Objective design meets Rust



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- 3 years in Nokia as C++ developer doing BTS stuff
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- since October in *Anixe* as Rust developer doing prizing calculation

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OOP = Classes + Inheritance

- + Polymorphism
- + Casting
- + Hermetization
- + Mixins
- + ...





Object-oriented programs are made up of objects. An object packages both data and the procedures that operate on that data. The procedures are typically called methods or operations.



- structures with fields as data
- impl blocks for structures as methods
- · variables which are structures instances

We are already there.



```
struct Vec2d {
   x: f32,
   y: f32,
impl Vec2d {
  fn translate(&mut self , other: Vec2d) {
    self.x += other.x;
    self.y += other.y;
```

Objective Programming Wikipedia



Object-oriented programming (OOP) is a programming paradigm based on the concept of "objects", which may contain data, in the form of fields, often known as attributes; and code, in the form of procedures, often known as methods.



Object-oriented programming (OOP) is a programming paradigm based on the concept of "objects", which may contain data, in the form of fields, often known as attributes; and code, in the form of procedures, often known as methods.

Features

- encapsulation
- composition, inheritance, and delegation
- polymorphism

SOLID

GRASP



Programming paradigm focusing on hiding data behind behaviour.

Core features:

- types/classes/representations
- interfaces/concepts/contracts
- objects/instances
- polymorphism (possibly compile-time!)
- hermetization



Building blocks



```
struct Foo {
    f1: String,
    pub f2: bool,
    pub(crate) f3: FooBar,
}
impl Foo {
    fn method(&self) {
    }
}
```

```
enum Bar {
    B1,
    B2(Foo),
    B3{ f: Foo, u: u32 }
}
impl Bar {
    fn method(&self) {
    }
}
```



```
trait Filo {
    fn push(&mut self , item: u32);
    fn pop(&mut self) -> Option<u32>;
impl Filo for Vec<u32> {
    fn push(&mut self , item: u32) {
        self.push(item)
    fn pop(&mut self) -> Option<u32> {
        self.pop()
```



```
fn foo(x: &mut impl Filo) {
    x.push(5)
fn bar(x: &mut impl Filo) {
    println!("{:?}", x.pop())
fn main() {
    let mut v = vec![];
    foo(&mut v);
    bar(&mut v);
```



```
fn foo(x: &mut dyn Filo) {
    x.push(5)
fn bar(x: &mut dyn Filo) {
    println!("{:?}", x.pop())
fn main() {
    let mut v: Box<dyn Filo> = Box::new(vec![]);
    foo(\&mut *v);
    bar(&mut *v);
```



```
fn new_filo() -> impl Filo {
    vec![2, 3]
}

fn main() {
    let mut filo = new_filo();
    // println!("{}", filo.is_empty());
    println!("{:?}", filo.pop());
    println!("{:?}", filo.pop());
    println!("{:?}", filo.pop());
}
```



Guideline for being OOPish in Rust:

- · define your interfaces as Traits
- define your classes as Structs implementing your Traits
- return 'impl Trait'/boxed 'dyn Trait' wherever it makes sense
- take args as 'impl Trait'/'dyn Trait' wherever it makes sense



Inheritance



```
class Filo {
public:
    virtual void push (int x) = 0;
    virtual int pop() = 0;
class VecFilo: public Filo {
public:
    virtual void push(int x) override { data.push_back(x); }
    virtual void pop() override {
        int last = data.back();
        data.pop_back();
        return last;
private:
    std::vector<int> data;
```



```
trait Filo {
    fn push(&mut self , item: u32);
    fn pop(&mut self) -> Option<u32>;
impl Filo for Vec<u32> {
    fn push(&mut self , item : u32) {
         self.push(item)
    fn pop(\&mut self) \rightarrow Option<u32> {
         self.pop()
```



```
class VecFiloWithPop2: public VecFilo {
public:
    std::tuple < int , int > pop2() {
        std::tuple { pop() , pop() }
    }
};
```

```
trait Pop2 {
    fn pop2(&mut self) -> (Option<u32>, Option<u32>);
}
impl Pop2 for Vec<u32> {
    fn pop2(&mut self) -> (Option<u32>, Option<u32>) {
        (self.pop(), self.pop())
    }
}
```



```
trait Pop2 {
    fn pop2(&mut self) -> (Option<u32>, Option<u32>);
}

impl<T: Filo > Pop2 for T {
    fn pop2(&mut self) -> (Option<u32>, Option<u32>) {
        (self.pop(), self.pop())
    }
}
```

Problem: there may be only one existing implementation for every type (direct or indirect).

Solution: specializations incomming! (RFC 1210)



```
class FunnyVec: public std::vector<int> {
private:
    int funny_field;
};
```

Sometimes bad designs will fail faster in Rust

Catherine West @ Rustconf, QotW 252



Not so bad scenario - vector and funny_field are independent

```
class ItemAccessor: public std::vector<int> {
  public:
    int get_item() {
       return (*this)[index];
    }
  private:
    size_t index;
};
```



```
class ItemAccessor {
public:
    int get_item() {
        return data[index];
private:
    std::vector<int> & data;
    size_t index;
};
struct ItemAccessor < 'a> {
    data: &'a Vec < u32 >,
    index: usize,
impl < 'a> ItemAccessor < 'a> {
    fn get_item(&self) -> u32 {
         self.data[self.index]
```



```
class AccumulatedVec: public std::vector<int> {
public:
    void clear() { ... }
    void insert() { ... }
    std::vector<int>::iterator erase(
        std::vector<int> iterator pos) { ... }
    ...
private:
    int sum;
};
```

And then in 2011 someone adds 'emplace'...



Using inheritance to reuse part of previous implementation is in most cases bad by design. This approach reuses not only existing implementation details, but also everything what will came up in future and cannot be predicted.

Prefer encapsulation over inheritance.



```
struct ItemAccessor {
    data: Vec<u32>,
    index: usize,
}

impl Deref for ItemAccessor {
    type Target = Vec<u32>;

    fn deref(&self) -> &Vec<u32> {
        &self.data
    }
}
```

Problems:

- semantics deref means "dereferencing to", not "is a"
- not working with traits



Polymorphism



```
fn foo(x: &mut dyn Filo) {
    x.push(5)
fn bar(x: &mut dyn Filo) {
    println!("{:?}", x.pop())
fn main() {
    let mut v: Box<dyn Filo> = Box::new(vec![]);
    foo(\&mut *v);
    bar(&mut *v);
```



```
fn foo(x: &mut impl Filo) {
    x.push(5)
fn bar(x: &mut impl Filo) {
    println!("{:?}", x.pop())
fn main() {
    let mut v: Box<dyn Filo> = Box::new(vec![]);
    foo(\&mut *v);
    bar(&mut *v);
```

error[E0277]: the size for values of type 'dyn Filo' cannot be known at compilation time



```
fn foo(x: &mut impl Filo) {
    x.push(5)
fn bar(x: &mut impl Filo) {
    println!("{:?}", x.pop())
fn main() {
    let mut v: Box<dyn Filo > = Box::new(vec![]);
    foo(&mut v);
    bar(&mut v);
```

error[E0277]: the trait bound 'std::boxed::Box(dyn Filo): Filo' is not satisfied



```
use std::ops::DerefMut;
impl Filo for Box<dyn Filo> {
    fn push(&mut self, item: u32) {
        self.deref_mut().push(item)
    }

    fn pop(&mut self) -> Option<u32> {
        self.deref_mut().pop()
    }
}
```

Pros:

transparent

Cons:

- boilerplate
- heap allocation



```
enum DynamicFilo {
    Vec(Vec<u32>),
    List (LinkedList < u32 > ),
impl Filo for DynamicFilo {
    fn push(&mut self , item : u32) {
        match self {
             DynamicFilo:: Vec(v) =>
                  Filo::push(v, item),
             DynamicFilo::List(I) =>
                  Filo::push(I, item),
    fn pop(&mut self) \rightarrow Option<u32> { /* \dots */ }
```

Pros:

everything on stack

Cons:

- more boilerplate
- · difficult to be maintained
- not extensible



```
https://crates.io/crates/enum_dispatch
```

```
#[enum_dispatch]
enum DynamicFilo {
    Vec(Vec<32>),
    List(LinkedList<u32>),
}

#[enum_dispatch(DynamicFilo)]
trait Filo {
    fn push(&mut self, item: u32);
    fn pop(&mut self) -> Option<u32>;
}
```

Pros:

- · everything on stack
- reduced boilerplate

Cons:

- still need to maintain
- not extensible

Thank you

Discussion Time