练习题

1.

Solve the ODE, $\ddot{y} + +6\ddot{y} + 11\dot{y} + 6y = 1$, with zero initial conditions. Using Laplace transforms, partial fraction expansion and inverse Laplace transforms.

2. Using final value theorem to find $y(t=\infty)$ for

$$Y(s) = \frac{5s+2}{s(5s+4)}$$

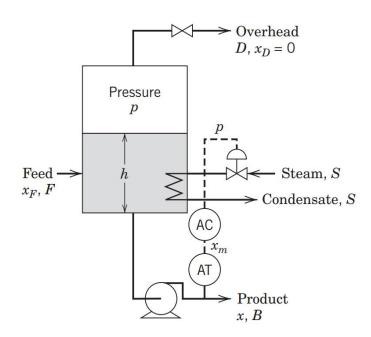
Consider the following transfer function:

$$G(s) = \frac{Y(s)}{U(s)} = \frac{5}{10s+1}$$

- (a) What is the steady-state gain?
- **(b)** What is the time constant?
- (c) If U(s) = 2/s, what is the value of the output y(t) when $t \to \infty$?
- (d) For the same U(s), what is the value of the output when t = 10? What is the output when expressed as a fraction of the new steady-state value?

4

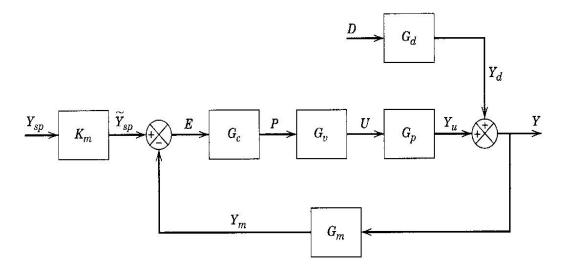
A steam-heated evaporator used to concentrate a feed stream by evaporating water is shown in figure below. The mass fraction of solute in the exit stream x is measured and controlled by adjusting the steam flow rate, S.



Questions:

- (1) Draw block diagram for this control system
- (2) List controlled variable, manipulated variable and possible disturbance variables.
- (3) Should fail-close valve or fail-open valve be used to adjust S?
- (4) Is the controller AC reverse acting or direct acting?

Consider a feedback control system:



$$G_p(s) = \frac{2}{(s+1)}$$
 $G_m(s) = \frac{1}{(s+3)}$ $G_v(s) = \frac{2}{(s+2)}$ $G_c(s) = k_c$

Using Routh stability method to determine the range of *Kc* which makes the closed loop control system stable.