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# O.1 — [S14O1] Point-in-polygon (ray casting)

Your Task:

Implement ray-casting point-in-polygon; treat points on edges as inside.

## Code:

```
def point_on_segment(px, py, x1, y1, x2, y2):
    """Check if point (px,py) lies on segment (x1,y1)-(x2,y2)."""
    if cross != 0:
    return False
    if min(x1, x2) \leftarrow px \leftarrow max(x1, x2) and min(y1, y2) \leftarrow py \leftarrow max(y1, y2):
        return True
    return False
def point_in_polygon(px, py, poly):
    """Ray-casting point-in-polygon with edge inclusion."""
    n = len(poly)
    inside = False
    for i in range(n):
        x1, y1 = poly[i]
        x2, y2 = poly[(i + 1) % n]
        if point_on_segment(px, py, x1, y1, x2, y2):
            return True
```

```
for i in range(n):
        x1, y1 = poly[i]
        x2, y2 = poly[(i + 1) % n]
        if y1 > y2:
             x1, x2 = x2, x1
             y1, y2 = y2, y1
         if y1 <= py < y2:
             x_{inters} = x1 + (py - y1) * (x2 - x1) / (y2 - y1)
             if px < x inters:</pre>
                 inside = not inside
     return inside
def points_in_polygon(poly, pts):
     """Return boolean list for each point wrt polygon."""
    return [point_in_polygon(px, py, poly) for (px, py) in pts]
poly = [(0,0),(4,0),(4,4),(0,4)]
pts = [(2,2),(5,5)]
print(points in polygon(poly, pts))
```

## **OUTPUT:**

[True,False]

## **OBSERAVATION:**

- \* Correctly includes edge/vertex points using point\_on\_segment.
- \* Ray-casting logic is implemented properly (avoids double-counting edges).
- \* Works for both convex and concave polygons.
- \* Complexity is optimal (O(n)).
- \* Only improvement: add floating-point tolerance for numerical stability.

```
O.2 — [S14O2] Compute rolling median (w=3)
```

Your Task:

Return the median for each sliding window; prefer an efficient approach.

#### Code:

```
import bisect

def rolling_median(nums, w=3):
    """Compute rolling medians with window size w."""
    if w <= 0:
        raise ValueError("Window size must be positive")
    if len(nums) < w:
        return []

window = sorted(nums[:w])
    medians = []

for i in range(w, len(nums) + 1):
    if w % 2 == 1:
        medians.append(window[w // 2])
    else:
        medians.append((window[w // 2 - 1] + window[w // 2]) / 2)

    if i == len(nums):
        break</pre>
```

```
out_num, in_num = nums[i - w], nums[i]
    window.pop(bisect.bisect_left(window, out_num))
    bisect.insort(window, in_num)

return medians

print(rolling_median([1, 3, 2, 5, 4], 3))
print(rolling_median([1, 2, 3], 3))
print(rolling_median([5, 4], 3))
print(rolling_median([], 3))
print(rolling_median([], 3))
print(rolling_median([], 3))
```

# OUTPUT: [2, 3, 4] [2]

[]

[]

[15.0, 25.0, 35.0]

## **OBSERVATION:**

- \* Correctly computes sliding medians using a sorted window with bisect (O(n log w)).
- \* Handles odd and even window sizes.
- \* Covers edge cases: empty list, list shorter than w, exact-size list.
- \* Produces expected outputs on test cases ([2, 3, 4] for sample).
- \* For very large n, a two-heaps approach may be more scalable, but this solution is clean and efficient enough for typical telecom monitoring workloads.