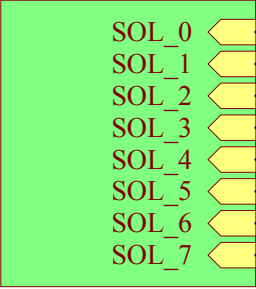
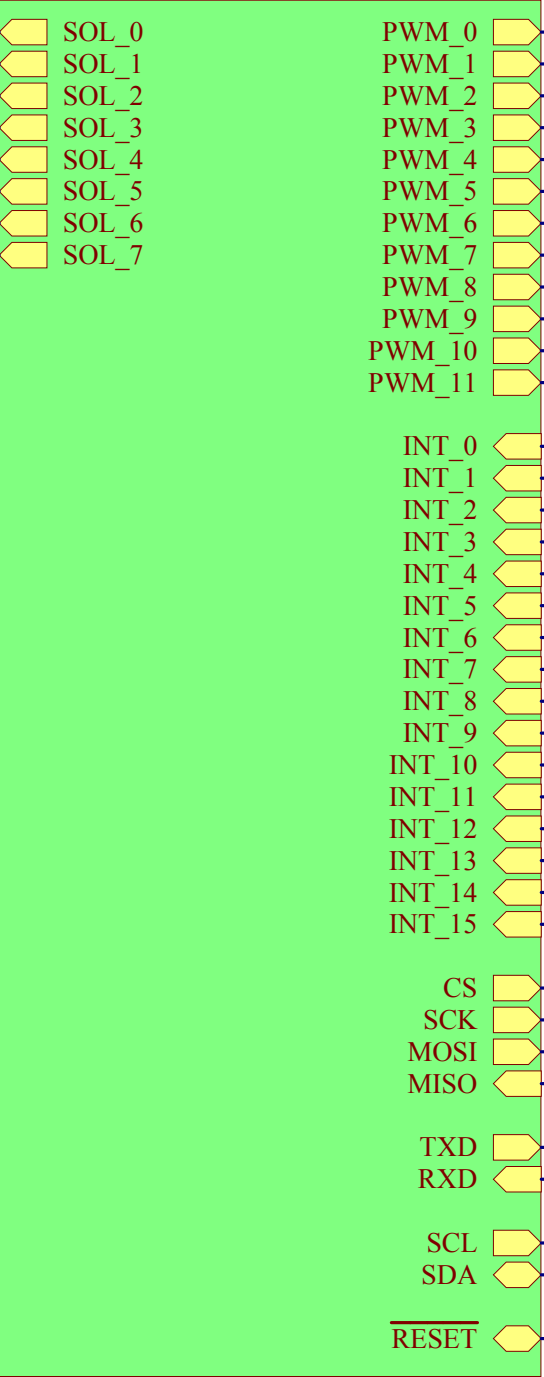


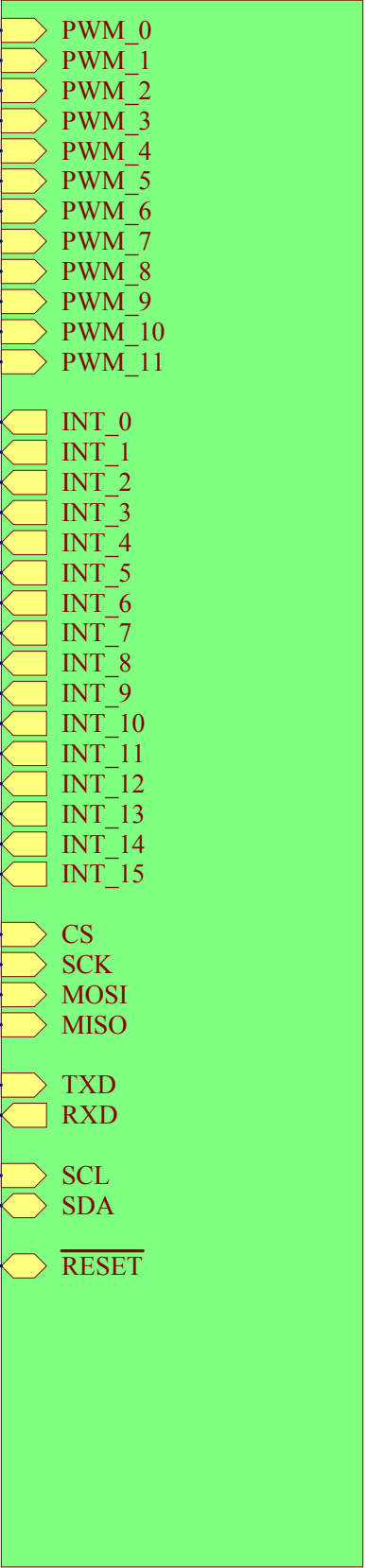
Solenoid Drive Circuits
Solenoids.SchDoc



MicroController
Co-Processor.SchDoc



Connectors
Connectors.SchDoc



Power
Power.SchDoc



▲ Co-Processor Signals (STMF103...)
12 PWM
8 Solenoid outputs
8 Encoder Inputs (16 external interrupts)

YUN Processor Signals
12-14 DIO
6 Analog Inputs

Co-Processor & YUN Signals
1 I2C
1 SPI
1 USART

▲ 0.499" mil distance between the two boards
0.416" length of the pins below the board surface

Top Level

Size: A

Date: 6/13/2014

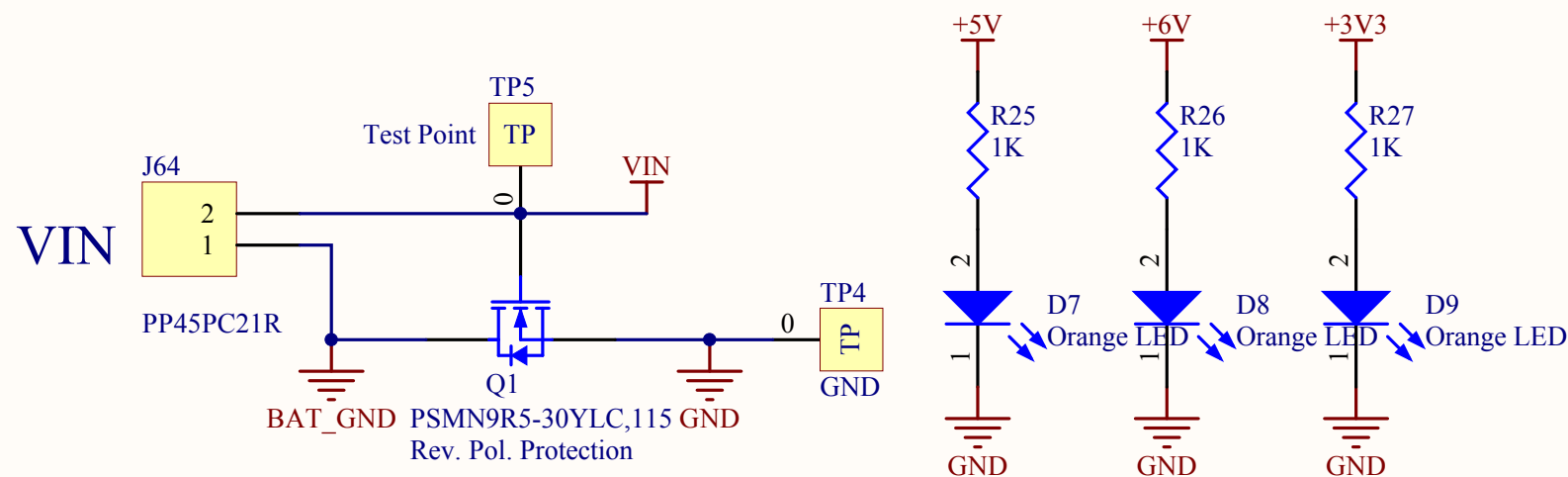
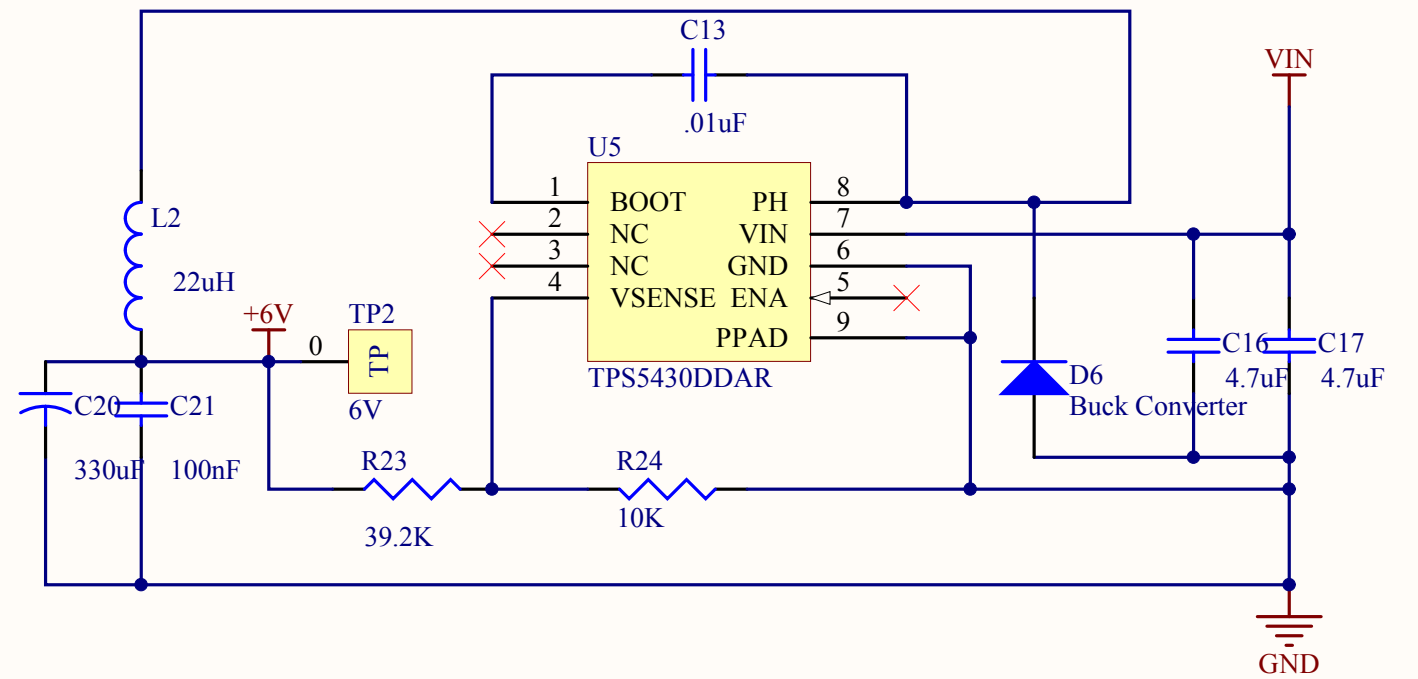
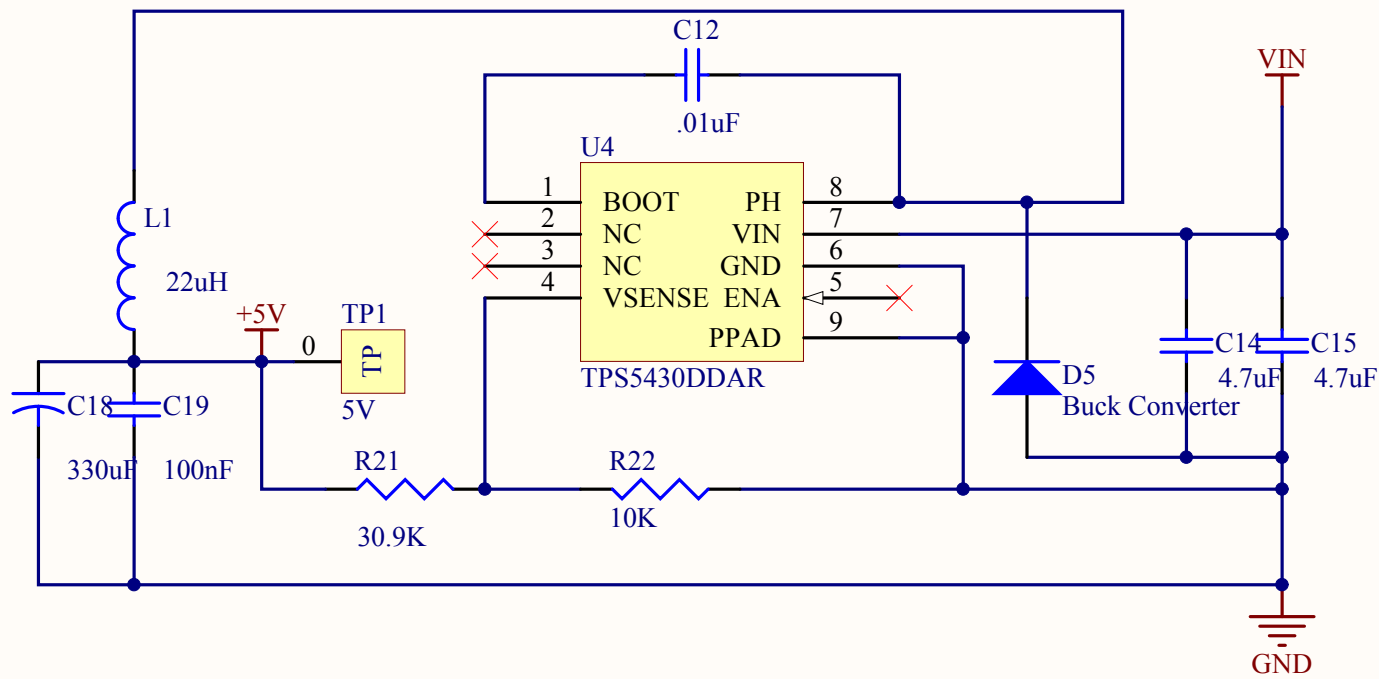
Revision: 1.0

Engineer: K. Chambls

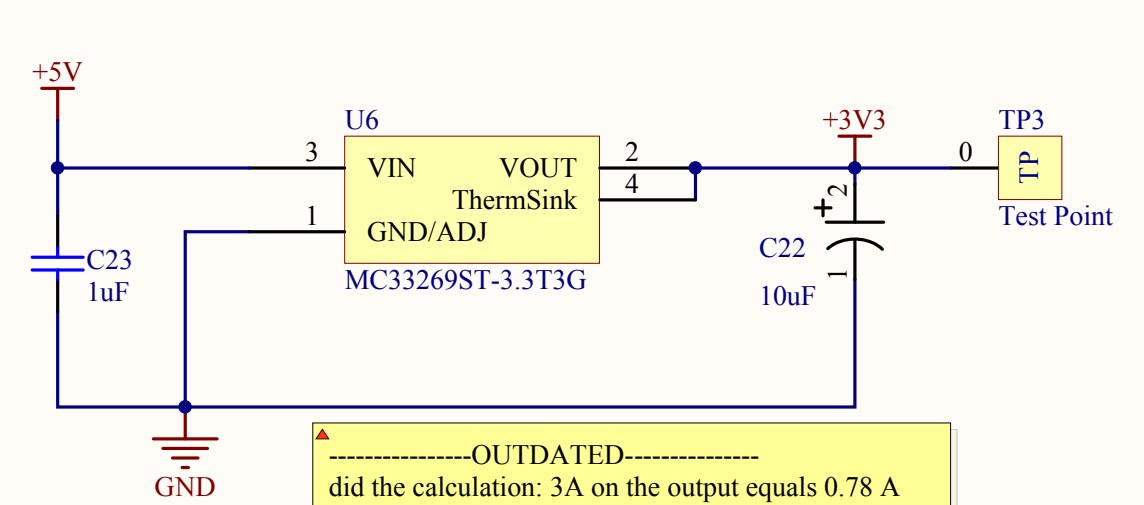
Sheet: 1 of 5

Drawn By: K. Chambls





-----OUTDATED-----
The maximum output voltage, given a minimum input voltage of 6V with a variety of output currents, ranges from 5.13 V (when I_o = 0.1 A) to 4.46 V (when I_o = 3 A)

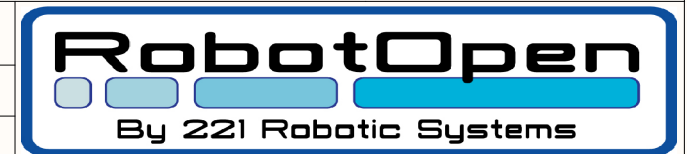
$$V_{outmax} = 0.87 * ((V_{inmin} - I_{omax} * 0.230) + V_d) (I_{omax} * R_L) - V_d$$


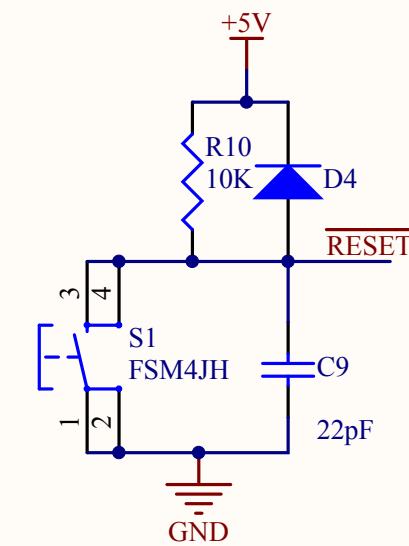
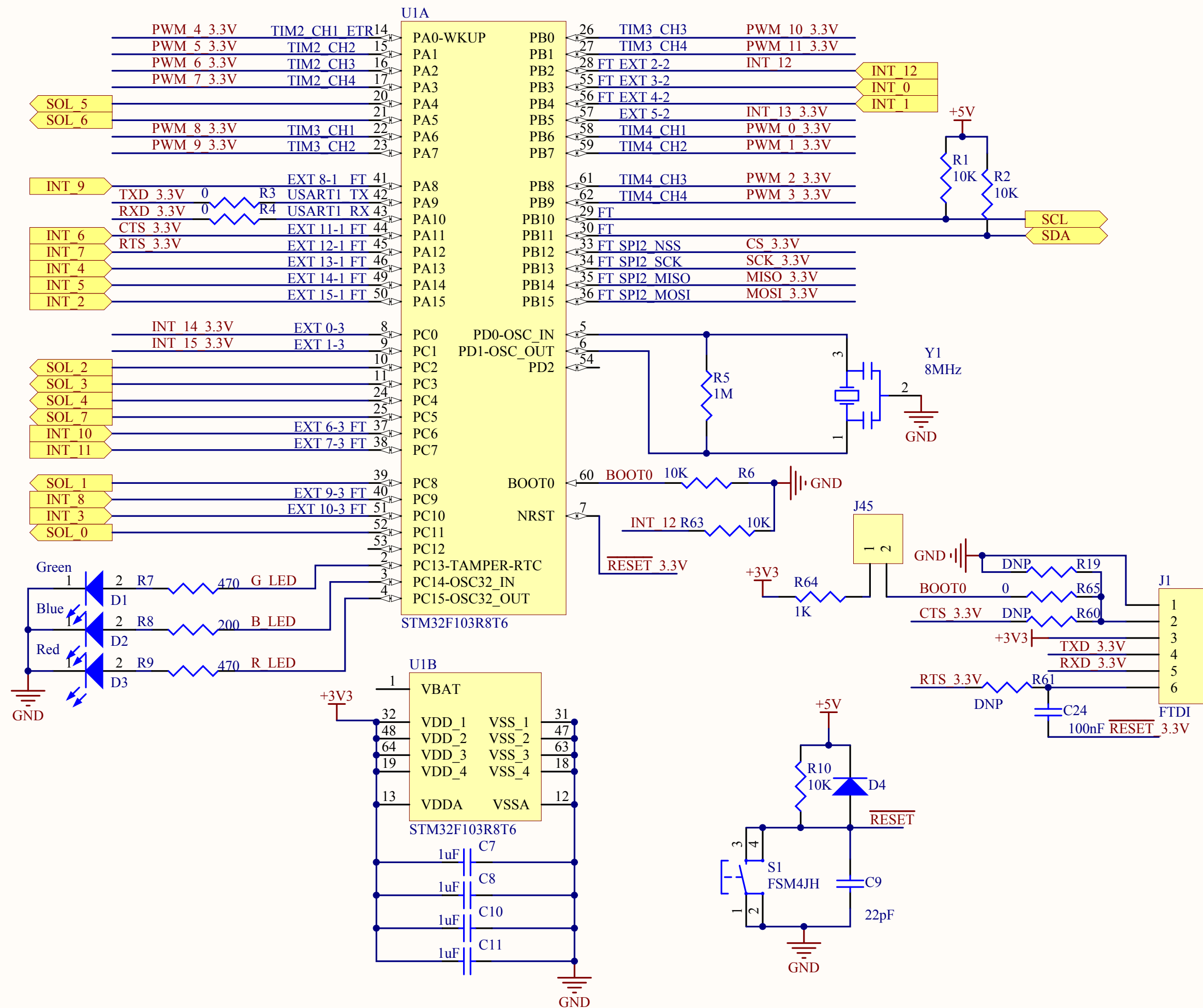
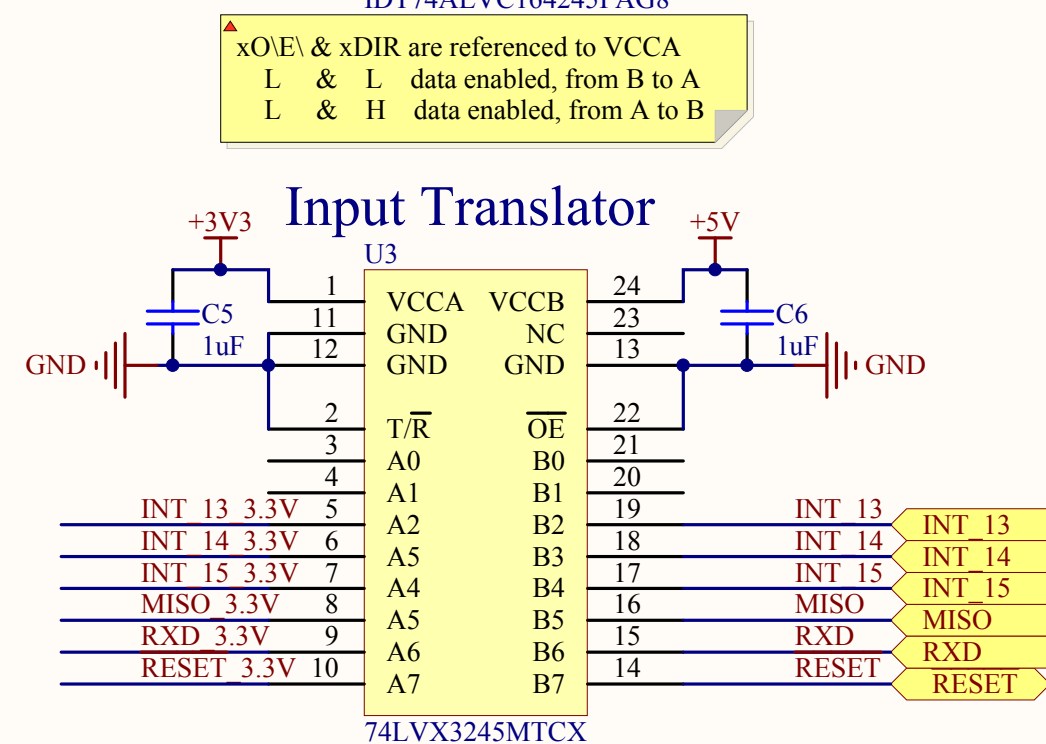
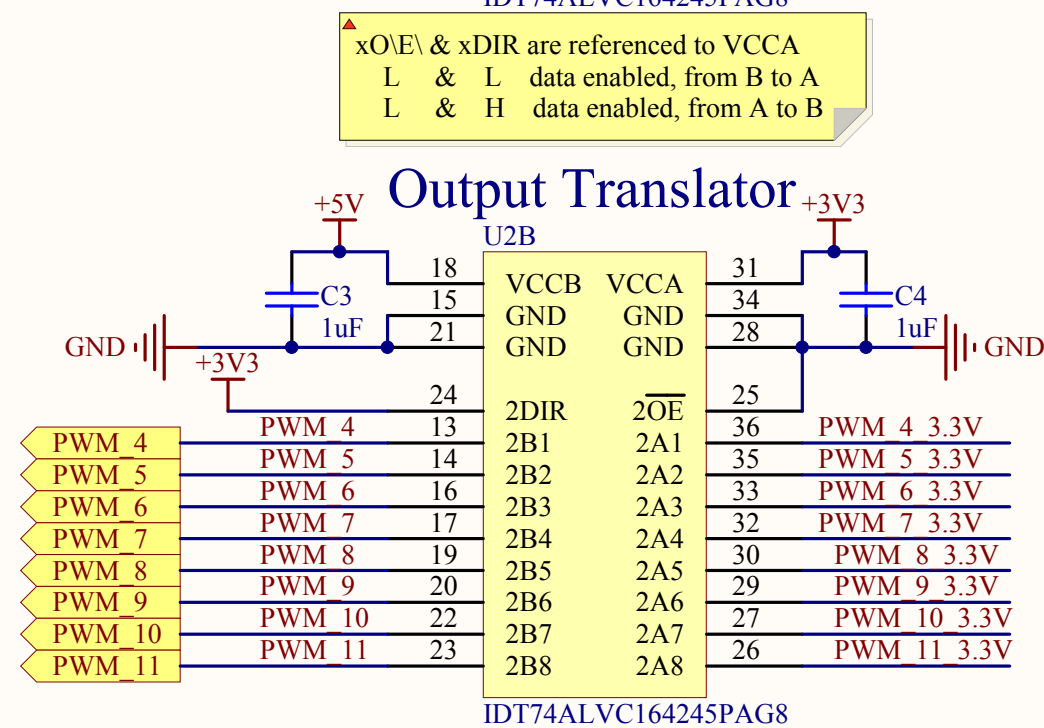
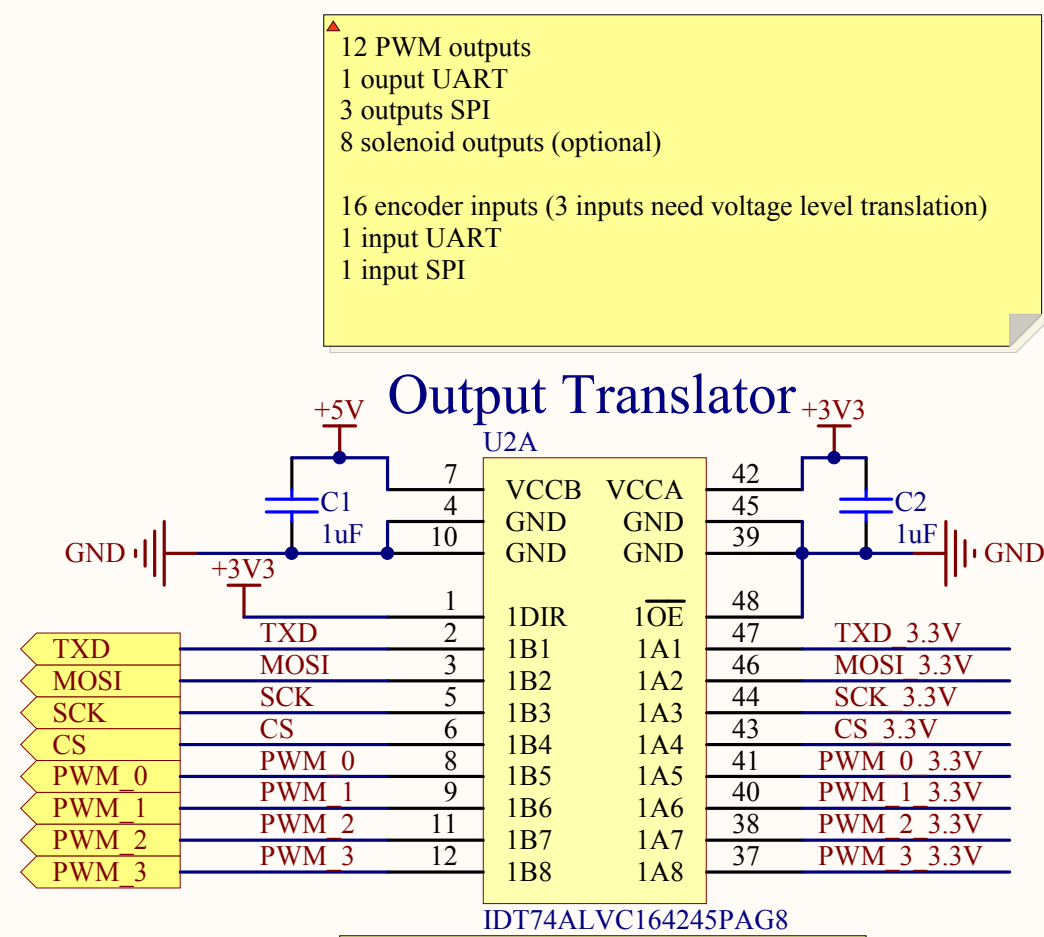
-----OUTDATED-----
did the calculation: 3A on the output equals 0.78 A on the input for 5V and 0.94A on the input for 6V

that is with 80% efficient and it should be higher than this, so we are good, I have a trace width available for about 7A, therefore 4A on Solenoid, plus 2A on 5V & 6V brings us to 6

Power

Size: A	Date: 6/13/2014	Revision: 1.0
Engineer: K. Chambls	Sheet: 2	of 5
Drawn By: K. Chambls		





A

B

C

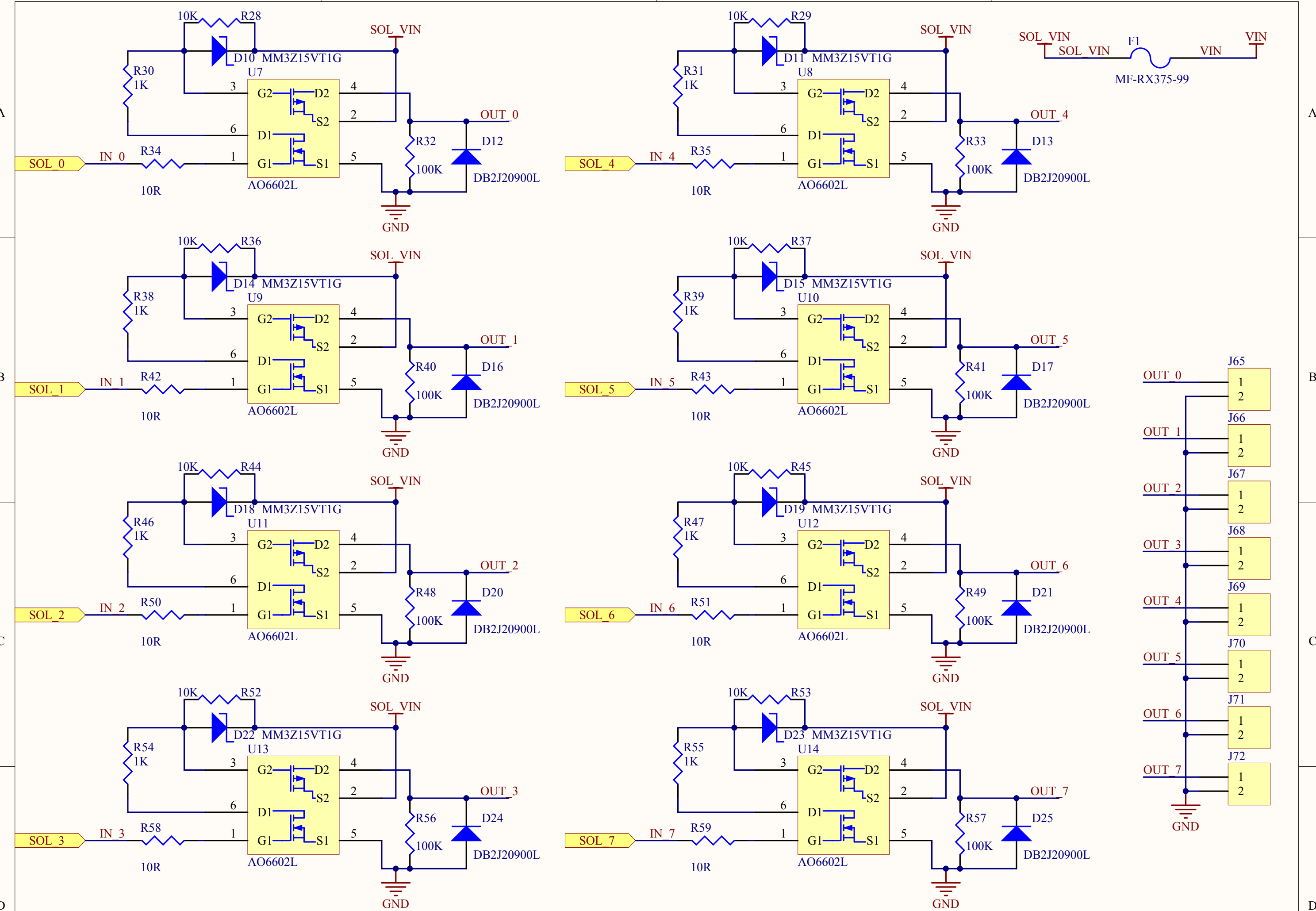
D

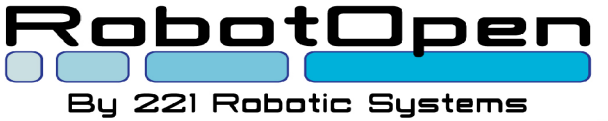
A

B

C

D



Solenoids			 By 221 Robotic Systems
Size: A	Date: 6/13/2014	Revision: 1.0	
Engineer: K. Chambls		Sheet: 4 of 5	
Drawn By: K. Chambls			

A

B

C

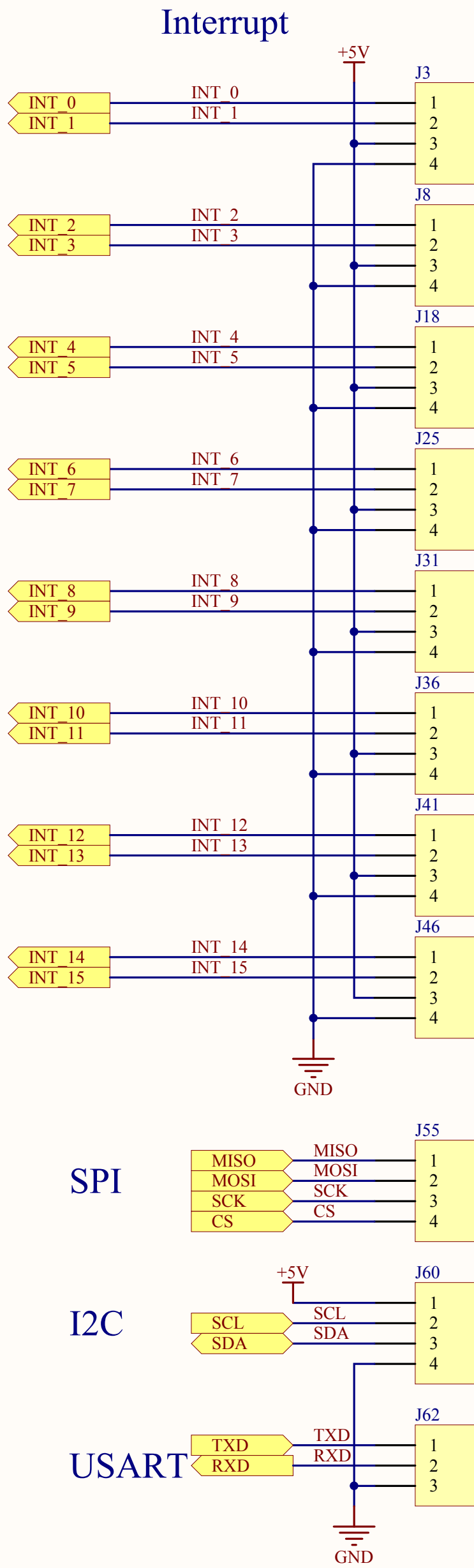
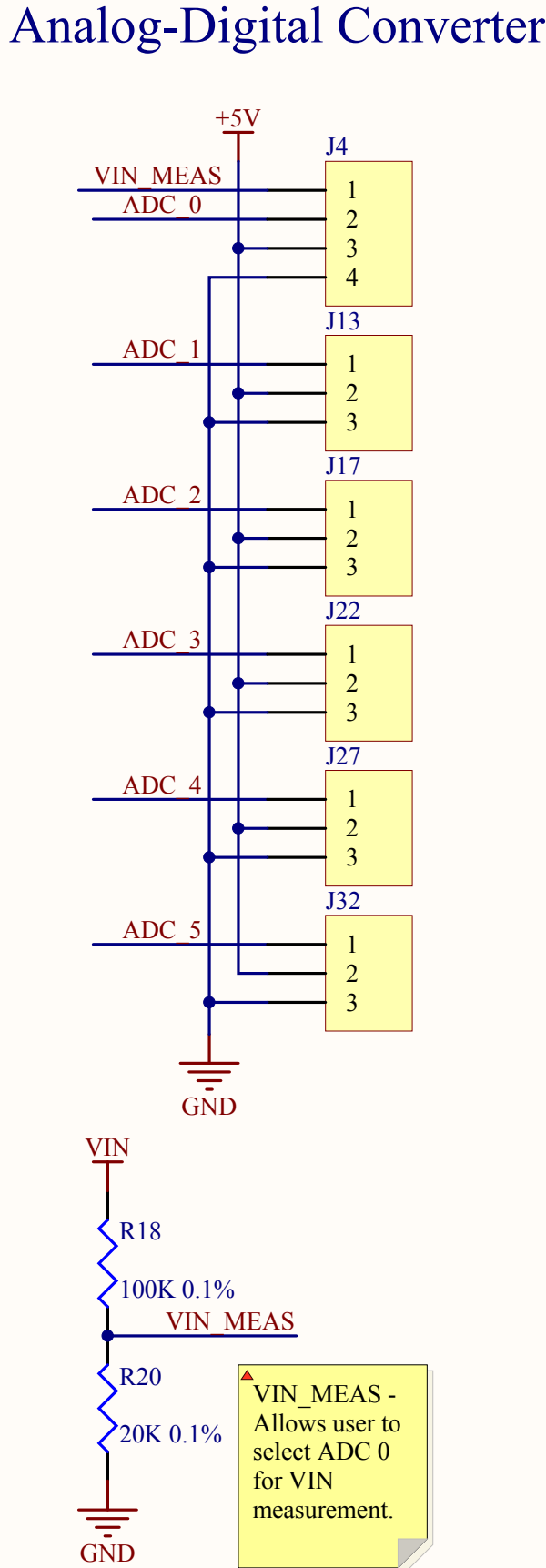
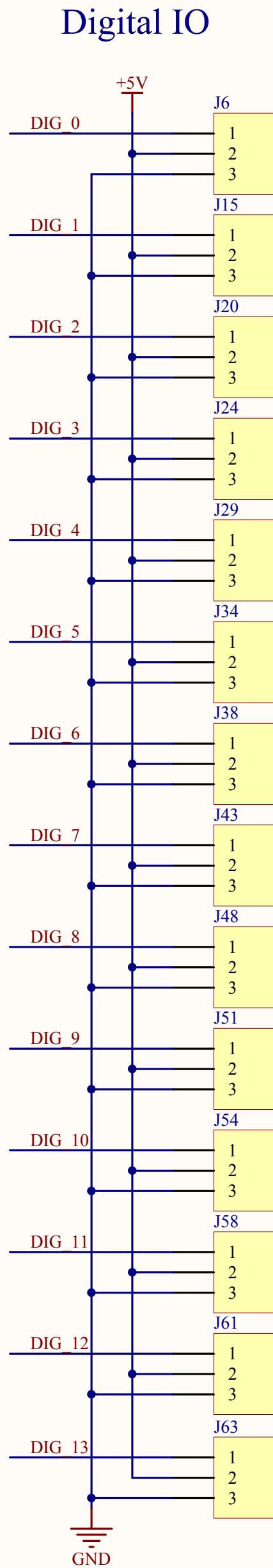
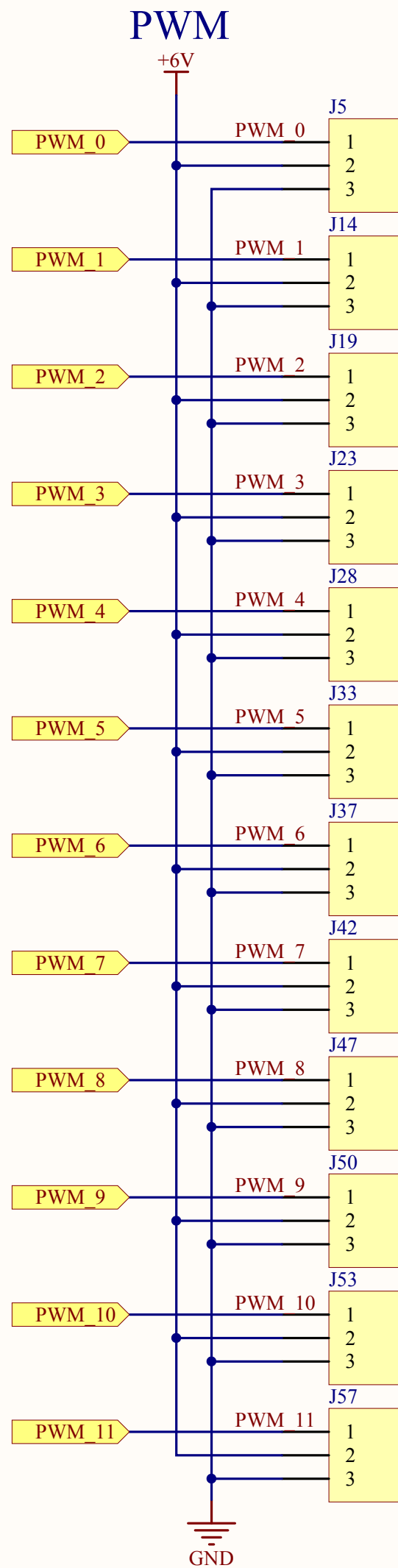
D

A

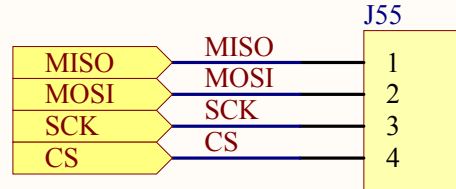
B

C

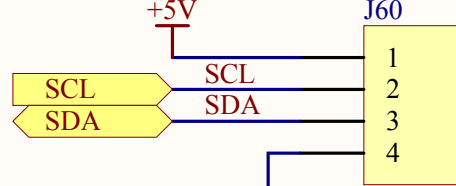
D



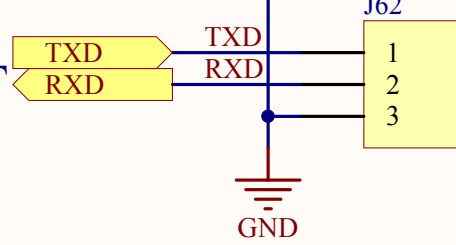
SPI



I2C

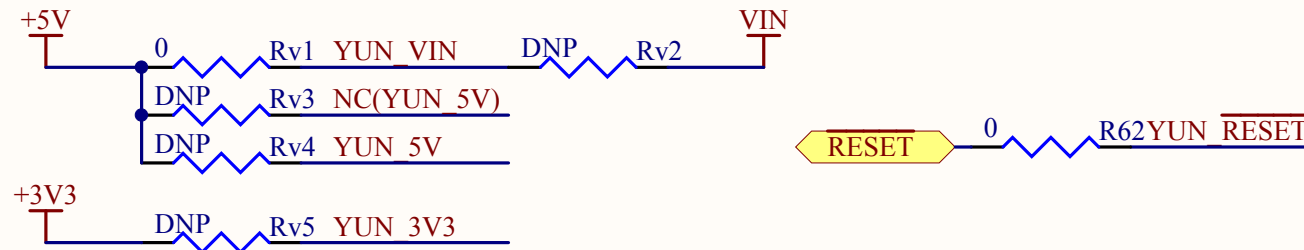
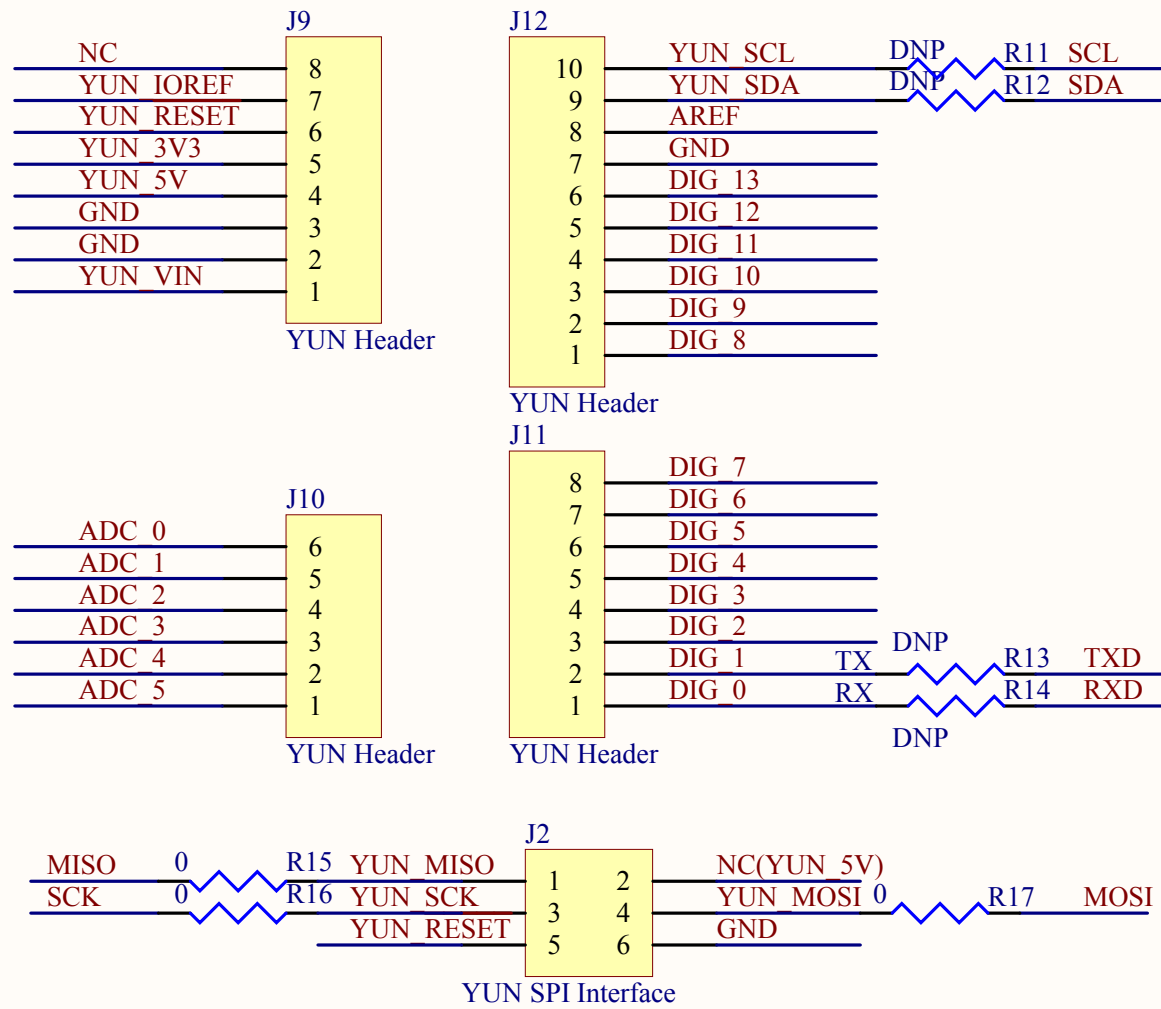


USART



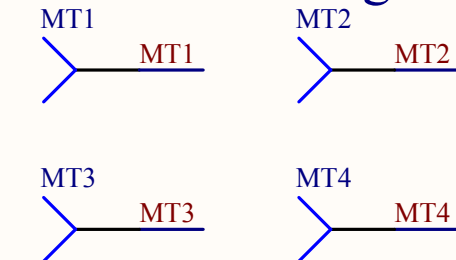
PREC040SFAN-RC Potential Part number for "YUN connectors" which will now be the breakaway, 0.1" spacing male headers since the YUN board will be mounted upside down/inverted. (0.416" tall header, resulting in a 0.499" mating height)

YUN Connectors



INITIAL NOTES ONLY (will be revised once exact desired function is identified, this config provides options)
Rv1 - use as 1 option for getting 5V/VIN into the YUN, do not connect any other RvX
Rv2 - use when not using the YUN (parallel 5 & 3.3 generated) do not connect any other RvX
Rv3 - use as 1 option for getting 5V into the YUN, do not connect any other RvX
Rv4 & Rv5 - use when not using the YUN (single 5 & 3.3 generated) do not connect any other RvX

Board Mounting Holes



Connectors

Size: B	Date: 6/13/2014	Revision: 1.0
Engineer: K. Chambls	Sheet: 5	of 5
Drawn By: K. Chambls		

