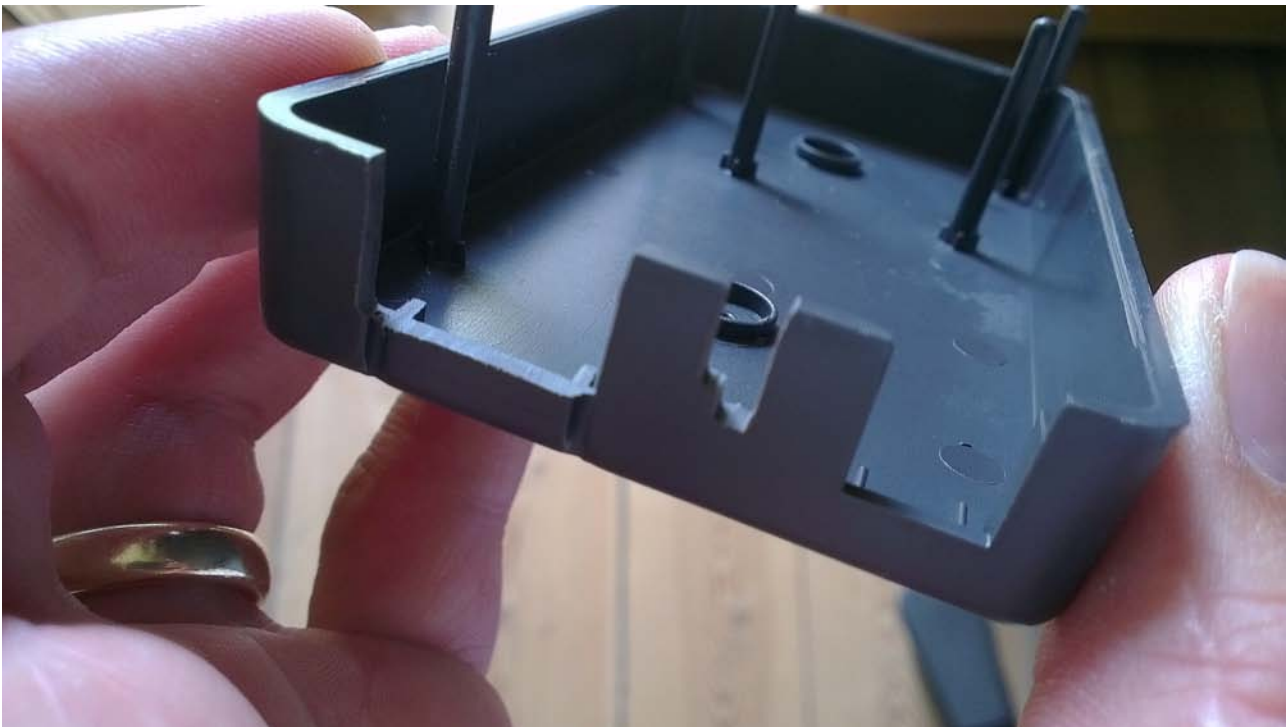


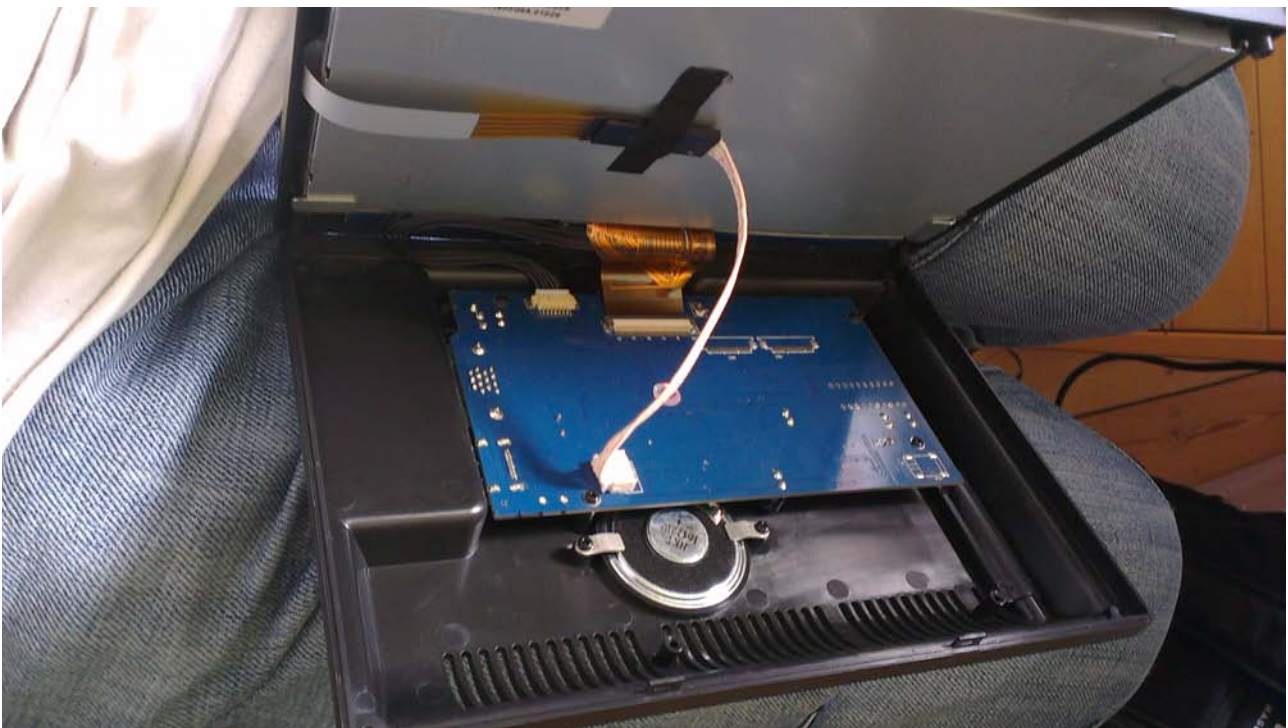
# DIY instructions for the Arduino/ATEM Touchscreen

See [http://skaarhoj.com/wiki/index.php/Touchscreen\\_for\\_Arduino/ATEM](http://skaarhoj.com/wiki/index.php/Touchscreen_for_Arduino/ATEM)

*Comments are under the pictures*



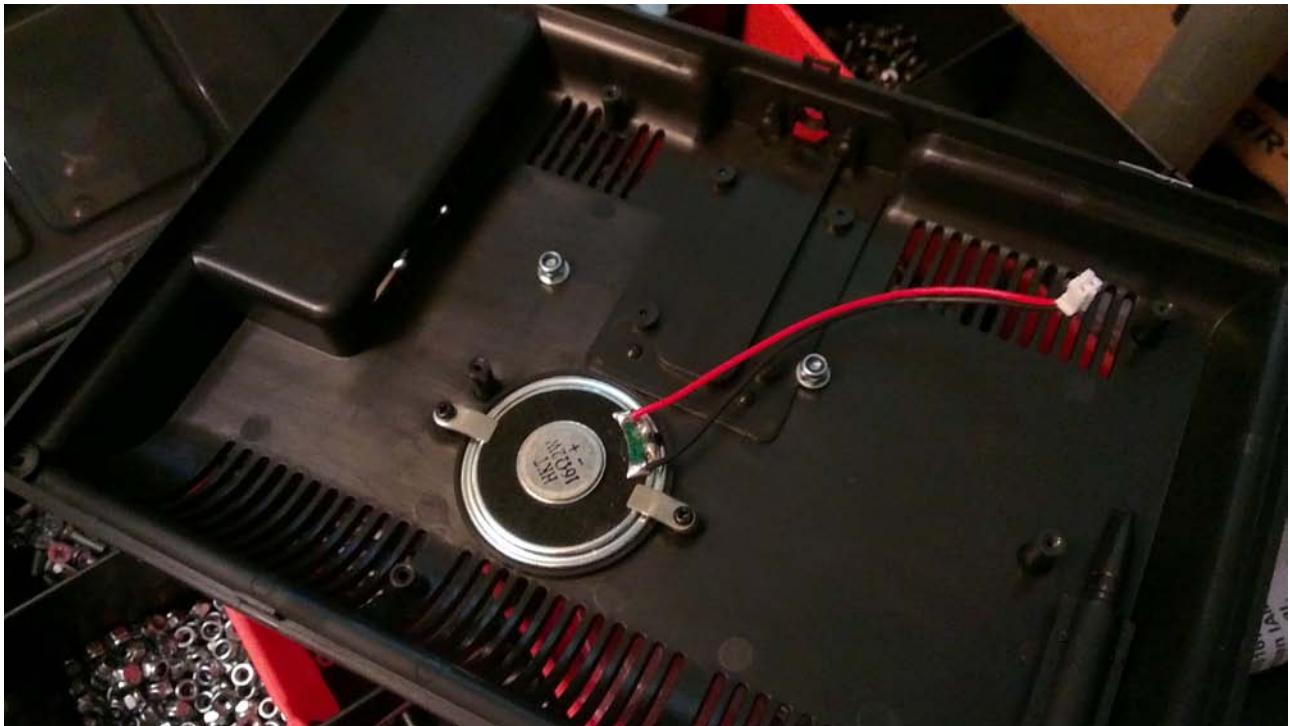
You need to modify the Arduino enclosure a bit so the **slot for the USB plug can host the Ethernet jack** on an Arduino Ethernet module. Use a sharp knife, a saw or something else, just keep your fingers safe in the process.



Remove the screws that hold the screen together. It looks like this when opened. You need to squeeze the plastic enclosure a bit in the top to make two small latches flip out. **Unmount the cables and the blue PCB** (printed circuit board).



**Drill two holes for 3mm bolts** through the bottom of the Arduino enclosure and the back of the monitor (which has the PCB removed now). Also **drill an extra hole larger** (around 6+mm) for the wires.



The two M3 bolts (10mm long) are tightened with **locking nuts**.





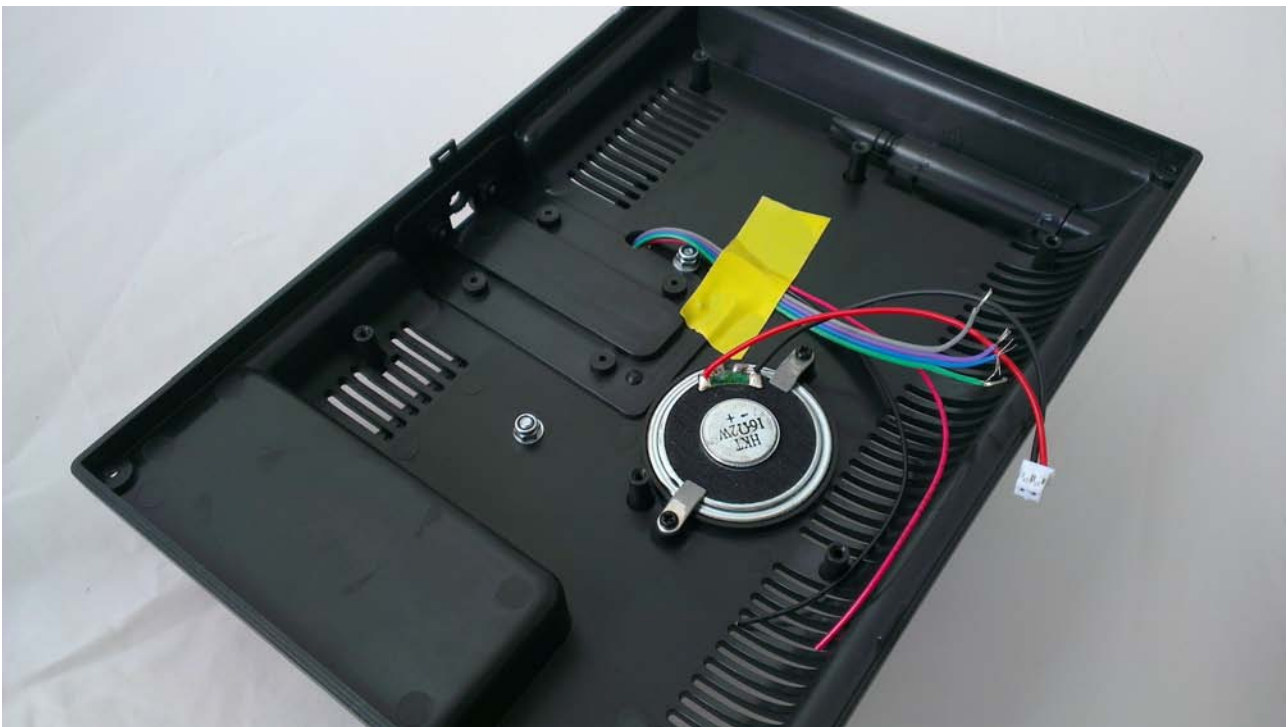
The nuts from the arduino side. Notice the 6mm hole for wires.



Cut off this particular plastic rod (it covers the FTDI programming header).



**Mount the breakout shield, solder on wires for the touchscreen and power.** Make sure they are **long enough to unmount the shield**. Notice the **red powerline goes to Vin** on the arduino which is directly connected to the DC plug. On the monitor this wire is soldered also to the DC plug. In this way the arduino is powered by the 12V supply for the monitor and needs no PSU for itself.



The wires going into the monitor case, **fixed with tape**.

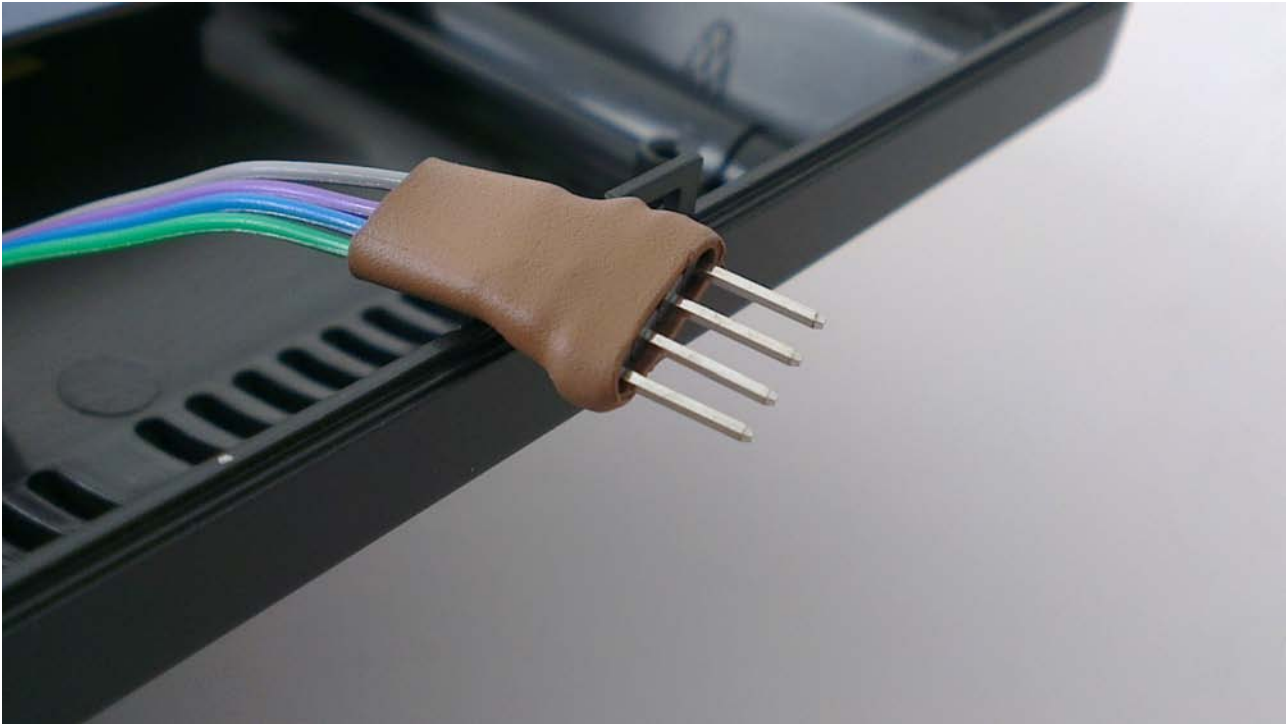


The **power wires soldered to the DC plug** of the monitor.

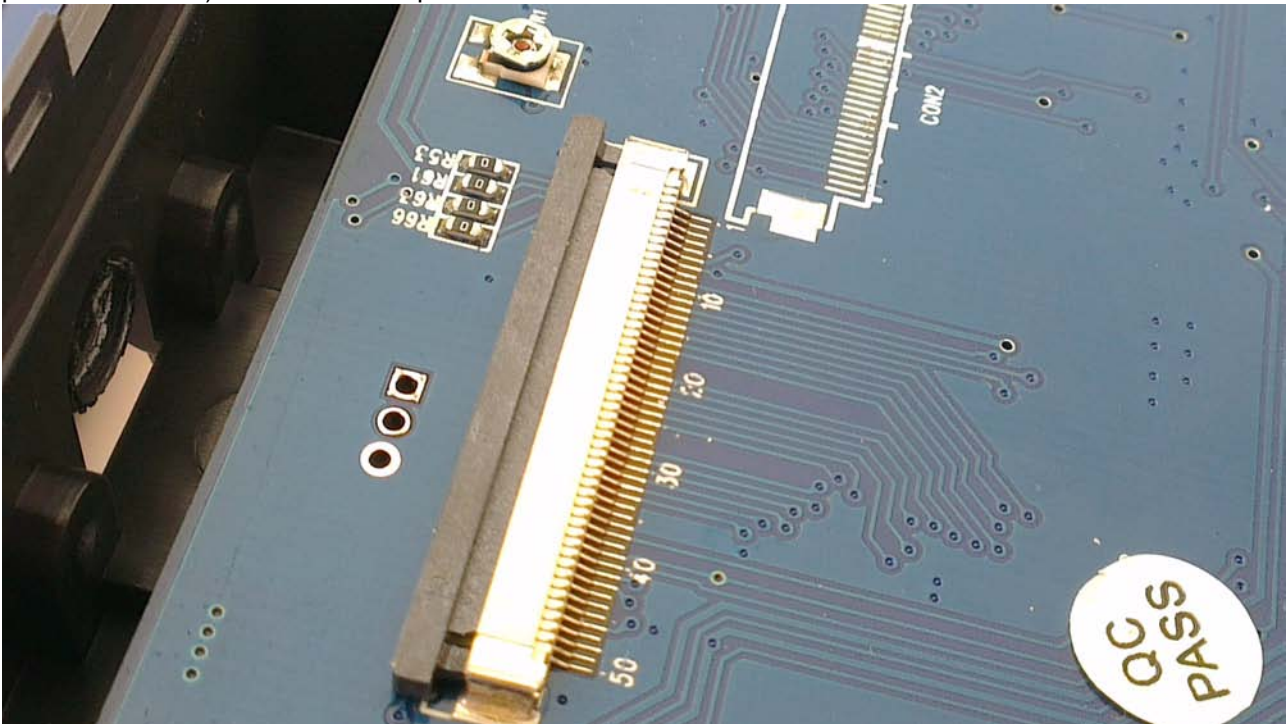


The **pin1** of the touchscreen.

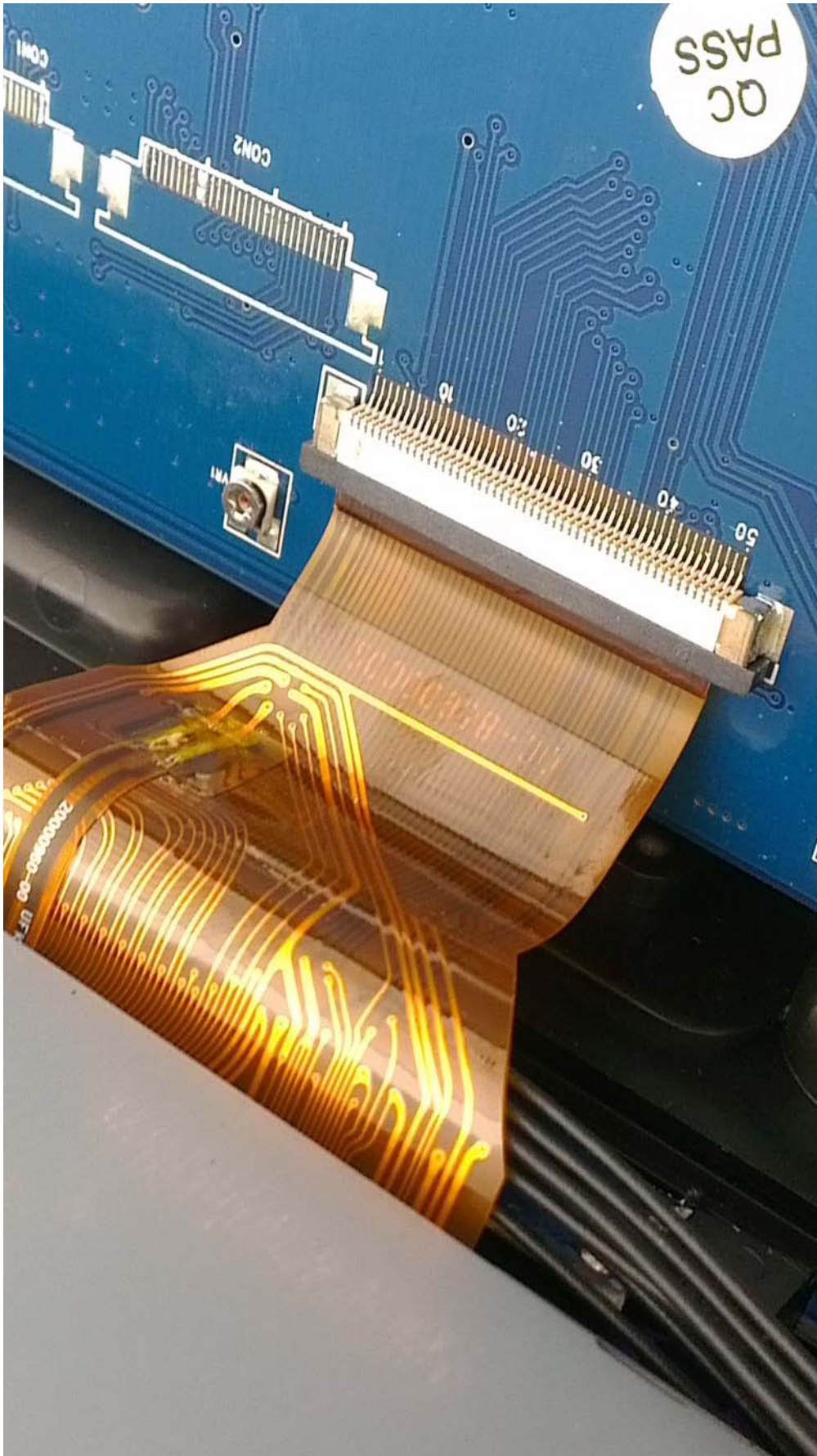




The **4-wire cable** from the arduino breakout shield is **soldered onto a small 4-pin header post** - notice the brown **shrink-tube to isolate**. You can use tape if you like. The gray wire is pin one (soldered to the square pan on the shield) and connects to pin1 on the touchscreen.

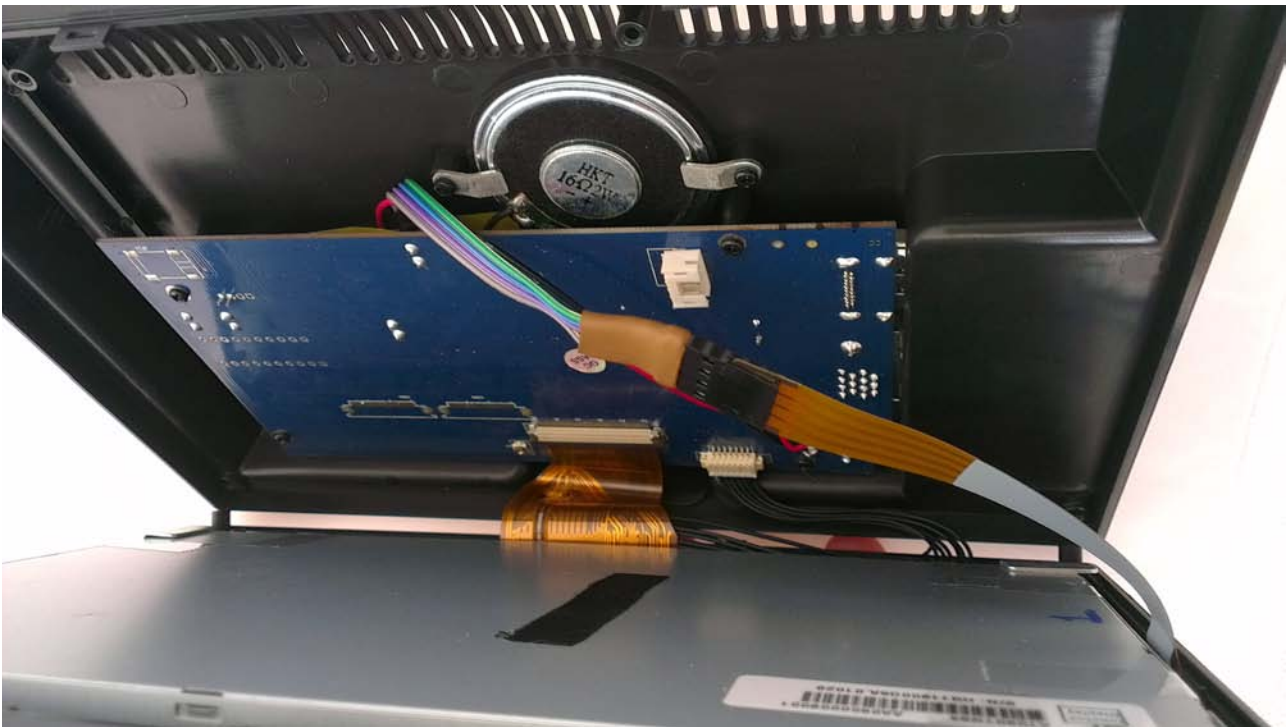


Most likely the touchscreen panel slipped out of this connector. Don't worry. It's easy to get it in again, just push the brown/gray bar away from the white part. It easily moves out 1 mm or so.



Then, insert the flatcable from the panel into the connector and press the brown part back against the white part. It will fix the flatcable again. Make sure the flatcable was pushed all the way in and is now nicely aligned.





Connect the touch screen with the arduino before you close up the case.



If you want to make sure the power connections are right, you should be able to **measure a connection between the two DC plugs directly.**





I like to **block the DC plug** of the arduino now that it is obsolete.



The **FTDI programming cable** is attached to the 6-pin header on the Arduino Ethernet board. The black wire (out of the 6 in total) of the FTDI cable is always close to the edge. You only need this cable for programming. Notice, that even if this cable is a USB cable it needs a special driver installed before the Arduino IDE can program it. See step 3 at <http://arduino.cc/en/Guide/Howto> and <http://www.ftdichip.com/Drivers/VCP.htm>



For testing the touch coordinates above you don't need to power up the screen at all. Just the Arduino needs USB power.

The screenshot shows the Arduino IDE interface. The top window is titled 'Touch\_Test | Arduino 1.0.1' and displays the following code:

```

// *****
// ...
// - Jasper
// * This example code is in the public domain.
// */

#include "SkoarhojUtils.h"
SkoarhojUtils utils;

void setup() {
  Serial.begin(9600);
  Serial.println("Serial started");
  Serial.println("Coordinate system origo should be at the top left corner of the screen");
  utils.touch_init();

  // The line below is calibration numbers for
  // Substitute this with calibration for YOUR screen
  utils.touch_calibrationPointRowCoordinates(32);
}

void loop() {
  Serial.print(utils.touch_isTouched());
  Serial.print(" - Row reading (x,y): ");
  Serial.print(utils.touch_getRowVal());
  Serial.print(", ");
  Serial.print(utils.touch_getRowVal());
  Serial.print("\n");

  Serial.print(" - Calibrated (x,y): ");
  Serial.print(utils.touch_coordX(utils.touch_getRowVal()));
  Serial.print(", ");
  Serial.print(utils.touch_coordY(utils.touch_getRowVal()));
  Serial.print("\n");
}

```

The bottom window is titled '/dev/tty.usbserial-FTG545A4' and shows the serial output of the sketch. It displays a series of raw and calibrated coordinates for each touch event:

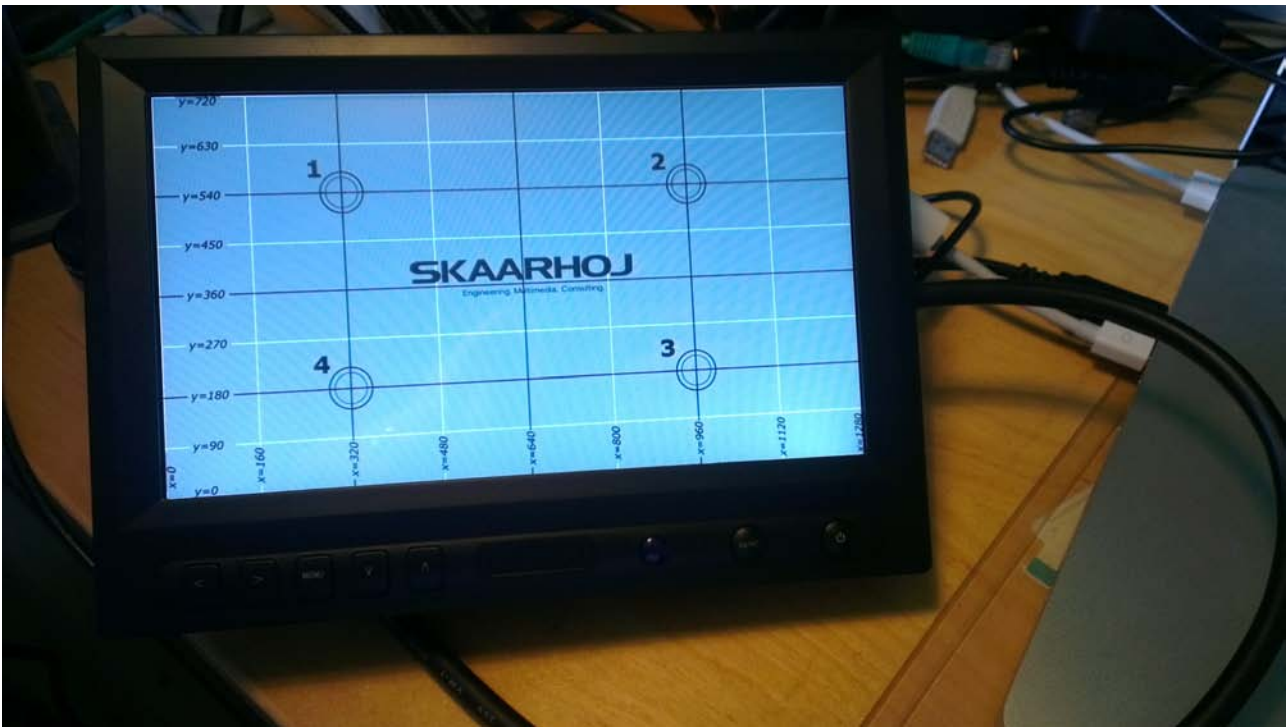
```

1 - Row reading (x,y): 493,518 - Calibrated (x,y): 564,348
1 - Row reading (x,y): 491,515 - Calibrated (x,y): 561,345
1 - Row reading (x,y): 490,513 - Calibrated (x,y): 560,343
1 - Row reading (x,y): 489,510 - Calibrated (x,y): 558,340
1 - Row reading (x,y): 488,509 - Calibrated (x,y): 557,339
1 - Row reading (x,y): 623,675 - Calibrated (x,y): 754,585
1 - Row reading (x,y): 473,491 - Calibrated (x,y): 535,321
1 - Row reading (x,y): 461,480 - Calibrated (x,y): 517,310
1 - Row reading (x,y): 459,477 - Calibrated (x,y): 514,307
1 - Row reading (x,y): 460,474 - Calibrated (x,y): 516,304
1 - Row reading (x,y): 461,474 - Calibrated (x,y): 517,304
1 - Row reading (x,y): 474,479 - Calibrated (x,y): 536,309
1 - Row reading (x,y): 487,484 - Calibrated (x,y): 555,314
1 - Row reading (x,y): 492,484 - Calibrated (x,y): 563,314
1 - Row reading (x,y): 502,489 - Calibrated (x,y): 577,319
1 - Row reading (x,y): 502,488 - Calibrated (x,y): 577,318
1 - Row reading (x,y): 503,490 - Calibrated (x,y): 579,320
1 - Row reading (x,y): 503,492 - Calibrated (x,y): 579,322
1 - Row reading (x,y): 501,494 - Calibrated (x,y): 576,324
1 - Row reading (x,y): 487,491 - Calibrated (x,y): 555,321
1 - Row reading (x,y): 478,492 - Calibrated (x,y): 542,322
1 - Row reading (x,y): 474,491 - Calibrated (x,y): 536,321
1 - Row reading (x,y): 467,488 - Calibrated (x,y): 526,318
1 - Row reading (x,y): 460,484 - Calibrated (x,y): 516,314
1 - Row reading (x,y): 458,483 - Calibrated (x,y): 513,313
1 - Row reading (x,y): 470,488 - Calibrated (x,y): 531,318
1 - Row reading (x,y): 483,495 - Calibrated (x,y): 550,325
1 - Row reading (x,y): 494,500 - Calibrated (x,y): 566,330
1 - Row reading (x,y): 499,504 - Calibrated (x,y): 573,334

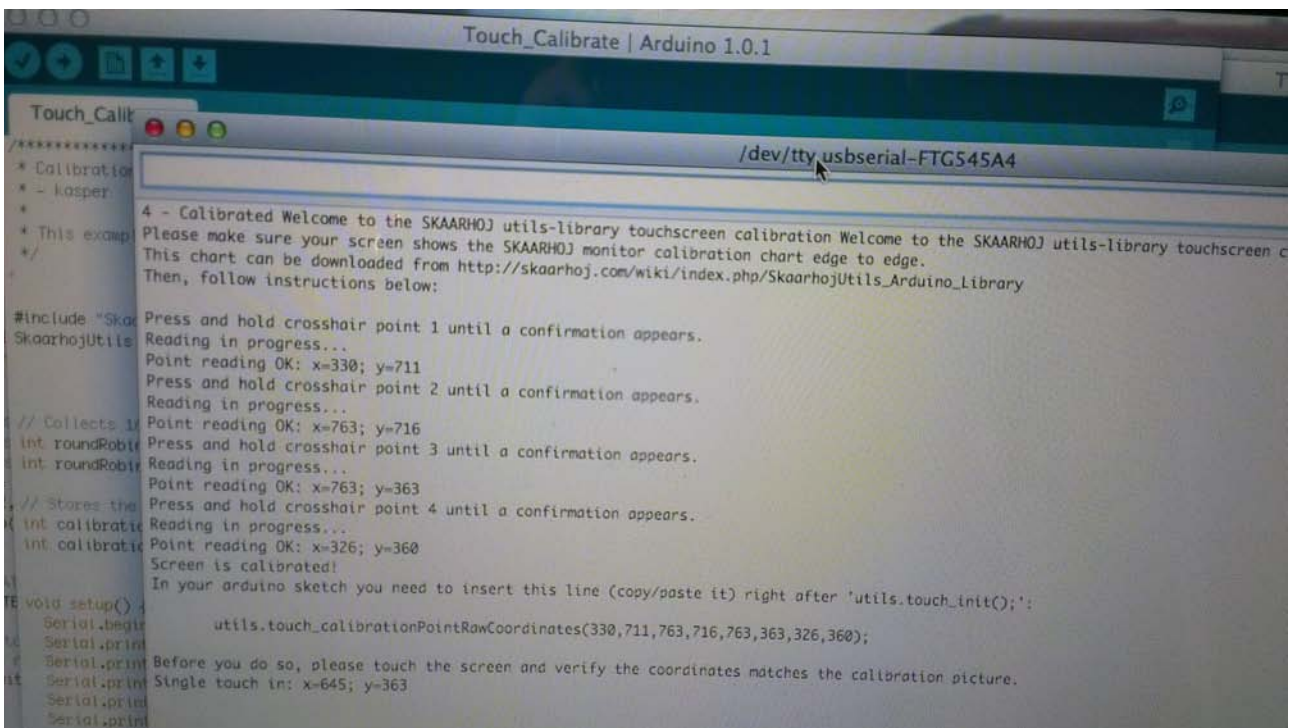
```

Upload the **Touch\_Test** sketch and you should see coordinates when you touch the screen.





Power up the monitor and connect it to an image source. You could use a second computer or your ATEM switcher. **Display the SKAARHOJ monitor calibration chart on the screen.** It has 4 cross hairs used for calibration.

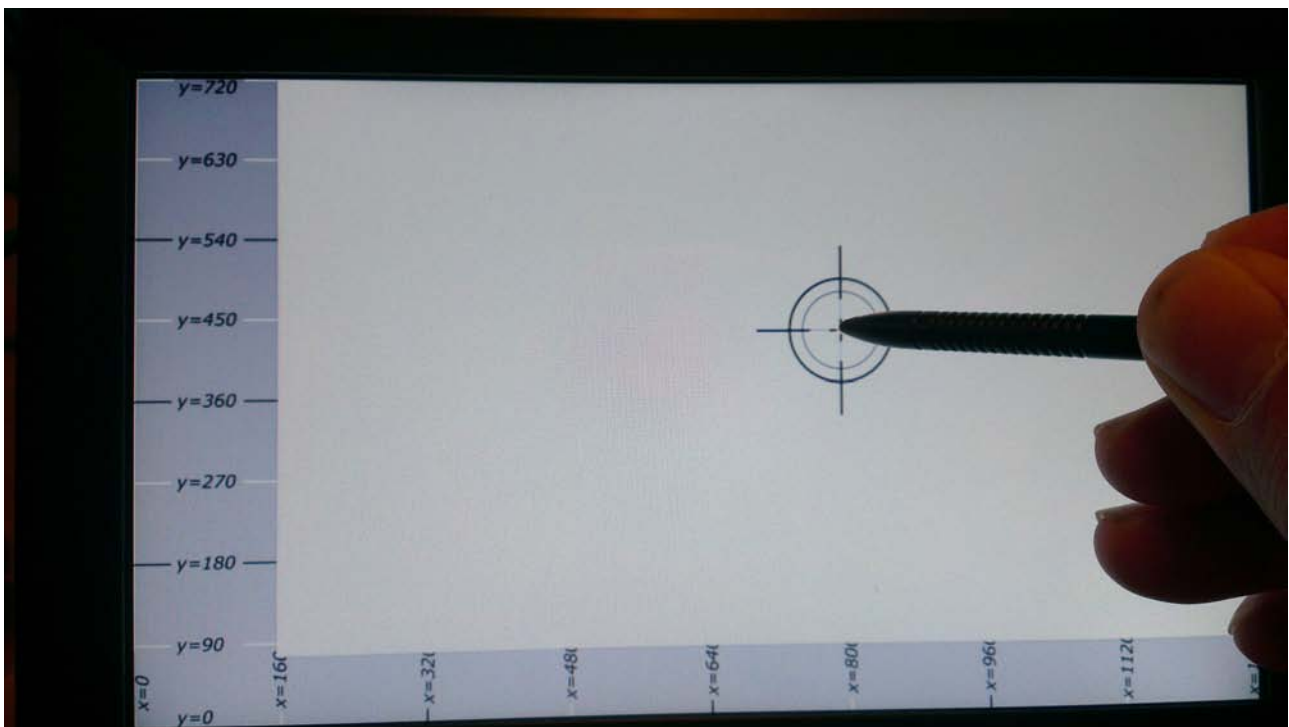


**Upload the Touch\_Calibrate example sketch to the Arduino.** It will guide you through the calibration. This process eventually **gives you a codeline to copy/paste into other Arduino sketches** to make sure it's correctly calibrated.





Also, **take of the label from the back of the Arduino and reapply it on top**. This is the MAC address of the ethernet port. It's more useful to have this visible on top when programming. I usually reapply it to the header jack itself so I can see. In particular the last 3 hex numbers are important (the first 3 tend to be the same for Arduino boards).



Have fun with tracking a cross hair using the **ATEMtouchCrosshair** sketch should you have an ATEM 1M/E! :-)

## Finalization

For actually using the screen as a touchscreen switching interface with the ATEM Multiviewer you should upload the example **ATEMtouchControl**. This will set any input source you touch in the multiviewer to Preview. Notice that it's optimized for the default layout of a 1M/E switcher. If you press and hold the Program window on the multiviewer it will change mode so that a touch of an input source is going directly to

program. In order to get a visual feedback on these two modes you can add a bi-color LED by doing the following which is already supported by this Arduino sketch:

- Take a bi-color (green and red) LED with common cathode (GND)
- Solder on a 330 Ohm resistor to each anode ("red and green leg")
- Connect the cathode to GND
- Connect green to digital pin 2
- Connect red to digital pin 3

LED colors:

- When the default "Preview" mode is on, it's green.
- When "Program" mode, it's red.
- When the board is trying to connect to the ATEM switcher but has no connection yet, it's yellow (both red and green)

- kasper