

MTL103 Minor 1

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TOTAL POINTS

19 / 25

QUESTION 1

1 Q1 4.5 / 5

+ 0 pts Incorrect/not attempted

✓ + 5 pts Correct

+ 1 pts Some positive approach towards correct solution

+ 2 pts For every point x^* , lies on the line segment between x^* and global min, $f(x) \leq f(x^*)$.

+ 1 pts For some x on the line segment between x^* and global min, $x \in N_\epsilon(x^*)$ but no proof.

+ 2 pts For some x on the line segment between x^* and global min, $x \in N_\epsilon(x^*)$ with partially correct proof.

+ 2 pts Correct for $n=1$. that is $R^n = R$

+ 0.5 pts Some correct approach for $n=1$.

- 0.5 Point adjustment

QUESTION 2

2 Q2 5 / 10

- 0 pts Correct

✓ - 10 pts *unattempted/incorrect*

- 5 pts if/only if part not proven or incomplete

+ 5 Point adjustment

QUESTION 3

3 Q3 4 / 4

✓ - 0 pts Correct

- 1 pts Did not show feasible solution

- 1.5 pts Did not show basic solution

- 1.5 pts Did not show non-degenerate solution

- 4 pts Incorrect

QUESTION 4

4 Q4 3 / 3

✓ - 0 pts Correct

- 3 pts Wrong graph.

- 0.5 pts Reason for degeneracy is not given.

- 0.5 pts Feasible region is not marked.

- 0.5 pts One point is wrong.

- 1 pts Two points are wrong.

- 1.5 pts Three points are wrong.

- 2 pts Four points are wrong.

- 0.5 pts Wrong bfs points are mentioned.

QUESTION 5

5 Q5 2.5 / 3

✓ - 0 pts Correct

- 0.5 pts Definition of x_{ijg} where $i \in I$, $j \in J$, $g \in G$, I, J, G are sets of neighbourhoods, schools and grades

- 0.5 pts Optimization Objective (min Total distance travelled by students)

- 0.5 pts Non negativity constraints on x_{ijg}

✓ - **0.5 pts** Integer constraint on x_{ijg}

- **0.5 pts** Capacity constraint on school capacity

C_{jg}

- **0.5 pts** Assignment constraint on student

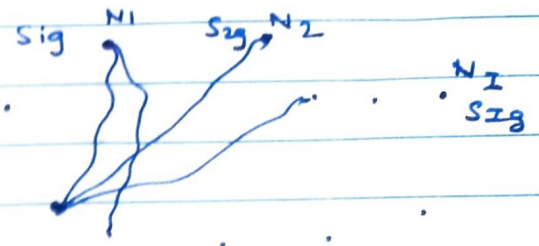
population S_{ig}

- **3 pts** Incorrect/Not attempted

Q5.

Let us define

$x_{ijg} \equiv$ No. of students in
neighbourhood i going
to school j in grade g



Then we have the constraints:

$$x_{ijg} \geq 0 \quad \forall i, j, g \quad \text{--- ①}$$

$$\sum_{j \in J} x_{ijg} = S_{ig} \quad \text{--- ②} \quad (\text{Assign ALL students in neighbourhood } i \text{ grade } g \text{ to a school})$$

$$\sum_{i \in I} x_{ijg} \leq C_{jg} \quad \text{--- ③} \quad (\text{Should be less than or equal to capacity of schools})$$

We want to minimize:

$$f = \sum_g \sum_j \sum_i x_{ijg} \cdot d_{ij}$$

 \therefore The LP is:

$$\min \sum_g \sum_j \sum_i x_{ijg} \cdot d_{ij}$$

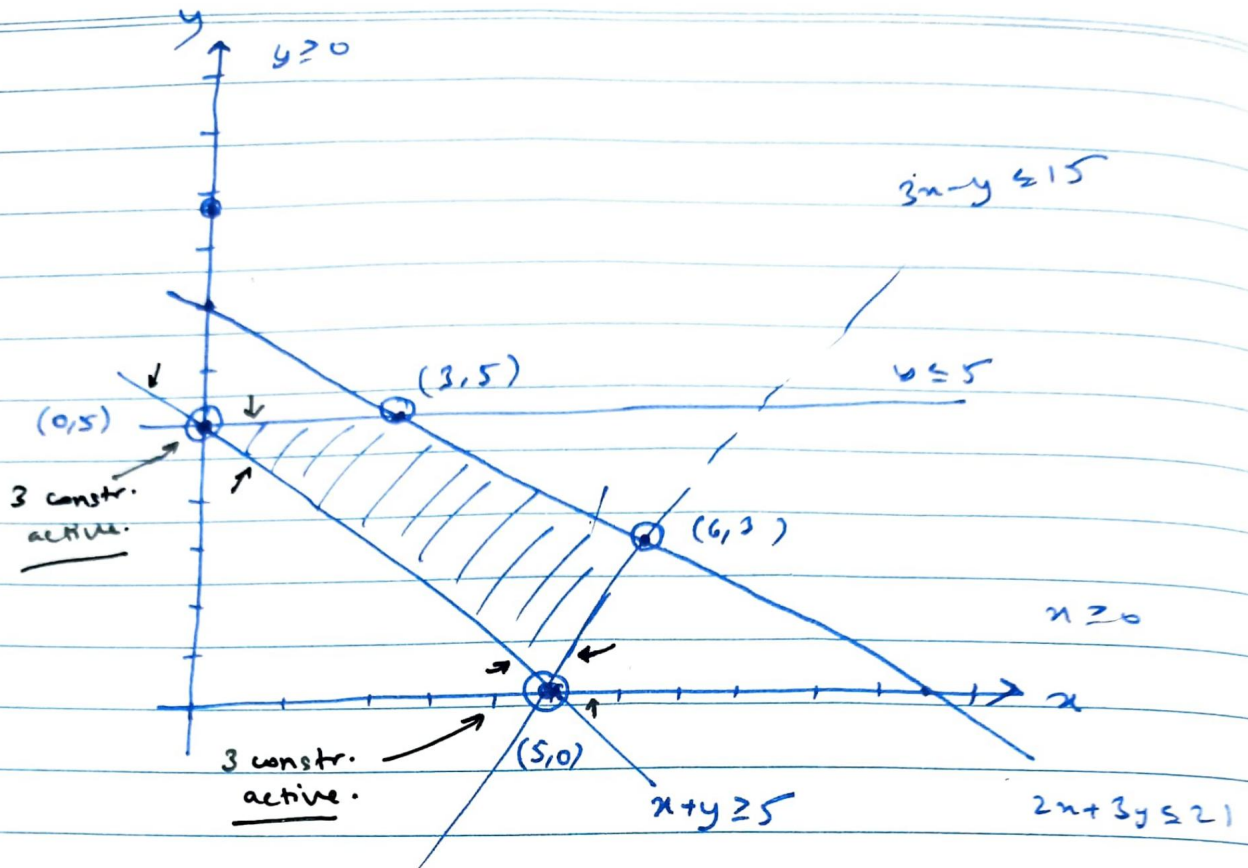
s.t.:

$$\sum_{j \in J} x_{ijg} = S_{ig} \quad \forall i, g$$

$$\sum_i x_{ijg} \leq C_{jg} \quad \forall j, g$$

$$x_{ijg} \geq 0 \quad \forall i, j, g$$

Q4.



$$\begin{aligned} 3x - y &= 15 \times 2 \\ 2x + 3y &= 21 \times 3 \end{aligned}$$

The feasible region is as drawn above.

Note that since it is non-empty,
corner point \equiv BFS.

$$\begin{aligned} 6x + 9y &= 63 \\ -6x + 2y &= 30 \\ \hline 11y &= 93 \\ y &= 3 \end{aligned}$$

The corner points are,

$(0,5)$, $(3,5)$, $(6,3)$, $(5,0)$

$$2x + 9 = 21 \times 2$$

Note that at $(0,5)$ and $(5,0)$, there are 3 constraints active, while the dimensionality of the space is 2.

\therefore These are degenerate.

DEGENERATE: $(0,5)$, $(5,0)$

NON-DEGENERATE: $(3,5)$, $(6,3)$

Q3. $P = \{x \in \mathbb{R}^n \mid Ax \leq b, x \geq 0\}$

$$P' = \{(x, z) \in \mathbb{R}^{n+m} \mid Ax + z = b, x \geq 0, z \geq 0\}$$

Given x^* is BFS of P

Note that,

$$Ax^* + b - Ax^* = b. \text{ Further, } x^* \geq 0 \text{ since } x^* \in P$$

$$\therefore \cancel{Ax^*} \text{ and } Ax^* \leq b \Rightarrow b - Ax^* \geq 0.$$

$\therefore (x^*, b - Ax^*)$ is a feasible solution.

Suppose $A = m \times n$. Since x^* is a non-degenerate BFS, it has exactly m non-zero entries in its vector representation.

Now, consider the solution

$$(x^*, b - Ax^*).$$

x^* is a BFS $\Rightarrow \exists n$ L.I. active constraints at x^* .

Notice that since x^* has m non-zero entries, $\therefore n-m$ entries are zero $\Rightarrow n-m$ constraints of the form $x_i \geq 0$ are active.

\therefore Remaining m active constraints are from

$$\boxed{Ax \leq b}$$

$$\therefore x^* \text{ satisfies } \underline{Ax^* = b} \Rightarrow b - Ax^* = 0$$

$$\therefore \text{For the solution } (x^*, \underbrace{b - Ax^*}_0)$$

we have exactly m
non-zero entries.

\therefore ~~n~~ n active constraints from $x \geq 0, z \geq 0$,
 m constraints from $Ax + z = b$

$$\Rightarrow \underline{m+n \text{ active constraints at } (x^*, b - Ax^*)}$$

Solution

\therefore is basic. Since x has m non-zero entries, so does $(x^*, b - Ax^*) \Rightarrow (x^*, b - Ax^*)$ is not degenerate.

Therefore we have proved that

$$y = (x^*, b - Ax^*)$$

is a basic, feasible, non-degenerate solution.

9. $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $S \subset \mathbb{R}^n$.

Note that if f is convex over \mathbb{R}^n , it is convex over S .

Consider any point $x \in S$. Then we have that,

$$f(\lambda x^* + (1-\lambda)x) \leq \lambda f(x^*) + (1-\lambda)f(x) \quad \forall \lambda \in (0,1).$$

Now, we know $\exists \epsilon > 0$ s.t. $f(x^*) \leq f(x) \quad \forall \|x - x^*\| \leq \epsilon$.

We want λ s.t. $x \rightarrow x^*$

$$\begin{aligned} \text{if } \|x - x^*\| &\leq \epsilon \\ \Rightarrow \lambda x^* + (1-\lambda)x &\end{aligned}$$

We claim $\exists \lambda$ s.t.

$$\|x^* - (\lambda x^* + (1-\lambda)x)\| \leq \epsilon$$

$$\Rightarrow \|(1-\lambda)(x^* - x)\| \leq \epsilon$$

$$1-\lambda \leq \frac{\epsilon}{\|x^* - x\|}$$

$$\Rightarrow \lambda \geq 1 - \frac{\epsilon}{\|x^* - x\|}$$

\therefore If we pick $\lambda \geq 1 - \frac{\epsilon}{\|x^* - x\|}$ for any point x

we will have that $\|x^* - \underline{x}\| \leq \epsilon$

\Rightarrow For this λ ,

$$f(\lambda x^* + (1-\lambda)x) \geq f(x^*)$$

So we get, for our choice of λ (>0)

$$f(n^*) \leq f(\lambda n^* + (1-\lambda)n) \leq \lambda f(n^*) + (1-\lambda)f(n)$$

$$\Rightarrow (1-\lambda)f(n^*) \leq (1-\lambda)f(n)$$

Since $\lambda \in (0,1)$, $1-\lambda > 0$

$$\Rightarrow \boxed{f(n^*) \leq f(n) \quad \forall n \in S}$$

Q2. $[\Rightarrow]$ Let x be a feasible solution.

We know for a standard LP,

the optimal solution must be basic

feasible solution.

$$\begin{array}{c} \text{Min } C^T d \\ (x_1, \dots, x_m, 0, \dots, 0) \\ \underbrace{\hspace{1cm}}_{n \times m} \end{array}$$

~~∴~~ \therefore At least $m-n$ variables are zero.

$$\therefore |K| \geq m-n.$$

Consider the problem,

$$\min C^T d$$

$$\underbrace{A d = 0}_{m \text{ constraints}}, \quad d_i \geq 0, \quad i \in K.$$

m constraints.

Note that at least $m-n$ constraints of the form $d_i \geq 0$ will be active. Let

~~$d_i \neq 0$~~ $I = \{i \mid d_i \neq 0\}$. then we have,

$$A d = \cancel{\sum_{j=1}^n A_j d_j}$$

$$= \sum_{j \in K} A_j d_j + \sum_{j \in I} A_j d_j$$

$$= \sum_{j \in I} A_j d_j = 0$$

We know that the columns of A corresponding to the indices where $d_i \neq 0 \Rightarrow$ cols. of A corr. to indices where $x_i \neq 0 \Rightarrow A_j$'s are linearly independent

$$\Rightarrow d_i = 0 \quad \forall i \in I.$$

$$\therefore d = (0, 0, \dots, 0)$$

$$\therefore \underline{C^T d = 0}.$$

[\Leftarrow] Consider the LP problem,
 $Ad = 0$.
 $d_i \geq 0, i \in K$.

Then we have as earlier,

$$\sum_{j \in I} A_j d_j = 0.$$

Now consider the indices set I . We have for
 $i \in I, \underline{x_i} \neq 0$.

~~For the optimal cost~~

If the optimal cost $CT_d = 0 \Rightarrow d = 0$

$\therefore A_j$'s are L.I.

\Rightarrow Cols in A are L.I.

$\Rightarrow x$ is BFS \therefore ~~for~~ optimal.
