

Unsupervised Neural Machine Translation with SMT as Posterior Regularization

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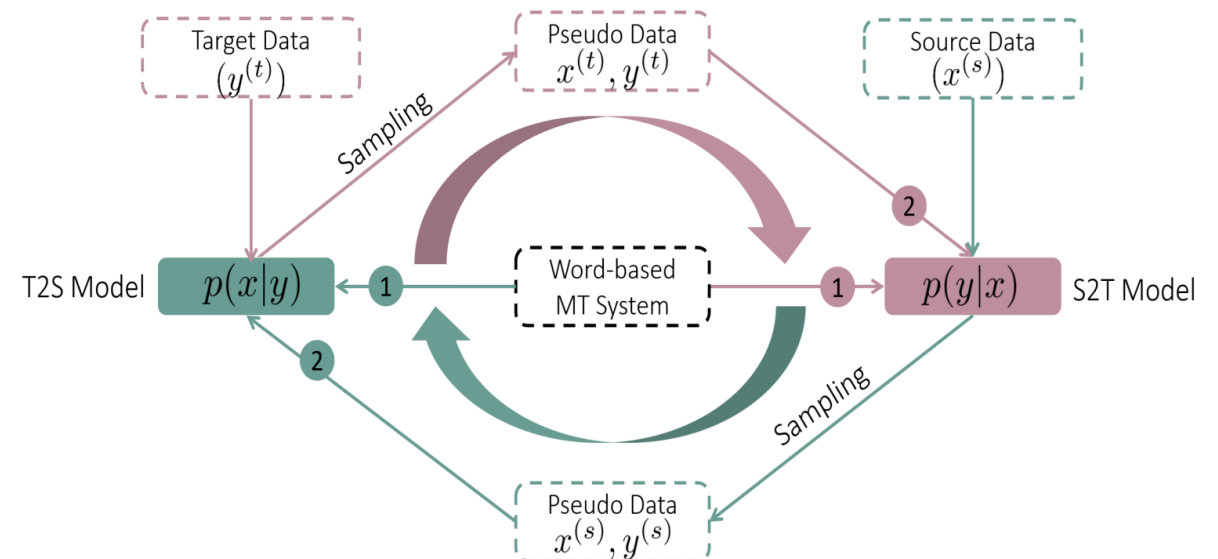
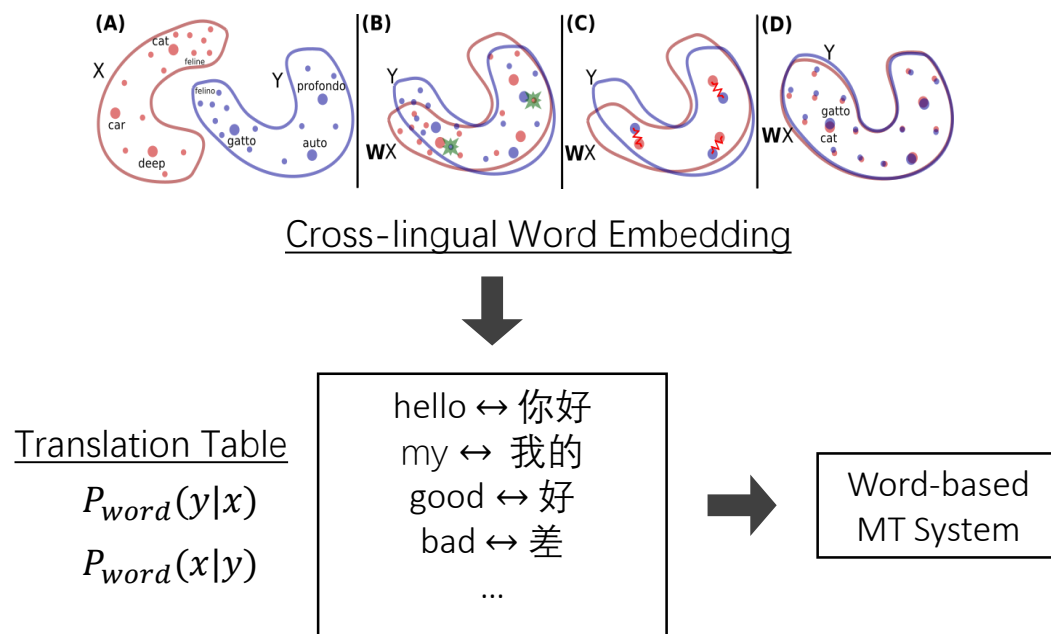
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* Contribution during internship at Microsoft Research Asia.

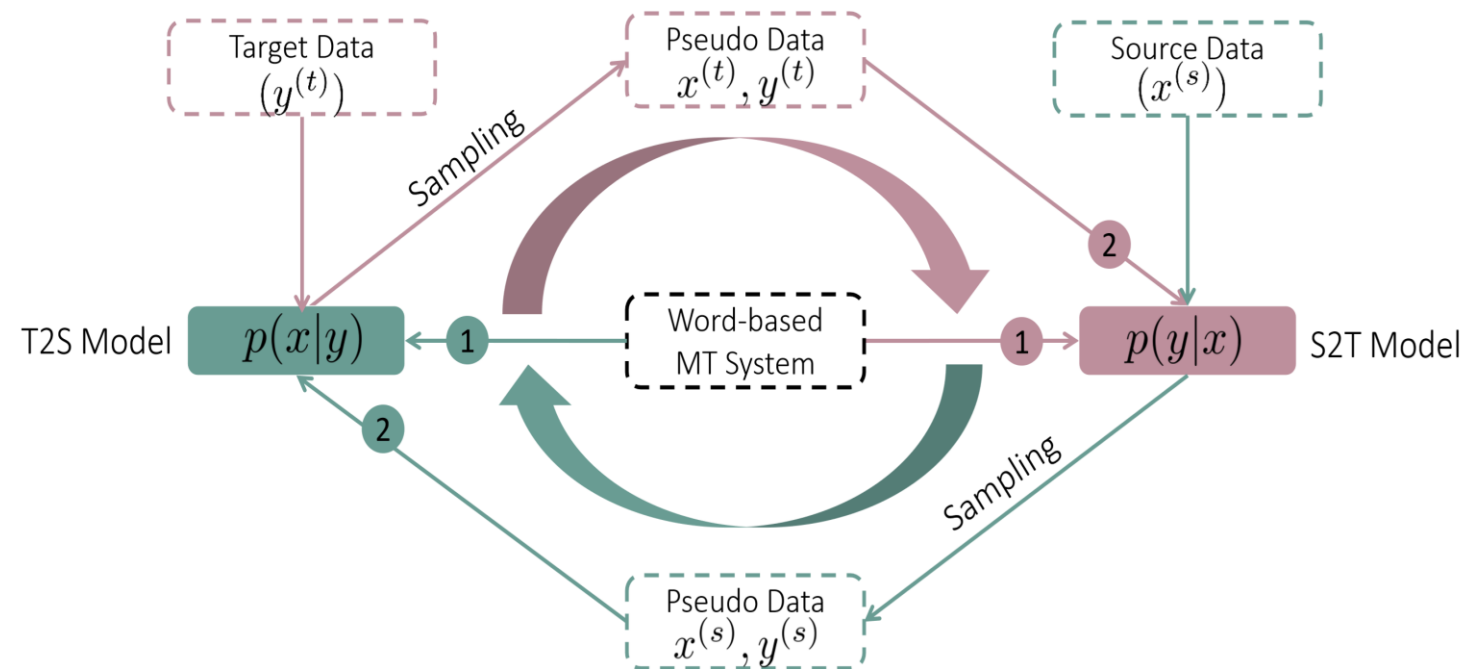
Background

- Two main components of unsupervised NMT (Lample et al. 2018)
 - Model Initialization
 - Iterative Back-translation



Motivation

- Noisy pseudo data generated with back-translation method



- Bad pseudo sentence pairs hurt the performance.
- Due to weak supervision, noises and errors will be accumulated and reinforced.
- SMT performs better than NMT in tackling noisy data (Khayrallah et al. 2018)

Unsupervised MT

- Unsupervised NMT (Artetxe et al. (2017), Lample et al. (2017), Yang et al. (2018))
 - Modifications of the enc-dec structure.
 - Weight sharing of both translation directions
 - Denoising auto-encoder and iterative back-translation are leveraged
- Unsupervised SMT (Artetxe et al. (2018), Lample et al. (2018))
 - Initialized by word-to-word translation tables.
 - Iterative back-translation performed by two SMT models

Combination NMT with SMT

- NMT as feature
 - He et al. (2016) integrate probability calculated by NMT as a feature into a log-linear model.
- Introducing phrase table into NMT
 - Tang et al. (2016) and Wang et al. (2017) leverage gate mechanisms to introduce a phrase table or candidates provided by SMT into NMT models.
- SMT as posterior regularization
 - Zhang et al. (2017) integrate more prior knowledge defined by some SMT features into NMT with the framework of posterior regularization.

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- SMT as **posterior regularization**
 - Zhang et al. (2017) integrate more prior knowledge defined by some SMT features into NMT with the framework of posterior regularization.
 - **✓ leaving the architecture of NMT unchanged**

Posterior Regularization

- Posterior regularization (Ganchev et al. 2010) can incorporate indirect supervision from a desired distribution $q(\mathbf{y})$ via constraints on posterior distribution

$$F(q; \theta) = \mathcal{L}(\theta) - \sum_{n=1}^N \min_{q \in Q} \mathbf{KL}(q(\mathbf{y}) || p(\mathbf{y} | \mathbf{x}_n; \theta))$$

Q is a constraint posterior set satisfying: $Q = \{q(\mathbf{y}) : \mathbf{E}_q[\phi(\mathbf{x}, \mathbf{y})] \leq \mathbf{b}\}$

- Update models via EM framework:

$$E : q^{t+1} = \arg \min_{q \in Q} \mathbf{KL}(q(\mathbf{y}) || p(\mathbf{y} | \mathbf{x}_n; \theta^t))$$

$$M : \theta^{t+1} = \arg \max_{\theta} \mathcal{L}(\theta) + \mathbf{E}_{q^{t+1}} [\log p(\mathbf{y} | \mathbf{x}_n; \theta)]$$

SMT as Posterior Regularization

- Leverage SMT to denoise and guide the training of unsupervised NMT models in the iterative back-translation process
- We replace the posterior regularization term $q(y)$ with the SMT models $(\vec{p}_s(y|x; \theta_{x \rightarrow y})$ and $\overleftarrow{p}_s(x|y; \theta_{y \rightarrow x})$):

$$\begin{aligned}
 \mathcal{J}(\theta_{\mathbf{x} \rightarrow \mathbf{y}}, \theta_{\mathbf{x} \leftarrow \mathbf{y}}, \vec{p}_s, \overleftarrow{p}_s) &= \bar{\mathcal{L}}(\theta_{\mathbf{x} \rightarrow \mathbf{y}}, \theta_{\mathbf{x} \leftarrow \mathbf{y}}) \\
 &- \sum_{i=1}^M \min_{\vec{p}_s} \mathbf{KL}(\vec{p}_s(\mathbf{y}|\mathbf{x}_i) || \vec{p}_n(\mathbf{y}|\mathbf{x}_i; \theta_{\mathbf{x} \rightarrow \mathbf{y}})) \\
 &- \sum_{j=1}^N \min_{\overleftarrow{p}_s} \mathbf{KL}(\overleftarrow{p}_s(\mathbf{x}|\mathbf{y}_j) || \overleftarrow{p}_n(\mathbf{x}|\mathbf{y}_j; \theta_{\mathbf{x} \leftarrow \mathbf{y}}))
 \end{aligned}$$

$$\begin{aligned}
 &\bar{\mathcal{L}}(\theta_{\mathbf{x} \rightarrow \mathbf{y}}, \theta_{\mathbf{x} \leftarrow \mathbf{y}}) \\
 &= \sum_{i=1}^M \mathbf{E}_{\mathbf{y} \sim \vec{p}_n(\mathbf{y}|\mathbf{x}_i; \theta_{\mathbf{x} \rightarrow \mathbf{y}})} [\log \overleftarrow{p}_n(\mathbf{x}_i|\mathbf{y}; \theta_{\mathbf{x} \leftarrow \mathbf{y}})] \\
 &+ \sum_{j=1}^N \mathbf{E}_{\mathbf{x} \sim \overleftarrow{p}_n(\mathbf{x}|\mathbf{y}_j; \theta_{\mathbf{x} \leftarrow \mathbf{y}})} [\log \vec{p}_n(\mathbf{y}_j|\mathbf{x}; \theta_{\mathbf{x} \rightarrow \mathbf{y}})]
 \end{aligned}$$

EM Training Algorithm

- E-Step: Optimize SMT models to minimize the KL distance between SMT models and NMT models
- M-Step: Optimize NMT models using the pseudo data generated by SMT models and the corresponding reverse NMT models

$$E : \overleftarrow{p}_s^{t+1} = \arg \max_{\overleftarrow{p}_s} \mathcal{J}(\theta_{\mathbf{x} \rightarrow \mathbf{y}}, \theta_{\mathbf{x} \leftarrow \mathbf{y}}, \overrightarrow{p}_s, \overleftarrow{p}_s)$$

$$= \arg \min_{\overleftarrow{p}_s} \mathbf{KL}(\overleftarrow{p}_s(\mathbf{x}|\mathbf{y}_j) || \overleftarrow{p}_n(\mathbf{x}|\mathbf{y}_j; \theta_{\mathbf{x} \leftarrow \mathbf{y}}^t))$$

$$\overrightarrow{p}_s^{t+1} = \arg \max_{\overrightarrow{p}_s} \mathcal{J}(\theta_{\mathbf{x} \rightarrow \mathbf{y}}, \theta_{\mathbf{x} \leftarrow \mathbf{y}}, \overrightarrow{p}_s, \overleftarrow{p}_s)$$

$$= \arg \min_{\overrightarrow{p}_s} \mathbf{KL}(\overrightarrow{p}_s(\mathbf{y}|\mathbf{x}_i) || \overrightarrow{p}_n(\mathbf{y}|\mathbf{x}_i; \theta_{\mathbf{x} \rightarrow \mathbf{y}}^t))$$

$$M : \theta_{\mathbf{x} \leftarrow \mathbf{y}}^{t+1} = \arg \max_{\theta_{\mathbf{x} \leftarrow \mathbf{y}}} \mathcal{J}(\theta_{\mathbf{x} \rightarrow \mathbf{y}}, \theta_{\mathbf{x} \leftarrow \mathbf{y}}, \overrightarrow{p}_s, \overleftarrow{p}_s)$$

$$= \arg \max_{\theta_{\mathbf{x} \leftarrow \mathbf{y}}} \{ \mathbf{E}_{\overleftarrow{p}_s^{t+1}} [\log \overleftarrow{p}_n(\mathbf{x}|\mathbf{y}_j; \theta_{\mathbf{x} \leftarrow \mathbf{y}})]$$

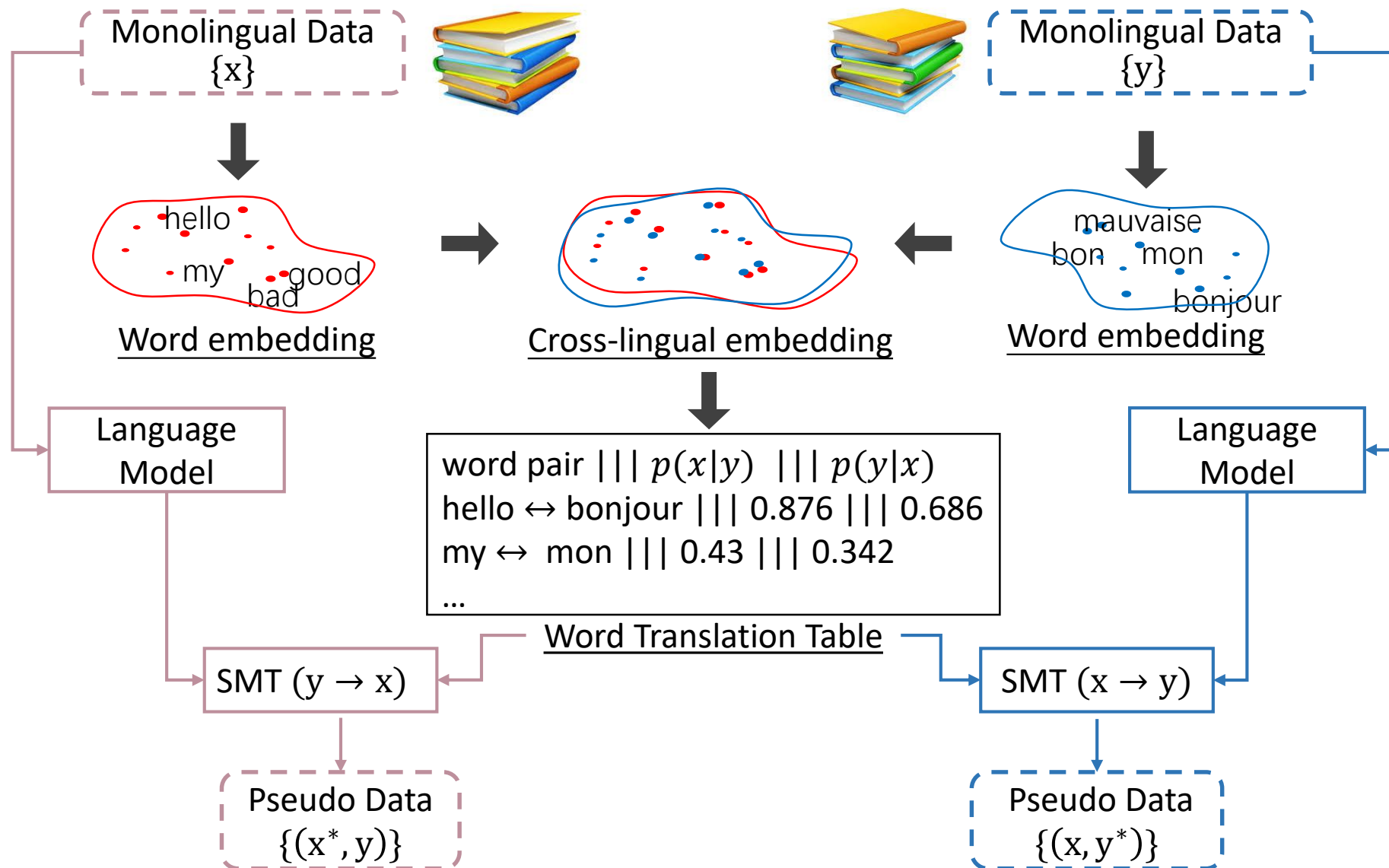
$$+ \mathbf{E}_{\overrightarrow{p}_n(\mathbf{y}|\mathbf{x}_i; \theta_{\mathbf{x} \rightarrow \mathbf{y}}^t)} [\log \overleftarrow{p}_n(\mathbf{x}_i|\mathbf{y}; \theta_{\mathbf{x} \leftarrow \mathbf{y}})] \}$$

$$\theta_{\mathbf{x} \rightarrow \mathbf{y}}^{t+1} = \arg \max_{\theta_{\mathbf{x} \rightarrow \mathbf{y}}} \mathcal{J}(\theta_{\mathbf{x} \rightarrow \mathbf{y}}, \theta_{\mathbf{x} \leftarrow \mathbf{y}}, \overrightarrow{p}_s, \overleftarrow{p}_s)$$

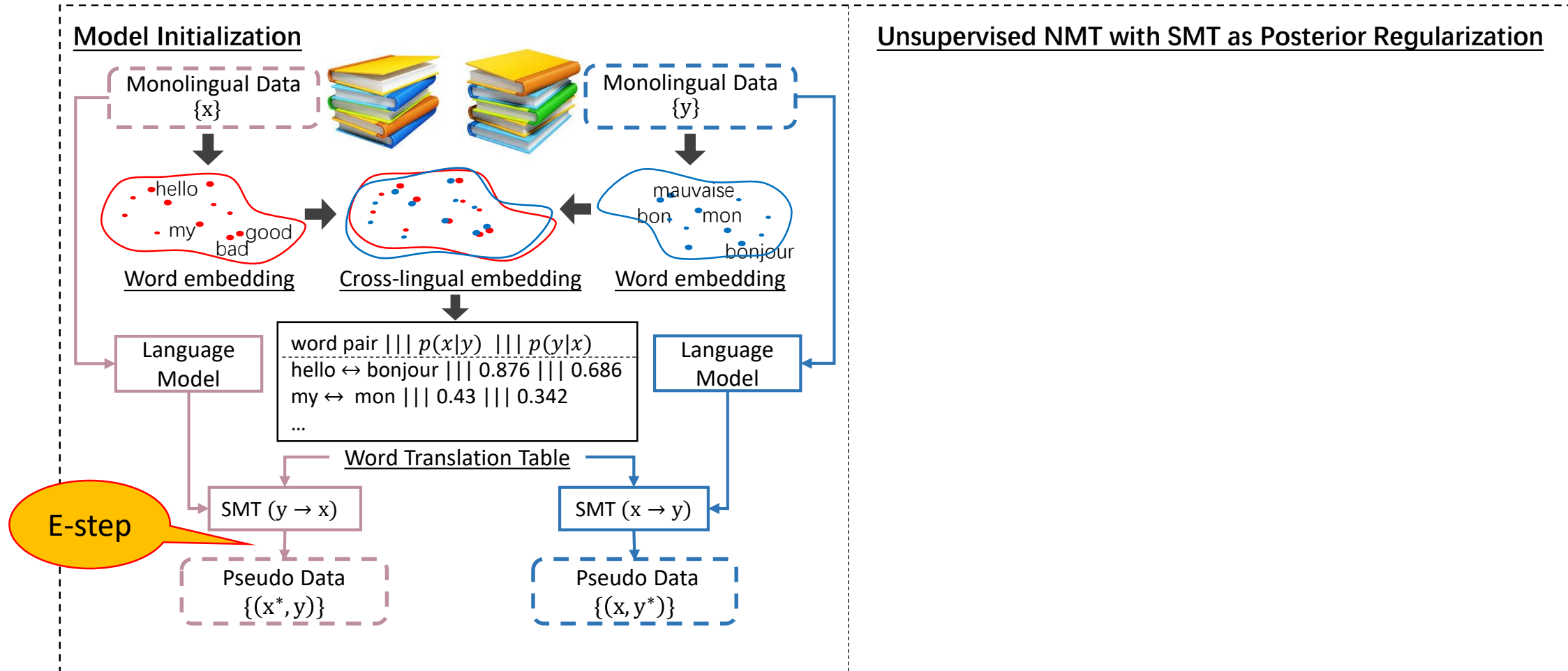
$$= \arg \max_{\theta_{\mathbf{x} \rightarrow \mathbf{y}}} \mathbf{E}_{\overrightarrow{p}_s^{t+1}} [\log \overrightarrow{p}_n(\mathbf{y}|\mathbf{x}_i; \theta_{\mathbf{x} \rightarrow \mathbf{y}})]$$

$$+ \mathbf{E}_{\overleftarrow{p}_n(\mathbf{x}|\mathbf{y}_j; \theta_{\mathbf{x} \leftarrow \mathbf{y}}^t)} [\log \overrightarrow{p}_n(\mathbf{y}_j|\mathbf{x}; \theta_{\mathbf{x} \rightarrow \mathbf{y}})]$$

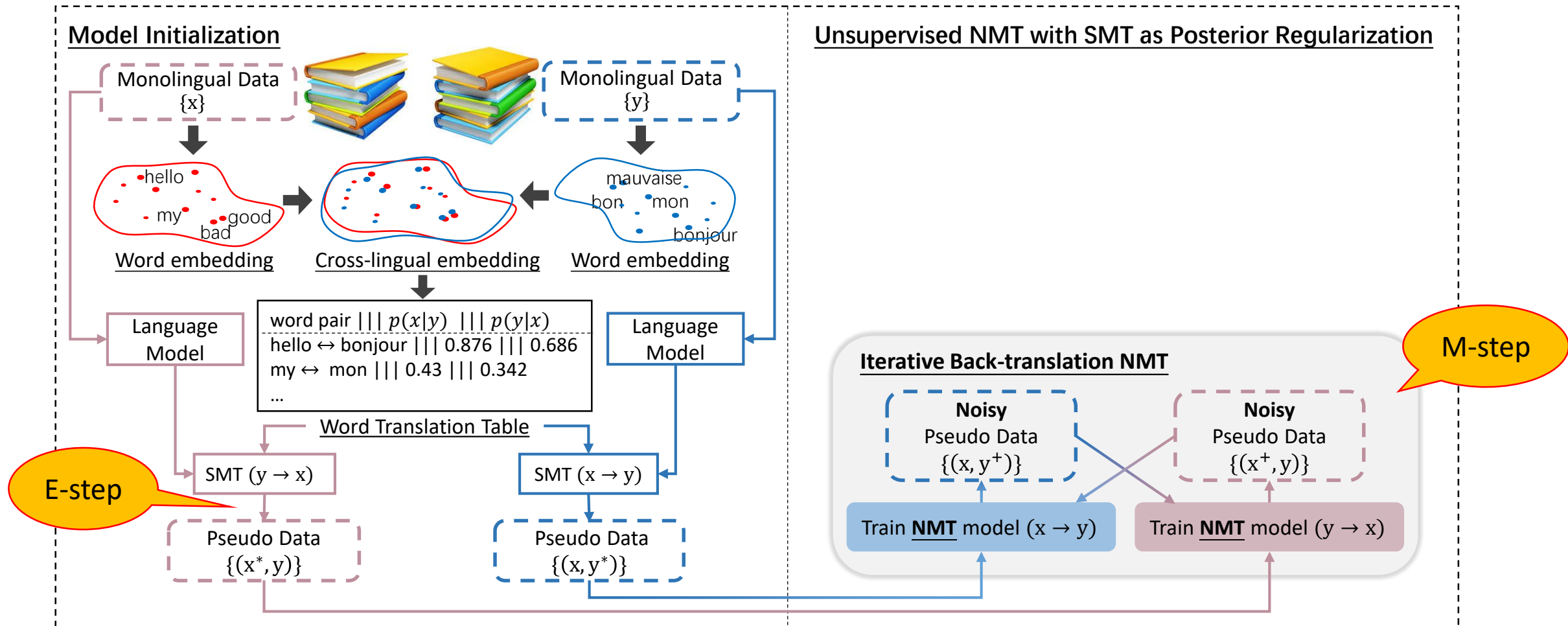
Model Initialization



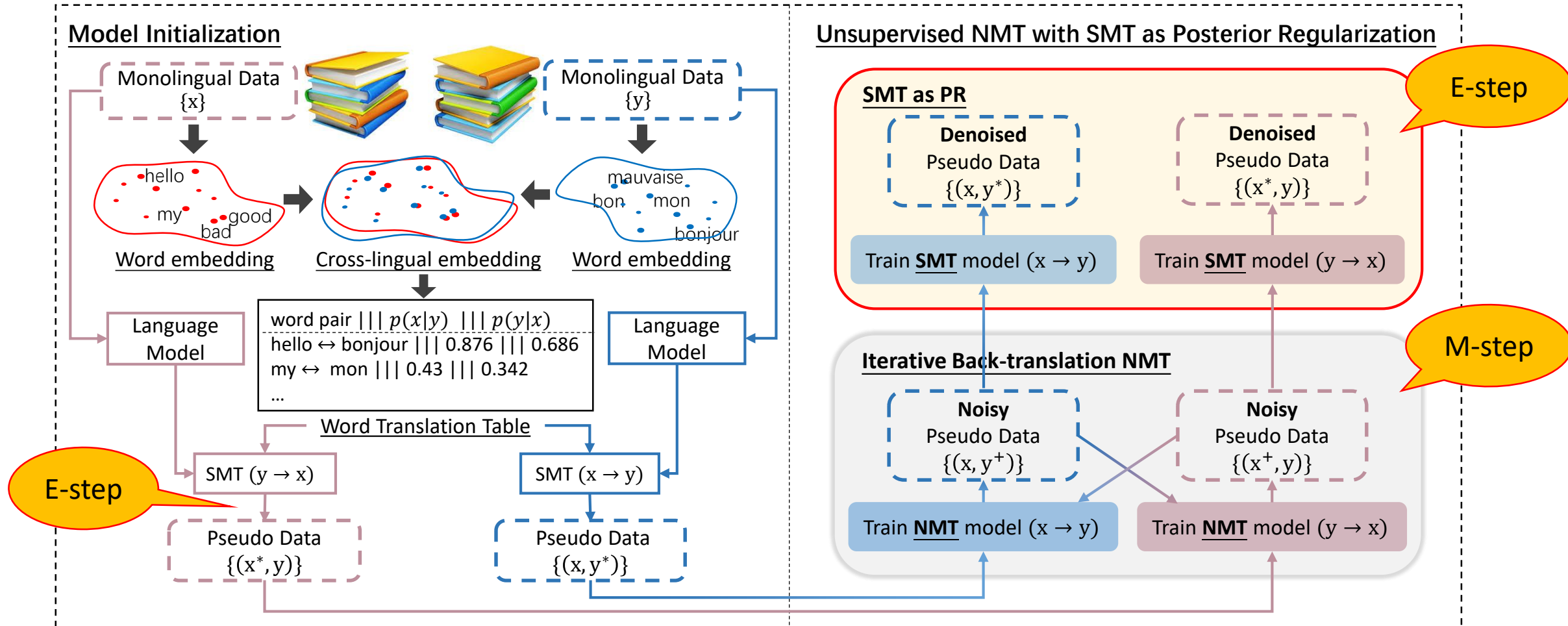
SMT as Posterior Regularization



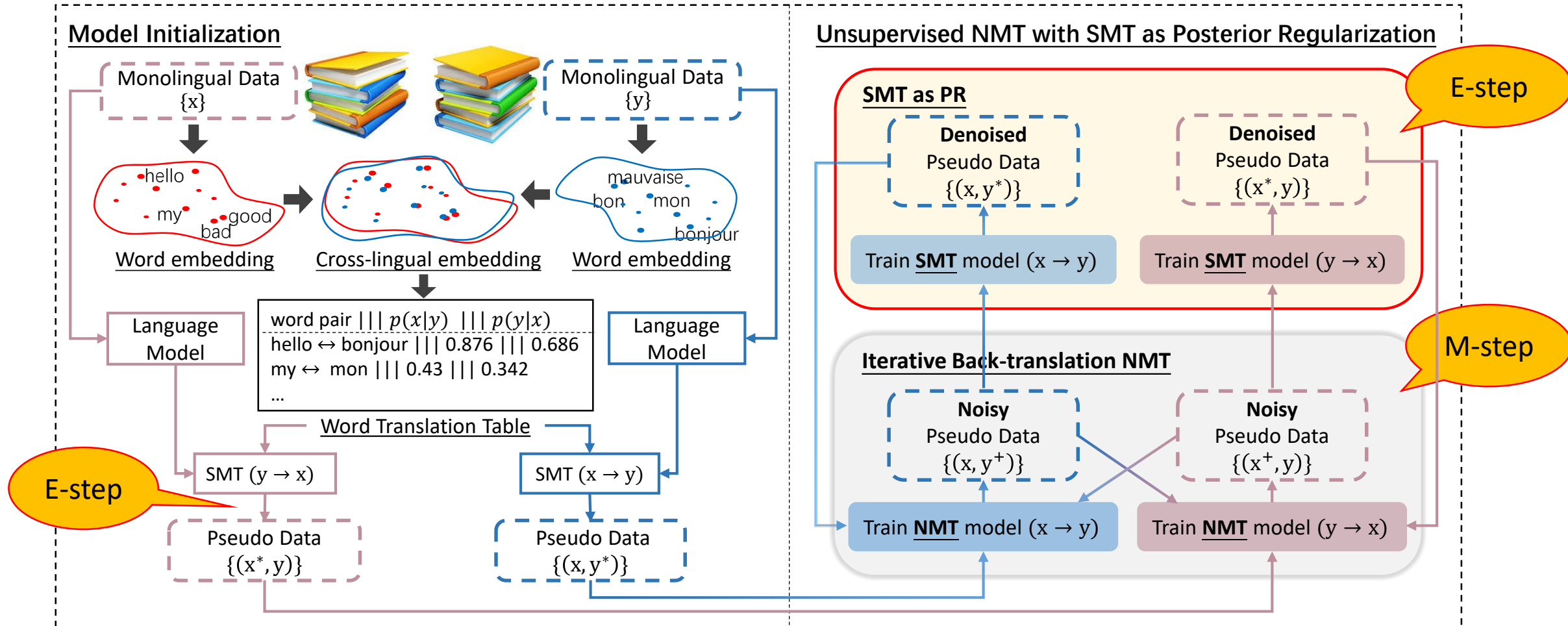
SMT as Posterior Regularization



SMT as Posterior Regularization



SMT as Posterior Regularization



Comparison Results

- Dataset
 - Monolingual data: Following the setting in (Lample et al. 2018), select 50M English, French and German sentences in NewsCrawl
 - Test data
 - English-French translation task: news-test 2014
 - English-German translation task: news-test 2014 and 2016

- Result

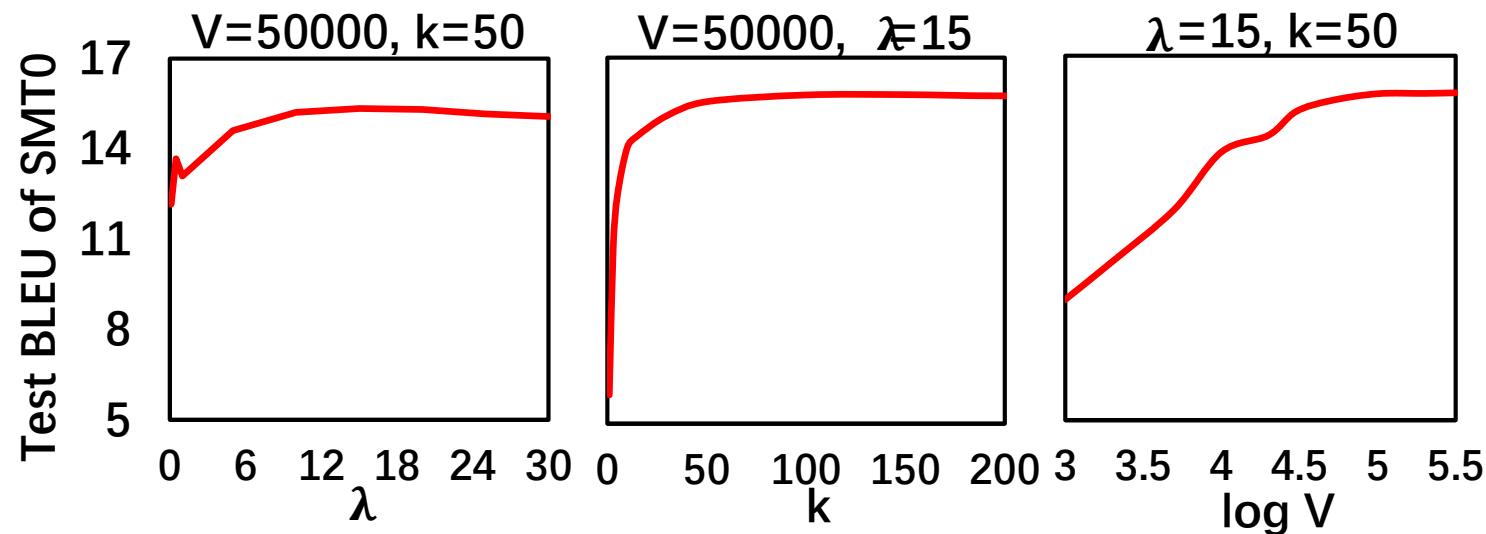
Method	fr-en	en-fr	de-en (2014)	en-de (2014)	de-en (2016)	en-de (2016)
(Artetxe et al. 2017)	15.56	15.13	10.21	6.89	-	-
(Lample, Denoyer, and Ranzato 2017)	14.31	15.05	-	-	13.33	9.64
(Yang et al. 2018)	15.58	16.97	-	-	14.62	10.86
(Lample et al. 2018), NMT	24.18	25.41	-	-	21.00	17.16
(Lample et al. 2018), PBSMT	27.16	28.11	-	-	22.68	17.77
(Lample et al. 2018), NMT+PBSMT	26.29	27.12	-	-	22.06	17.52
(Lample et al. 2018), PBSMT+NMT	27.68	27.60	-	-	25.19	20.23
Our Method	28.92	29.53	20.43	16.97	26.32	21.65

Supervised MT:
 en-fr: 41.8
 en-de(2014): 28.4

Table 1: Comparison with previous methods.

Discussion on Initialization

- Test of initial models with various hyper-parameters



$$p(y_j|x_i) = \frac{\exp [\lambda \cos(e_{x_i}, e_{y_j})]}{\sum_k \exp [\lambda \cos(e_{x_i}, e_{y_k})]}$$

λ : the peakiness controller

K : tok- k candidates in the word-to-word translation table

V : vocabulary size of both languages

- The effect of SMT0 (the first SMT models) on NMT0 (the first NMT models)

Initialization Method	fr-en	en-fr	de-en	en-de
NMT0 without SMT0	12.29	12.46	7.32	4.81
NMT0 with SMT0	24.06	24.82	16.29	12.88

Using word-to-word translation to generate pseudo data rather than SMT0 models

Example

Source	J'ai eu des relations difficiles avec lui jusqu'à ce qu'il devienne vieux, <u>malade</u> .
SMT0	I've gotten of difficult relations with him until he will become old, <u>sick</u> .
NMT0	I've had difficult relations with him until he's become old, <u>ill-fated</u> .
SMT1	I've had difficult relationships with him until he became old, <u>sick</u> .
NMT1	I had difficult relations with him until he became old and <u>sick</u> .
Reference	I had a difficult relationship with him until he became old and <u>ill</u> .
Source	Le fonds d'investissement qui était propriétaire de cette <u>bâtisse-là</u> avait des choix à faire.
SMT0	The owner of this <u>building</u> , so had to make a choice of which was an investment fund.
NMT0	The investment fund that was an owner of that <u>canopy-back business</u> had <u>plenty of</u> choice to do.
SMT1	The investment fund that was the owner of this <u>building</u> just had to make choices.
NMT1	The investment fund that was the owner of this <u>building</u> had choices to make.
Reference	The investment fund that owned the <u>building</u> had to make a choice.
Source	M. Dutton a <u>rendu visite à</u> Mme Plibersek pour garantir qu'aucun dollar <u>du</u> plan de sauvetage ne sera dépensé en bureaucratie supplémentaire.
SMT0	Mr Dutton <u>paid a visit to</u> Ms Plibersek to guarantee that the greenback no rescue plan of not be spent in extra bureaucracy.
NMT0	Mr Dutton <u>said</u> Ms Plibersek' <u>visit to</u> guarantee any dollar <u>from</u> the rescue plan will be spent in extra bureaucracy.
SMT1	Mr Dutton <u>was visiting</u> Ms Plibersek to guarantee that no dollar rescue plan will be spent on additional bureaucracy.
NMT1	Mr Dutton <u>paid a visit to</u> Ms Plibersek to guarantee that no dollar <u>from</u> the rescue plan will be spent on extra bureaucracy.
Reference	Mr Dutton <u>called on</u> Ms Plibersek to guarantee that not one dollar <u>out of</u> the rescue package would be spent on additional bureaucracy.

Table 4: Cases of translation results from French to English in *newstest* 2014. The models of SMT0, NMT0, SMT1 and NMT1 are corresponding to the steps in Table 2.

Thanks!
Q & A



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