ZHIHAO WANG

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EDUCATION

Harbin Institute of Technology, Weihai Campus, Shandong, China

Sep. 2020 – Present

- B.S. in Intelligent Vehicle Engineering, Expected June 2024
- GPA:92.36/100 Rank:3/73 Top:4.1% TOEFL:99 CET6:639
- Major courses: Linear Algebra and Analytic Geometry(99), Calculus(96), Circuits and Electronics(99), Environment Perception of Intelligent Vehicle(98), Planning and Decision-Making for Intelligent Vehicle(96), Structure of Automobile(97), Automatic Control Principle(99), Data Mining(94)

C EXPERIENCE

Harbin Institute of Technology's Formula Student Driverless Team

Feb. 2021 – Present

Team Leader of Driverless System

Shandong, China – Instructor: Jianfeng Wang

- * Training and Implementation of Yolov5 Model with Nvidia TensorRT for Fast Cone Detections
 - Created customized dataset with data enhacement tricks, used for network training
 - Optimized detection speed through CUDA programming, boosted from less than 50 fps to 140+ fps
 - Migration from x86 PC to ARM platform including Jetson and Huawei Mobile Data Center (MDC)
- * Cones' Visual Features Extraction and Visualization Based on ORB-SLAM2
 - Calibration of a monocular camera and joint calibration between a lidar and a camera
 - Restricted input image with cone detection then extract ORB features from interested regions
 - Projected 2D features to 3D space and utilized ICP algorithm to iterative optimize camera poses
- * Flexible and Multi-use Remote Terminal Control Node via SSH
 - It displays completely and elgantly within a terminal window, able to fit windows' size automatically
 - This auto starts all nodes for autonomous driving, receives and shows messages, displays vehicle status

Tencent Autonomous Driving Simulator Software Development

Nov. 2022 – Present

2022

Core Team Member

Shandong, China – Instructor: Quan Wang

- Produced an interface program, transferring virtual camera data from simulator to ROS's sensor_msgs::Image
- Completed structure and content of the class *Environment Perception of Intelligent Vehicle*

Overall Integration Technology Development of Ground Unmanned Vehicles of Beijing Institute of Aerospace Launch Technology Mar. 2023 – May. 2023

Core Team Member

Shandong, China – Instructor: Jianfeng Wang

- Formed a new CAN FD program based on Huawei communication rules and deployed it with cross-compile
- Migrated project's all former ROS packages from Jetson to Huawei Mobile Data Center (MDC)

THONORS AND AWARDS

1st Prize, Silver medal, Award on 2021 Formula Student Autonomous China (delayed by Covid-19)
 Jun. 2022
 1st Prize, Bronze medal, Award on 2022 Formula Student Autonomous China
 Sep. 2022
 1st Prize Scholarship (rank 1st in major)
 May. 2023

Other awards: Excellent Student, 2nd Prize Physics Competition for Colleges in Shandong

MISCELLANEOUS

- Personal Website: zhwang.xyz
- Languages: English Fluent, Mandarin Native speaker
- Programming Languages: C++(mastered), Python(skilled), C, Shell, HTML, CSS, Markdown, LaTex
- Prospective: Fascinated by autonomous driving, currently interested in Neural Radiance Field (NeRF)