# Lesson 3 Dynamical Systems

3-6: The Ergodic Theorem

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#### From Recurrence to Averages

 $(X, \mathcal{B}, \mu)$  probability space,  $T: X \to X \mu$ -preserving.

Poincaré recurrence: For every measurable  $E \subseteq X$  with  $\mu(E) > 0$ , almost every point in E returns to E infinitely often.

Question: Can we say something about how often a point returns on average?

- ightharpoonup Assume  $X = A^{\mathbb{N}}$ , A finite, T shift mapping,  $E = [\sigma]$ .
- For a sequence x to return to E then means that σ occurs as a substring in x.
- ightharpoonup The average number of returns to  $[\sigma]$  by time n is then given as

▶ Q: Does this average converge? To  $\mu[\sigma]$ ?

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→ Ergodic Theorem

#### The Ergodic Theorem

T measure-preserving transformation on probability space  $(X, \mathcal{B}, \mu)$ .

▶ If f is a  $\mu$ -integrable function on X, then the average

$$\frac{1}{n}\sum_{i=0}^{n-1}f(T^{i}(x))$$

converges for  $\mu$ -almost every  $x \in X$ .

- ▶ If we denote the limit by  $f^*(x)$ , then  $f^*$  is integrable  $(L^1(\mu))$  and  $\int f d\mu = \int f^* d\mu$ . Furthermore,  $f^*$  is T-invariant, i.e.  $f^* \circ T = f^*$ .
- Finally, if T is ergodic, then  $f^*$  is constant  $\mu$ -a.e. and hence  $f^*(x) = \int f d\mu$ , which means

$$\frac{1}{n}\sum_{i=0}^{n-1}f(\underline{T}^{i}(x))\overset{n\to\infty}{\longrightarrow}\int fd\mu.$$



#### Example - Law of Large Numbers

- Let  $(X_n)$  be a binary Bernoulli process with P(1) = p, P(0) = 1 p.
- ▶  $\mu_p$  Kolmogorov measure on  $2^{\mathbb{N}}$ , i.e.  $\mu_p[1] = p$ ,  $\mu_p[0] = 1 p$ .  $\mu_p$  is invariant under shift map T.
- ▶ Let  $f = \chi_{[1]}$ . We have  $f(T^ix) = 1$  iff  $T^ix \in [1]$  iff  $x_i = 1$ .
- ▶ By the ergodic theorem, for  $\mu_p$ -almost every  $x \in 2^{\mathbb{N}}$ ,

$$\lim_{n} \frac{1}{n} \sum_{i=0}^{n-1} \chi_{[1]}(T^{i}x) = \lim_{n} \frac{|\{i < n : x_{i} = 1\}|}{n} \longrightarrow \int \chi_{[1]} d\mu_{p}$$

$$= \lim_{n} \frac{x_{0} + x_{1} + \dots + x_{n-1}}{n} = \mu_{p}[1] = p.$$

Therefore, the ergodic theorem can be seen as an extension of penn State the strong law of large numbers to arbitrary stationary processes.

#### Proving the Ergodic Theorem (I)

It suffices to consider real-valued  $f \in L^1(\mu)$ . Put

$$f^*(x) = \limsup_{n} \frac{1}{n} \sum_{i=0}^{n-1} f(T^i x)$$
 and  $f_*(x) = \liminf_{n} \frac{1}{n} \sum_{i=0}^{n-1} f(T^i x)$ .

We want to show:  $f^*(x) = f_*(x) \mu$ -almost everywhere.

For real r < s, let

$$E_{r,s} = \{ \underline{x \in X} : f_*(x) < r \text{ and } f^*(x) > s \}.$$

We have

$$\{x: f_*(x) < f^*(x)\} = \bigcup_{r < s \in \mathbb{Q}} E_{r,s}.$$

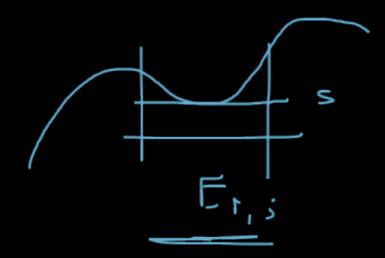
Hence it suffices to show  $\mu(E_{r,s}) = 0$ .



## Proving the Ergodic Theorem (II)

Idea: Show that

$$\int_{E_{r,s}} \underline{f} d\mu \geqslant s\mu(E_{r,s}),$$



and at the same time

$$\int_{E_{r,s}} f d\mu \leqslant r\mu(E_{r,s}).$$

If r < s, this forces  $\mu(E_{r,s}) = 0$ .

This follows from the maximal ergodic theorem.





#### Maximal Ergodic Theorem

THM: Let T be a measure-preserving transformation on a probability space  $(X, \mathcal{B}, \mu)$ , and  $f \in L^1(\mu)$ . Define

$$f^*(x) = \limsup_{n} \frac{1}{n} \sum_{i=0}^{n-1} f(T^i x).$$

Then, for any  $\lambda \in \mathbb{R}$ 

$$\int_{\{f^*>\lambda\}} f d\mu \geqslant \lambda \mu \{f^*>\lambda\}.$$



Suppose T is the shift on  $2^{\mathbb{N}}$  and  $\mu$  is shift-invariant and ergodic.

Let's try to give a more ``direct'' proof that almost surely,

$$\lim_{n} \frac{1}{n} \sum_{i=0}^{n-1} x_{i} = \mu[1].$$

Suppose the statement is false, then wlog for some  $\varepsilon > 0$ , the set

$$E = \{x: \limsup_{n} \frac{1}{n} \sum_{i=0}^{n-1} x_i \geqslant \mu[1] + \varepsilon\}$$

has positive measure  $\mu(E) > 0$ .

 $\overline{\it E}$  is  $\it T$ -invariant ( $\it TE \subseteq \it E$ ), so by ergodicity  $\it \mu(\it E)=$  1.

So almost every  $x \in 2^{\mathbb{N}}$  has a long stretch of ``too many" 1's infinitely often.



On the other hand, at any finite point in time, the expected value of  $\sum_{i < n} x_i / n$  must be  $\mu[1]$ , since

$$\mu[1] = \int \chi_{[1]}(x) d\mu(x) = \int (\chi_{[1]} \circ T)(x) d\mu(x)$$

$$= \int \frac{1}{n} \sum_{i=0}^{n-1} \chi_{[1]}(T^{i}x) d\mu(x) = \int \frac{\sum_{i < n} \chi_{i}}{n} d\mu(x)$$
(\*)

Idea: Find a long interval that contains many short intervals in which the number of 1's is too large for (\*) to hold.



Assume  $x \in E$ . Since  $TE \subseteq E$ , for every n there exists a minimal  $s(n) = s_x(n)$  for which

$$\frac{x_n+x_{n+1}+\cdots+x_{s(n)-1}}{s(n)-n}\geqslant \mu[1]+\varepsilon.$$

Only a certain fraction of x has a large  $s_x(0)$ : Given  $\delta > 0$ , there exists L such that

$$\mu(D) \leqslant \delta^2$$
, where  $D = \{x: s_x(0) > L\}$ .

Hence if we give up a little bit of measure, we can work with sequences that obtain an  $\varepsilon$ -excess of 1's by a fixed time L.



Furthermore, not many orbits will visit D very often: Let  $g_N(x)$  be the average number of visits of  $T^ix$  to D by time N,

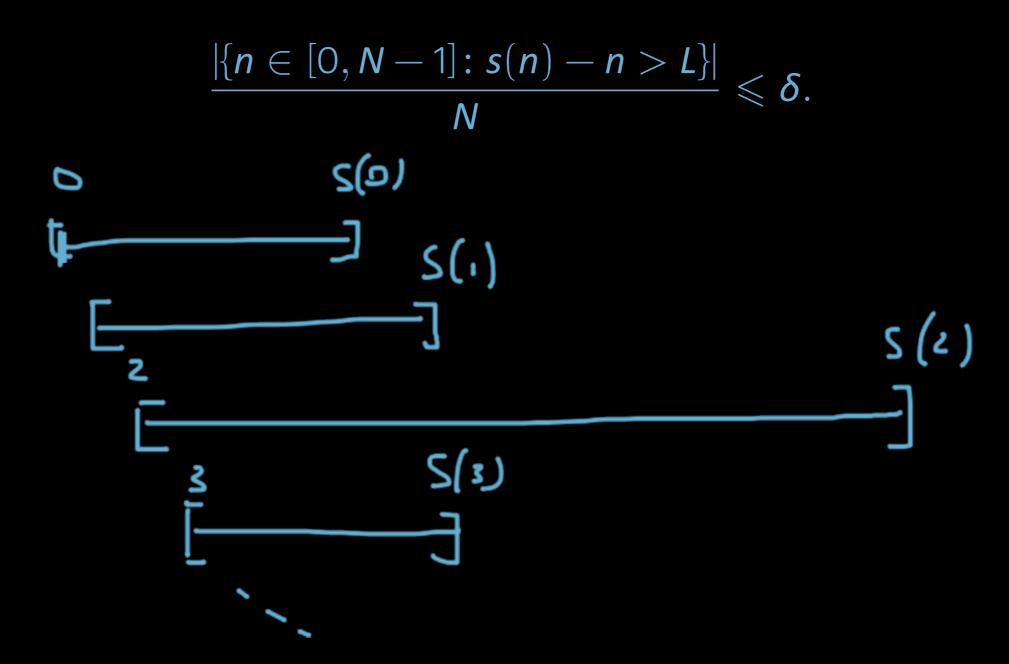
$$g_N(x) = \frac{1}{N} \sum_{i=0}^{N-1} \chi_D(T^i x).$$

T measure preserving implies  $\int g_N d\mu \leqslant \delta^2$ . Then Markov's inequality yields

$$\mu(G_N) \geqslant 1 - \delta$$
, where  $G_N = \{x : g_N(x) \leqslant \delta\}$ .

 $\mu \neq x : g_N \neq \delta \neq 1 - g_N \neq 1 - g$ 

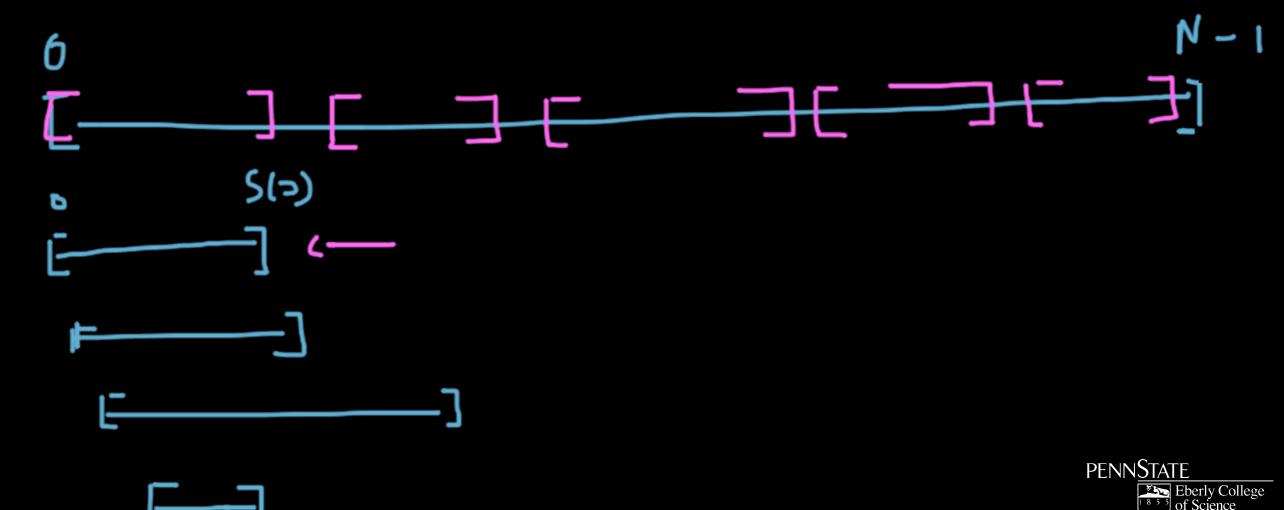
For  $x \in G_N$ , the portion of long intervals with starting point in [0, N-1] is not more than  $\delta$ :



#### The Packing Lemma

LEMMA: Suppose  $x \in G_N$ . There exists a sequence  $n_1 < n_2 < n_3 < \cdots < n_k$  of natural numbers such that

- (1) the intervals  $[n_i, s_x(n_i)]$  are disjoint,
- (2)  $[n_i, s_x(n_i)] \subseteq [0, N-1]$  for all  $i \leqslant k$ ,
- (3)  $|\bigcup_{i}[n_{i},s_{x}(n_{i})]| \geqslant (1-2\delta)N$ .



The Lemma allows us to bound the number of 1's in [0, N - 1] from below:

$$\sum_{j=0}^{N-1} x_j \geqslant \sum_{i=1}^k \sum_{j=n_i}^{s(n_i)} x_j \geqslant (1-2\delta)N(\mu[1]+\epsilon).$$

Note that this bound is independent of x (though the sequence of  $n_i$ 's does depend on x), as long as  $x \in G_N$ . Hence we can bound the integral

$$\int \sum_{j=0}^{N-1} x_j \geqslant (1-2\delta) \mathcal{N}(\mu[1]+\varepsilon) \mu(G_N).$$

Thus,

$$\underline{\mu[1]} = \int \frac{\sum_{i < N} x_i}{N} d\mu(x) \geqslant (1 - 2\delta)(1 - \delta)(\underline{\mu[1]} + \varepsilon),$$

which is impossible, since  $\delta$  can be chosen arbitrarily small.

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[Source: Shields, *The ergodic theory of discrete sample paths*]