Started on	Wednesday, 16 February 2022, 8:15 AM
State	Finished
Completed on	Wednesday, 16 February 2022, 8:44 AM
Time taken	29 mins 27 secs
Marks	30.00/30.00
Grade	<b>20.00</b> out of 20.00 ( <b>100</b> %)

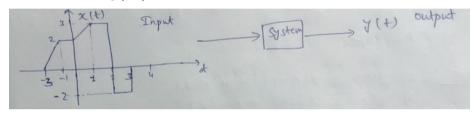
Correct

Mark 2.00 out of 2.00

Consider a signal  $\mathbf{x}(t)$  as shown below. This signal is passed through a system which gives output y(t). The system response is given by

$$y(t)=x\left(rac{-t}{3}+2
ight)$$
 .

Find the value of y(12).



Answer: 1 ✓

Put value if t in argument of input signal and compute the time at which input signal value is needed.

The correct answer is: 1.00

Correct

Mark 2.00 out of 2.00

A continuous time LTI system is described by:

$$rac{d^2y(t)}{dt^2} + 4rac{dy(t)}{dt} + 3y(t) = 2rac{dx(t)}{dt} + 4x(t)$$

Assuming zero initial conditions, the response y(t) of the above system for the input  $x(t) = \exp(-2t)u(t)$  is given by:

Select one:

- $\bigcirc$  a.  $(e^t + e^{3t})u(t)$
- igodesign b.  $(e^{-t}-e^{-3t})u(t)$
- $\checkmark$  c.  $(e^{-t}+e^{-3t})u(t)$
- $\bigcirc$  d.  $(e^t-e^{3t})u(t)$
- e. Select this if you don't want to attempt

The correct answer is:  $(e^{-t}-e^{-3t})u(t)$ 

# Question 3

Correct

Mark 2.00 out of 2.00

Convolution of x(t+4) with impulse function  $\delta(t-8)$ 

is equal to

Select one:

- $\bigcirc$  a. x(t+4)
- lacksquare b. x(t-4)
- $\bigcirc$  c. x(t-12)
- d. x(t+12)

Your answer is correct.

The correct answer is: x(t-4)

Correct

Mark 2.00 out of 2.00

Let y[n] denote the convolution of h[n] and g[n], where  $h[n]=(\frac{1}{2})^nu[n]$  and g[n] is a causal sequence. If y[0]=1 and  $y[1]=\frac{1}{2}$ , then g[1] equals

Select one:

- a.  $\frac{1}{2}$
- o b.  $\frac{3}{2}$
- c. 1
- d. 0

The correct answer is: 0

### Question 5

Correct

Mark 2.00 out of 2.00

The impulse response of a discrete time sytem is given by:

$$h[n] = (-1)^n \frac{n}{2^n} u[n]$$

For a bounded input with bound  $B_{X}$  the output bound will be:

Select one:

lacksquare a.  $2B_X$ 

**4** 

- igcup b.  $4B_X$
- o. The system is unstable.
- $\bigcirc$  d.  $8B_X$

The correct answer is:  $2B_{X}$ 

Correct

Mark 2.00 out of 2.00

Let x(t) and y(t) denote the input and output of a continuous time system. Which of the following descriptions corresponds to a casual system?

Select one:

$$\bigcirc$$
 a.  $y(t)=(t-4)x(t+1)$ 

$$lacksquare b. \ y(t) = (t+5)x(t-1)$$

$$igcup c. \ y(t) = x(t-3) + x(t+2)$$

o d. 
$$y(t) = (t+3)x(t+3)$$

Your answer is correct.

The correct answer is: y(t) = (t+5)x(t-1)

#### Question 7

Correct

Mark 2.00 out of 2.00

Which of the following represents an invertible system?

Select one:

$$igcap a.\ y[n] = x[n]x[n-1]$$

$$igcup b. \ y(t) = x^2(t)$$

$$igcup_{t}$$
 c.  $y(t)=\sin(x(t))$ 

$$lacksquare$$
 d.  $y(t)=x(t-3)$ 



Your answer is correct.

The correct answer is: y(t) = x(t-3)

Correct

Mark 2.00 out of 2.00

s(t) is the step response and h(t) is impulse response of a system. Its response y(t) for any input u(t) is given by

Select one:

$$igcup a. rac{d}{dt} \int_0^t h(t- au) u( au) d au$$

$$igodesigm$$
 b.  $\int_0^t \int_0^ au s(t- au) u( au_1) d au_1 d au$ 

$$\bigcirc$$
 c.  $\int_0^t s(t- au) u( au) \$ d au$ 

$$igcolum_{t} = \int_{0}^{t} s(t- au) u( au) d au$$



Your answer is correct.

The correct answer is:  $rac{d}{dt} \int_0^t s(t- au) u( au) d au$ 

Correct

Mark 2.00 out of 2.00

if y[n] = x[n](g[n] + g[n-1]), for which of the following cases y[n] s time invariant?

Select one or more:

- lacksquare a. g[n]=u[n]
- lacksquare b. g[n]=n
- c.  $g[n] = (-1)^n$ 
  - **√**
- lacksquare d. g[n]=1 for all n



$$g[n]=1 \, \Rightarrow y[n]=2x[n] \Rightarrow$$
 Time Invariant

$$g[n] = n \Rightarrow y[n] = (2n-1)x[n] \Rightarrow$$
 Non Time Invariant

$$g[n] = (-1)^n \ \Rightarrow y[n] = x[n](1+(-1)^n)+1+(-1)^{-n} = 2x[n] \Rightarrow$$
 Time Invariant

$$g[n]=u[n]\Rightarrow y[n]=x[n](u[n]+u[n-1])=\delta[n]+2u[n-1]\Rightarrow$$
 Non Time Invariant

The correct answers are: g[n]=1 for all n

, 
$$g[n]=(-1)^n$$

# Question 10

Correct

Mark 2.00 out of 2.00 A system with input  $\boldsymbol{x}[n]$  and output  $\boldsymbol{y}[n]$  is given as

$$y[n] = (sinrac{5}{6}\pi n)x[n]$$

The system is

Select one:

- a. Linear, stable and invertible
- b. non-linear, stable and non-invertible
- c. Linear, unstable and invertible
- d. Linear, stable and non-invertible

Your answer is correct.

The correct answer is: Linear, stable and non-invertible

Correct

Mark 2.00 out of 2.00

Consider the following statement about continuous time LTI systems:

- 1. The output signal in an LTI system with known input and known impulse response can be determined.
- 2. A causal LTI system is always stable.
- 3. A stable LTI system has an impulse response h(t) which has a finite value when integrated over whole of time-axis, i.e.  $\int\limits_{-\infty}^{\infty}h(\lambda)d\lambda$  is finite.

Which of the statements given above are correct?

Select one or more:

- a. 1, 2 and 3
- b. 2 and 3
- c. 1 and 3 🗸
- d. 1 and 2

The correct answer is: 1 and 3

# Question 12

Correct

Mark 2.00 out of 2.00

The odd component of the signal  $x(t)=e^{\left(-2t\right)}cos(t)$  is

Select one:

- $\bigcirc$  a. -cosh(2t)cos(t)
- $\bigcirc$  b. sinh(2t)cos(t)
- c. -sinh(2t)cos(t)

**√** 

 $\bigcirc$  d. cosh(2t)cos(t)

Your answer is correct.

The correct answer is: -sinh(2t)cos(t)

Correct

Mark 2.00 out of 2.00

Determine whether or not each of the following systems are invertible with input x[n] and y[n].

1. 
$$y_1 = nx[n]$$

2. 
$$y_2 = (1 + (-1)^n)x[n]$$

#### Select one:

- lacksquare a. Both  $y_1$  and  $y_2$  are invertible
- lacksquare b. Both  $y_1$  and  $y_2$  are non-invertible
- $igcup c. \ y_1$  is non-invertible and  $\ y_2$  is invertible
- igcup d.  $y_1$  is invertible and  $y_2$  is non-invertible

Your answer is correct.

The correct answer is: Both  $y_1$  and  $y_2$  are non-invertible

### Question 14

Correct

Mark 2.00 out of 2.00

Consider the system with output response as  $y[n]=\left(\frac{n+0.5}{n-0.5}\right)^2x[n]$ . Which of the following are true for this system?

# Select one:

- a. Select this if you don't want to attempt
- b. Not stable but linear
- c. Neither stable nor linear
- d. Stable and linear
- e. Stable but non-linear

Stability:  $\left(\frac{n+0.5}{n-0.5}\right)^2$  has maximum value of 9 for n= 1. Hence, output is bounded for bounded input.

It is direct to prove that system is linear.

The correct answer is: Stable and linear

Correct

Mark 2.00 out of 2.00

The value of the integral  $\int_{-2}^4 \sin(2t) \delta(2t-\frac{\pi}{2}) dt$  is

Select one:

- igcap a.  $\sqrt{2}$
- o b. 0
- - **√**
- $\quad \ \ \, \text{d.}\,\,\sqrt{3}$

Your answer is correct.

The correct answer is:  $\frac{1}{2}$ 

**◄** Quiz 4

Jump to...

Part B ▶