# ZHIHAO WANG

**Z** zh1haowang@stu.pku.edu.cn · ♠ Birthday: 05/28/2002 · ♦ Personal page: zh1hao.wang

### **EDUCATION**

## Peking University, Beijing, China

Sep. 2024 – Present

- M.Eng. in Mechanical Enginerring, expected June 2027
- Advised by: Professor Junzhi Yu (IEEE fellow)

#### Harbin Institute of Technology, Shandong, China

Sep. 2020 – Jun. 2024

- B.Eng. in Intelligent Automotive Engineering
- GPA:92.36/100 Rank:3/73 Top:4.1% TOEFL:99 CET6:639
- Major courses: Linear Algebra and Analytic Geometry, Calculus, Circuits and Electronics, Environment Perception of Intelligent Vehicle, Planning and Decision-Making for Intelligent Vehicle, Structure of Automobile, Automatic Control Principle

## **□** Publications

# X-VLA: Soft-Prompted Transformer as Scalable Cross-Embodiment Vision-Language-Action Model Champion @ AgiBot World Challenge @ IROS 2025, Preprint

Jinliang Zheng\*, Jianxiong Li\*, **Zhihao Wang**, Dongxiu Liu, Xirui Kang, Yuchun Feng, Yinan Zheng, Jiayin Zou, Yilun Chen, Jia Zeng, Ya-Qin Zhang, Jiangmiao Pang, Jingjing Liu, Tai Wang, Xianyuan Zhan

#### PhysiAgent: An Embodied Agent Framework in Physical World

New In ML @ ICML 2025 Workshop, Preprint

<u>Zhihao Wang\*</u>, Jianxiong Li\*, Jinliang Zheng\*, Wencong Zhang, Dongxiu Liu, Yinan Zheng, Haoyi Niu, Junzhi Yu, Xianyuan Zhan

#### Robo-MUTUAL: Robotic Multimodal Task Specification via Unimodal Learning ICRA 2025

Jianxiong Li\*, **Zhihao Wang\***, Jinliang Zheng\*, Xiaoai Zhou, Guanming Wang, Guanglu Song, Yu Liu, Jingjing Liu, Ya-Qin Zhang, Junzhi Yu, Xianyuan Zhan

#### **Universal Actions for Enhanced Embodied Foundation Models**

**CVPR 2025** 

Jinliang Zheng\*, Jianxiong Li\*, Dongxiu Liu\*, Yinan Zheng, **Zhihao Wang**, Zhonghong Ou, Yu Liu, Jingjing Liu, Ya-Qin Zhang, Xianyuan Zhan

#### **Efficient Robotic Policy Learning via Latent Space Backward Planning**

**ICML 2025** 

Dongxiu Liu\*, Haoyi Niu\*, **Zhihao Wang**, Jinliang Zheng, Yinan Zheng, Zhonghong Ou, Jianming Hu, Jianxiong Li, Xianyuan Zhan

# A Novel ViDAR Device With Visual Inertial Encoder Odometry and RL-Based Active SLAM Method IEEE Transactions on Industrial Informatics (IF 11.7), 2025

Zhanhua Xin, **Zhihao Wang**, Shenghao Zhang, Wanchao Chi, Yan Meng, Shihan Kong, Yan Xiong, Chong Zhang, Yuzhen Liu, Junzhi Yu

#### © EXPERIENCES

Institute for AI Industry Research (AIR), Tsinghua University	Jun. 2024 – Present
Student research intern, Beijing, China	Advised by: Xianyuan Zhan
Machine Intelligence Lab, College of Engineering, Peking University	Oct. 2023 – May. 2024
Research Assistant, Beijing & & Shandong, China	Advised by: Junzhi Yu
Harbin Institute of Technology's Formula Student Driverless Team	Feb. 2021 – Sep. 2023
Team leader of perception group, Shandong, China	Advised by: Jianfeng Wang

## **THEORY AND AWARDS**

Peking University Graduate Student Special Academic Scholarship	2025
1st at AIR Summer 2024 Projects Competition	2024
Shandong Outstanding Graduates	2024
Undergraduate National Scholarship	2023
Huawei Intelligent Foundation Scholarship	2023
1st Prize, Twice, Award on Formula Student Autonomous China	2022

# ACADEMIC SERVICE

- Reviewer at conferences: ICLR 2026, AAAI 2026
- Reviewer at workshops: EWM@NeurIPS 2025, WRL@ICLR 2025

## **MISCELLANEOUS**

- Something familiar with: Python, Shell, JAX, PyTorch, HTML, LaTex, Copilot, ROS(1&&2), robot arms (AgileX, AgiBot-G1, AIRBOT)
- Takeaway: An indefatigable youth passionate about learning more and widen his worldview about AI.