

# Machine Learning Assignment 8

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**Problem 1**

Given a linearly separable dataset  $\mathcal{D} \Rightarrow$  Soft Margin SVM

The cost function for Soft Margin SVM is given by:

$$f_0(w, b, \xi) = \frac{1}{2}w^T w + C \sum_{i=1}^N \xi_i$$

And the constraints are given by

$$\begin{aligned} y_i(w^T x_i + b) - 1 + \xi_i &\geq 0 \quad i = 1, \dots, N \\ \xi_i &\geq 0 \quad i = 1, \dots, N \end{aligned}$$

The definition of Soft Margin SVM says that we try to minimize  $f_0(w, b, \xi)$  by allowing some errors (points to be misclassified) to formulate a good generalization model. The penalty we impose on misclassified cases (error) depends on value of  $C$ .

- (1)  $\xi_i = 0 \Rightarrow$  These data points are either on the margin or on the correct side of the margin. These data points are classified correctly.
- (2)  $0 < \xi_i \leq 1 \Rightarrow$  These data points lie inside the margin but on the correct side of the decision boundary. These data points are also classified correctly.
- (3)  $\xi_i > 1 \Rightarrow$  These data points lie on the wrong side of the decision boundary. These points are thus misclassified

Thus, to conclude it is not guaranteed that all training samples in  $\mathcal{D}$  are classified correctly. Some of them can be misclassified depending on the value of  $\xi$

**Problem 2**

The cost function for Soft Margin SVM is given by:

$$f_0(w, b, \xi) = \frac{1}{2}w^T w + C \sum_{i=1}^N \xi_i$$

Our goal is to maximize the margin while softly penalizing points that lie on the wrong side of the margin boundary.

C controls tradeoff between slack variable penalty and margin.

(1) Large Values Of  $C \Rightarrow$  Chooses a smaller-margin hyperplane if that hyperplane does a better job of getting all the training points classified correctly.

$C \rightarrow \infty$  means that we impose infinite penalty on misclassified cases and it is thus a Hard Margin SVM

(2) Small Values Of  $C \Rightarrow$  Chooses for a larger-margin separating hyperplane, even if that hyperplane misclassifies more points. For very tiny values of C, we get misclassified cases, often even if training data is linearly separable

$C = 0$  means we impose no penalty on the misclassified cases. And in this case it is possible that entire data set is misclassified.

Thus to conclude  $C > 0$  to impose at least some penalty on misclassified cases otherwise the model is too general and always misclassifies the data points.

### Problem 3

The Kernel is given by:

$$k(x, y) = (x^T y + c)^d \text{ where } c \geq 0 \text{ and } d \in \mathbb{N}^+$$

To prove a kernel is valid:

(1) Symmetric :  $k(x, y) = k(y, x)$

$$x = (x_1, x_2, \dots, x_N) \text{ and } y = (y_1, y_2, \dots, y_N)$$

$$k(x, y) = (x^T y + c)^d = (x_1 y_1 + x_2 y_2 + \dots x_N y_N + c)^d \dots (1)$$

$$k(y, x) = (y^T x + c)^d = (x_1 y_1 + x_2 y_2 + \dots x_N y_N + c)^d \dots (2)$$

From (1) and (2) it is clear that  $k(x, y) = k(y, x)$

Thus, it is symmetric

(2) Kernel Matrix  $\mathbf{K}$  is positive semi-definite

For some vector  $\mathbf{z}$  we have ,

$$\mathbf{z}^T \mathbf{K} \mathbf{z} = \sum_i \sum_j z_i K_{ij} z_j = \sum_i \sum_j z_i \mathbf{x}_i \mathbf{x}_j z_j = \sum_i z_i \mathbf{x}_i \sum_j z_j \mathbf{x}_j = \left\| \sum_i z_i \mathbf{x}_i \right\|^2 \geq 0$$

$$\Rightarrow \mathbf{z}^T \mathbf{K} \mathbf{z} \geq 0$$

Thus it symmetric

Hence, it is a valid kernel

**Problem 4**

$$\phi_n(x) = \left\{ e^{-x^2/2\sigma^2}, e^{-x^2/2\sigma^2} \frac{x}{\sigma}, \frac{e^{-x^2/2\sigma^2} \left(\frac{x}{\sigma}\right)^2}{\sqrt{2}}, \dots, \frac{e^{-x^2/2\sigma^2} \left(\frac{x}{\sigma}\right)^n}{\sqrt{n!}} \right\}$$

Suppose,  $n \rightarrow \infty$  we have,

$$\phi_\infty(x) = \left\{ e^{-x^2/2\sigma^2}, e^{-x^2/2\sigma^2} \frac{x}{\sigma}, \frac{e^{-x^2/2\sigma^2} \left(\frac{x}{\sigma}\right)^2}{\sqrt{2}}, \dots, \frac{e^{-x^2/2\sigma^2} \left(\frac{x}{\sigma}\right)^i}{\sqrt{i!}}, \dots \right\}$$

This transformation maps feature space defined as  $\phi_\infty : \mathbb{R} \rightarrow \mathbb{R}^\infty$ .

We have an infinite dimensional feature space. It is not possible to store it in memory. Thus it is infeasible to compute in this feature space. We do not calculate  $\phi_\infty(x)$  directly, instead use kernel trick to solve this kind of problem.

For a given pair of vectors  $\mathbf{x}$  and  $\mathbf{y}$   
 $k(\mathbf{x}, \mathbf{y}) = \phi_\infty^T(\mathbf{x})\phi_\infty(\mathbf{y}) = C(\text{scalar})$

Thus, we compute the dot product in the higher-dimensional space without explicitly transforming the vectors into the higher-dimensional space first and use them

**Problem 5**

$$\phi_\infty(x) = \left\{ e^{-x^2/2\sigma^2}, e^{-x^2/2\sigma^2} \frac{x}{\sigma}, \frac{e^{-x^2/2\sigma^2} \left(\frac{x}{\sigma}\right)^2}{\sqrt{2}}, \dots, \frac{e^{-x^2/2\sigma^2} \left(\frac{x}{\sigma}\right)^i}{\sqrt{i!}}, \dots \right\}$$

$$K(x, y) = \sum_{i=0}^{\infty} \phi_{\infty,i}(x)\phi_{\infty,i}(y)$$

Putting in the values of  $x$  and  $y$ , we get

$$K(x, y) = \phi_{\infty,0}(x)\phi_{\infty,0}(y) + \phi_{\infty,1}(x)\phi_{\infty,1}(y) + \phi_{\infty,2}(x)\phi_{\infty,2}(y) + \dots$$

$$K(x, y) = e^{-x^2-y^2/2\sigma^2} + e^{-x^2-y^2/2\sigma^2} \frac{xy}{\sigma^2} + \frac{e^{-x^2-y^2/2\sigma^2} \left(\frac{xy}{\sigma^2}\right)^2}{2!} + \dots + \frac{e^{-x^2-y^2/2\sigma^2} \left(\frac{xy}{\sigma^2}\right)^i}{i!}$$

$$K(x, y) = e^{-\frac{x^2-y^2}{2\sigma^2}} \left\{ 1 + \frac{xy}{\sigma^2} + \frac{\left(\frac{xy}{\sigma^2}\right)^2}{2!} + \dots + \frac{\left(\frac{xy}{\sigma^2}\right)^i}{i!} \right\}$$

$$K(x, y) = e^{-\frac{x^2-y^2}{2\sigma^2}} \sum_{n=0}^{\infty} \frac{1}{n!} \left(\frac{xy}{\sigma^2}\right)^n$$

Using the Taylor Expansion  $e^Z = \sum_{n=0}^{\infty} \frac{1}{n!} (Z)^n$ , we get

$$K(x, y) = e^{-\frac{x^2-y^2}{2\sigma^2}} e^{\frac{xy}{\sigma^2}} = e^{-\frac{x^2-y^2+2xy}{2\sigma^2}} = e^{-\frac{(x-y)^2}{2\sigma^2}}$$

$$K(x, y) = e^{-\frac{(x-y)^2}{2\sigma^2}}$$

For a linear classifier : Overfitting increases as the dimensions of the feature/input space increases

For SVM : If we use the kernel function, then problem of overfitting can be avoided. This is because we do not explicitly calculate these feature space and kernel takes care of it.

### Problem 6

Linear Separability in Feature Space defined by  $\phi_{\infty}$  depending on choice of  $\sigma$

$$K(x, y) = e^{-\frac{(x-y)^2}{2\sigma^2}}$$

Consider the following cases :

(a)  $\sigma \rightarrow 0$

$$K(x, y) = \begin{cases} 0 & x \neq y \\ 1 & x = y \end{cases}$$

$\mathbf{K}$  is a diagonal matrix with 1 at diagonal and 0 elsewhere

For points to be correctly classified in SVM,

$$y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + b) > 1 \quad \forall i \dots (1)$$

$$\mathbf{w} = \sum_{j=1}^N \alpha_j y_j \phi(\mathbf{x}_j) \dots (2)$$

Using (1) and (2), we have

$$y_i \left( \sum_{j=1}^N \alpha_j y_j \phi^T(\mathbf{x}_j) \phi(\mathbf{x}_i) + b \right) > 1 \quad \forall i$$

$$\Rightarrow y_i \left( \sum_{j=1}^N \alpha_j y_j K(\phi(\mathbf{x}_j), \phi(\mathbf{x}_i)) + b \right) > 1 \quad \forall i$$

$$\Rightarrow y_i ((\alpha_i y_i) + b) > 1 \quad \forall i$$

Setting  $b = 0$  and we know  $\alpha_i \geq 0 \quad \forall i$ ,

$$\Rightarrow \alpha_i y_i^2 > 1$$

This is true for all the data points. Thus the points can be linearly separated if  $\sigma$  very small

(b)  $\sigma \rightarrow \infty$

$$K(x, y) = 1$$

For points to be correctly classified in SVM,

$$y_i (\mathbf{w}^T \phi(\mathbf{x}_i) + b) > 1 \quad \forall i \dots (1)$$

$$\mathbf{w} = \sum_{j=1}^N \alpha_j y_j \phi(\mathbf{x}_j) \dots (2)$$

$$\Rightarrow y_i \left( \sum_{j=1}^N \alpha_j y_j K(\phi(\mathbf{x}_j), \phi(\mathbf{x}_i)) + b \right) > 1 \quad \forall i$$

$$\Rightarrow y_i b > 1$$

We know  $y_i = \{-1, 1\}$  and  $b \in \mathbb{R}$ . This condition is not true for all the data points.

For a larger sigma, the decision tends to be flexible and smooth, it tends to make wrong classification while predicting, but avoids the hazard of overfitting. For a smaller sigma, the decision boundary tends to be strict and sharp, and it tends to overfit.

If the distance between  $x_i$  and  $x_j$  is much larger than  $\sigma$ , the kernel function tends to be zero. Thus, if the  $\sigma$  is very small, only the  $x_i$  within the certain distance can affect the predicting point. In other words, smaller sigma tends to make a local classifier, larger sigma tends to make a much more general classifier.

To conclude,  $\sigma \rightarrow 0$  for all the points to be classified correctly

### Problem 7

Classify vector  $\mathbf{x}$

k training Samples  $\Rightarrow \mathcal{N} = \{\mathbf{x}^{(s_1)}, \mathbf{x}^{(s_2)}, \dots, \mathbf{x}^{(s_k)}\}$

$$K(\mathbf{x}, \mathbf{y}) = \phi^T(\mathbf{x}) \phi(\mathbf{y}) \dots (1)$$

For the transformed space , the distance is given by  $\|\phi(\mathbf{x}) - \phi(\mathbf{x}^{(s_i)})\|_2$

Squaring this distance, as it will not affect result

$$\|\phi(\mathbf{x}) - \phi(\mathbf{x}^{(s_i)})\|_2^2 = \phi^T(\mathbf{x})\phi(\mathbf{x}) + \phi^T(\mathbf{x}^{(s_i)})\phi(\mathbf{x}^{(s_i)}) - 2\phi^T(\mathbf{x})\phi(\mathbf{x}^{(s_i)})$$

The first term is same for all data points, thus it is a constant. The distance is given by

$$D(\phi(\mathbf{x}), \phi(\mathbf{x}^{(s_i)})) = \phi^T(\mathbf{x}^{(s_i)})\phi(\mathbf{x}^{(s_i)}) - 2\phi^T(\mathbf{x})\phi(\mathbf{x}^{(s_i)}) \dots (2)$$

Using (1) and (2) , we have,

$$D(\phi(\mathbf{x}), \phi(\mathbf{x}^{(s_i)})) = K(\mathbf{x}^{(s_i)}, \mathbf{x}^{(s_i)}) - 2K(\mathbf{x}, \mathbf{x}^{(s_i)})$$