

## ELL205 Signals and Systems Major Exam - 80 marks, 120 minutes

- 1) **(15 marks)** Let  $x[n] = 1 + 2^2 + \dots + n^2$ . Using properties of the Z-transform, find a general expression for the sum of square of integers using properties of the Z-transform. You possibly already know the formula for this sum. HINT: How are  $x[n+1]$  and  $x[n]$  related?

So,

$$x[n] = 1^2 + 2^2 + \dots + n^2, \quad x[n+1] = 1^2 + 2^2 + \dots + (n+1)^2. \quad (1)$$

We can easily find out  $x[n+1] - x[n]$  as

$$x[n+1] - x[n] = (n+1)^2 \quad (2)$$

Now taking Unilateral Z-Transform on both sides, we get:

$$zX[z] - X[z] = \sum_{n=0}^{\infty} (n+1)^2 z^{-n} = \sum_{n=0}^{\infty} n(n+1) z^{-n} + \sum_{n=0}^{\infty} n z^{-n} + \sum_{n=0}^{\infty} z^{-n} \quad (3)$$

Further, we can write above equation in Z-transform as:

$$zX[z] - X[z] = \sum_{n=-\infty}^{\infty} n(n+1)u[n]z^{-n} + \sum_{n=-\infty}^{\infty} nu[n]z^{-n} + \sum_{n=-\infty}^{\infty} u[n]z^{-n} \quad (4)$$

We know the following Z-transform of sequence  $u[n]$  as

$$\sum_{n=0}^{\infty} z^{-n} = \frac{1}{1 - z^{-1}}. \quad (5)$$

Using differentiation properties of Z-transform, we can write

$$\frac{d}{dz} \sum_{n=0}^{\infty} z^{-n} = \frac{d}{dz} \frac{1}{(1 - z^{-1})}. \quad (6)$$

We get

$$\sum_{n=0}^{\infty} n z^{-n-1} = \frac{1}{(z-1)^2}. \quad (7)$$

Further, again performing  $\frac{d}{dz}$  on above equation, we get:

$$\sum_{n=0}^{\infty} n(n+1) z^{-n-2} = \frac{2}{(z-1)^3}. \quad (8)$$

Performing  $\frac{d}{dz}$  on above equation once again, we get

$$\sum_{n=0}^{\infty} n(n+1)(n+2) z^{-n-3} = \frac{6}{(z-1)^4}. \quad (9)$$

Therefore, using above equations, we get:

$$X[z](z-1) = \frac{2z^2}{(z-1)^3} + \frac{z}{(z-1)^2} + \frac{z}{(z-1)} \quad (10)$$

Further solving, we get:

$$X[z] = \frac{z^3 + z^2}{(z-1)^4} = \frac{z^3}{(z-1)^4} + \frac{z^2}{(z-1)^4} \quad (11)$$

Since,  $X[z] = \sum_{n=0}^{\infty} x[n]z^{-n}$ . The sum  $x[n]$  is coefficient of  $z^{-n}$  in  $X[z]$ .

Using (9), we can write:

$$\sum_{n=0}^{\infty} \frac{n(n+1)(n+2)}{6} z^{-n} = \frac{z^3}{(z-1)^4}. \quad (12)$$

$$\sum_{n=0}^{\infty} \frac{n(n+1)(n+2)}{6} z^{-n-1} = \frac{z^2}{(z-1)^4}. \quad (13)$$

Hence  $X(z)$  in (11) can be written as:

$$X(z) = \sum_{n=0}^{\infty} \frac{n(n+1)(n+2)}{6} z^{-n} + \sum_{n=0}^{\infty} \frac{n(n+1)(n+2)}{6} z^{-n-1}. \quad (14)$$

The second summation can be re-written as:

$$X(z) = \sum_{n=0}^{\infty} \frac{n(n+1)(n+2)}{6} z^{-n} + \sum_{n=1}^{\infty} \frac{(n-1)(n)(n+1)}{6} z^{-n}. \quad (15)$$

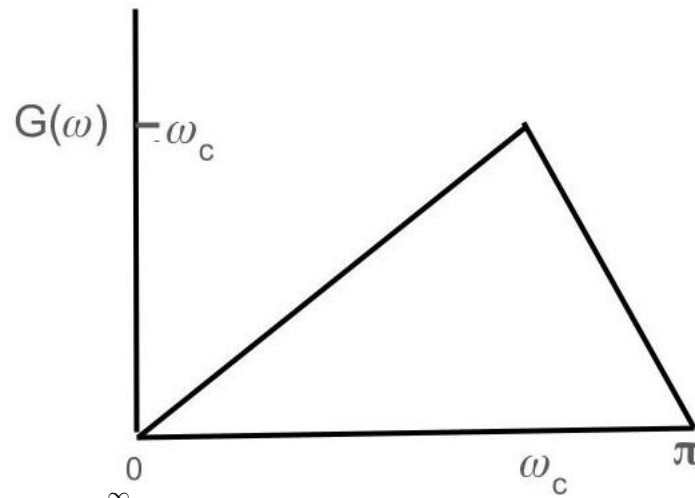
Since, coefficient of  $z^{-n}$  will give the required sum  $x[n]$ . Therefore, coefficient of  $z^{-n}$  is:

$$\frac{n(n+1)(n+2)}{6} + \frac{(n-1)(n)(n+1)}{6} = \frac{n(n+1)(2n+1)}{6} \quad (16)$$

- 2) **(25 marks)** A differentiator needs to be built for a continuous-time signal  $x(t)$  whose frequency content does not exceed  $\Omega_c$  radians/second. However, such differentiators have some practical problems. For this reason, an engineer decides to sample the signal  $x(t)$  and use a discrete-time differentiator. She then converts the output of the discrete-time differentiator to a continuous-time signal  $y(t)$ . The idea is to ensure that  $y(t) = \frac{dx(t)}{dt}$ . Note that this setup has none of the difficulties associated with the continuous-time differentiator.

- (1 mark)** Using concepts learnt in the course explain why the continuous-time differentiator is prone to noise (thermal noise for example).
- (1 mark)** What should be the minimum sampling rate used to ensure no aliasing?

- c) (7 marks) What should the frequency response  $H(e^{j\omega})$  of the discrete-time differentiator be? What is the impulse response  $h[n]$  when the minimum sampling rate is used?
- d) (3 marks) Suppose the impulse response obtained above is truncated for  $|n| > N$ . What is the energy in the error in representation of the frequency response  $H(e^{j\omega})$  over a  $2\pi$  interval?
- e) (9 marks) To produce an impulse response that is easier to implement, the student decided to use a filter with frequency response  $H(e^{j\omega}) = jG(\omega)$ ,  $0 \leq \omega \leq \pi$  as depicted below (note that the frequency response is depicted only for  $0 \leq \omega \leq \pi$ ). What is the impulse response of the filter? What is the sampling rate required to ensure that the overall system still works as a continuous-time differentiator? What is the impulse response for the specific case of  $\omega_c = \pi/2$ ? Can you see an implementation advantage?



- f) (4 marks) Evaluate  $\sum_{n=1}^{\infty} \frac{1}{n^2}$  using concepts from this course.

ANS: a) Any thermal noise present in the system with a high frequency component gets amplified by the frequency response of the differentiator  $j\omega$ , which causes large noise amplification.

b) Clearly,  $\frac{2\pi}{T_s} > 2\omega_c$  should be the sampling rate.

c) Clearly:  $H(e^{j\omega}) = j\omega - \pi < \omega < \pi$ . Using Fourier series concepts and the duality of the DTFT and the CTFS, we have:

$$h[n] = \frac{(-1)^n}{n}$$

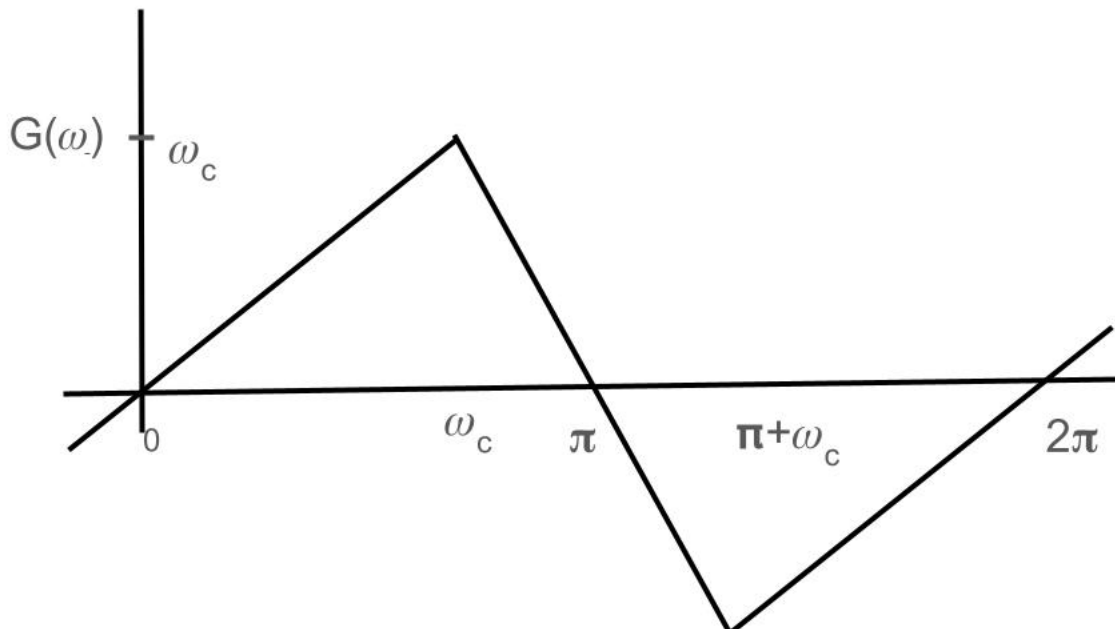
You need to use properties of the DTFT or CTFS to derive the above, these details are omitted (direct evaluation is not acceptable).

d) Denote the approximate impulse response by  $\hat{h}[n]$  and its DTFT by  $\hat{H}(e^{j\omega})$ . Then, the following

follows from the Parseval's theorem:

$$\int_{-\pi}^{\pi} |H(e^{j\omega}) - \hat{H}(e^{j\omega})|^2 d\omega = 2\pi \sum_n |h[n] - \hat{h}[n]|^2 = 2\pi \sum_{n \notin [-N, N]} |h[n]|^2$$

e) We need to note that  $h[n]$  is real, which implies that  $H(e^{j\omega}) = H^*(e^{-j\omega})$ . This implies that  $G(\omega)$  is odd (its value from  $-\pi$  to  $\pi$  is known.  $H(e^{j\omega})$  is now specified from  $-\pi$  to  $\pi$ . To find  $h[n]$ , we use several approaches (FS concepts or properties of the DTFT for example). All you need to



do now is to invert  $H(e^{j\omega}) = jG(\omega)$ ... This can be done in several ways... I suggest something like double differentiation and use of differentiation property... When  $\omega_c = \pi/2$  you can see that it has a triangular form... The impulse response will be squared  $\sin(x)/x$ , and therefore decays fast. It is therefore easy to implement in practice. You can check to see that these type of impulse response is not implementable by a pole-zero system (constant coefficient linear difference equation). This makes the ability to truncate the response very important. The flip side? The sampling rate has to be larger! Earlier it was  $1/T_s > \frac{\Omega_c}{\pi}$ . Now it becomes  $1/T_s > \frac{\Omega_c}{\omega_c}$ , and  $\Omega_c < \pi$  implies that the sampling rate has increased.

f) We can use the Parseval's relation and use the fact that  $\omega_c = \pi$  here to get:

$$\sum_{n=-\infty}^{\infty} |x[n]|^2 = \sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{1}{2\pi} \int_{-\pi}^{\pi} |H(e^{j\omega})|^2 d\omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} \omega^2 d\omega \quad (17)$$

3) (10 marks) You are given that  $x(t) = 0$  for  $t < 0$ . Solve for  $x(t)$  if you are also given that

$$x(t) = e^{-t} + \int_0^t \cosh(t - \tau) x(\tau) d\tau, \quad t \geq 0$$

Do you need to impose any constraints on  $x(t)$ ?

The integral can be written as:

$$x(t) = e^{-t} + \cosh tu(t) * x(t), \quad t \geq 0. \quad (18)$$

Taking Unilateral Laplace transform on both sides, we get:

$$X(s) = \int_{t=0}^{\infty} e^{-t} e^{-st} dt + \int_{t=0}^{\infty} (\cosh tu(t) * x(t)) u(t) e^{-st} dt. \quad (19)$$

Further, above equation can be written as:

$$X(s) = \int_{t=-\infty}^{\infty} e^{-t} u(t) e^{-st} dt + \sum_{n=-\infty}^{\infty} (\cosh tu(t) * x(t)) u(t) e^{-st} dt. \quad (20)$$

Now, using property of Laplace transform and using  $\mathcal{L}\{\cosh at\} = \frac{s}{(s^2 - a^2)}$ , we get:

$$X(s) = \frac{1}{(s+1)} + X(s) \frac{s}{(s^2 - 1)}. \quad (21)$$

On solving, we get

$$X(s) = \frac{s-1}{(s^2 - s - 1)}. \quad (22)$$

We can rewrite this as:

$$X(s) = \frac{(s-1/2)}{((s-1/2)^2 - 5/4)} - \frac{1/2}{((s-1/2)^2 - 5/4)}. \quad (23)$$

Using,  $\mathcal{L}\{\cosh at\} = \frac{s}{(s^2 - a^2)}$  and  $\mathcal{L}\{\sinh at\} = \frac{a}{(s^2 - a^2)}$  and properties of Laplace transform, we get:

$$x(t) = \cosh \frac{\sqrt{5}t}{2} e^{-t/2} u(t) - \frac{\sqrt{5}}{4} \sinh \frac{\sqrt{5}t}{2} e^{-t/2} u(t) \quad (24)$$

4) **(18 marks)** Evaluate the following integrals using concepts learnt in this course:

$$I_1 = \int_{-\infty}^{\infty} \frac{2 \sin(Wt)}{\pi t \left(1 + \left(\frac{t}{2}\right)^2\right)} dt$$

$$I_2 = \int_{-\pi}^{\pi} \frac{\sin\left(2\omega\left(N_1 + \frac{1}{2}\right)\right) \sin\left(\omega\left(N_2 + \frac{1}{2}\right)\right)}{\sin(\omega) \sin(\omega/2)} d\omega, \quad N_1 > N_2$$

ANS: Using the time-scaling property, it is easy to see that:

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{2}{1 + \left(\frac{\omega}{2}\right)^2} e^{j\omega t} d\omega = 2e^{-2|t|}$$

Using duality, by interchanging  $-\omega$  and  $t$  we can see that:

$$4\pi e^{-2|\omega|} = \int_{-\infty}^{\infty} \frac{2}{1 + \left(\frac{t}{2}\right)^2} e^{-j\omega t} dt$$

From the generalized Parseval's theorem, we have:

$$\int_{-\infty}^{\infty} x(t)y^*(t)dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega)Y^*(j\omega)d\omega$$

Using  $x(t) = \frac{\sin(Wt)}{\pi t}$  and  $y(t) = \frac{2}{1 + \left(\frac{t}{2}\right)^2}$ , it can be seen that integral  $I_1$

is  $\int_{-W}^W \frac{1}{2} e^{-2|\omega|} d\omega = \frac{1}{4} \int_{-2W}^{2W} e^{-|\omega|} d\omega = \frac{1}{2} \int_0^{2W} e^{-|\omega|} d\omega$ . This evaluates to  $\frac{1}{2} (1 - e^{-2W})$

To evaluate  $I_2$  we use:

$$\sum_{n=-\infty}^{\infty} x[n]y^*[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})Y^*(e^{j\omega})d\omega$$

Noting that

$$y[n] = \begin{cases} 1 & -N_2 \leq n \leq N_2 \\ 0 & \text{Otherwise} \end{cases} \iff \frac{\sin\left(\omega\left(N_2 + \frac{1}{2}\right)\right)}{\sin(\omega/2)} \quad (25)$$

and that

$$x[n] = \begin{cases} x_1[n/2] & n \text{ even} \\ 0 & n \text{ odd} \end{cases} \iff \frac{\sin\left(2\omega\left(N_1 + \frac{1}{2}\right)\right)}{\sin(\omega)} \quad (26)$$

It can be inferred using  $N_1 > N_2$  that

$$I_2 = 2\pi \sum_{n=-N_2}^{N_2} x[n]y[n] = 2N_2 - 1 \quad (27)$$

- 5) (7 marks) Find a sequence  $x[n]$  whose Z-transform is  $X(z) = e^{-2z}$  (also specify the ROC that results in the sequence).

ANS: use the Taylor  $\exp(-2z) = \sum_{n=0}^{\infty} \frac{(-2z)^n}{n!}$ . Using  $-n$  for  $n$ , we have  $X(z) = \sum_{n=-\infty}^0 \frac{(-2)^{-n}}{(-n)!} z^{-n} = \sum_{n=-\infty}^{\infty} \frac{(-2)^{-n}}{(-n)!} u[-n] z^{-n}$  from which we can identify the discrete sequence as  $x[n] = \frac{(-2)^{-n}}{(-n)!} u[-n]$ .

In the above, the negative factorial has to be interpreted correctly.

- 6) **(5 marks)** Consider  $X(t) = A \cos(\omega_c t + \Phi)$  where  $A$  and  $\omega_c$  are constants, and  $\Phi$  is a uniformly distributed random variable that takes values between  $-\pi$  and  $\pi$ . Find the mean and autocorrelation of  $X(t)$ , and comment on the nature of  $X(t)$ .

ANS: Mean  $\mu(t) = E\{X(t)\} = A \cos(\omega_c t + \Phi) = A 2\pi \int_{-\pi}^{\pi} \cos(\omega_c t + \phi) d\phi = 0$  (constant, and not time-dependent).

Similarly,  $E\{X(t)X(t+\tau)\} = A^2 E\{\cos(\omega_c t + \Phi) \cos(\omega_c(t+\tau) + \Phi)\} = A^2 \int_{-\pi}^{\pi} \cos(\omega_c t + \phi) \cos(\omega_c(t+\tau) + \phi) d\phi$  Using Trigonometric formulae, it can be shown that the above reduces to  $\frac{A^2}{2} \cos(\omega_c \tau)$ . Clearly,  $X(t)$  is wide-sense stationary.