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1 Homework 7 Problem 4

1.1 Setup Python Imports

```
import math
from sympy import *
```

1.2 Givens

First we have to ingest the given information so we can use it to solve.

```
Ty = -2e3
t = 0.2 # thickness
E = 10e6
v = 0.33
L1 = 6
L2 = 12

(F1x, F1y, F2x, F2y) = symbols("F1x, F1y, F2x, F2y")
F3x = 0;
F3y = 0;
F4x = 0;
F4y = 0;
F = Matrix([F1x,
             F1y,
             F2x,
             F2y,
             F3x,
             F3y,
             F4x,
             F4y])

var("(u:v)(3:5)")
u1 = 0
v1 = 0
```

```

u2 = 0
v2 = 0
d = Matrix([u1,
             v1,
             u2,
             v2,
             u3,
             v3,
             u4,
             v4])

# the coordinates of each node
nodes = Matrix([[ 0,  0],
                [ 0, L1],
                [L2, L1],
                [L2, 0]])
assembly = Matrix([[0, 2, 1],
                  [0, 3, 2]]);
connectivity = Matrix([[0, 1, 4, 5, 2, 3],
                      [0, 1, 6, 7, 4, 5]])

```

1.3 Converted Nodal Forces

```

F_traction = 0.5*Ty*(t*L1)

F_conv = Matrix([
                0,
                0,
                0,
                0,
                0,
                F_traction,
                0,
                F_traction])

pprint(F_conv)

```

1.4 Stiffness Equations

First we start by calculating $[B]$ for each element.

```

B = list()

for row_num in range(assembly.rows):
    row = assembly.row(row_num)
    i = row[0];
    j = row[1];
    m = row[2];

```

```

beta_i = nodes[j, 1] - nodes[m, 1]
beta_j = nodes[m, 1] - nodes[i, 1]
beta_m = nodes[i, 1] - nodes[j, 1]
gamma_i = nodes[m, 0] - nodes[j, 0]
gamma_j = nodes[i, 0] - nodes[m, 0]
gamma_m = nodes[j, 0] - nodes[i, 0]
B.append(Matrix([[ beta_i,      0,  beta_j,      0,  beta_m,
↪ 0],
[      0, gamma_i,      0, gamma_j,      0,
↪ gamma_m],
[gamma_i, beta_i, gamma_j, beta_j, gamma_m,
↪ beta_m]]))

pprint(B[-1])
print("")

```

Next we create the $[D]$ matrix. This is the same for each element since they are the same material.

```

D = E/(1-v**2)*Matrix([[1, v,      0],
[ v, 1,      0],
[0, 0, (1-v)/2]])

pprint(D)

```

Next we can find the area of each triangle using the area of a polygon.

```

A = list()

for row_num in range(assembly.rows):
    row = assembly.row(row_num)
    i = Point(nodes[row[0], :])
    j = Point(nodes[row[1], :])
    m = Point(nodes[row[2], :])
    shape = Polygon(i, j, m)
    A.append(shape.area)
print(A[-1])

```

Finally we have all of the components for our element stiffness matrices.

```

k = list()

for e in range(assembly.rows):
    k.append(t*A[e]*B[e].T*D*B[e])
    pprint(k[-1])
print("")

```

Next we must assemble the global stiffness matrix

```

k_g = zeros(2*nodes.rows)

for e in range(assembly.rows):
    for i in range(6):
        for j in range(6):
            C = connectivity
            k_g[C[e, i], C[e, j]] += k[e][i,j]

pprint(k_g)

```

1.5 Solve for Displacements & Forces

Now that we have the global stiffness matrix we can solve for the unknown displacements & forces.

```

soln = solve(Eq(k_g*d,F+F_conv))
print(soln)
F1x = soln[F1x]
F1y = soln[F1y]
F2x = soln[F2x]
F2y = soln[F2y]
u3 = soln[u3]
u4 = soln[u4]
v3 = soln[v3]
v4 = soln[v4]

d = Matrix([u1,
             v1,
             u2,
             v2,
             u3,
             v3,
             u4,
             v4])

F = Matrix([F1x,
             F1y,
             F2x,
             F2y,
             F3x,
             F3y,
             F4x,
             F4y])

```

1.6 Stress & Strain

Now that we have the displacements we can find the strains

```

d_e = list([Matrix([u1,
                    v1,
                    u3,
                    v3,
                    u2,
                    v2]),
            Matrix([u1,
                    v1,
                    u4,
                    v4,
                    u3,
                    v3])])

strain = [B[i]*d_e[i] for i in range(assembly.rows)]
stress = [D[i]*strain[i] for i in range(assembly.rows)]
pprint(strain)
print("")
pprint(stress)

```