

Paper 1

Online Link = “ [Safe speeds: fatality and injury risks of pedestrians, cyclists, motorcyclists, and car drivers impacting the front of another passenger car as a function of closing speed and age](#) “

What dataset did you use?

- Dataset: GIDAS (Germany), 1999–2020
- Features: Speed, age, injury level, safety use, crash type, year
- Processing: Data weighted to match national accident statistics

Which ML model did you use?

- Model: Logistic Regression (binary classification)
- Target: Injury (1 = injured, 0 = not injured)
- Inputs: Closing speed, Age
- Models tested:
 - Model 1: Speed only
 - Model 2: Speed + Age (better)
- Evaluation: 5-fold cross-validation, ROC & AUC
- Purpose: Create injury risk curves for different road users

What did the result show?

Topic	Result
Model Performance (AUC)	0.66 – 0.94 (good)
Highest Risk User	Pedestrian
Lowest Risk User	Car occupant
Safe Closing Speed (10% MAIS3+F)	Ped: 29, Cyclist: 44, Motorcyclist: 48, Car: 112 km/h
Safe Vehicle Speed	Ped–Car: 25, Bike–Car: 20–25, Car–Car: 55 km/h
Safety Equipment Effect	Helmet, jacket, AEB increase safe speed
Main Limitations	Low motorcycle data, wide uncertainty

4. What did they say about future work / limitations at the end?

- Limitation
 - Only car hits from front were studied
 - Other crashes were not included
 - Age was used in a simple way
 - Children were not included
 - Only injury accidents were used

- Old vehicles are in the data
 - Data is from Germany only
 - Gender was not used
 - Future Work
 - Study other types of crashes
 - Include more vehicles
 - Use new safety technology data
 - Use better models for age
 - Compare with other countries
 - Add gender and social data
 - Improve zero-speed risk idea
 - Use model in smart cars
-

Paper 2

Online Link = “ [Automated Construction of Time-Space Diagrams for Traffic Analysis Using Street-View Video Sequences](#) ”

What dataset did you use?

- KITTI = real road data from car cameras & sensors
- Images, videos & LiDAR = see roads and object distances

- GPS & calibration = know car location & measure correctly
- Annotations = label cars, people, and other objects
- YOLOv5 + StrongSORT = detect and track objects, estimate distance

Which ML model did you use?

- No traditional ML = Linear Regression, Random Forest, etc. were not used
- YOLOv5 = CNN-based model for real-time object detection, fine-tuned on KITTI
- StrongSORT = tracks multiple objects while moving
- Distance estimation = uses camera geometry & GPS, not ML
- Summary = research uses deep learning & computer vision, not classic ML models

What did the result show?

What	Result
YOLOv5 Detection	Vehicles detected very well (mAP ~0.78–0.79)
StrongSORT Tracking	Vehicles detected very well (mAP ~0.78–0.79)

Distance & Trajectory	Some errors (RMSE 1.4–4.4 m, flickering boxes)
-----------------------	--

What did they say about future work / limitations at the end?

- Limitation
 - Sometimes the car looks too close or too far
 - Boxes around cars and people jump or disappear
 - Only one road video (KITTI) was used
 - Future Work
 - Use LiDAR or RADAR to see distance better
 - Teach the computer with more roads and smooth paths
 - Try fake roads in a simulator
 - Mix moving cameras with fixed cameras
-

Paper 3

Online Link = “ [Linear Regression-Based Traffic Flow Simulation: Vehicle Density and Speed Analysis on Buah Batu Road](#) ”

What dataset did you use?

- Speed = Road length ÷ Time
- Density = Cars coming ÷ Max cars
- Dataset has: No, T in, T out, Speed, Density
- Main features are Speed & Density
- Other columns are just helpers

Which ML model did you use?

- They used Linear Regression
- To see how Speed and Density are friends
- The formula : $v(p) = -6.904 + 4.302p$
- Intercept = -6.904, Slope = 4.302
- No tricky models like Random Forest or Neural Net

What did the result show?

Thing	Happened
Model	Linear Regression
Fit	Graph looks okay
Metrics	No numbers like RMSE
Simulation	Traffic spreads, jam goes down
Next Steps	Add metrics & try cool models

What did they say about future work / limitations at the end?

- Limitation
 - Only Linear Regression
 - No real-time traffic
 - Only Speed & Density
 - Used Upwind math
 - Model is simple
- Future Work
 - Try non-linear or ML models
 - Add real-time & smart traffic data
 - Add weather, road, and driver factors
 - Try better numerical methods
 - Make it more complete & realistic