## Counting Number of Inversions in an Array

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### Introduction

• The Inversion Count of an array  $\mathbf{A}$  is the count of all the pairs (i,j) such that i < j and  $\mathbf{A}[i] > \mathbf{A}[j]$ 

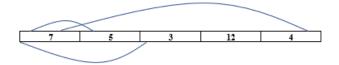


Figure: An example of inversion in array.

 Thus, Inversion Count for an array indicates – how far the array is from being sorted.

## Algorithm Description and Analysis

**Naive Approach** involves a Brute Force approach where we iterate over all the pairs of the array (which can be done through a nested loop), and if any pair (i,j) satisfies our condition, we increase our Inversion Count by one.

#### Divide and Conquer Approach

Suppose we divide our array A into two equal, or almost equal parts. Let's call the first one L and the other one R. Also, let's say we know the Inversion Count of both L and R. Let's call them  $inv_1$  and  $inv_2$ .

Now, any inversion in **A** would be of type:

- $0 i \in L \text{ and } j \in R.$
- $0 i \in L$  and  $j \in L$ .
- $i \in R$  and  $j \in R$ .

## Algorithm - Divide and Conquer

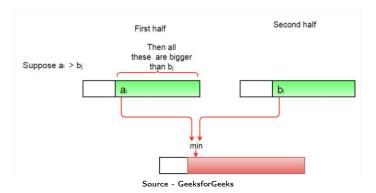
#### For Case 1

- The total inversions upon combining will be at least
   inv<sub>1</sub> + inv<sub>2</sub>. But there may be some more inversions, as we
   merge L and R. So we need to find for each index i ∈ L, the
   number of indices j ∈ R such that L<sub>i</sub> > R<sub>i</sub>.
- Let's say that we have sorted the arrays L and R. and their sizes are N and M respectively.

## Algorithm - Divide and Conquer

### Case 1(contd.)

Say, at certain point we encounter L[I] > R[r].
 Now, because L and R are sorted, we know that there are going to be N-i more inversions in A, because all elements to the right of L[I] will also be greater than R[r].



## Algorithm - Divide and Conquer

#### For Cases 2 and 3

• Now for the second and the third case: If we encounter that situation, we again divide them up into further two arrays and repeat this recursively, until we have arrived on the base case that includes just one element. And in this case, we know the inversions will be 0, because there is just a single element in the array.

#### Note

Here, one more important thing is that in the first case, we require the arrays  ${\bf L}$  and  ${\bf R}$  to be sorted. So we need to incorporate that when we merge two arrays

### Pseudo Code

#### mergeTwoArrays

```
i, k = beg
i = end
newarr
  while i < mid \text{ AND } j \leq end \text{ do}
      if arr[i] < arr[j] then
         newarr[k]=arr[i]
         increment k.i
     else
         newarr[k]=arr[j]
         invCount+= mid - i
         increment k,i
     end if
  end while
  while i < mid do
      temp[k] = arr[i]
     increment k.i
  end while
  while i < end do
     temp[k] = arr[i]
      increment k,i
  end whileit = beg
  while it < end do
      arr[it] = newarr[it]
      increment it
  end while
```

return invCount

#### enhancedMergeSort

```
arr: The Array
beg: Start iterator
end: End iterator
mid, invCount = 0

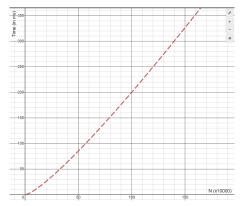
if end > beg then
mid = (beg+end)/2
invCount +=
enhancedMergeSort(arr,left,mid)
invCount +=
enhancedMergeSort(arr,mid+1,right)
invCount += mergeTwoArrays(arr,left,mid+1,right)
end if
return invCount
```

## **Time Complexity**

In the **Divide and Conquer** algorithm , the input array is divided into two halves each time it is processed. As such it can be expressed with following recurrence relation,

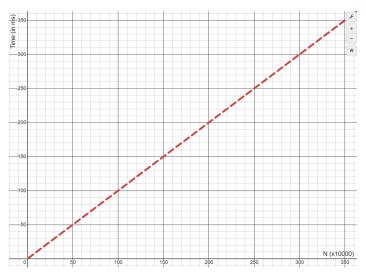
$$T(n) = 2T(n/2) + \theta(n).$$

 $O(N \log(N))$ 



# Space Complexity

O(N)



### References

- Introduction to Algorithms by Thomas H. Cormen, Charles E. Leiserson, Ronald Rivest, Clifford Stein
- Introduction to Design and Analysis of Algorithms by Anany Levitin
- Algorithms by Robert Sedgewick and Kevin Wayne