

goal Stack planning

A B C

A
B
C

Stack

{on(A|B), on(B|C)}

on(A|B)

on(B|C)

stack(A|B)

{holding(B), clear(C)}

holding(B)

clear(C)

pickup(B)

{onT(B), clearB, AE}

onT(B)

clear(B)

AE

stack(A|B)

{holding(A), clear(B)}

holding(A)

clear(B)

pickup(A)
{onT(A), clear(A), AE}
onT(A)
clear(A)

plan



