

The Diagonal Lemma

In the following, we consider the **diagonal function** d , defined by

$$d(n) = \begin{cases} {}^\frown \forall y (y = \underline{n} \rightarrow \sigma(y))^\frown & \text{if } n = {}^\frown \sigma(v_0)^\frown \text{ for an } L\text{-formula } \sigma(v_0) \\ 0 & \text{otherwise.} \end{cases}$$

Lemma 0.1.

Let T be an L -theory, $\theta(v_0)$ an L -formula with the single free variable v_0 . If the diagonal function d is representable in T , then there exists an L -sentence G with the property

$$T \vdash G \leftrightarrow \theta({}^\frown \underline{G}^\frown).$$

If $\theta(v_0)$ is a Π_1 -formula, then G can also be chosen as a Π_1 -sentence.

Proof. If d is represented in T by the formula $\delta(x, y)$, then define

$$\psi(v_0) := \forall y (\delta(v_0, y) \rightarrow \theta(y)),$$

and set $n := {}^\frown \psi(v_0)^\frown$.

Note: n is actually a number in which the variable v_0 does not occur; however, the Gödel number of v_0 does enter into the calculation of n .

For G , we now choose the sentence

$$G := \forall y (y = \underline{n} \rightarrow \psi(y)).$$

Then G has Gödel number $d({}^\frown \psi(v_0)^\frown)$. If $\delta(x, y)$ is a Σ_1 -formula and $\theta(v)$ is a Π_1 -formula, then ψ and G are (equivalent to) Π_1 -formulas. Thus it remains to show that $T \vdash G \leftrightarrow \theta({}^\frown \underline{G}^\frown)$:

It is clear that

$$(1) \quad T \vdash G \leftrightarrow \psi(\underline{n}), \quad \text{i.e., by the definition of } \psi$$

$$(1) \quad T \vdash G \leftrightarrow \forall y (\delta(\underline{n}, y) \rightarrow \theta(y)).$$

But the fact that d is represented in T by $\delta(x, y)$ means

$$d(n) = {}^\frown \underline{G}^\frown \Rightarrow T \vdash \delta(\underline{n}, {}^\frown \underline{G}^\frown) \quad \text{and} \quad T \vdash \exists ! y \delta(\underline{n}, y).$$

Thus in particular

- (2) $T \vdash \forall y (\delta(\underline{n}, y) \leftrightarrow y = \underline{^r G})$ and together with (1) it follows
 $T \vdash G \leftrightarrow \forall y (y = \underline{^r G} \rightarrow \theta(y)),$ hence
 $T \vdash G \leftrightarrow \theta(\underline{^r G}).$

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