

Collaborative Retail Shelf Restock Manager

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Revolutionising Retail Restocking



AI-Driven Multi-Agent System

Automated retail restocking using intelligent robotic coordination



Smart Task Allocation

Priority-based scheduling with real-time cloud coordination



Proven Results

Improved efficiency and balanced workload distribution



The Challenge

Dynamic retail environments demand efficient multi-robot coordination to maintain optimal stock levels and customer satisfaction.



Uneven Workloads

Robots experience excessive idle time whilst others remain overloaded



Static Scheduling

Inflexible systems cannot adapt to changing store conditions



Poor Adaptability

Traditional methods fail to respond to real-time priority changes

Project Objectives

01

Data Collection

Retrieve restock data from Agent 1 via Google Cloud Storage

02

Task Prioritisation

Analyse urgency and proximity factors for optimal scheduling

03

Implement Scheduling

Deploy priority-based system with greedy robot selection

04

Visualise Execution

Create 2D grid representation of task allocation

05

Evaluate Performance

Measure metrics and share feedback to cloud platform

Methodology & Algorithms



Priority Queue Scheduling

Urgent tasks processed first based on criticality



Greedy Robot Selection

Assign nearest available robot to minimise travel



Dynamic Load Balancing

Real-time workload redistribution across fleet

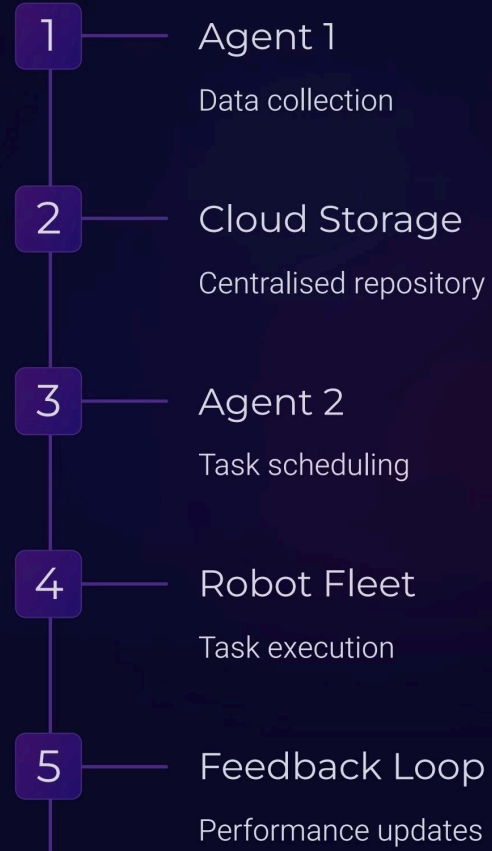


AI-Heuristic Optimisation

Adaptive responses to congestion and demand

System Architecture

📄 **Core Technologies:** Python scheduling algorithms (heapq), Matplotlib visualisation, real-time performance metrics tracking



Performance Results

35%

Faster
Completion

Reduced total task
completion time versus
static scheduling

25%

Better Utilisation

Improved robot
utilisation efficiency
across fleet

100%

Task Success

All priority items
restocked within target
timeframes

Sample assignments demonstrate intelligent routing: Eggs003 → R2 (closest at [3, 8]), Milk001 → R1 (minimal travel distance)



Visual Task Execution



Key Achievements

- Clear 2D path visualisation
- Balanced task distribution
- Reduced travel distances
- Real-time adaptability

System Benefits

- Transparent operations
- Predictable outcomes
- Scalable architecture
- Data-driven decisions



Future Scope



Smarter Scheduling

Incorporate battery levels, load capacity, path congestion



IoT Integration

Connect with smart shelves for predictive restocking



Reinforcement Learning

Adaptive intelligence through continuous system improvement



Enterprise Scale

Multi-store collaboration and fleet management

Thank You

Efficiency Through Intelligent Automation

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Algorithm Design & Simulation

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Cloud Integration

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Testing & Documentation

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Data Handling & Visualisation

Questions & Discussion

