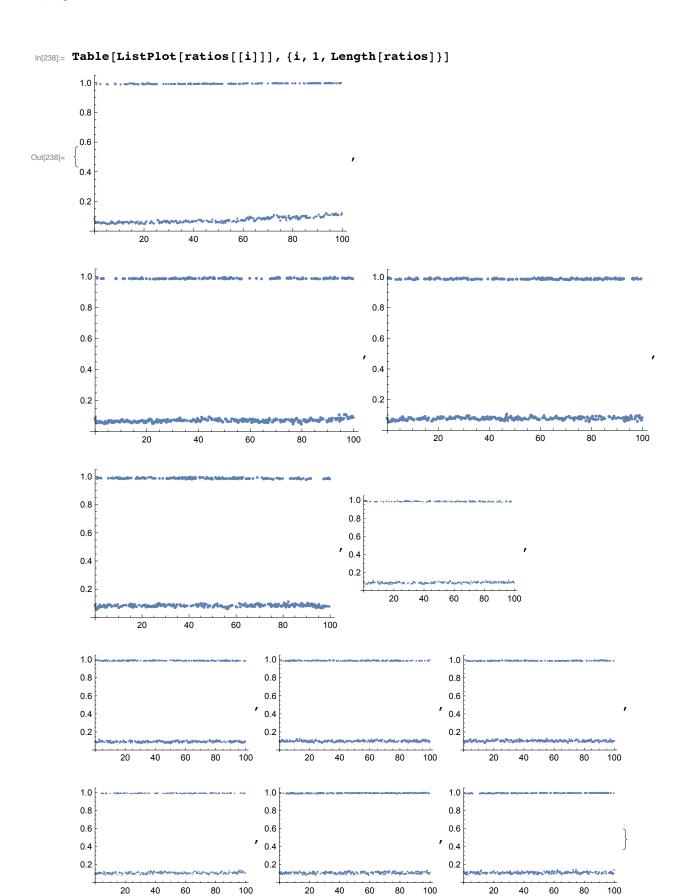
```
ln[230] := LSquared[r_, v_] := (r[[1]] * v[[2]] - r[[2]] * v[[1]])^2;
      I\omega Squared[r1_, r2_, 1_] := (ArcTan[r1[[4]], r1[[3]]] - ArcTan[r2[[4]], r2[[3]]])^2
      AngularKERatio[d_, n_] :=
       Module[
        {dir = d, name = n},
        {nparticles, dt, particlesT} = ParticleTimeSeries[dir, name];
        lSquared = Total[particlesT[[1, 1, 3;; 4]]^2];
        velocitiesT = Differences[particlesT] / dt;
        linearKEt = velocitiesT[[All, All, 1]]^2 + velocitiesT[[All, All, 2]]^2;
        anglesT = ArcTan[particlesT[[All, All, 4]], particlesT[[All, All, 3]]];
        angularVelocitiesT = Differences[anglesT] / dt;
        avSquaredT = angularVelocitiesT[[All, All]]^2;
        angularKEt = avSquaredT * lSquared / 12;
        (*moment of inertia or rod about center = ml^2/12*)
        ratio =
         Table[
          {
            (t-1)*dt
           Mean[angularKEt[[t]]] / (Mean[angularKEt[[t]]] + Mean[linearKEt[[t]]])
          {t, 1, Length[velocitiesT]}
          ];
        ratio
       ]
In[220]:= {nparticles, dt, particlesT} = ParticleTimeSeries[mdwout <> pdirs[[1]], "rods"];
     \rho s = \{"0", ".08", ".16", ".24", ".32", ".40", ".48", ".56", ".64", ".72", ".80"\};
     \rhodirs = Table["sticky_clnks_nm1_np500_amRho.05_pmRho" <> \rho, {\rho, \rhos}];
In[233]:= ratios = Table[AngularKERatio[mdwout <> pdir, "rods"], {pdir, pdirs}];
In[235]:= ratios[[1, 1]]
Out[235]= \{0., 0.0854279\}
```



```
log[212]= Ls = Table[AngularMomentum[mdwout \leftrightarrow \rhodir, "rods"], {\rhodir, \rhodirs}];
In[215]:= Ls2 = Table[
           Table[
             \{Ls[[t, i, 1]], Mean[Ls[[t, i, 2]]]\},
             {i, 1, Length[Ls[[t]]]}],
            {t, 1, Length[Ls]}];
In[203]:= Ls = Insert[Ls, L1, 1];
In[217]:= ListLinePlot[Ls2]
       250
       200
       150
Out[217]=
       100
        50
                     20
                                40
                                                       80
                                                                  100
In[199]:= ListPlot[L1]
Out[199]=
        5
```

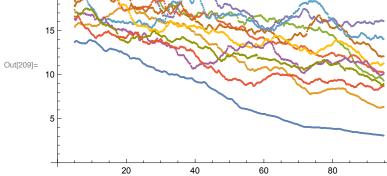
20

40

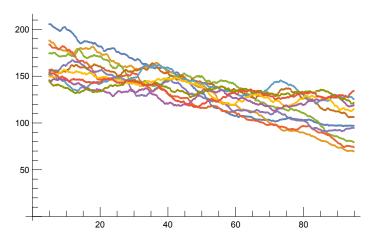
60

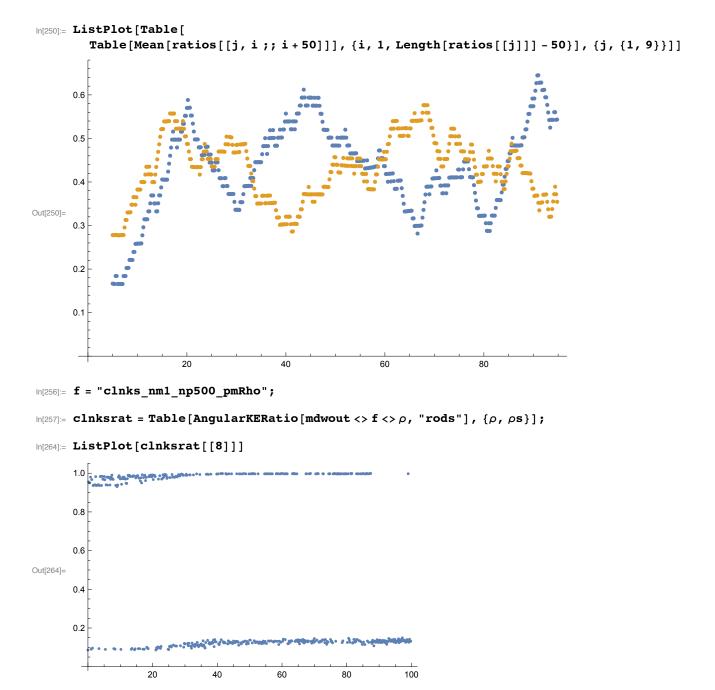
80

100



 $\label{listPlotTable Table Mean Ls2 [[j, i; i+50]]} $$ \{i, 1, Length[Ls2[[j]]] - 50\}], $$ \{j, 1, Length[Ls2]\}]]$$$





In[255]:= frat[[1;; 25]] // TableForm

Out[255]//TableForm=

0.0652402 0. 0.2 0.0417947 0.4 0.984295 0.6 0.033866 0.8 0.0331282 1. 0.948516 0.946084 1.2 0.0326801 1.4 1.6 0.0335144 1.8 0.0308725 0.973398 2. 2.2 0.0391537 2.4 0.0388016 2.6 0.944913 2.8 0.946281 0.988597 3. 0.0330915 3.2 3.4 0.948701 3.6 0.971692 3.8 0.0375677

0.949982

0.0397617

0.974503

0.949231 0.946843

4.

4.2

4.4

4.6

4.8

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