

## Problem sheet–9

1. Using duality between Continuous-time Fourier Series and Discrete-time Fourier Transform, prove

$$\sum_{n=-\infty}^{\infty} |x[n]|^2 = \frac{1}{2\pi} \int_{2\pi} |X(e^{j\Omega})|^2 d\Omega$$

2. John evaluated the DTFT of the output of an accumulator, that is,  $y[n] = \sum_{m=-\infty}^n x[m]$ , by thinking about the output as the convolution of the input with the unit-step response as

$$y[n] = \sum_{m=-\infty}^n x[m] u[n-m] = x[n] * u[n]$$

By substituting the frequency response of the input and the unit-step response, he obtained the following

$$Y(e^{j\Omega}) = \frac{X(e^{j\Omega})}{1 - e^{-j\Omega}} + \pi X(e^{j0}) \sum_{p=-\infty}^{\infty} \delta(\Omega - 2\pi p)$$

Amit evaluated the DTFT of the output of an accumulator by writing corresponding difference equation

$$y[n] - y[n-1] = x[n]$$

By substituting frequency responses of each part, he obtained the following result:

$$Y(e^{j\Omega}) = \frac{X(e^{j\Omega})}{1 - e^{-j\Omega}}$$

Explain the differences between the two answers.

### 3. Difference equations

Consider an LTI system that is characterized by the difference equation:

$$y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = 2x[n]$$

- Find the impulse response of the above system.
- Do we do any error similar to what Amit did in solving a difference equation in question 2?
- Why did we not require any auxiliary conditions for solving the impulse response?
- Using operators (converting system into polynomials), find the frequency response.
- Does system stability influence our solutions?

4. Prove if a periodic-time signal  $x[n]$  with period  $N$  has Fourier series coefficients  $a_k$ , then  $a_n$  has Fourier series coefficients  $\frac{1}{N}x[-k]$

### 5. Comparison of decimation and low frequency sampling

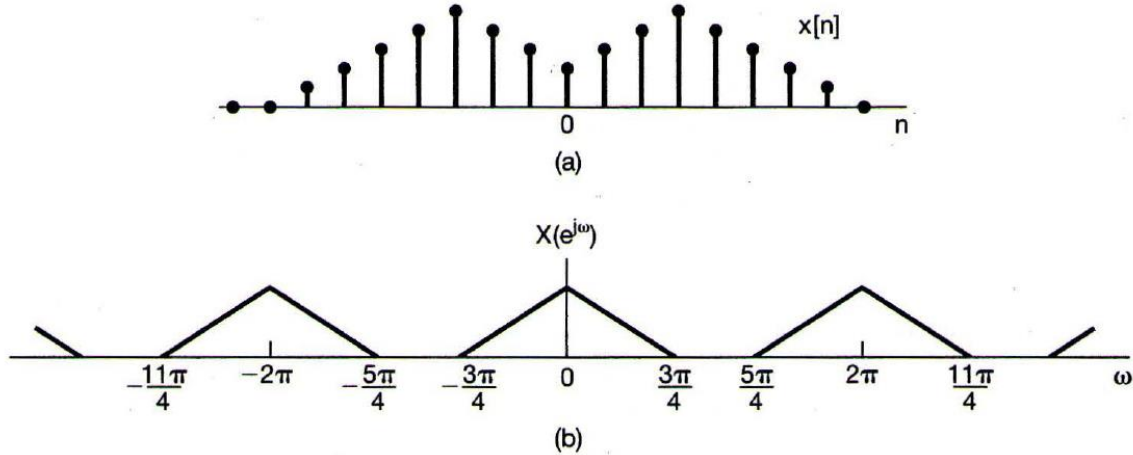
Consider a discrete-time sequence  $x[n]$  from which we form two new sequences,  $x_p[n]$  and  $x_d[n]$ , where  $x_p[n]$  corresponds to sampling  $x[n]$  with a sampling period of 2 and  $x_d[n]$  corresponds to decimating  $x[n]$  by a factor of 2, so that

$$x_p[n] = \begin{cases} x[n], & n = 0, \pm 2, \pm 4 \dots \\ 0, & n = \pm 1, \pm 3 \dots \end{cases}$$

and

$$x_d[n] = x[2n]$$

- If  $x[n]$  is as illustrated in Figure (a), sketch the sequences  $x_p[n]$  and  $x_d[n]$ .
- If  $X(e^{j\omega})$  is as shown in Figure (b), sketch  $X_p(e^{j\omega})$  and  $X_d(e^{j\omega})$ .



## 6. Fourier transform of decimated signal

Consider the system shown in the figure below, with input  $x[n]$  and the corresponding output  $y[n]$ . The zero-insertion system inserts two points with zero amplitude between each of the sequence values in  $x[n]$ . The decimation is defined by

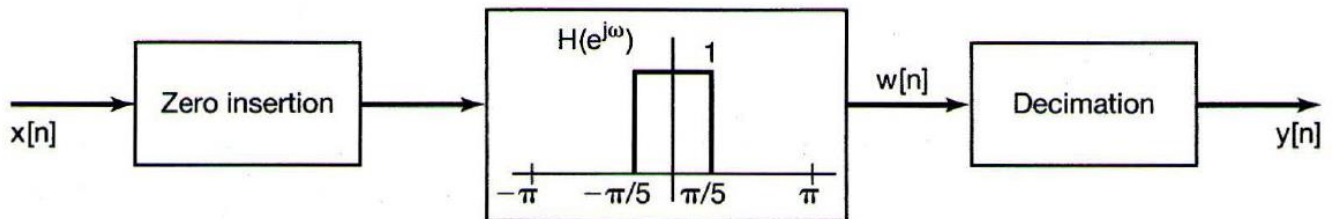
$$y[n] = w[5n]$$

where  $w[n]$  is the input sequence for the decimation system. If the input is of the form

$$x[n] = \frac{\sin(w_1 n)}{\pi n}$$

determine the output  $y[n]$  for the following values of  $w_1$  :

- $w_1 \leq \frac{3\pi}{5}$
- $w_1 > \frac{3\pi}{5}$

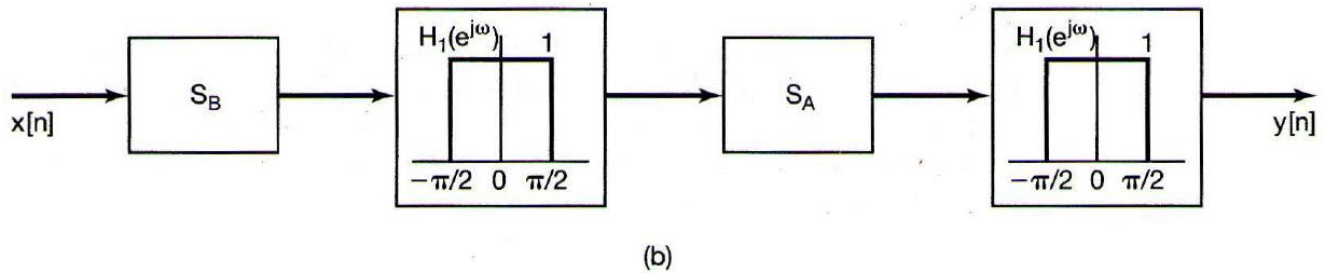
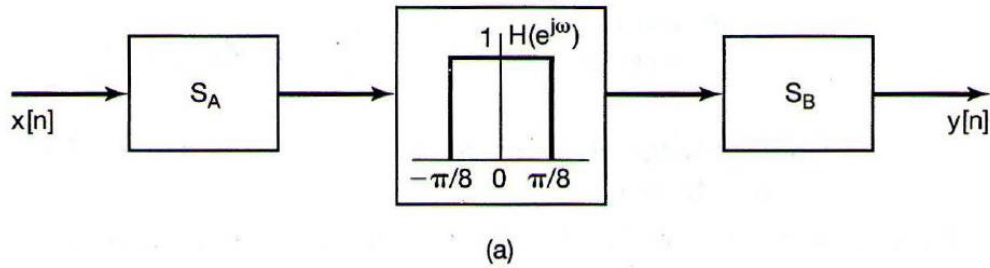


## 7. Graphical analysis of Decimation and Interpolation function

Two discrete-time systems  $S_1$  and  $S_2$  are proposed for implementing an ideal low-pass filter with cutoff frequency  $\pi/4$ . System  $S_1$  is depicted in figure (a) below. System  $S_2$  is depicted in the figure (b). In these figures,  $S_A$  corresponds to a zero insertion system that inserts one zero after every input sample, while  $S_B$  corresponds to a decimation system that extracts every second sample of its input.

(a) Does the proposed system  $S_1$  correspond to the desired ideal low-pass filter?

(b) Does the proposed system  $S_2$  correspond to the desired ideal low-pass filter?



## 8. Graphical Analysis of Low pass Filter

A signal  $x[n]$  with Fourier transform  $X(e^{j\omega})$  has the property that

$$\left( x[n] \sum_{k=-\infty}^{\infty} \delta[n - 3k] \right) * \left( \frac{\sin \frac{\pi}{3} n}{\frac{\pi}{3} n} \right) = x[n]$$

For what values of  $\omega$  is it guaranteed that  $X(e^{j\omega}) = 0$ ?

## 9. Graphical Analysis of Interpolation and Decimation

A real-valued discrete-time signal  $x[n]$  has a Fourier transform  $X(e^{j\omega})$  that is zero for  $3\pi/14 \leq \omega \leq \pi$ . The nonzero portion of the Fourier transform of one period of  $X(e^{j\omega})$  can be made to occupy the region  $|\omega| < \pi$  by first performing up-sampling by a factor of  $L$  and then performing down-sampling by a factor of  $M$ . Specify the values of  $L$  and  $M$