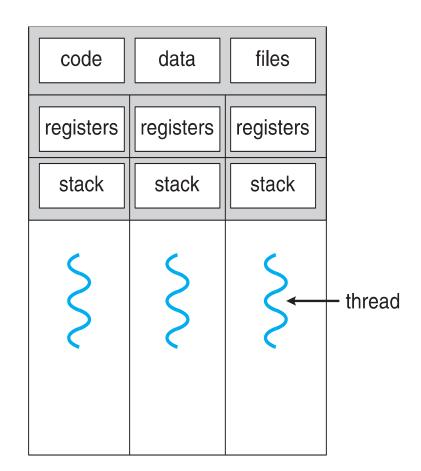




Single and Multithreaded Processes



single-threaded process



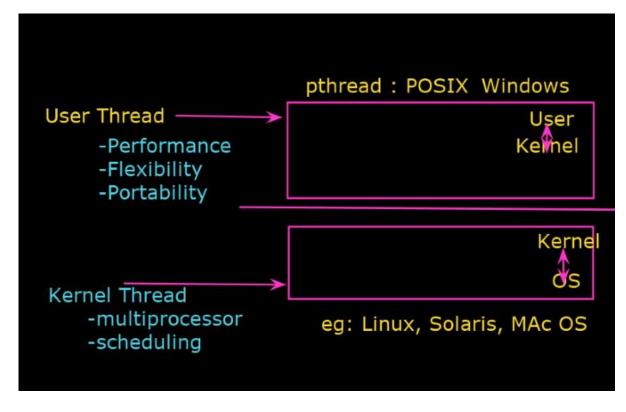
multithreaded process





Types of Thread

- There are two types of threads:
 - User Threads
 - Kernel Threads







User Threads and Kernel Threads

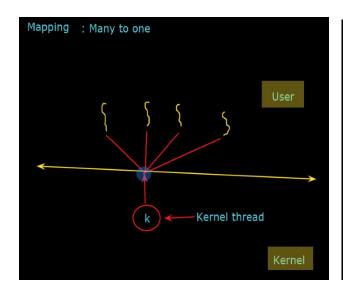
- User threads management done by user-level threads library
- Three primary thread libraries:
 - POSIX Pthreads
 - Windows threads
 - Java threads
- Kernel threads Supported by the Kernel
- Examples virtually all general purpose operating systems, including:
 - Windows
 - Solaris
 - Linux
 - Tru64 UNIX
 - Mac OS X

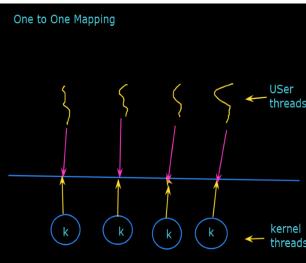


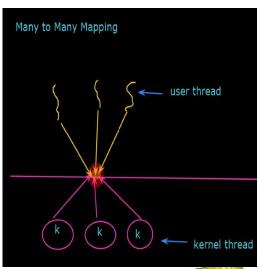


Multithreading Models

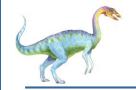
- Many-to-One
- One-to-One
- Many-to-Many





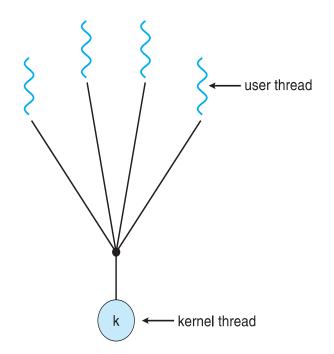






Many-to-One

- Many user-level threads mapped to single kernel thread
- One thread blocking causes all to block
- Multiple threads may not run in parallel on muticore system because only one may be in kernel at a time
- Few systems currently use this model
- Examples:
 - Solaris Green Threads
 - GNU Portable Threads

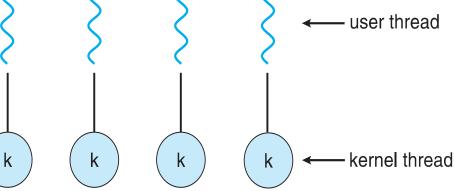






One-to-One

- Each user-level thread maps to kernel thread
- Creating a user-level thread creates a kernel thread
- More concurrency than many-to-one
- Number of threads per process sometimes restricted due to overhead
- Examples
 - Windows
 - Linux
 - Solaris 9 and later

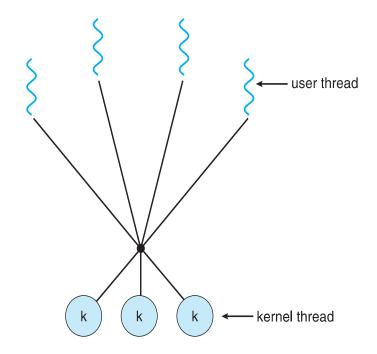






Many-to-Many Model

- Allows many user level threads to be mapped to many kernel threads
- Allows the operating system to create a sufficient number of kernel threads
- Solaris prior to version 9
- Windows with the ThreadFiber package

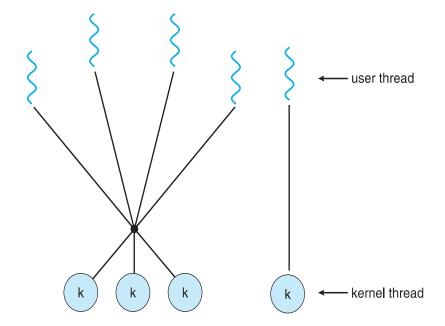






Two-level Model

- Similar to M:M, except that it allows a user thread to be **bound** to kernel thread
- Examples
 - IRIX
 - HP-UX
 - Tru64 UNIX
 - Solaris 8 and earlier



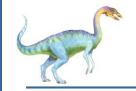




Thread Libraries

- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS



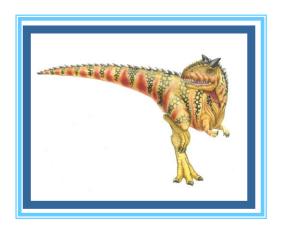


Pthreads

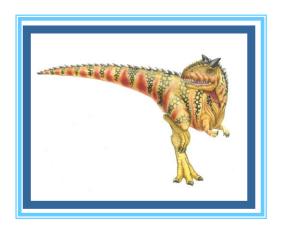
- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- Specification, not implementation
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Solaris, Linux, Mac OS X)

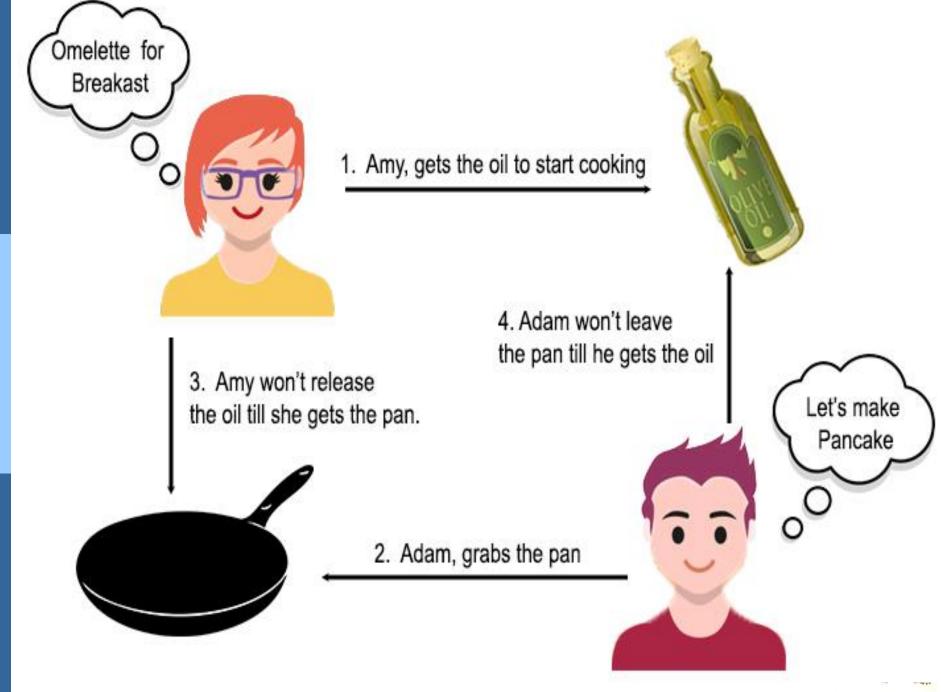


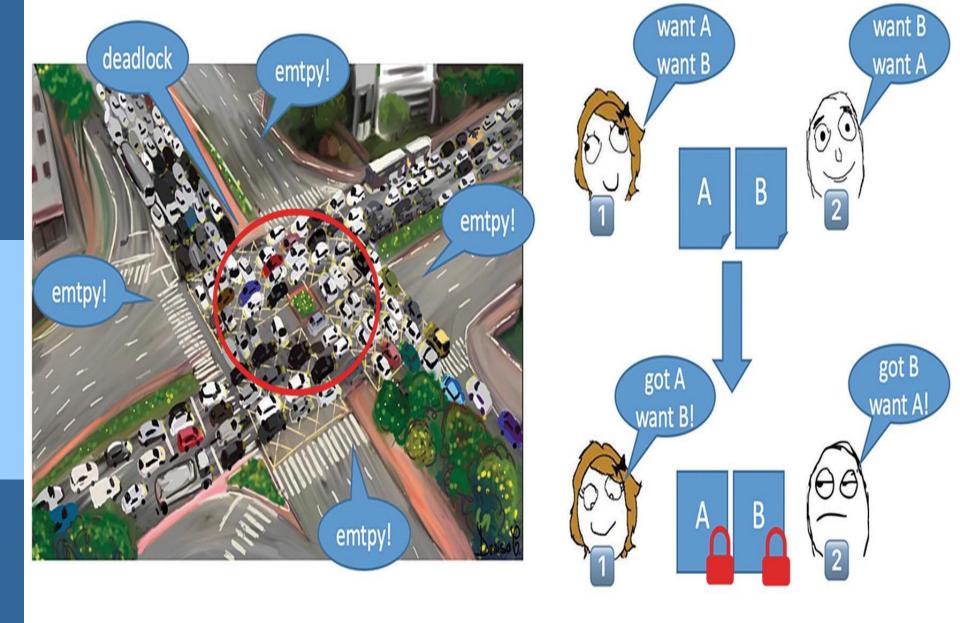
End of Chapter 4



Chapter 7: Deadlocks







(a) Deadlock in real life

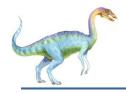
(b) Deadlock in virtual life

A process in Operating System uses different resources and uses resources in following way

-Request a resource

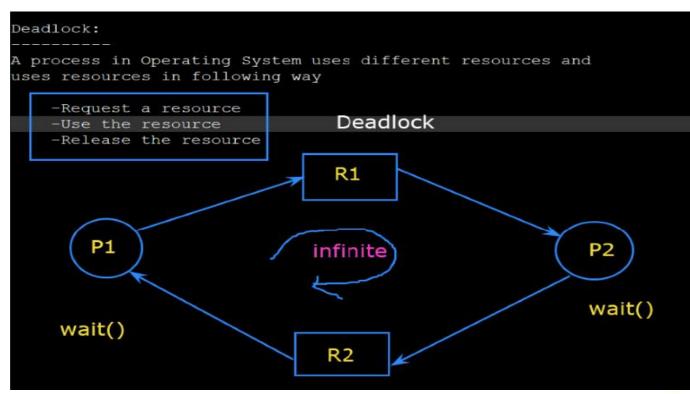
- -Use the resource
- -Release the resource

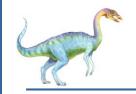
Deadlock: Resources, Process request use release



System Model

- System consists of resources
- Resource types $R_1, R_2, ..., R_m$ CPU cycles, memory space, I/O devices
- Each resource type R_i has W_i instances.
- Each process utilizes a resource as follows:
 - request
 - use
 - release

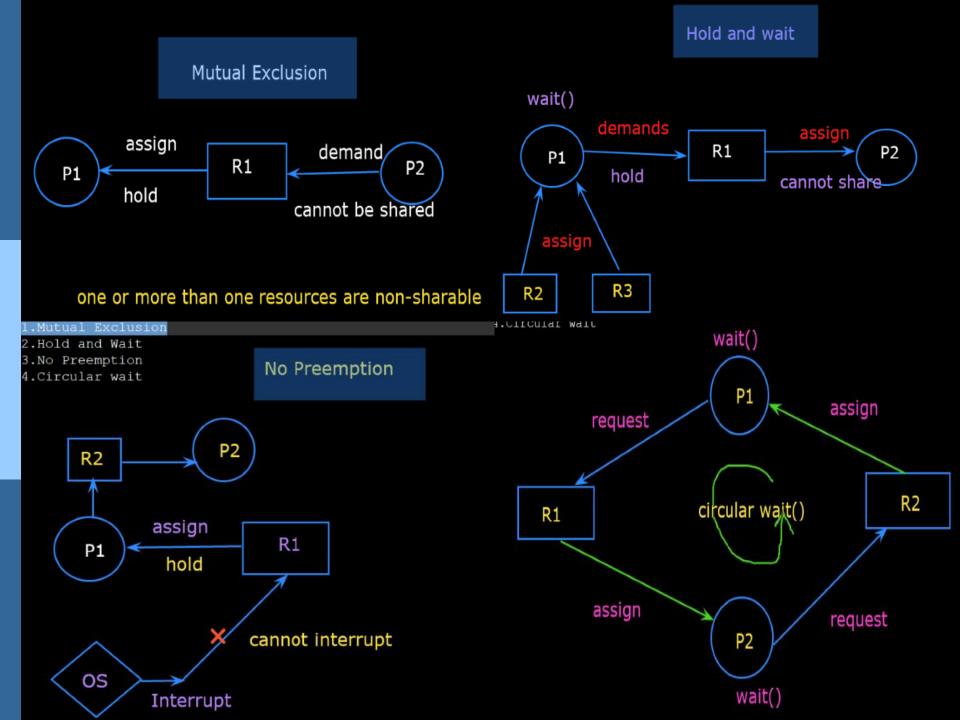




Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

- Mutual exclusion: only one process at a time can use a resource
- Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes
- No preemption: a resource can be released only voluntarily by the process holding it, after that process has completed its task
- Circular wait: there exists a set $\{P_0, P_1, ..., P_n\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1, P_1 is waiting for a resource that is held by $P_2, ..., P_{n-1}$ is waiting for a resource that is held by P_n , and P_n is waiting for a resource that is held by P_0 .



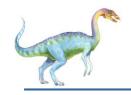


Resource-Allocation Graph

A set of vertices V and a set of edges E.

- V is partitioned into two types:
 - $P = \{P_1, P_2, ..., P_n\}$, the set consisting of all the processes in the system
 - $R = \{R_1, R_2, ..., R_m\}$, the set consisting of all resource types in the system
- request edge directed edge $P_i \rightarrow R_j$
- **assignment edge** directed edge $R_i \rightarrow P_i$





Resource-Allocation Graph (Cont.)

Process

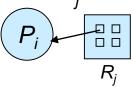


Resource Type with 4 instances



P_i requests instance of P_i P_i R_i

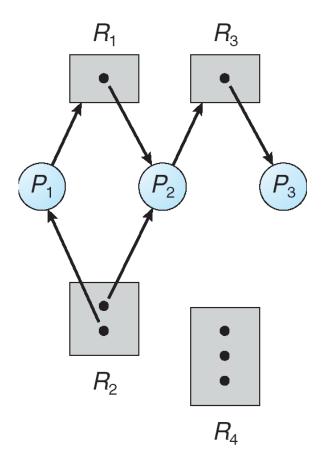
 \blacksquare P_i is holding an instance of R_i







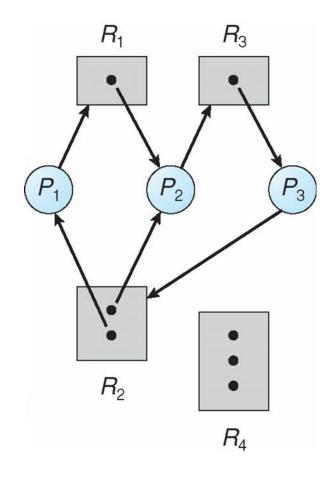
Example of a Resource Allocation Graph







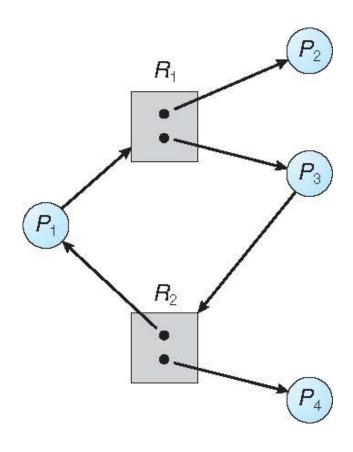
Resource Allocation Graph With A Deadlock



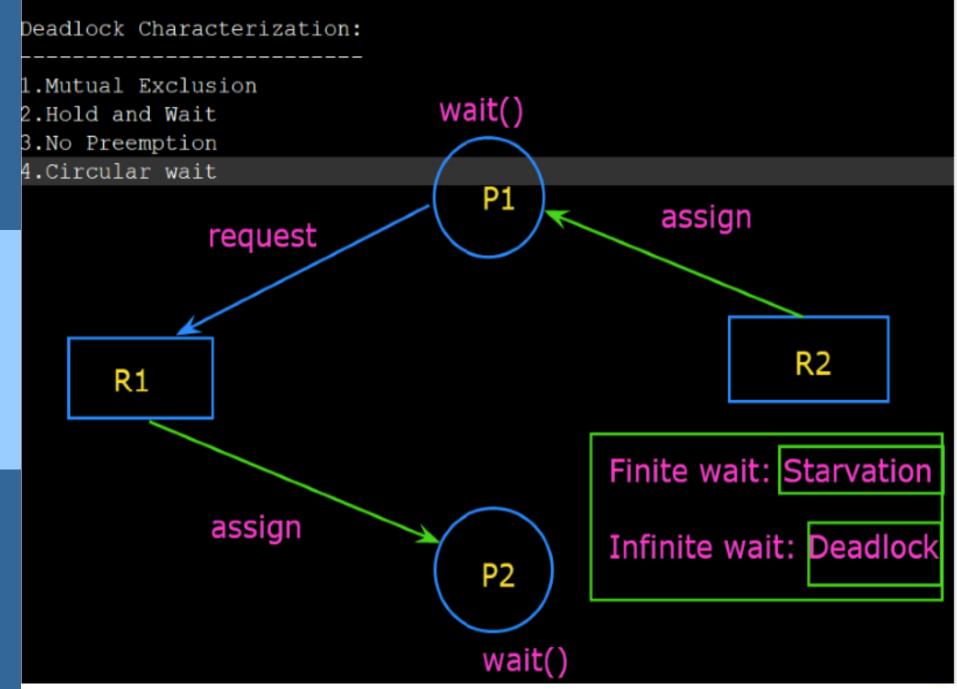




Graph With A Cycle But No Deadlock









Basic Facts

- If graph contains no cycles ⇒ no deadlock
- If graph contains a cycle ⇒
 - if only one instance per resource type, then deadlock
 - if several instances per resource type, possibility of deadlock





Methods for Handling Deadlocks

- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidence
- Allow the system to enter a deadlock state and then recover
- Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including UNIX





Deadlock Prevention

Restrain the ways request can be made

- Mutual Exclusion not required for sharable resources (e.g., read-only files); must hold for nonsharable resources
- Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources
 - Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.
 - Low resource utilization; starvation possible





Deadlock Prevention (Cont.)

■ No Preemption –

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released
- Preempted resources are added to the list of resources for which the process is waiting
- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting
- Circular Wait impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration



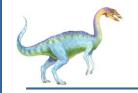


Deadlock Avoidance

Requires that the system has some additional *a priori* information available

- Simplest and most useful model requires that each process declare the *maximum number* of resources of each type that it may need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes





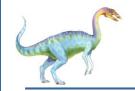
Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- System is in safe state if there exists a sequence $\langle P_1, P_2, ..., P_n \rangle$ of ALL the processes in the systems such that for each P_i , the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_i , with i < l

That is:

- If P_i resource needs are not immediately available, then P_i can wait until all P_i have finished
- When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on

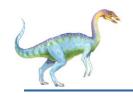




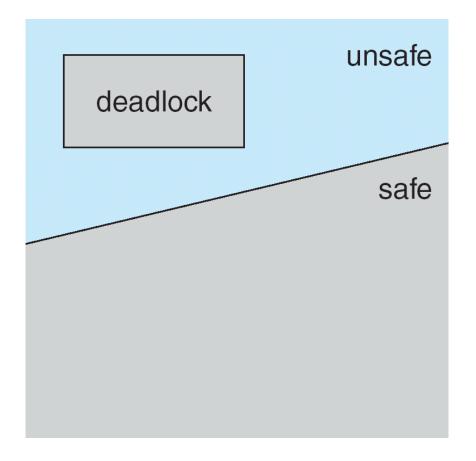
Basic Facts

- If a system is in safe state ⇒ no deadlocks
- If a system is in unsafe state ⇒ possibility of deadlock
- Avoidance ⇒ ensure that a system will never enter an unsafe state.

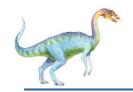




Safe, Unsafe, Deadlock State







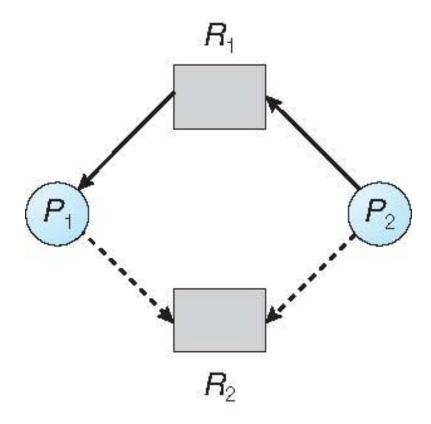
Avoidance Algorithms

- Single instance of a resource type
 - Use a resource-allocation graph
- Multiple instances of a resource type
 - Use the banker's algorithm





Resource-Allocation Graph



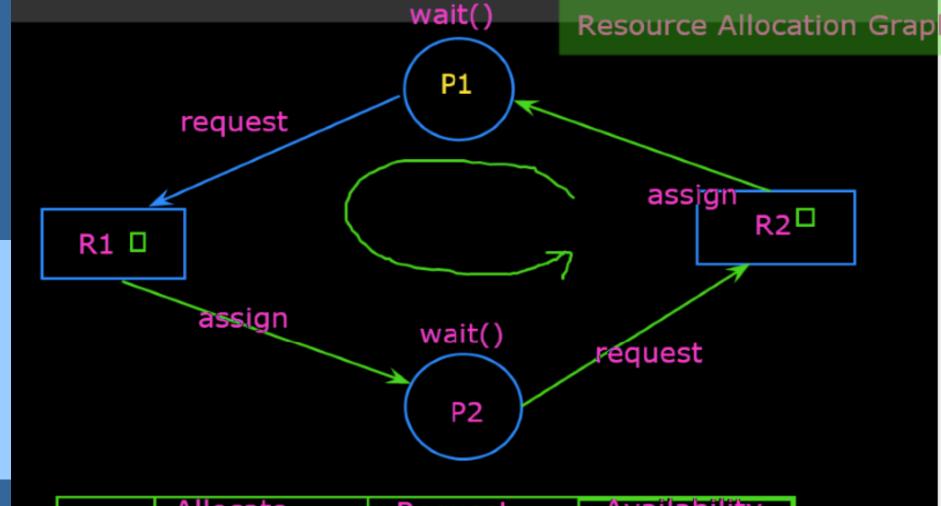




Resource-Allocation Graph Algorithm

- Suppose that process P_i requests a resource R_j
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph





	Allocate		Request		Avai	Availability	
	R1	R2	R1	R2	R1	R2	
P1	0	1	1	0	0	0	
P2	1	0	0	1			

Deadlock



Banker's Algorithm

- Multiple instances
- Each process must a priori claim maximum use
- When a process requests a resource it may have to wait
- When a process gets all its resources it must return them in a finite amount of time





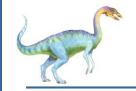
Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- Available: Vector of length m. If available [j] = k, there are k instances of resource type R_i available
- **Max**: $n \times m$ matrix. If Max[i,j] = k, then process P_i may request at most k instances of resource type R_i
- Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i is currently allocated k instances of R_j
- **Need**: $n \times m$ matrix. If Need[i,j] = k, then P_i may need k more instances of R_i to complete its task

Need[i,j] = Max[i,j] - Allocation[i,j]





Safety Algorithm

1. Let **Work** and **Finish** be vectors of length *m* and *n*, respectively. Initialize:

Work = Available
Finish
$$[i]$$
 = false for $i = 0, 1, ..., n-1$

- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$ If no such *i* exists, go to step 4
- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If **Finish** [i] == true for all i, then the system is in a safe state





Resource-Request Algorithm for Process P_i

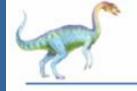
 $Request_i = request \ vector for process P_i$. If $Request_i[j] = k$ then process P_i wants k instances of resource type R_i

- If Request_i ≤ Need_i go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
- 2. If $Request_i \le Available$, go to step 3. Otherwise P_i must wait, since resources are not available
- 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

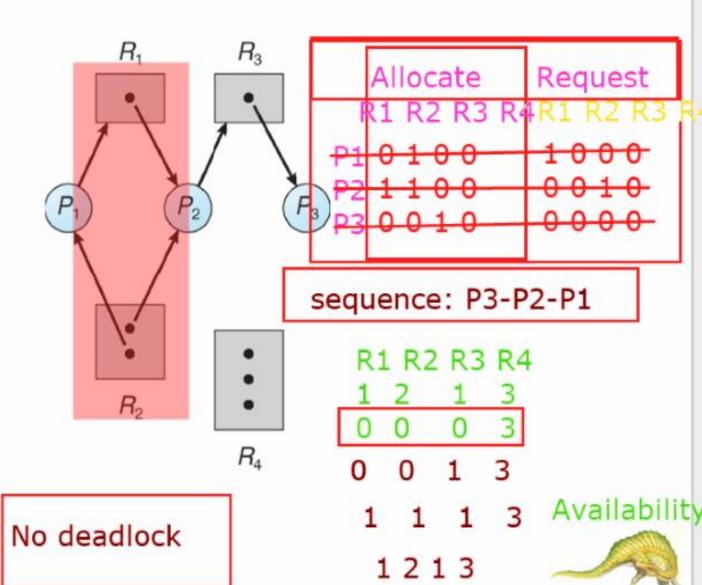
Available = Available - Request_i; Allocation_i = Allocation_i + Request_i; Need_i = Need_i - Request_i;

- If safe ⇒ the resources are allocated to P_i
- If unsafe $\Rightarrow P_i$ must wait, and the old resource-allocation state is restored





Example of a Resource Allocation Graphraph



R1:1 R2:2

R3:1

R4:3

P1:



Example of Banker's Algorithm

■ 5 processes P_0 through P_4 ;

3 resource types:

A (10 instances), B (5instances), and C (7 instances)

Snapshot at time T_0 :

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	753	3 3 2
P_1	200	322	
P_2	302	902	
P_3	211	222	
P_4	002	4 3 3	





Example (Cont.)

The content of the matrix *Need* is defined to be *Max* – *Allocation*

$$\frac{Need}{ABC}$$
 ABC
 P_0 743
 P_1 122
 P_2 600
 P_3 011
 P_4 431

■ The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria



Example: P_1 Request (1,0,2)

■ Check that Request \leq Available (that is, $(1,0,2) \leq (3,3,2) \Rightarrow$ true

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	7 4 3	230
P_1	302	020	
P_2	302	600	
P_3	211	0 1 1	
P_4	002	4 3 1	

- Executing safety algorithm shows that sequence $< P_1, P_3, P_4, P_0, P_2>$ satisfies safety requirement
- Can request for (3,3,0) by P_4 be granted?
- Can request for (0,2,0) by P_0 be granted?





Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme

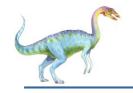




Recovery from Deadlock: Process Termination

- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated
- In which order should we choose to abort?
 - 1. Priority of the process
 - How long process has computed, and how much longer to completion
 - Resources the process has used
 - 4. Resources process needs to complete
 - 5. How many processes will need to be terminated
 - 6. Is process interactive or batch?





Recovery from Deadlock: Resource Preemption

- Selecting a victim minimize cost
- Rollback return to some safe state, restart process for that state
- Starvation same process may always be picked as victim, include number of rollback in cost factor



End of Chapter 7

