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In [ ]: # Import necessary libraries
import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras.models import Model
from tensorflow.keras.layers import Input, LSTM, RepeatVector
from tensorflow.keras.datasets import cifar10
from sklearn.model_selection import train_test_split
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.callbacks import EarlyStopping

# Load CIFAR-10 dataset
(x_train, y_train), (x_test, y_test) = cifar10.load_data()

# Normalize the data: scale pixel values to the range [0, 1]
x_train = x_train.astype('float32') / 255.0
x_test = x_test.astype('float32') / 255.0

# Reshape the data for LSTM input (sequence length 32, features 32*3 for RGB channels)
# Each image is reshaped into a sequence of 32 rows and 96 features (32*3 for RGB)
x_train = x_train.reshape(-1, 32, 32 * 3)
x_test = x_test.reshape(-1, 32, 32 * 3)

# Split the training data into training and validation sets (80% training, 20% validation)
x_train, x_val, y_train, y_val = train_test_split(x_train, x_train, test_size=0.2, random_state=42)

# Define the LSTM autoencoder model with increased latent space size and added layers
input_img = Input(shape=(32, 32 * 3)) # Input shape: sequence length of 32, 32*3 features

# Encoder with two LSTM layers
encoded = LSTM(512, activation='tanh', return_sequences=True)(input_img) # First LSTM layer
encoded = LSTM(256, activation='tanh')(encoded) # Second LSTM layer

# Latent space representation
latent_space = RepeatVector(32)(encoded)

# Decoder with two LSTM layers
decoded = LSTM(256, activation='tanh', return_sequences=True)(latent_space) # First LSTM layer in the decoder
decoded = LSTM(32 * 3, activation='sigmoid', return_sequences=True)(decoded) # Second LSTM layer in the decoder

# Create the autoencoder model
autoencoder = Model(input_img, decoded)

# Compile the model with Adam optimizer and a reduced learning rate
autoencoder.compile(optimizer=Adam(learning_rate=0.0001), loss='mse')

# Set up early stopping to monitor validation loss and stop training if no improvement after 10 epochs
early_stopping = EarlyStopping(monitor='val_loss', patience=10, restore_best_weights=True)

# Train the model for 200 epochs, using early stopping to stop when validation loss stops improving
history = autoencoder.fit(x_train, x_train, epochs=200, batch_size=128, validation_data=(x_val, x_val), callbacks=[early_stopping])

# Plot the training and validation loss
plt.plot(history.history['loss'], label='Training Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.title('Training and Validation Loss')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.legend()
plt.show()

# Evaluate the model on the test set
test_loss = autoencoder.evaluate(x_test, x_test)
print(f"Test Loss: {test_loss}")

# Generate reconstructed images using the trained autoencoder
reconstructed = autoencoder.predict(x_test)

# Visualize the original and reconstructed images
n = 5 # Number of images to display
plt.figure(figsize=(15, 5))
for i in range(n):
    # Original
    ax = plt.subplot(2, n, i + 1)
    plt.imshow(x_test[i].reshape(32, 32, 3))
    plt.title("Original")
    plt.axis("off")

    # Reconstructed
    ax = plt.subplot(2, n, i + 1 + n)
    plt.imshow(reconstructed[i].reshape(32, 32, 3))
    plt.title("Reconstructed")
    plt.axis("off")


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plt.show()
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Downloading data from <https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz>

170498071/170498071  **4s** 0us/step

Epoch 1/200

313/313  **41s** 104ms/step - loss: 0.0525 - val_loss: 0.0299

Epoch 2/200

313/313  **33s** 91ms/step - loss: 0.0281 - val_loss: 0.0253


Epoch 3/200

313/313  **25s** 79ms/step - loss: 0.0238 - val_loss: 0.0222

Epoch 4/200

313/313  **41s** 78ms/step - loss: 0.0214 - val_loss: 0.0205

Epoch 5/200

313/313  **42s** 80ms/step - loss: 0.0199 - val_loss: 0.0192

Epoch 6/200

313/313  **41s** 79ms/step - loss: 0.0188 - val_loss: 0.0184


Epoch 7/200

313/313  **42s** 83ms/step - loss: 0.0179 - val_loss: 0.0174


Epoch 8/200

313/313  **40s** 81ms/step - loss: 0.0170 - val_loss: 0.0169


Epoch 9/200

313/313  **40s** 78ms/step - loss: 0.0165 - val_loss: 0.0163

Epoch 10/200

313/313  **25s** 79ms/step - loss: 0.0160 - val_loss: 0.0157


Epoch 11/200

313/313  **41s** 80ms/step - loss: 0.0154 - val_loss: 0.0155

Epoch 12/200

313/313  **41s** 80ms/step - loss: 0.0150 - val_loss: 0.0150

Epoch 13/200

313/313  **41s** 79ms/step - loss: 0.0147 - val_loss: 0.0145

Epoch 14/200

313/313  **43s** 85ms/step - loss: 0.0142 - val_loss: 0.0142

Epoch 15/200

313/313  **39s** 80ms/step - loss: 0.0139 - val_loss: 0.0139


Epoch 16/200

313/313  **40s** 77ms/step - loss: 0.0136 - val_loss: 0.0137


Epoch 17/200

313/313  **41s** 79ms/step - loss: 0.0135 - val_loss: 0.0135


Epoch 18/200

313/313  **41s** 80ms/step - loss: 0.0132 - val_loss: 0.0132


Epoch 19/200

313/313  **41s** 79ms/step - loss: 0.0130 - val_loss: 0.0130


Epoch 20/200

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Epoch 21/200

313/313  **42s** 83ms/step - loss: 0.0125 - val_loss: 0.0126


Epoch 22/200

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Epoch 23/200

313/313  **25s** 81ms/step - loss: 0.0122 - val_loss: 0.0123


Epoch 24/200

313/313  **25s** 81ms/step - loss: 0.0120 - val_loss: 0.0121

Epoch 25/200

313/313  **41s** 81ms/step - loss: 0.0118 - val_loss: 0.0119


Epoch 26/200

313/313  **41s** 82ms/step - loss: 0.0117 - val_loss: 0.0118


Epoch 27/200

313/313  **41s** 83ms/step - loss: 0.0116 - val_loss: 0.0116


Epoch 28/200

313/313  **41s** 82ms/step - loss: 0.0114 - val_loss: 0.0115


Epoch 29/200

313/313  **41s** 81ms/step - loss: 0.0113 - val_loss: 0.0113


Epoch 30/200

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Epoch 31/200

313/313  **40s** 80ms/step - loss: 0.0110 - val_loss: 0.0110

Epoch 32/200

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Epoch 33/200

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Epoch 34/200

313/313  **41s** 80ms/step - loss: 0.0106 - val_loss: 0.0107

Epoch 35/200

313/313  **41s** 81ms/step - loss: 0.0105 - val_loss: 0.0106


Epoch 36/200

313/313  **41s** 82ms/step - loss: 0.0104 - val_loss: 0.0104


Epoch 37/200

313/313  **41s** 82ms/step - loss: 0.0103 - val_loss: 0.0104

Epoch 38/200

313/313  **41s** 81ms/step - loss: 0.0102 - val_loss: 0.0102

Epoch 39/200

313/313  **41s** 82ms/step - loss: 0.0101 - val_loss: 0.0101

Epoch 40/200

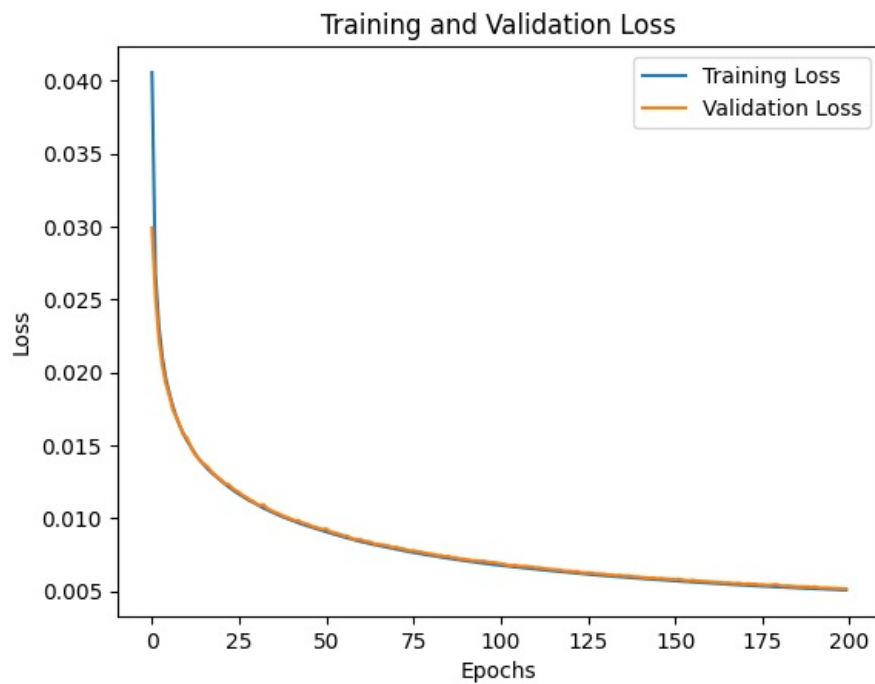
313/313  **40s** 80ms/step - loss: 0.0100 - val_loss: 0.0101

Epoch 41/200				
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Epoch 42/200				
313/313	<div></div>	42s	84ms/step	loss: 0.0098 - val_loss: 0.0098
Epoch 43/200				
313/313	<div></div>	25s	80ms/step	loss: 0.0097 - val_loss: 0.0099
Epoch 44/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0096 - val_loss: 0.0097
Epoch 45/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0095 - val_loss: 0.0096
Epoch 46/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0095 - val_loss: 0.0096
Epoch 47/200				
313/313	<div></div>	41s	81ms/step	loss: 0.0094 - val_loss: 0.0094
Epoch 48/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0093 - val_loss: 0.0094
Epoch 49/200				
313/313	<div></div>	42s	83ms/step	loss: 0.0092 - val_loss: 0.0093
Epoch 50/200				
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Epoch 51/200				
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Epoch 52/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0090 - val_loss: 0.0091
Epoch 53/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0090 - val_loss: 0.0090
Epoch 54/200				
313/313	<div></div>	41s	81ms/step	loss: 0.0089 - val_loss: 0.0090
Epoch 55/200				
313/313	<div></div>	41s	81ms/step	loss: 0.0088 - val_loss: 0.0089
Epoch 56/200				
313/313	<div></div>	41s	81ms/step	loss: 0.0087 - val_loss: 0.0088
Epoch 57/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0087 - val_loss: 0.0088
Epoch 58/200				
313/313	<div></div>	41s	81ms/step	loss: 0.0086 - val_loss: 0.0086
Epoch 59/200				
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Epoch 60/200				
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Epoch 61/200				
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Epoch 62/200				
313/313	<div></div>	42s	85ms/step	loss: 0.0084 - val_loss: 0.0084
Epoch 63/200				
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Epoch 64/200				
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Epoch 65/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0081 - val_loss: 0.0082
Epoch 66/200				
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Epoch 67/200				
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Epoch 68/200				
313/313	<div></div>	36s	81ms/step	loss: 0.0081 - val_loss: 0.0081
Epoch 69/200				
313/313	<div></div>	42s	85ms/step	loss: 0.0080 - val_loss: 0.0081
Epoch 70/200				
313/313	<div></div>	39s	80ms/step	loss: 0.0080 - val_loss: 0.0080
Epoch 71/200				
313/313	<div></div>	25s	80ms/step	loss: 0.0079 - val_loss: 0.0080
Epoch 72/200				
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Epoch 73/200				
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Epoch 74/200				
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Epoch 75/200				
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Epoch 76/200				
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Epoch 77/200				
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Epoch 78/200				
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Epoch 79/200				
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Epoch 81/200				
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Epoch 82/200				

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Epoch 83/200				
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Epoch 84/200				
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Epoch 85/200				
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Epoch 86/200				
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Epoch 87/200				
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Epoch 88/200				
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Epoch 89/200				
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Epoch 90/200				
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Epoch 91/200				
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Epoch 92/200				
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Epoch 93/200				
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Epoch 94/200				
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Epoch 95/200				
313/313	40s	78ms/step	- loss: 0.0069	- val_loss: 0.0071
Epoch 96/200				
313/313	41s	80ms/step	- loss: 0.0069	- val_loss: 0.0071
Epoch 97/200				
313/313	41s	81ms/step	- loss: 0.0069	- val_loss: 0.0070
Epoch 98/200				
313/313	41s	82ms/step	- loss: 0.0068	- val_loss: 0.0070
Epoch 99/200				
313/313	27s	85ms/step	- loss: 0.0068	- val_loss: 0.0070
Epoch 100/200				
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Epoch 101/200				
313/313	41s	82ms/step	- loss: 0.0067	- val_loss: 0.0069
Epoch 102/200				
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Epoch 103/200				
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Epoch 104/200				
313/313	41s	82ms/step	- loss: 0.0067	- val_loss: 0.0068
Epoch 105/200				
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Epoch 106/200				
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Epoch 107/200				
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Epoch 108/200				
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Epoch 109/200				
313/313	41s	80ms/step	- loss: 0.0066	- val_loss: 0.0067
Epoch 110/200				
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Epoch 111/200				
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Epoch 112/200				
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Epoch 113/200				
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Epoch 114/200				
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Epoch 115/200				
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Epoch 116/200				
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Epoch 117/200				
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Epoch 118/200				
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Epoch 119/200				
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Epoch 120/200				
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Epoch 121/200				
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Epoch 122/200				
313/313	41s	80ms/step	- loss: 0.0062	- val_loss: 0.0063
Epoch 123/200				
313/313	26s	84ms/step	- loss: 0.0062	- val_loss: 0.0064

Epoch 124/200				
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Epoch 125/200				
313/313	<div></div>	41s	78ms/step	loss: 0.0061 - val_loss: 0.0063
Epoch 126/200				
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Epoch 127/200				
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Epoch 128/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0061 - val_loss: 0.0062
Epoch 129/200				
313/313	<div></div>	25s	79ms/step	loss: 0.0061 - val_loss: 0.0062
Epoch 130/200				
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Epoch 131/200				
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Epoch 132/200				
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Epoch 133/200				
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Epoch 134/200				
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Epoch 135/200				
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Epoch 136/200				
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Epoch 137/200				
313/313	<div></div>	41s	79ms/step	loss: 0.0060 - val_loss: 0.0060
Epoch 138/200				
313/313	<div></div>	40s	77ms/step	loss: 0.0059 - val_loss: 0.0060
Epoch 139/200				
313/313	<div></div>	42s	80ms/step	loss: 0.0059 - val_loss: 0.0060
Epoch 140/200				
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Epoch 141/200				
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Epoch 142/200				
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Epoch 143/200				
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Epoch 144/200				
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Epoch 145/200				
313/313	<div></div>	39s	80ms/step	loss: 0.0058 - val_loss: 0.0059
Epoch 146/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0058 - val_loss: 0.0059
Epoch 147/200				
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Epoch 148/200				
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Epoch 149/200				
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Epoch 150/200				
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Epoch 151/200				
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Epoch 152/200				
313/313	<div></div>	40s	81ms/step	loss: 0.0057 - val_loss: 0.0058
Epoch 153/200				
313/313	<div></div>	41s	81ms/step	loss: 0.0057 - val_loss: 0.0058
Epoch 154/200				
313/313	<div></div>	41s	81ms/step	loss: 0.0057 - val_loss: 0.0057
Epoch 155/200				
313/313	<div></div>	40s	79ms/step	loss: 0.0057 - val_loss: 0.0057
Epoch 156/200				
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Epoch 157/200				
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Epoch 158/200				
313/313	<div></div>	41s	82ms/step	loss: 0.0056 - val_loss: 0.0057
Epoch 159/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0056 - val_loss: 0.0057
Epoch 160/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0056 - val_loss: 0.0057
Epoch 161/200				
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Epoch 162/200				
313/313	<div></div>	25s	81ms/step	loss: 0.0055 - val_loss: 0.0056
Epoch 163/200				
313/313	<div></div>	41s	80ms/step	loss: 0.0055 - val_loss: 0.0056
Epoch 164/200				
313/313	<div></div>	26s	83ms/step	loss: 0.0055 - val_loss: 0.0056
Epoch 165/200				

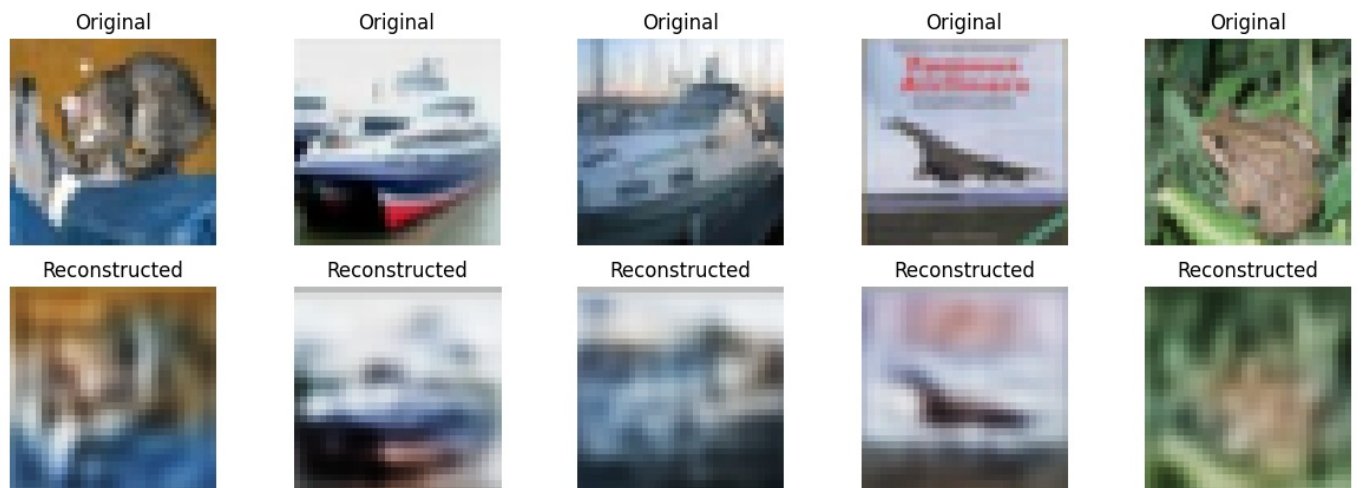
313/313	40s	80ms/step	- loss: 0.0055	- val_loss: 0.0056
Epoch 166/200				
313/313	41s	80ms/step	- loss: 0.0055	- val_loss: 0.0056
Epoch 167/200				
313/313	41s	80ms/step	- loss: 0.0055	- val_loss: 0.0056
Epoch 168/200				
313/313	41s	80ms/step	- loss: 0.0054	- val_loss: 0.0055
Epoch 169/200				
313/313	41s	80ms/step	- loss: 0.0054	- val_loss: 0.0056
Epoch 170/200				
313/313	42s	84ms/step	- loss: 0.0054	- val_loss: 0.0055
Epoch 171/200				
313/313	40s	79ms/step	- loss: 0.0054	- val_loss: 0.0055
Epoch 172/200				
313/313	25s	79ms/step	- loss: 0.0054	- val_loss: 0.0055
Epoch 173/200				
313/313	25s	80ms/step	- loss: 0.0054	- val_loss: 0.0055
Epoch 174/200				
313/313	25s	80ms/step	- loss: 0.0054	- val_loss: 0.0055
Epoch 175/200				
313/313	25s	79ms/step	- loss: 0.0054	- val_loss: 0.0054
Epoch 176/200				
313/313	41s	80ms/step	- loss: 0.0054	- val_loss: 0.0055
Epoch 177/200				
313/313	25s	80ms/step	- loss: 0.0053	- val_loss: 0.0054
Epoch 178/200				
313/313	26s	82ms/step	- loss: 0.0053	- val_loss: 0.0054
Epoch 179/200				
313/313	41s	81ms/step	- loss: 0.0053	- val_loss: 0.0054
Epoch 180/200				
313/313	41s	81ms/step	- loss: 0.0053	- val_loss: 0.0055
Epoch 181/200				
313/313	26s	83ms/step	- loss: 0.0053	- val_loss: 0.0054
Epoch 182/200				
313/313	41s	83ms/step	- loss: 0.0053	- val_loss: 0.0054
Epoch 183/200				
313/313	40s	81ms/step	- loss: 0.0053	- val_loss: 0.0054
Epoch 184/200				
313/313	25s	80ms/step	- loss: 0.0052	- val_loss: 0.0054
Epoch 185/200				
313/313	42s	84ms/step	- loss: 0.0052	- val_loss: 0.0053
Epoch 186/200				
313/313	40s	81ms/step	- loss: 0.0052	- val_loss: 0.0053
Epoch 187/200				
313/313	41s	81ms/step	- loss: 0.0052	- val_loss: 0.0053
Epoch 188/200				
313/313	41s	81ms/step	- loss: 0.0052	- val_loss: 0.0053
Epoch 189/200				
313/313	25s	80ms/step	- loss: 0.0052	- val_loss: 0.0053
Epoch 190/200				
313/313	40s	78ms/step	- loss: 0.0052	- val_loss: 0.0053
Epoch 191/200				
313/313	42s	81ms/step	- loss: 0.0052	- val_loss: 0.0053
Epoch 192/200				
313/313	41s	80ms/step	- loss: 0.0051	- val_loss: 0.0053
Epoch 193/200				
313/313	41s	80ms/step	- loss: 0.0051	- val_loss: 0.0052
Epoch 194/200				
313/313	41s	81ms/step	- loss: 0.0051	- val_loss: 0.0052
Epoch 195/200				
313/313	41s	80ms/step	- loss: 0.0051	- val_loss: 0.0052
Epoch 196/200				
313/313	41s	80ms/step	- loss: 0.0051	- val_loss: 0.0052
Epoch 197/200				
313/313	41s	81ms/step	- loss: 0.0051	- val_loss: 0.0052
Epoch 198/200				
313/313	41s	80ms/step	- loss: 0.0051	- val_loss: 0.0052
Epoch 199/200				
313/313	41s	81ms/step	- loss: 0.0051	- val_loss: 0.0052
Epoch 200/200				
313/313	41s	80ms/step	- loss: 0.0051	- val_loss: 0.0052



313/313 ————— 6s 18ms/step - loss: 0.0052

Test Loss: 0.005131924524903297

313/313 ————— 7s 22ms/step



The Original images to understand what the classes of images look like

```
In [3]: import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras.datasets import cifar10

# Load CIFAR-10 dataset
(x_train, y_train), (x_test, y_test) = cifar10.load_data()

# Get unique labels (classes)
unique_labels = np.unique(y_train)

# Create a figure and axes
plt.figure(figsize=(15, 3))

# Iterate through unique labels
```



```

for i in range(10):
    # Find an image with the current label
    index = np.where(y_train == i)[0][0]
    image = x_train[index]

    # Create a subplot for each image
    ax = plt.subplot(1, 10, i + 1)
    plt.imshow(image)
    plt.title(f"Class {i}")
    plt.axis("off")

# Show the plot
plt.show()

```



Pixel representation of the images after normalization

```

In [5]: import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras.datasets import cifar10

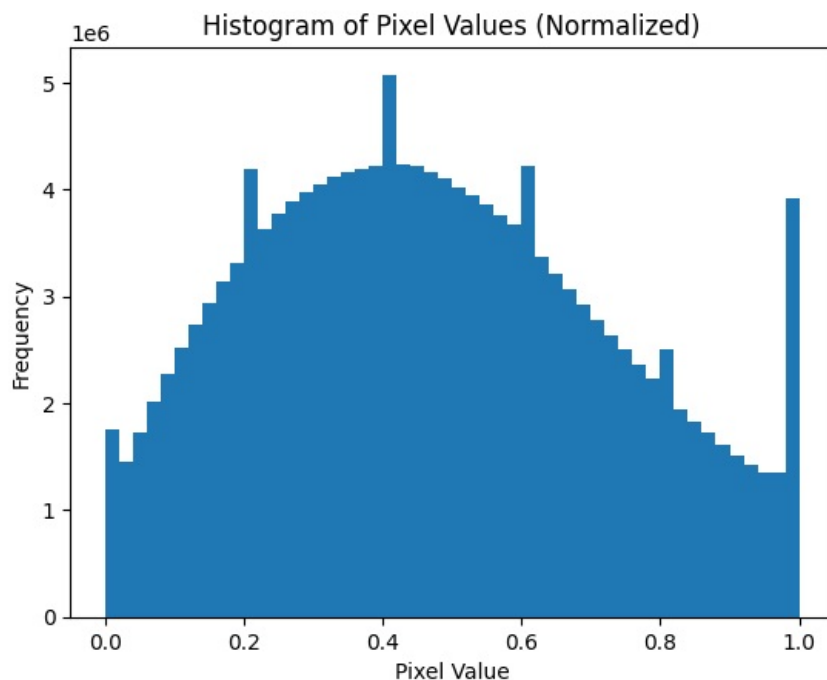
# Load CIFAR-10 dataset
(x_train, y_train), (x_test, y_test) = cifar10.load_data()

# Normalize the data: scale pixel values to the range [0, 1]
x_train = x_train.astype('float32') / 255.0

# Flatten the normalized image data
flattened_images = x_train.reshape(-1)

# Create a histogram of the pixel values
plt.hist(flattened_images, bins=50) # Adjust the number of bins for better visualization
plt.xlabel('Pixel Value')
plt.ylabel('Frequency')
plt.title('Histogram of Pixel Values (Normalized)')
plt.show()

```



Mean variances of images to access the brightness

```

In [8]: import numpy as np
import pandas as pd

# Load CIFAR-10 dataset
(x_train, y_train), (x_test, y_test) = cifar10.load_data()

# Normalize the data: scale pixel values to the range [0, 1]

```



```

x_train = x_train.astype('float32') / 255.0

# Calculate mean and variance for each image
means = []
variances = []

for image in x_train:
    means.append(np.mean(image))
    variances.append(np.var(image))

# Create a Pandas DataFrame to store and display the data
data = {'Mean Pixel Intensity (Normalized)': means, 'Variance': variances}
df = pd.DataFrame(data)

# Display the DataFrame
print(df)
# Optionally, you can round the values for better readability
# df = df.round(2)

# Display the rounded DataFrame
print(df.round(2))

```

	Mean Pixel Intensity (Normalized)	Variance
0	0.405676	0.041542
1	0.511166	0.056251
2	0.524473	0.104832
3	0.314605	0.020457
4	0.405784	0.056382
...
49995	0.594171	0.058287
49996	0.572502	0.096438
49997	0.411914	0.087331
49998	0.664484	0.050202
49999	0.517177	0.051731

[50000 rows x 2 columns]

	Mean Pixel Intensity (Normalized)	Variance
0	0.41	0.04
1	0.51	0.06
2	0.52	0.10
3	0.31	0.02
4	0.41	0.06
...
49995	0.59	0.06
49996	0.57	0.10
49997	0.41	0.09
49998	0.66	0.05
49999	0.52	0.05

[50000 rows x 2 columns]

Relationships between pixel values accross the RGB colour channels

```

In [9]: import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras.datasets import cifar10

# Load CIFAR-10 dataset
(x_train, y_train), (x_test, y_test) = cifar10.load_data()

# Normalize the data (optional, but helps with visualization)
x_train = x_train.astype('float32') / 255.0

# Choose a random image from the training set
image_index = np.random.randint(0, len(x_train))
image = x_train[image_index]

# Extract the red, green, and blue channels
red_channel = image[:, :, 0]
green_channel = image[:, :, 1]
blue_channel = image[:, :, 2]

# Create a scatter plot for Red vs Green, Green vs Blue, and Red vs Blue
plt.figure(figsize=(15, 5))

plt.subplot(1, 3, 1)
plt.scatter(red_channel.flatten(), green_channel.flatten(), s=1) # s=1 for smaller marker size
plt.xlabel('Red Channel')
plt.ylabel('Green Channel')
plt.title('Red vs. Green')

```

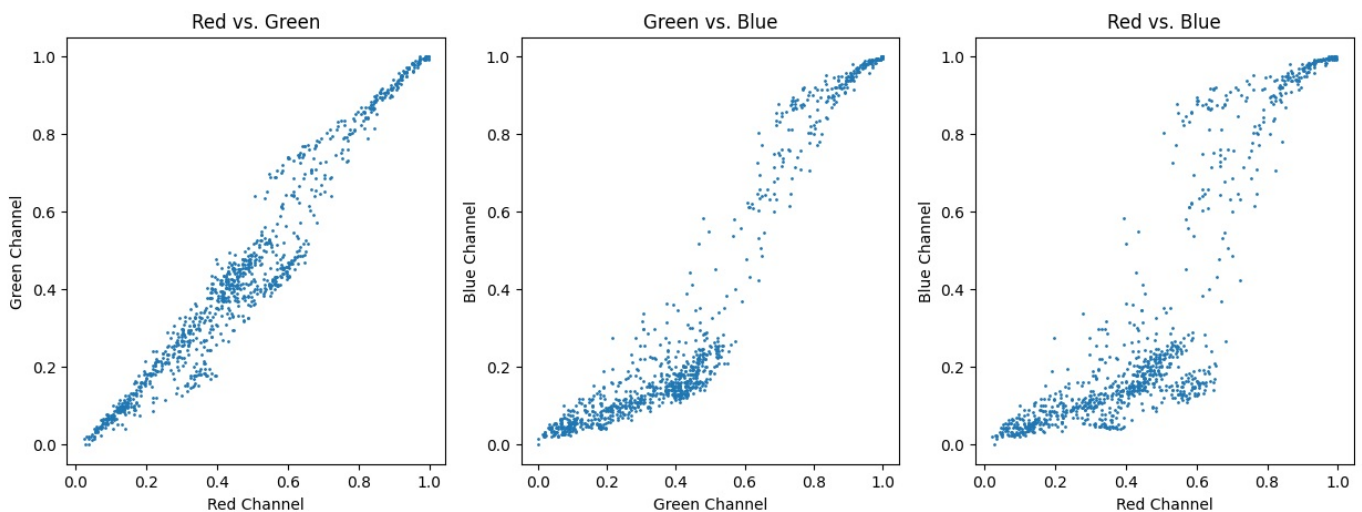
```
plt.subplot(1, 3, 2)
plt.scatter(green_channel.flatten(), blue_channel.flatten(), s=1)
plt.xlabel('Green Channel')
plt.ylabel('Blue Channel')
plt.title('Green vs. Blue')

plt.subplot(1, 3, 3)
plt.scatter(red_channel.flatten(), blue_channel.flatten(), s=1)
plt.xlabel('Red Channel')
plt.ylabel('Blue Channel')
plt.title('Red vs. Blue')

plt.show()

# You can also calculate correlation coefficients between the channels to quantify the relationships.
correlation_rg = np.corrcoef(red_channel.flatten(), green_channel.flatten())[0, 1]
correlation_gb = np.corrcoef(green_channel.flatten(), blue_channel.flatten())[0, 1]
correlation_rb = np.corrcoef(red_channel.flatten(), blue_channel.flatten())[0, 1]

print(f"Correlation between Red and Green: {correlation_rg}")
print(f"Correlation between Green and Blue: {correlation_gb}")
print(f"Correlation between Red and Blue: {correlation_rb}")
```



Correlation between Red and Green: 0.9741234363831361
Correlation between Green and Blue: 0.9332290393269796
Correlation between Red and Blue: 0.8661948968530371

```
In [10]: import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
import pandas as pd
from tensorflow.keras.datasets import cifar10

# Load CIFAR-10 dataset
(x_train, y_train), (x_test, y_test) = cifar10.load_data()

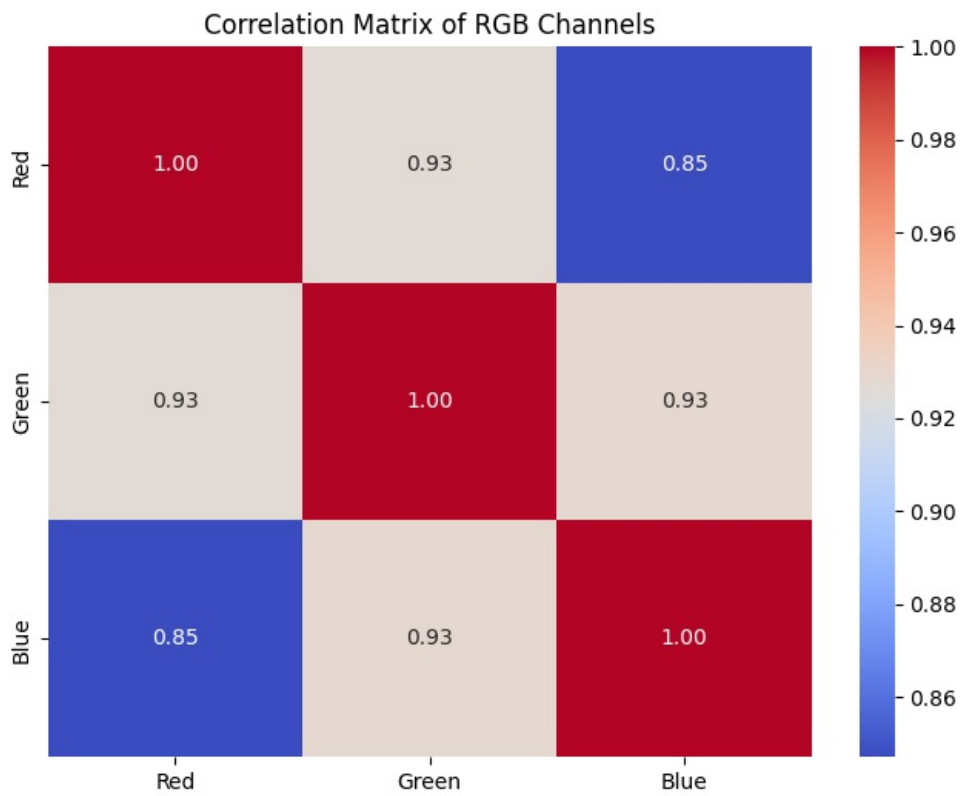
# Normalize the data (optional, but helps with visualization)
x_train = x_train.astype('float32') / 255.0

# Calculate correlation matrix for RGB channels
correlation_matrix = np.zeros((3, 3))
for i in range(len(x_train)):
    image = x_train[i]
    red_channel = image[:, :, 0].flatten()
    green_channel = image[:, :, 1].flatten()
    blue_channel = image[:, :, 2].flatten()
    channels = np.stack((red_channel, green_channel, blue_channel))
    correlation_matrix += np.corrcoef(channels)

correlation_matrix /= len(x_train)

# Create a DataFrame for the correlation matrix
df_correlation = pd.DataFrame(correlation_matrix, columns=['Red', 'Green', 'Blue'], index=['Red', 'Green', 'Blue'])

# Plot the correlation matrix using Seaborn
plt.figure(figsize=(8, 6))
sns.heatmap(df_correlation, annot=True, cmap='coolwarm', fmt=".2f")
plt.title('Correlation Matrix of RGB Channels')
plt.show()
```



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