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State Finished

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Time taken 49 mins 55 secs

Marks 14.00/15.00

Grade 3.73 out of 4.00 (93%)

## Question 1

Correct

Mark 1.00 out of 1.00

Let 
$$g(t)=x(t)+\alpha x(-t)$$
 where  $x(t)=\beta e^{-t}u(t)$  and the Laplace transform of  $g(t)$  is  $G(s)=rac{s}{s^2-1}, \qquad -1< Re\{s\}<1$ 

The values of the constants  $\alpha$  and  $\beta$  are

Select one:

$$\bigcirc$$
 a.  $\alpha=1$ ,  $eta=rac{1}{2}$ 

$$\bigcirc$$
 b.  $lpha=-1$ ,  $eta=-rac{1}{2}$ 

c. 
$$lpha=-1$$
,  $eta=rac{1}{2}$ 

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$$\bigcirc$$
 d.  $lpha=1$ ,  $eta=-rac{1}{2}$ 

e. Incomplete question or none of the options is correct.

Your answer is correct.

The correct answer is: lpha=-1,  $eta=rac{1}{2}$ 

#### Question 2

Correct

Mark 1.00 out of 1.00

Consider the signal

$$x[n] = egin{cases} (rac{1}{3})^n cos(rac{\pi}{4}n) & n \leq 0 \ 0 & n > 0 \end{cases}$$

The poles and ROC for X(z) are given by

Select one:

$$\bigcirc$$
 a. poles at  $z=rac{1}{3}e^{\pm jrac{\pi}{2}}$  , ROC :  $|z|<rac{1}{3}$ 

$$\bigcirc$$
 b. poles at  $z=rac{1}{3}e^{\pm jrac{\pi}{4}}$  , ROC :  $|z|>rac{1}{3}$ 

$$\quad \ \ \, \bigcirc$$
 c. poles at  $z=\frac{1}{3}e^{\pm j\frac{\pi}{2}}$  , ROC :  $|z|>\frac{1}{3}$ 

$$\bigcirc$$
 d. poles at  $z=rac{1}{3}e^{\pm jrac{\pi}{4}}$  , ROC :  $|z|\leqrac{1}{3}$ 

e. Incomplete question or none of the options is correct

Your answer is correct.

The correct answer is: Incomplete question or none of the options is correct

Correct

Mark 1.00 out of 1.00

Let x[n] be a signal whose rational Z-transform X(z) contains a pole at  $z=\frac{1}{2}$ . Given that  $x_1[n]=(\frac{1}{4})^nx[n]$  is absolutely summable and  $x_2[n]=(\frac{1}{8})^nx[n]$  is not absolutely summable. Then, x[n] is

### Select one:

- a. Left sided
- b. Right sided
- c. Two sided or both sided
- d. Incomplete question or none of the options is correct

Your answer is correct.

The correct answer is: Two sided or both sided

## Question 4

Correct

Mark 1.00 out of 1.00

Consider a discrete time signal given by x[n] = -0.25nu[n] + 0.5nu[-n-1]. The region of convergence of its Z-transform would be:

#### Select one:

- a. Incomplete question or none of the options is correct
- b. the annular region between the two circles, both centered at origin and having radii 0.25 and 0.5. √
- o. the region inside the circle of radius 0.5 and centered at origin.
- d. the entire Z plane.
- e. the region outside the circle of radius 0.25 and centered at origin.

Your answer is correct.

The correct answers are: the annular region between the two circles, both centered at origin and having radii 0.25 and 0.5., Incomplete question or none of the options is correct

# Question 5

Correct

Mark 1.00 out of 1.00

The Laplace transform of  $f(t)=2\sqrt{t/\pi}$  is  $\,s^{-3/2}.$  The Laplace transform of  $g(t)=\sqrt{1/\pi t}$  is

#### Select one:

- igcap a.  $rac{3}{2}s^{-5/2}$
- $igcup b. \ s^{3/2}$
- $igcap c. \ s^{1/2}$
- d. Incomplete question or none of the options is correct
- lacksquare e.  $s^{-1/2}$

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Your answer is correct.

The correct answer is:  $s^{-1/2}$ 

Correct

Mark 1.00 out of 1.00

An input  $x(t) = exp(-2t)u(t) + \delta(t-6)$  is applied to an LTI system with impulse response h(t) = u(t). The output is:

Select one:

- $igcap a. \ 0.5[1-exp(-2t)]u(t)+u(t+6)$
- o b. [1 exp(-2t)]u(t) + u(t+6)
- o c. 0.5[1 exp(-2t)]u(t) + u(t-6)

**√** 

- $igcup d. \ [1-exp(-2t)]u(t)+u(t-6)$
- e. Incomplete question or none of the options is correct

Your answer is correct.

The correct answer is: 0.5[1 - exp(-2t)]u(t) + u(t-6)

# Question 7

Correct

Mark 1.00 out of 1.00

Let the Laplace transform of a function f(t) which exists for t>0 be  $F_1(s)$  and the Laplace transform of its delayed version  $f(t-\tau)$  be  $F_2(s)$ . Let  $F_1^*(s)$  be the complex conjugate of  $F_1(s)$  with the Laplace variable set as  $s=\sigma+j\omega$ . If  $G(s)=\frac{F_2(s)F_1^*(s)}{||F_1(s)||^2}$ , then the inverse Laplace transform of G(s) is:

Select one:

- igcup a. An ideal impulse  $\delta(t)$
- lacksquare b. An ideal delayed impulse  $\delta(t- au)$

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- o. An ideal delayed step function u(t- au)
- d. Incomplete question or none of the options is correct
- igcup e. An ideal step function u(t)

Your answer is correct.

The correct answer is: An ideal delayed impulse  $\delta(t- au)$ 

## Question 8

Correct

Mark 1.00 out of 1.00

Suppose x[n] is an absolutely summable discrete-time signal. Its z-transform is a rational function with two poles and two zeroes. The poles are at  $z=\pm 2j$ . Which of the following statements is TRUE for the signal x[n]?

Select one:

- a. It is a periodic signal.
- b. It is a finite duration signal.
- c. It is a causal signal.
- d. It is a non-causal signal. 

  ✓
- e. Incomplete question or none of the options is correct

Your answer is correct.

The correct answer is: It is a non-causal signal.

Correct

Mark 1.00 out of 1.00

The input-output relationship of a causal stable LTI system is given as

 $y[n]=\alpha y[n-1]+\beta x[n].$  If the impulse response h[n] of this system satisfies the condition  $\sum_{n=0}^\infty h[n]=2$ , the relationship between lpha and eta is

Select one:

- a. Incomplete question or none of the options is correct
- $\bigcirc$  b. lpha=2eta
- $\circ$  c. lpha=1+eta/2
- $\bigcirc$  d. lpha=-2eta
- $\odot$  e.  $\alpha=1-eta/2$



Your answer is correct.

The correct answer is: lpha=1-eta/2

# Question 10

Correct

Mark 1.00 out of 1.00

A causal LTI system S with impulse response h(t) has its input x(t) and output y(t) related through a linear constant-coefficient differential equation of the form

$$rac{d^3y(t)}{dt^3}+(1+lpha)rac{d^2y(t)}{dt^2}+lpha(lpha+1)rac{dy(t)}{dt}+lpha^2y(t)=x(t)$$

lf

$$g(t) = rac{dh(t)}{dt} + h(t)$$

How many poles does G(s) have?

Answer: 2

The correct answer is: 2

#### Question 11

Correct

Mark 1.00 out of 1.00

How many signals have a Laplace transform that may be expressed as  $\frac{(s-1)}{(s+2)(s+3)(s^2+s+1)}$  in its region of convergence?

Answer: 4

The correct answer is: 4

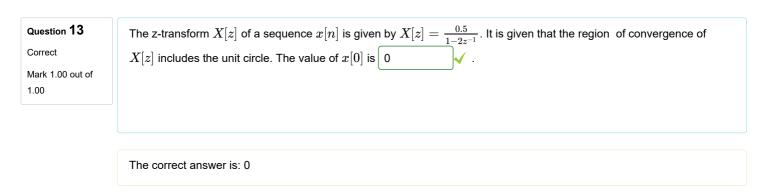
## Question 12

Incorrect

Mark 0.00 out of 1.00

The transfer function of a causal LTI system is  $H(s)=\frac{1}{s}$ . If the input to the system is  $x(t)=\frac{sin(t)}{\pi t}u(t)$ , where u(t) is a unit step function, the system output y(t) at  $t\to\infty$  is 0

The correct answer is: 0.5



Correct

Mark 1.00 out of
1.00

Let  $H_1(z)=(1-pz^{-1})^{-1}$ ,  $H_2(z)=(1-qz^{-1})^{-1}$ ,  $H(z)=H_1(z)+rH_2(z)$ . The quantities p,q and r are real numbers. Consider  $p=\frac{1}{2},\ q=-\frac{1}{4}$ , |r|<1. If the zero of H(z) lies on the unit circle, then |r|=0.50

The correct answer is: 0.5

# Question 15

Correct

Mark 1.00 out of 1.00

Two causal discrete -time signals x[n] and y[n] are related as  $y[n] = \sum_{m=0}^n x[m]$ . If the z-transform of y[n] is  $\frac{2}{z(z-1)^2}$ , the value of x[2] is  $\boxed{0}$ .

The correct answer is: 0

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