

Technical Approach

Core Architecture

1. Detection Pipeline

- Fine-tuned YOLOv11 model for player detection
- Confidence-based filtering for reliable detections
- Bounding box optimization for tracking accuracy

2. Tracking Algorithm

- Multi-object tracking with persistent IDs
- Kalman filtering for motion prediction
- Adaptive frame boundary detection

3. Re-identification System

- Appearance feature extraction using color histograms
- Cosine similarity matching for player re-entry.
- Exponential moving average for feature updates

Key Techniques Implemented

Motion Modeling: Implemented Kalman filters with constant velocity models for smooth trajectory prediction and handling temporary occlusions.

Appearance Features: Extracted HSV color histograms from player regions to create distinctive appearance signatures for re-identification.

Data Association: Used Hungarian algorithm for optimal assignment between detections and existing tracks, combining motion, appearance, and spatial cues.

Boundary Detection: Developed adaptive margin calculation based on bounding box dimensions to accurately determine frame entry/exit events.

Track Management: Implemented sophisticated track lifecycle management with configurable persistence duration for handling occlusions.

Challenges Encountered

1. Model Integration Complexity

Challenge: Integrating custom fine-tuned YOLOv11 models with tracking algorithms while maintaining real-time performance.

Solution: Optimized inference pipeline by using appropriate confidence thresholds and implementing efficient batch processing for video frames.

2. Re-identification Accuracy

Challenge: Maintaining consistent player identities when players temporarily exit and re-enter the frame, especially with similar appearances.

Solution: Developed multi-modal feature matching combining appearance features (color histograms) with spatial-temporal constraints and motion prediction.

3. Frame Boundary Detection

Challenge: Accurately determining when players are truly "out of frame" versus partially occluded or at frame edges.

Solution: Implemented adaptive boundary margins based on bounding box dimensions and visibility ratio calculations to distinguish between occlusion and frame exit.

4. Tracking Persistence

Challenge: Balancing between maintaining tracks during brief occlusions and avoiding false positive re-identifications.

Solution: Implemented configurable track persistence with exponential decay for confidence scores and multi-stage matching algorithms.

5. Performance Optimization

Challenge: Processing high-resolution video in real-time while maintaining tracking accuracy.

Solution: Optimized feature extraction algorithms, implemented efficient data structures for track history, and used vectorized operations for similarity computations.

6. Google Colab Limitations

Challenge: Memory constraints and session timeouts when processing longer videos.

Solution: Implemented progressive processing with checkpoint saving, memory-efficient frame handling, and optimized data structures.

Performance Metrics

The system tracks several key performance indicators:

- **Detection Accuracy:** Confidence scores and detection consistency
- **Tracking Continuity:** Track length and identity preservation
- **Re-identification Success:** Correct player matching after re-entry
- **Processing Speed:** Frames per second processing capability

Future Enhancements

- **Deep Learning Re-ID:** Integration of CNN-based appearance models

- **Multi-camera Tracking:** Cross-camera player association
- **Real-time Processing:** Optimization for live video streams
- **Advanced Analytics:** Player behavior pattern analysis

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Acknowledgments

- Ultralytics team for the YOLOv11 framework
- OpenCV community for computer vision tools
- Research contributions in multi-object tracking and re-identification