CM3 OPTIMISATION

Exemple: Méthode de Newton

$$f(x) = rac{1}{2}x_1^2 + rac{1}{4}x_2^4 - rac{1}{2}x_2^2$$

Gradient:

$$abla f(x) = egin{pmatrix} x_1 \ x_2^3 - x_2 \end{pmatrix}$$

Matrice Hessienne:

$$abla^2 f(x) = egin{pmatrix} 1 & 0 \ 0 & 3x_2^2 - 1 \end{pmatrix} \ (
abla^2 f(x))^{-1} = rac{1}{3x_2^2 - 1} egin{pmatrix} 3x_2^2 - 1 & 0 \ 0 & 1 \end{pmatrix}$$

1er cas:

$$X_0 = egin{pmatrix} 1 \ 0 \end{pmatrix}
ightarrow X_1 = egin{pmatrix} 1 \ 0 \end{pmatrix} + egin{pmatrix} -1 & 0 \ 0 & 1 \end{pmatrix} egin{pmatrix} 1 \ 0 \end{pmatrix}$$

$$X_1 = egin{pmatrix} 0 \ 0 \end{pmatrix}
ightarrow X_2 = egin{pmatrix} 0 \ 0 \end{pmatrix} + egin{pmatrix} -1 & 0 \ 0 & 1 \end{pmatrix} egin{pmatrix} 0 \ 0 \end{pmatrix}$$

Conclusion : c'est un point selle

2ème cas:

$$X_0 = egin{pmatrix} 1 \ 1 \end{pmatrix}
ightarrow X_1 = egin{pmatrix} 1 \ 1 \end{pmatrix} - rac{1}{2}egin{pmatrix} 2 & 0 \ 0 & 1 \end{pmatrix}egin{pmatrix} 1 \ 0 \end{pmatrix}$$

$$X_1 = egin{pmatrix} 0 \ 1 \end{pmatrix}
ightarrow X_2 = egin{pmatrix} 0 \ 1 \end{pmatrix} - rac{1}{2}egin{pmatrix} 2 & 0 \ 0 & 1 \end{pmatrix}egin{pmatrix} 0 \ 0 \end{pmatrix}$$

Conclusion: on obitent un minimum local.

Exemple: Critère des moindres carrés

$$egin{split} minf(x) &= rac{1}{2}[(x_i-a)^2+(y_i-b)^2-R^2] \ & \ r_i^2 &= R^2-(x_i^2+a-2x_ia)-(y_i^2+b^2-2y_ib) \ & \ minf(x) &= rac{1}{2}(r_1^2+r_2^2+\ldots+r_m^2) \end{split}$$

$$r_i = egin{bmatrix} 2x_i & 2y_i & 1 \end{bmatrix} egin{bmatrix} a \ b \ c \end{bmatrix} - egin{bmatrix} x_i^2 + y_i^2 \end{bmatrix} = ax_i + b_i$$

Finalement on obtient :

$$egin{bmatrix} 2x_1 & 2y_1 & 1 \ 2x_m & 2y_m & 1 \end{bmatrix} egin{bmatrix} a \ b \ R^2 - a^2 - b^2 \end{bmatrix} - egin{bmatrix} x_1^2 + y_1^2 \ x_m^2 + y_m^2 \end{bmatrix}$$

Exemple: Gauss-Newton

$$f(x,y) = rac{1}{2}[(x^2-y)^2+(1-x)^2] \ f(x) = rac{1}{2}x_1^2+rac{1}{4}x_2^4-rac{1}{2}x_2^2$$

Gradient:

$$abla f(x) = egin{pmatrix} 2x^3 - 2xy + x - 1 \ y - x^2 \end{pmatrix}$$

Matrice Hessienne:

$$egin{aligned}
abla^2 f(x) &= egin{pmatrix} 6x^2-2y+1 & -2x \ -2x & 1 \end{pmatrix} \
abla r_1 &= egin{pmatrix} 2x \ -1 \end{pmatrix}; \
abla r_2 &= egin{pmatrix} -1 \ 0 \end{pmatrix} \
abla^2 r_1 &= egin{pmatrix} 2 & 0 \ 0 & 0 \end{pmatrix}; \
abla^2 r_2 &= egin{pmatrix} 0 & 0 \ 0 & 0 \end{pmatrix} \end{aligned}$$

Matrice Jacobienne:

$$J(x) = egin{pmatrix} 2x & -1 \ -1 & 0 \end{pmatrix}$$

d'où:

$$abla f(x) = egin{pmatrix} 2x & -1 \ -1 & 0 \end{pmatrix} egin{pmatrix} x^2 - y \ 1 - x \end{pmatrix} = egin{pmatrix} 2x^3 - 2xy + x - 1 \ y - x^2 \end{pmatrix}$$

On approxime la matrice hessienne :

$$abla^2 f(x) = J.\,J^T = egin{pmatrix} 4x^2+1 & -2x \ -2x & 1 \end{pmatrix}$$