



Intro to Database Systems (15-445/645)

21 Introduction to Distributed Databases

Carnegie
Mellon
University

SPRING
2023

Charlie
Garrod

ADMINISTRIVIA

Project 3 due last night

Homework 5 released today

→ Due Friday, April 21st at 11:59 p.m.

Project 4 released today

→ Due Friday, April 28th at 11:59 p.m.

Interested in TAing this course?

→ <https://forms.gle/AvjfUtSaWtrNijMXA>

Final exam Monday, May 1st, 8:30 – 11:30 a.m.

LAST TIME: RECOVERY

Fuzzy checkpoints
ARIES

RECALL: PARALLEL VS. DISTRIBUTED

Parallel DBMSs:

- Nodes are physically close to each other.
- Nodes connected with high-speed LAN.
- Communication cost is assumed to be small.

Distributed DBMSs:

- Nodes can be far from each other.
- Nodes connected using public network.
- Communication cost and problems cannot be ignored.

DISTRIBUTED DBMSs

Use the building blocks that we covered in single-node DBMSs to now support transaction processing and query execution in distributed environments.

- Optimization & Planning
- Concurrency Control
- Logging & Recovery

TODAY'S AGENDA

System Architectures

Design Issues

Partitioning Schemes

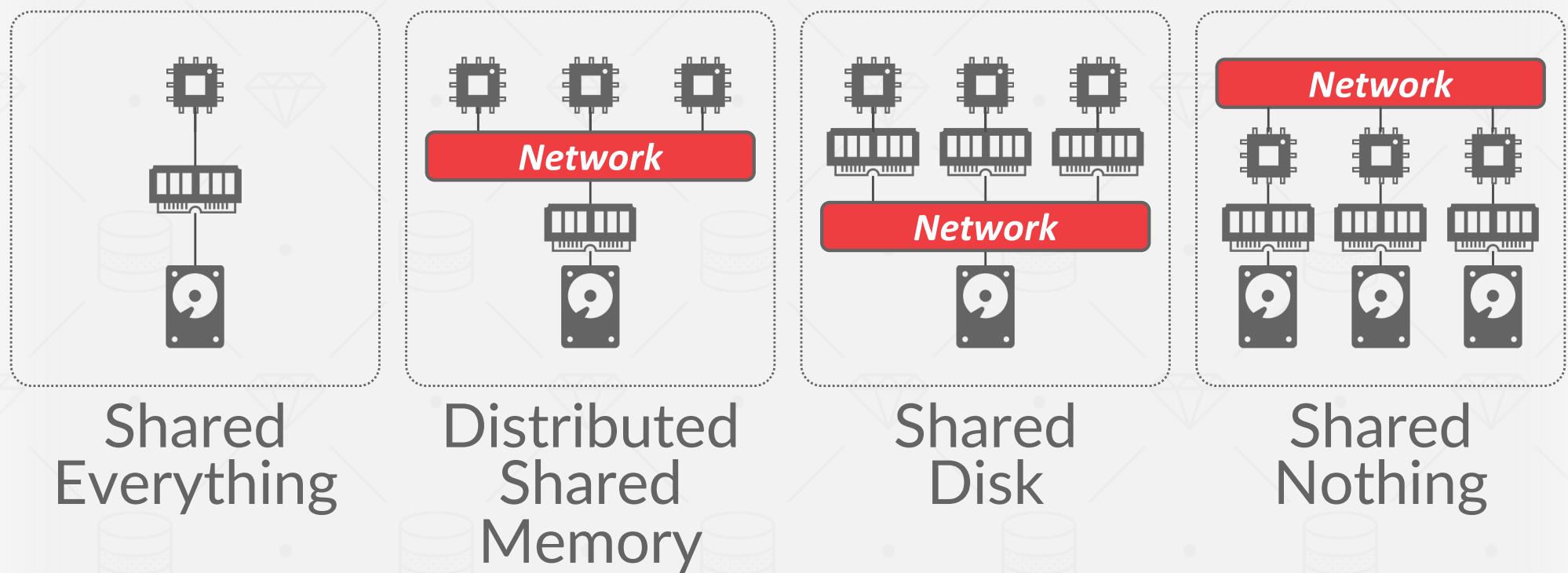
Distributed Concurrency Control

SYSTEM ARCHITECTURE

A distributed DBMS's system architecture specifies what shared resources are directly accessible to CPUs.

This affects how CPUs coordinate with each other and where they retrieve/store objects in the database.

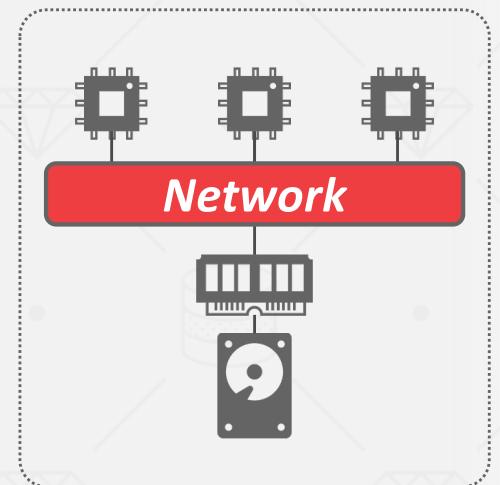
SYSTEM ARCHITECTURE



DISTRIBUTED SHARED MEMORY

CPUs have access to common memory address space via a fast interconnect.

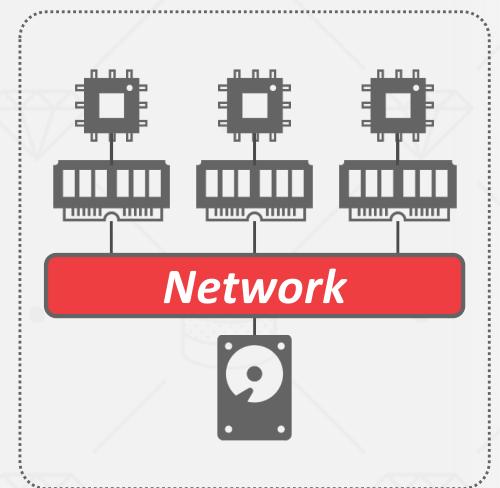
- Each processor has a global view of all the in-memory data structures.
- Each DBMS instance on a processor must "know" about the other instances.



SHARED DISK

All CPUs can access a single logical disk directly via an interconnect, but each have their own private memories.

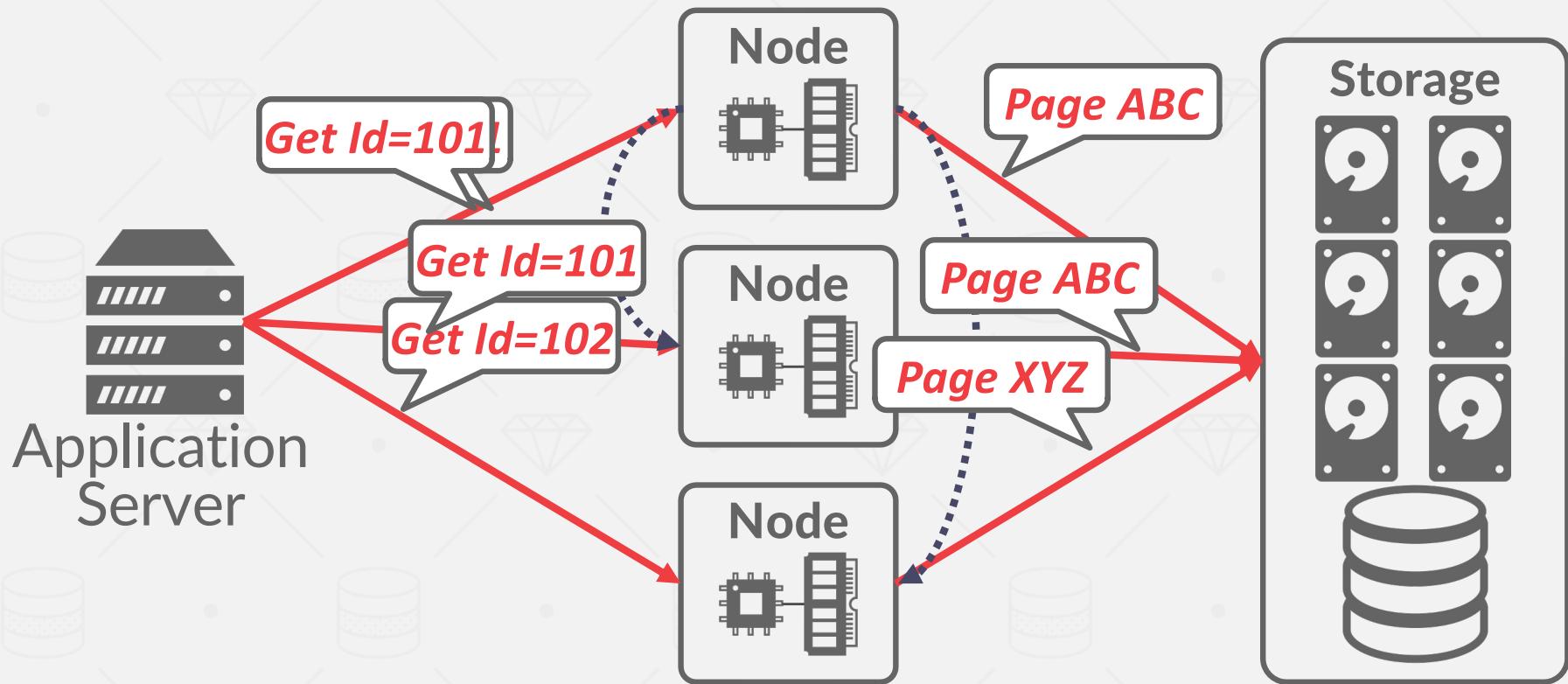
- Can scale execution layer independently from the storage layer.
- Must send messages between CPUs to learn about their current state.



15-445/645 (Spring 2023)



SHARED DISK EXAMPLE

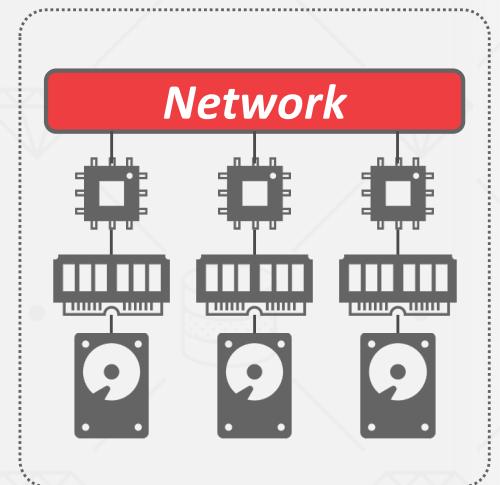


SHARED NOTHING

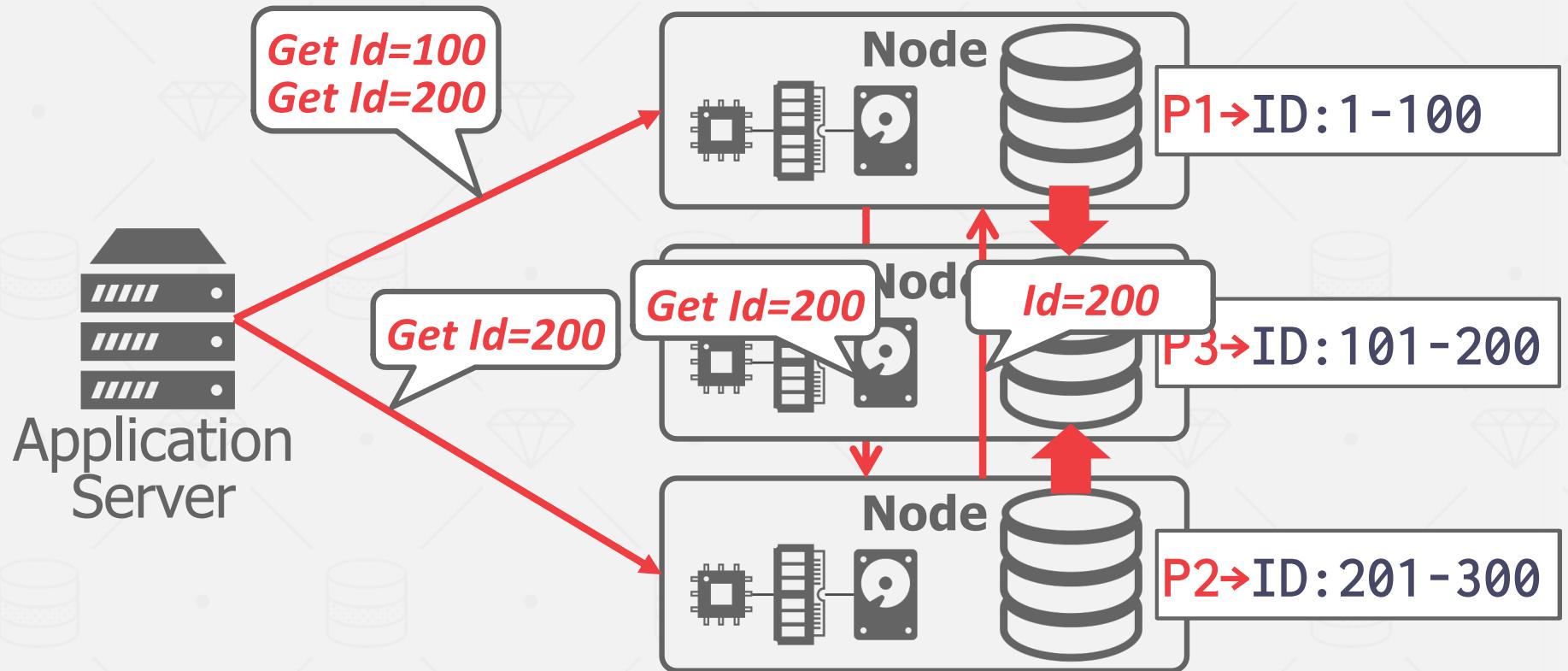
Each DBMS instance has its own CPU, memory, and local disk.

Nodes only communicate with each other via network.

- Harder to scale capacity.
- Harder to ensure consistency.
- Better performance & efficiency.



SHARED NOTHING EXAMPLE



EARLY DISTRIBUTED DATABASE SYSTEMS

MUFFIN – UC Berkeley (1979)

SDD-1 – CCA (1979)

System R* – IBM Research (1984)

Gamma – Univ. of Wisconsin (1986)

NonStop SQL – Tandem (1987)



Stonebraker



Bernstein



Mohan



DeWitt



Gray

DESIGN ISSUES

How does the application find data?

Where does the application send queries?

How to execute queries on distributed data?

- Push query to data.
- Pull data to query.

How does the DBMS ensure correctness?

Next Class

How do we divide the database across resources?

HOMOGENOUS VS. HETEROGENOUS

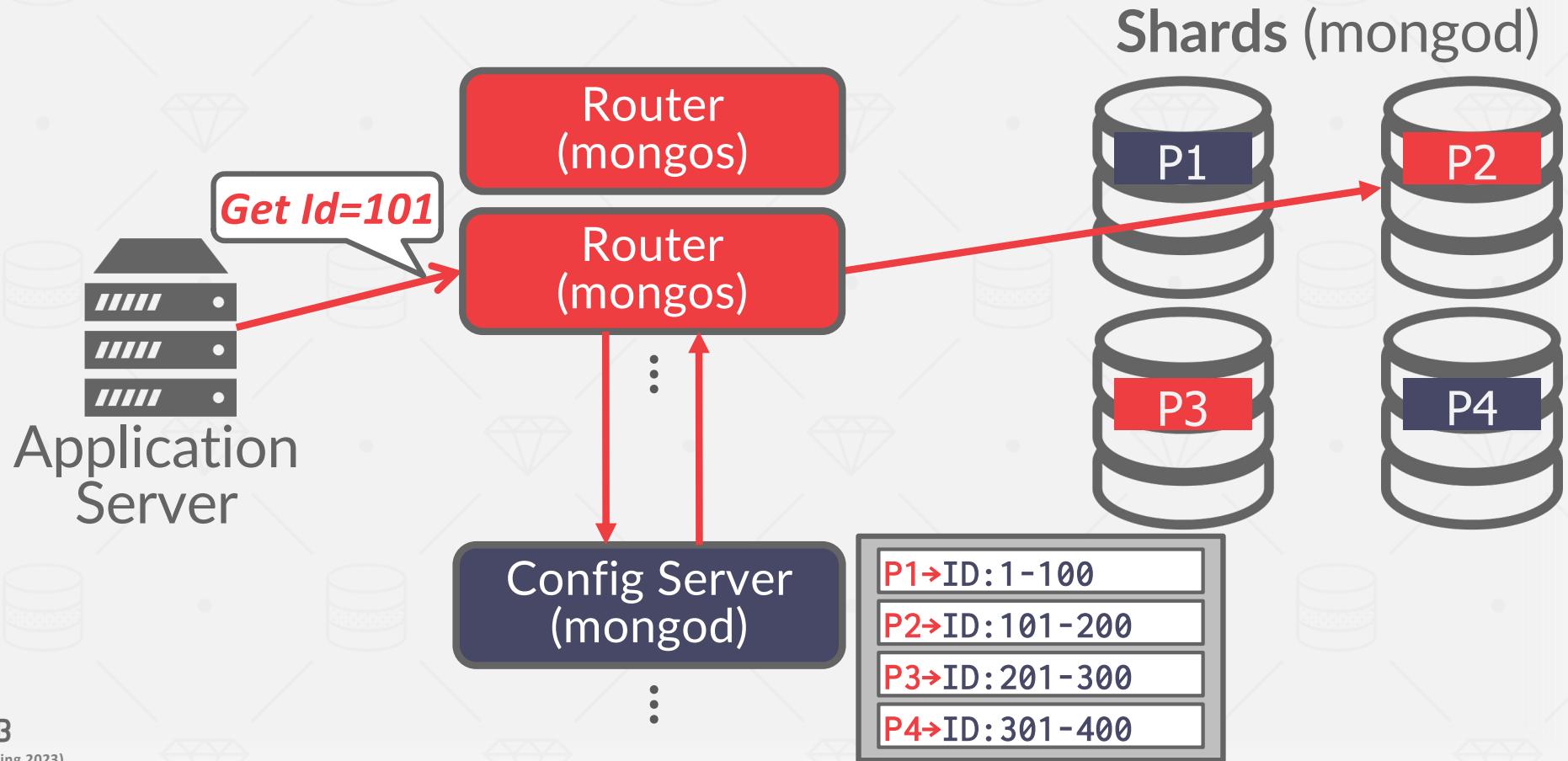
Approach #1: Homogenous Nodes

- Every node in the cluster can perform the same set of tasks (albeit on potentially different partitions of data).
- Makes provisioning and failover "easier".

Approach #2: Heterogenous Nodes

- Nodes are assigned specific tasks.
- Can allow a single physical node to host multiple "virtual" node types for dedicated tasks.

MONGODB HETEROGENOUS ARCHITECTURE



DATA TRANSPARENCY

Applications should not be required to know where data is physically located in a distributed DBMS.

→ Any query that runs on a single-node DBMS should produce the same result on a distributed DBMS.

In practice, developers need to be aware of the communication costs of queries to avoid excessively "expensive" data movement.

DATABASE PARTITIONING

Split database across multiple resources:

- Disks, nodes, processors.
- Often called "sharding" in NoSQL systems.

The DBMS executes query fragments on each partition and then combines the results to produce a single answer.

The DBMS can partition a database **physically** (shared nothing) or **logically** (shared disk).

NAÏVE TABLE PARTITIONING

Assign an entire table to a single node.

Assumes that each node has enough storage space for an entire table.

Ideal if queries never join data across tables stored on different nodes and access patterns are uniform.

NAÏVE TABLE PARTITIONING

Table1

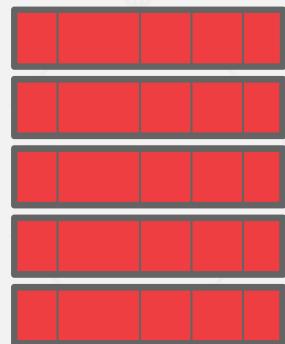
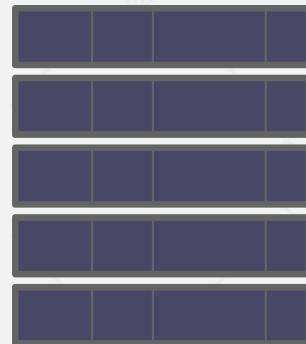


Table2



Partitions



Ideal Query:

```
SELECT * FROM table
```

VERTICAL PARTITIONING

Split a table's attributes into separate partitions.

Must store tuple information to reconstruct the original record.

```
CREATE TABLE foo (
    attr1 INT,
    attr2 INT,
    attr3 INT,
    attr4 TEXT
);
```

Partition #1

Tuple#1	attr1	attr2	attr3		attr4	Tuple#1
Tuple#2	attr1	attr2	attr3		attr4	Tuple#2
Tuple#3	attr1	attr2	attr3		attr4	Tuple#3
Tuple#4	attr1	attr2	attr3		attr4	Tuple#4

Partition #2

HORIZONTAL PARTITIONING

Split a table's tuples into disjoint subsets based on some partitioning key and scheme.

- Choose column(s) that divides the database equally in terms of size, load, or usage.

Partitioning Schemes:

- Hashing
- Ranges
- Predicates

HORIZONTAL PARTITIONING

Partitioning Key

Table1

101	a	XXX	2022-11-29
102	b	XXX	2022-11-28
103	c	XYZ	2022-11-29
104	d	XYX	2022-11-27
105	e	XYY	2022-11-29

Ideal Query:

```
SELECT * FROM table
WHERE partitionKey = ?
```

$$\text{hash}(a)\%4 = P2$$

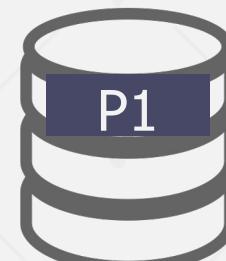
$$\text{hash}(b)\%4 = P4$$

$$\text{hash}(c)\%4 = P3$$

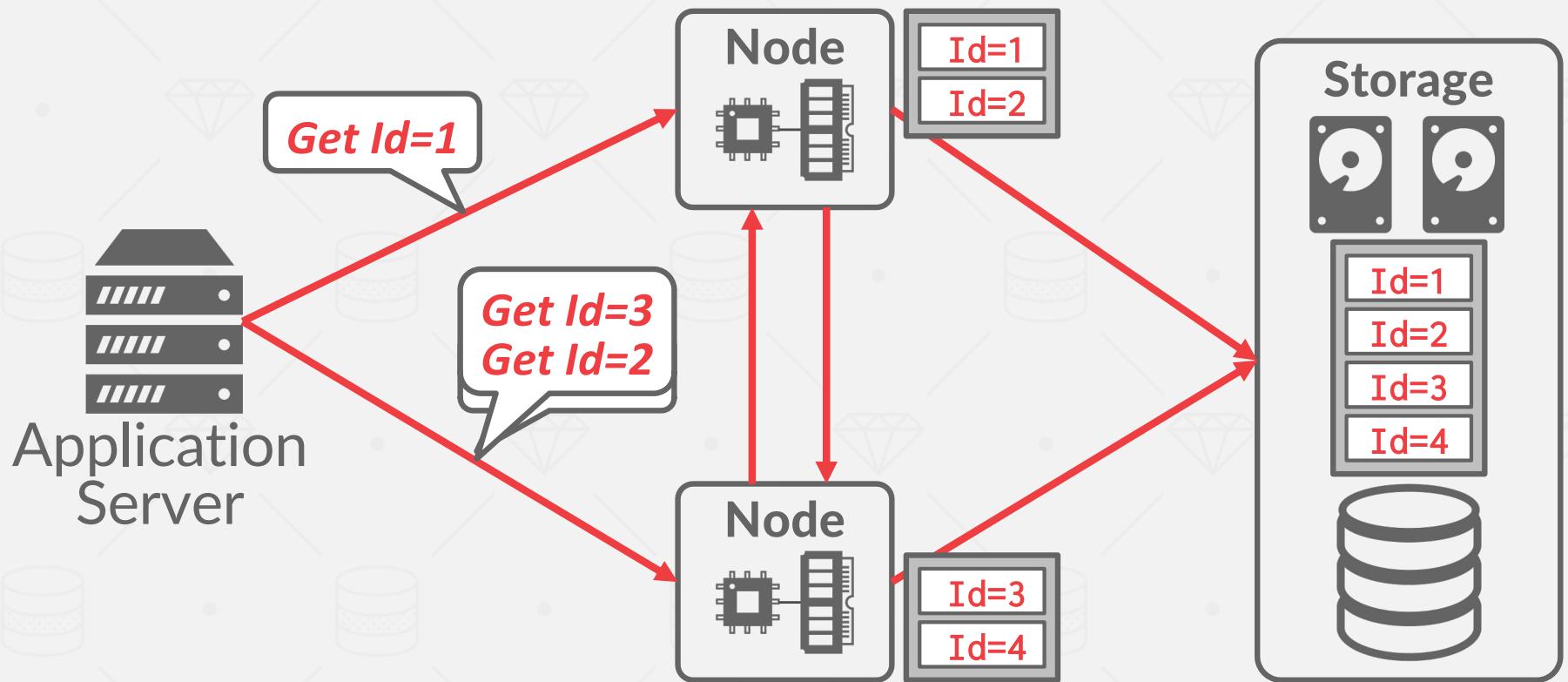
$$\text{hash}(d)\%4 = P2$$

$$\text{hash}(e)\%4 = P1$$

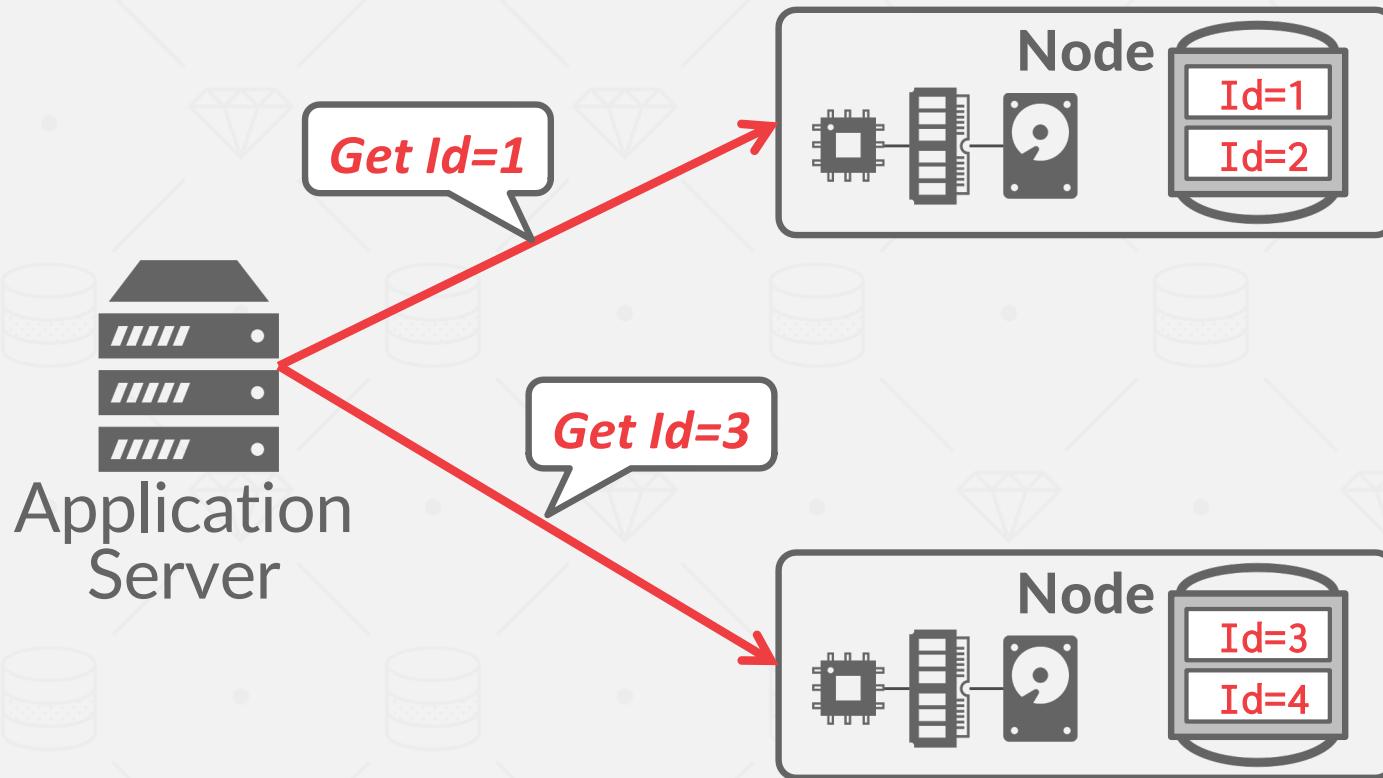
Partitions



LOGICAL PARTITIONING



PHYSICAL PARTITIONING



HORIZONTAL PARTITIONING

Partitioning Key

Table1

101	a	XXX	2022-11-29
102	b	XXY	2022-11-28
103	c	XYZ	2022-11-29
104	d	XYX	2022-11-27
105	e	XYY	2022-11-29

Ideal Query:

```
SELECT * FROM table
WHERE partitionKey = ?
```

$$\text{hash}(a) \% 4 = P2$$

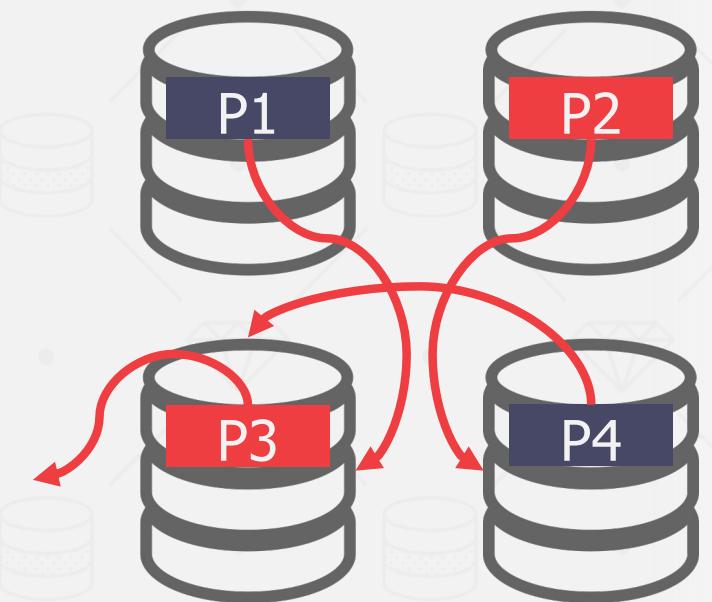
$$\text{hash}(b) \% 4 = P2$$

$$\text{hash}(c) \% 4 = P3$$

$$\text{hash}(d) \% 4 = P2$$

$$\text{hash}(e) \% 4 = P3$$

Partitions



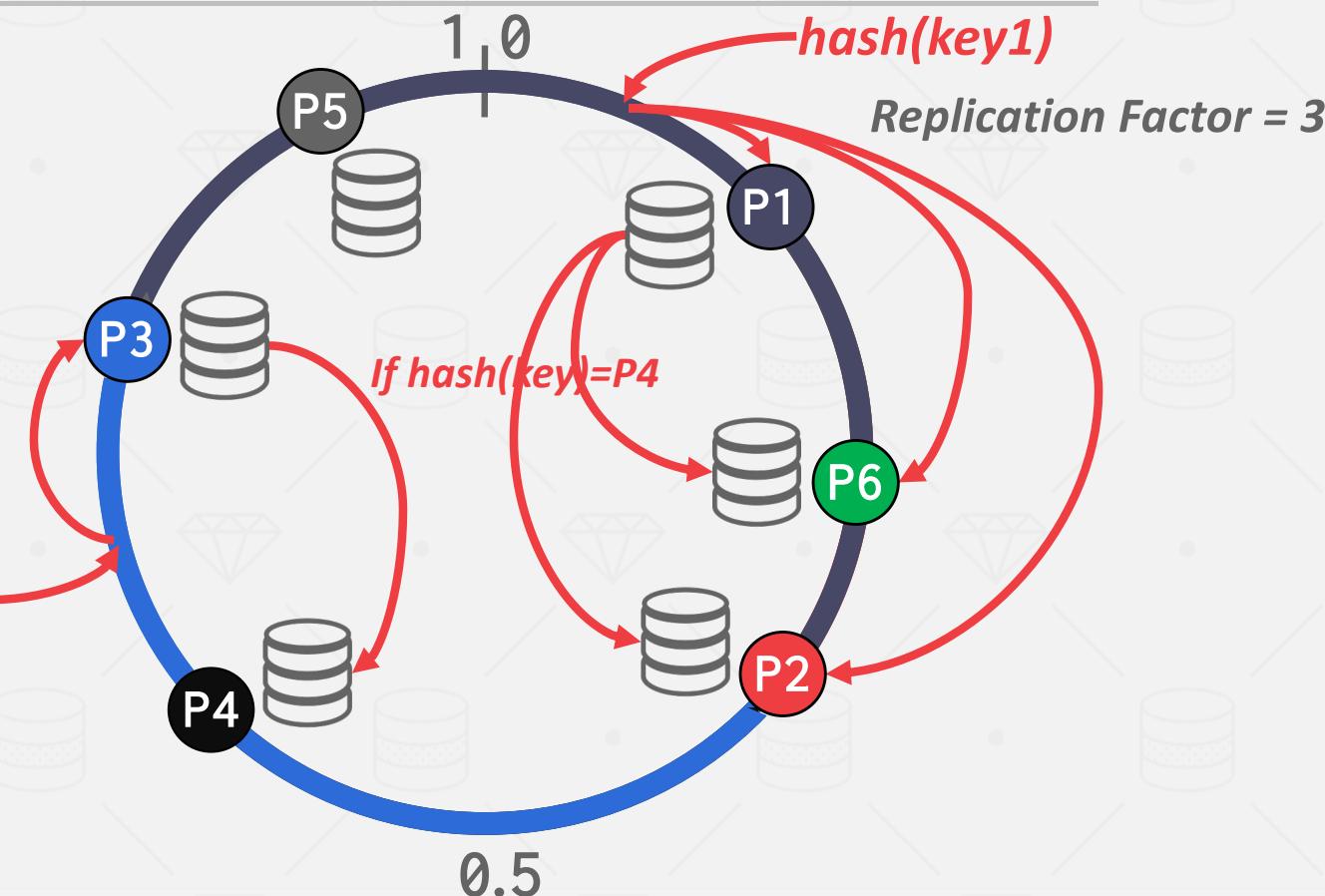
CONSISTENT HASHING



MEMCACHED

cassandra
hash(key2)

riak



SINGLE-NODE VS. DISTRIBUTED

A **single-node** txn only accesses data that is contained on one partition.

- The DBMS may not need check the behavior concurrent txns running on other nodes.

A **distributed** txn accesses data at one or more partitions.

- Requires expensive coordination.

TRANSACTION COORDINATION

If our DBMS supports multi-operation and distributed txns, we need a way to coordinate their execution in the system.

Two different approaches:

- **Centralized**: Global "traffic cop".
- **Decentralized**: Nodes organize themselves.

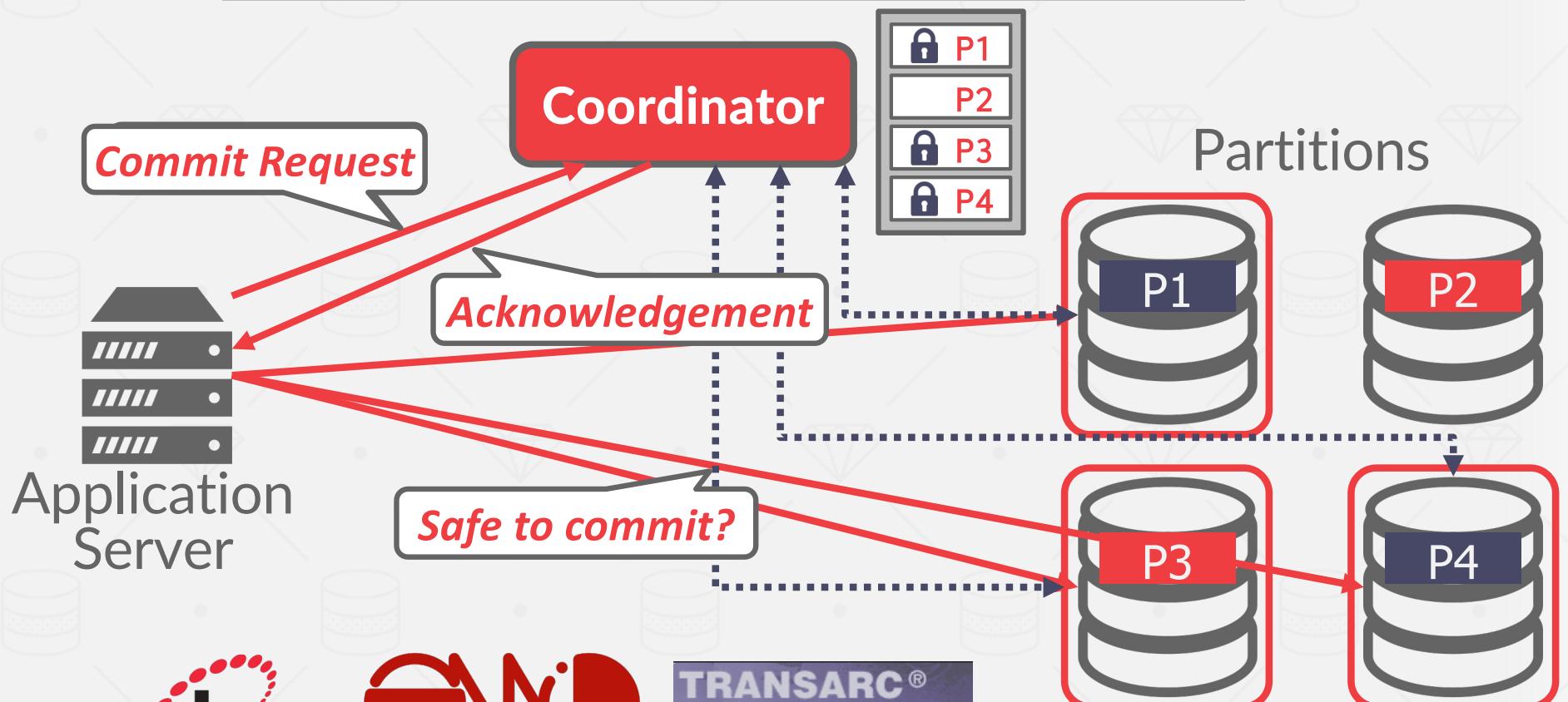
TP MONITORS

A **TP Monitor** is an example of a centralized coordinator for distributed DBMSs.

Originally developed in the 1970-80s to provide txns between terminals and mainframe databases.
→ Examples: ATMs, Airline Reservations.

Standardized protocol from 1990s: **X/Open XA**

CENTRALIZED COORDINATOR



CENTRALIZED COORDINATOR



mongoDB

planetscale

Application
Server

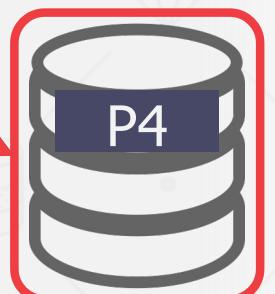
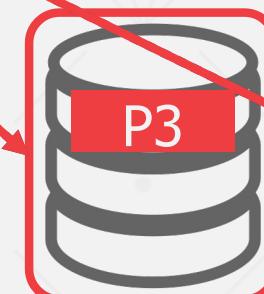
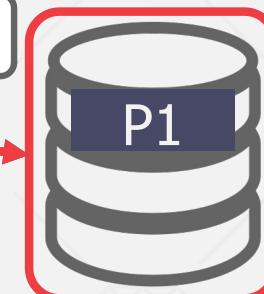
Commit Request

Middleware

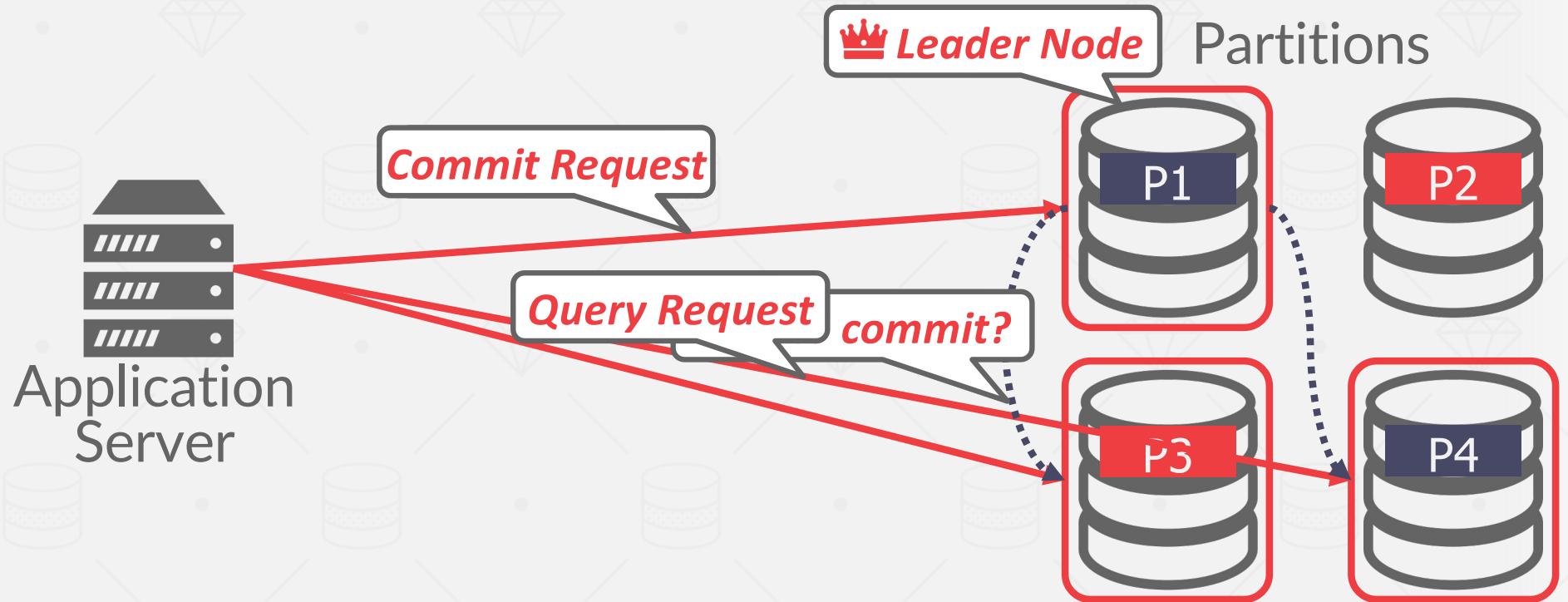
Safe to commit?

P1→ID:1-100	🔒
P2→ID:101-200	🔒
P3→ID:201-300	🔒
P4→ID:301-400	🔒

Partitions



DECENTRALIZED COORDINATOR



DISTRIBUTED CONCURRENCY CONTROL

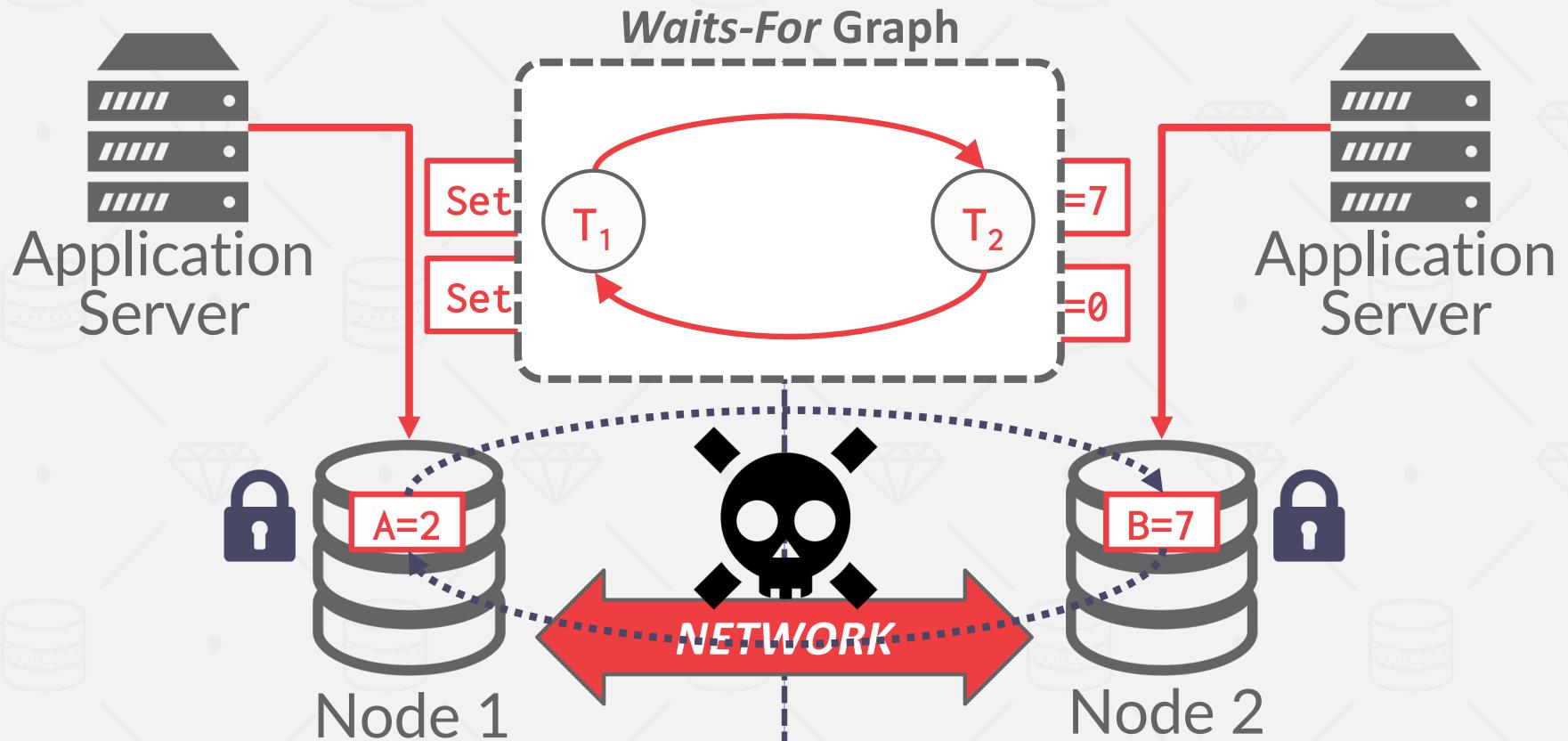
Need to allow multiple txns to execute simultaneously across multiple nodes.

→ Many of the same protocols from single-node DBMSs can be adapted.

This is harder because of:

- Replication.
- Network Communication Overhead.
- Node Failures.
- Clock Skew.

DISTRIBUTED 2PL



CONCLUSION

I have barely scratched the surface on distributed database systems...

It is **hard** to get this right.

PROJECT #4 – CONCURRENCY CONTROL

You will add support for concurrent transactions using two-phase locking in BusTub!

- Deadlock Detection
- Hierarchical Locking (Table, Tuple)
- Multiple Isolation Levels
- Aborts/Rollbacks

You do not need to worry about logging txns to disk.



Prompt: A dramatic and vibrant painting of a giant eye in the clouds looking down on a field of grazing sheep with padlocks as their heads.

<https://15445.courses.cs.cmu.edu/spring2023/project4/>

PROJECT #4 – TASKS

Lock Manager

- Maintain internal lock table and queues.
- Track the growing/shrinking phases of txns.
- Notify waiting txns when their locks are available.

Deadlock Detector:

- Build the waits-for graph and deterministically identify what txn to kill to break deadlocks

Execution Engine

- Modify Project #3 executors to support txn requests.

PROJECT #4 - LEADERBOARD

We have designed the Terrier benchmark to measure who has the fastest BusTub implementation.

Tasks:

- UpdateExecutor
- Predicate Pushdown

THINGS TO NOTE

Do not change any file other than the ones that you submit to Gradescope.

Make sure you pull in the latest changes from the BusTub main branch.

Post your questions on Piazza or come to TA office hours.

Compare against our [solution in your browser](#).

NEXT CLASS

Distributed OLTP Systems
Replication
CAP Theorem
Real-World Examples