Engaging with the COBRA Toolbox community

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Reviewers:

Search for existing solutions to problems

- The Frequently Asked Questions (FAQ) section of the documentation (https://opencobra.github.io/cobratoolbox/docs/FAQ.html) is a good starting point to find answers to questions you may have or issues you may face.
- The public forum associated with The COBRA toolbox, available at https://groups.google.com/forum/#!forum/cobra- toolbox, is a great way to search for solutions to previously recognised problems that are similar to problems novel to the user. This is especially so with respect to recent installation and configuration issues that have arisen due to asynchronous development of the many software packages integrated with The COBRA Toolbox.

Register online

Before posting a question to a problem, an application for membership at https://groups.google.com/forum/#!forum/cobra-toolbox is required to eliminate spam.

Facing an issue?

Post your question online to the COBRA Toolbox forum at https://groups.google.com/forum/#!forum/cobra- toolbox. Questions posted to the forum are welcome provided that some simple guidelines are followed to encourage a rapid and effective response from the community.

1. Make the question as detailed as possible to increase the probability of a rapid and helpful reply.
2. Append your message with the result of running `generateSystemConfigReport` so that we know what system we are helping you to debug. That is often the first question that comes to mind when considering to respond.

```
generateSystemConfigReport
```

```
> --------------------------------- SYSTEM CONFIGURATION REPORT ---------------------------------


    _____   _____   _____   _____      _____      |
   /  ___| /  _  \ |  _  \ |  _  \    / ___ \     |   COnstraint-Based Reconstruction and Analysis
   | |     | | | | | |_| | | |_| |   | |___| |    |   The COBRA Toolbox - 2017
   | |     | | | | |  _  { |  _  /   |  ___  |    |
   | |___  | |_| | | |_| | | | \ \   | |   | |    |   Documentation:
   \_____| \_____/ |_____/ |_|  \_\ |_|   |_|    |   http://opencobra.github.io/cobratoolbox
                                                  |


> Checking if git is installed ...  Done.
> Checking if the repository is tracked using git ...  Done.
> Checking if curl is installed ...  Done.
> Checking if remote can be reached ...  Done.
> Initializing and updating submodules ... Done.
```

```
 > Adding all the files of The COBRA Toolbox ...  Done.
 > Define CB map output... set to svg.
 > Retrieving models ...   Done.
 > TranslateSBML is installed and working properly.
 > Configuring solver environment variables ...
   - [--*-] ILOG_CPLEX_PATH: ~/Applications/IBM/ILOG/CPLEX_Studio1271/cplex/matlab/x86-64_osx
   - [---*] GUROBI_PATH: /Library/gurobi702/mac64/matlab
   - [----] TOMLAB_PATH :  --> set this path manually after installing the solver ( see instructions )
   - [----] MOSEK_PATH :  --> set this path manually after installing the solver ( see instructions )
   Done.
 > Checking available solvers and solver interfaces ... Done.
 > Setting default solvers ... Done.
 > Saving the MATLAB path ... Done.
   - The MATLAB path was saved in the default location.

 > Summary of available solvers and solver interfaces

   Support     LP   MILP     QP   MIQP    NLP
 ----------------------------------------------------------------------
 cplex_direct  full              0      0      0      0      -
 dqqMinos      full              1      -      -      -      -
 glpk          full              1      1      -      -      -
 gurobi        full              1      1      1      1      -
 ibm_cplex     full              1      1      1      -      -
 matlab        full              1      -      -      -      1
 mosek         full              0      0      0      -      -
 pdco          full              1      -      1      -      -
 quadMinos     full              1      -      -      -      1
 tomlab_cplex  full              0      0      0      0      -
 qpng          experimental      -      -      1      -      -
 tomlab_snopt  experimental      -      -      -      -      0
 gurobi_mex    legacy            0      0      0      0      -
 lindo_old     legacy            0      -      -      -      -
 lindo_legacy  legacy            0      -      -      -      -
 lp_solve      legacy            1      -      -      -      -
 opti          legacy            0      0      0      0      0
 ----------------------------------------------------------------------
 Total         -                 8      3      4      1      2

 + Legend: - = not applicable, 0 = solver not compatible or not installed, 1 = solver installed.


 > You can solve LP problems using: 'dqqMinos' - 'glpk' - 'gurobi' - 'ibm_cplex' - 'matlab' - 'pdco' - '
 > You can solve MILP problems using: 'glpk' - 'gurobi' - 'ibm_cplex'
 > You can solve QP problems using: 'gurobi' - 'ibm_cplex' - 'pdco' - 'qpng'
 > You can solve MIQP problems using: 'gurobi'
 > You can solve NLP problems using: 'matlab' - 'quadMinos'

 > Checking for available updates ...
 > There are 438 new commit(s) on <master> and 13 new commit(s) on <develop> [53ffeb @ engaging]
 > You can update The COBRA Toolbox by running updateCobraToolbox() (from within MATLAB).
Elapsed time is 32.028399 seconds.

--------------------------------------------------------------------------------------------------------
MATLAB Version: 9.1.0.441655 (R2016b)
MATLAB License Number: 886910
Operating System: Mac OS X  Version: 10.12.5 Build: 16F73
Java Version: Java 1.7.0_75-b13 with Oracle Corporation Java HotSpot(TM) 64-Bit Server VM mixed mode
--------------------------------------------------------------------------------------------------------
MATLAB                                                  Version 9.1         (R2016b)
Simulink                                                Version 8.8         (R2016b)
Aerospace Blockset                                      Version 3.18        (R2016b)
Aerospace Toolbox                                       Version 2.18        (R2016b)
Antenna Toolbox                                         Version 2.1         (R2016b)
Bioinformatics Toolbox                                  Version 4.7         (R2016b)
Communications System Toolbox                           Version 6.3         (R2016b)
Computer Vision System Toolbox                          Version 7.2         (R2016b)
Control System Toolbox                                  Version 10.1        (R2016b)
```

```
Curve Fitting Toolbox                                Version 3.5.4       (R2016b)
DSP System Toolbox                                   Version 9.3         (R2016b)
Database Toolbox                                     Version 7.0         (R2016b)
Datafeed Toolbox                                     Version 5.4         (R2016b)
Econometrics Toolbox                                 Version 3.5         (R2016b)
Embedded Coder                                       Version 6.11        (R2016b)
Filter Design HDL Coder                              Version 3.1         (R2016b)
Financial Instruments Toolbox                        Version 2.4         (R2016b)
Financial Toolbox                                    Version 5.8         (R2016b)
Fixed-Point Designer                                 Version 5.3         (R2016b)
Fuzzy Logic Toolbox                                  Version 2.2.24      (R2016b)
Global Optimization Toolbox                          Version 3.4.1       (R2016b)
HDL Coder                                            Version 3.9         (R2016b)
Image Acquisition Toolbox                            Version 5.1         (R2016b)
Image Processing Toolbox                             Version 9.5         (R2016b)
Instrument Control Toolbox                           Version 3.10        (R2016b)
LTE System Toolbox                                   Version 2.3         (R2016b)
MATLAB Coder                                         Version 3.2         (R2016b)
MATLAB Compiler                                      Version 6.3         (R2016b)
MATLAB Compiler SDK                                  Version 6.3         (R2016b)
MATLAB Report Generator                              Version 5.1         (R2016b)
Mapping Toolbox                                      Version 4.4         (R2016b)
Model Predictive Control Toolbox                     Version 5.2.1       (R2016b)
Neural Network Toolbox                               Version 9.1         (R2016b)
Optimization Toolbox                                 Version 7.5         (R2016b)
Parallel Computing Toolbox                           Version 6.9         (R2016b)
Partial Differential Equation Toolbox                Version 2.3         (R2016b)
Phased Array System Toolbox                          Version 3.3         (R2016b)
RF Toolbox                                           Version 3.1         (R2016b)
Robotics System Toolbox                              Version 1.3         (R2016b)
Robust Control Toolbox                               Version 6.2         (R2016b)
Signal Processing Toolbox                            Version 7.3         (R2016b)
SimBiology                                           Version 5.5         (R2016b)
SimEvents                                            Version 5.1         (R2016b)
SimRF                                                Version 5.1         (R2016b)
Simscape                                             Version 4.1         (R2016b)
Simscape Driveline                                   Version 2.11        (R2016b)
Simscape Electronics                                 Version 2.10        (R2016b)
Simscape Fluids                                      Version 2.1         (R2016b)
Simscape Multibody                                   Version 4.9         (R2016b)
Simscape Power Systems                               Version 6.6         (R2016b)
Simulink 3D Animation                                Version 7.6         (R2016b)
Simulink Coder                                       Version 8.11        (R2016b)
Simulink Control Design                              Version 4.4         (R2016b)
Simulink Design Optimization                         Version 3.1         (R2016b)
Simulink Design Verifier                             Version 3.2         (R2016b)
Simulink Desktop Real-Time                           Version 5.3         (R2016b)
Simulink Report Generator                            Version 5.1         (R2016b)
Simulink Test                                        Version 2.1         (R2016b)
Simulink Verification and Validation                 Version 3.12        (R2016b)
Stateflow                                            Version 8.8         (R2016b)
Statistics and Machine Learning Toolbox              Version 11.0        (R2016b)
Symbolic Math Toolbox                                Version 7.1         (R2016b)
System Identification Toolbox                        Version 9.5         (R2016b)
Trading Toolbox                                      Version 3.1         (R2016b)
Wavelet Toolbox                                      Version 4.17        (R2016b)

 > Default shell       :        /bin/bash
 > Version of shell    :        GNU bash, version 3.2.57(1)-release (x86_64-apple-darwin16)
Copyright (C) 2007 Free Software Foundation, Inc.
```

ANTICIPATED RESULTS

Generally, responses to questions can be expected within 1-2 days of posting, provided that posting guidelines are followed.

Suggest new solutions to problems

Reply to a question online COBRA toolbox forum. Community contributions are welcomed to help users overcome any issues they face and are noticed by existing COBRA community members.