

# §4 分块矩阵

- 一. 矩阵的分块
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# 一. 矩阵的分块

例如,  $A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} & a_{15} \\ a_{21} & a_{22} & a_{23} & a_{24} & a_{25} \\ a_{31} & a_{32} & a_{33} & a_{34} & a_{35} \\ a_{41} & a_{42} & a_{43} & a_{44} & a_{45} \end{pmatrix} \stackrel{\text{记}}{=} \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}$

$A_{ij}$  称为  $A$  的子块

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} & a_{15} \\ a_{21} & a_{22} & a_{23} & a_{24} & a_{25} \\ a_{31} & a_{32} & a_{33} & a_{34} & a_{35} \\ a_{41} & a_{42} & a_{43} & a_{44} & a_{45} \end{pmatrix} \stackrel{\text{记}}{=} (A_1 \ A_2 \ A_3 \ A_4 \ A_5) \quad A_i \text{ 称为 } A \text{ 的子块}$$

以子块为元素的矩阵称为**分块矩阵**.

## 二. 分块矩阵的运算法则

(1) 加法.  $A = \begin{pmatrix} A_{11} & \cdots & A_{1r} \\ \vdots & & \vdots \\ A_{s1} & \cdots & A_{sr} \end{pmatrix}, B = \begin{pmatrix} B_{11} & \cdots & B_{1r} \\ \vdots & & \vdots \\ B_{s1} & \cdots & B_{sr} \end{pmatrix}$

子块  $A_{ij}$  与  $B_{ij}$  有相同的行列数

则  $A + B = \begin{pmatrix} A_{11} + B_{11} & \cdots & A_{1r} + B_{1r} \\ \vdots & & \vdots \\ A_{s1} + B_{s1} & \cdots & A_{sr} + B_{sr} \end{pmatrix}$

(2) 数乘.  $A$  同上,  $\lambda$  为数, 则

$$\lambda A = \begin{pmatrix} \lambda A_{11} & \cdots & \lambda A_{1r} \\ \vdots & & \vdots \\ \lambda A_{s1} & \cdots & \lambda A_{sr} \end{pmatrix}$$

### (3) 矩阵乘法

将  $A_{m \times l}, B_{l \times n}$  按如下形式分块：

$$A = \begin{pmatrix} A_{11} & \cdots & A_{1t} \\ \vdots & & \vdots \\ A_{s1} & \cdots & A_{st} \end{pmatrix}, \quad B = \begin{pmatrix} B_{11} & \cdots & B_{1r} \\ \vdots & & \vdots \\ B_{t1} & \cdots & B_{tr} \end{pmatrix}$$

$A_{i1}, \cdots, A_{it}$  的列数分别等于  $B_{1j}, \cdots, B_{tj}$  的行数

则 
$$AB = \begin{pmatrix} C_{11} & \cdots & C_{1r} \\ \vdots & & \vdots \\ C_{s1} & \cdots & C_{sr} \end{pmatrix}$$

其中 
$$C_{ij} = \sum_{k=1}^t A_{ik} B_{kj} \quad (i = 1, \cdots, s; j = 1, \cdots, r)$$

**例1. 设**  $A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 2 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix}, B = \begin{pmatrix} 1 & 0 & 1 & 0 \\ -1 & 2 & 0 & 1 \\ 1 & 0 & 4 & 1 \\ -1 & -1 & 2 & 0 \end{pmatrix}$ , **求**  $AB, A^3$ .

(P48例 17)

**解: 将**  $A, B$  **分块,**

$$A = \begin{pmatrix} E & O \\ A_1 & E \end{pmatrix}, \quad B = \begin{pmatrix} B_{11} & E \\ B_{21} & B_{22} \end{pmatrix},$$

**其中**

$$A_1 = \begin{pmatrix} -1 & 2 \\ 1 & 1 \end{pmatrix}, \quad B_{11} = \begin{pmatrix} 1 & 0 \\ -1 & 2 \end{pmatrix}, \quad B_{21} = \begin{pmatrix} 1 & 0 \\ -1 & -1 \end{pmatrix}, \quad B_{22} = \begin{pmatrix} 4 & 1 \\ 2 & 0 \end{pmatrix}$$

$$AB = \begin{pmatrix} B_{11} & E \\ A_1 B_{11} + B_{21} & A_1 + B_{22} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 & 0 \\ -1 & 2 & 0 & 1 \\ -2 & 4 & 3 & 3 \\ -1 & 1 & 3 & 1 \end{pmatrix}$$

$$A^2 = \begin{pmatrix} E & O \\ A_1 & E \end{pmatrix} \begin{pmatrix} E & O \\ A_1 & E \end{pmatrix} = \begin{pmatrix} E & O \\ 2A_1 & E \end{pmatrix}$$

$$A^3 = A^2 A = \begin{pmatrix} E & O \\ 2A_1 & E \end{pmatrix} \begin{pmatrix} E & O \\ A_1 & E \end{pmatrix} = \begin{pmatrix} E & O \\ 3A_1 & E \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -3 & 6 & 1 & 0 \\ 3 & 3 & 0 & 1 \end{pmatrix}$$

问:  $A^n = ?$

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 2 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix}$$

其中  $A_1 = \begin{pmatrix} -1 & 2 \\ 1 & 1 \end{pmatrix}$



(4) 转置  $A^T = \begin{pmatrix} A_{11} & \cdots & A_{1r} \\ \vdots & & \vdots \\ A_{s1} & \cdots & A_{sr} \end{pmatrix}^T = \begin{pmatrix} A_{11}^T & \cdots & A_{s1}^T \\ \vdots & & \vdots \\ A_{1r}^T & \cdots & A_{sr}^T \end{pmatrix}$

(5) 分块对角阵  $A = \begin{pmatrix} A_1 & & \\ & A_2 & \\ & & \ddots \\ & & & A_r \end{pmatrix}$ ,  $A_k$  均为方阵

性质: ①  $|A| = |A_1| |A_2| \cdots |A_r|$

②  $|A_i| \neq 0 (i = 1, \cdots, r) \longrightarrow A \text{ 可逆, 且}$

$$A^{-1} = \begin{pmatrix} A_1^{-1} & & \\ & A_2^{-1} & \\ & & \ddots \\ & & & A_r^{-1} \end{pmatrix}$$

$$\begin{pmatrix} & & A_1 \\ & \ddots & \\ A_r & & \end{pmatrix}^{-1} = \begin{pmatrix} & & A_r^{-1} \\ & \ddots & \\ A_1^{-1} & & \end{pmatrix}$$



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**例2.**  $A = \begin{pmatrix} \underline{5} & \underline{0} & \underline{0} \\ 0 & 3 & 1 \\ 0 & 2 & 1 \end{pmatrix}$ , 求  $A^{-1}$  (P49 例 18)

**解:**  $A = \begin{pmatrix} A_1 & \\ & A_2 \end{pmatrix}$

$$A_1 = (5), \quad A_1^{-1} = \frac{1}{5}$$

$$A_2 = \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix}, \quad A_2^{-1} = \frac{1}{|A_2|} \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ -2 & 3 \end{pmatrix}$$

$$\therefore A^{-1} = \begin{pmatrix} A_1^{-1} & & \\ & A_2^{-1} & \\ & & \end{pmatrix} = \begin{pmatrix} \frac{1}{5} & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -2 & 3 \end{pmatrix}$$

### 三. 两种重要的分块法

约定: 列向量表为  $\vec{\alpha}, \vec{\beta}, \vec{x}, \vec{a}, \dots$

行向量表为  $\vec{\alpha}^T, \vec{\beta}^T, \vec{x}^T, \vec{a}^T, \dots$

#### (1) 按行分块

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & \cdots & a_{1n} \\ \hline a_{21} & a_{22} & \cdots & \cdots & a_{2n} \\ \hline \vdots & \vdots & & & \vdots \\ \hline a_{m1} & a_{m2} & \cdots & \cdots & a_{mn} \end{pmatrix} = \begin{pmatrix} \vec{\alpha}_1^T \\ \vec{\alpha}_2^T \\ \vdots \\ \vec{\alpha}_m^T \end{pmatrix}$$

记  $\vec{\alpha}_i^T = (a_{i1}, a_{i2}, \dots, a_{in})$

$$(1) \text{ 按行分块 } A = \begin{pmatrix} \vec{\alpha}_1^T \\ \vec{\alpha}_2^T \\ \vdots \\ \vec{\alpha}_m^T \end{pmatrix}$$

## (2) 按列分块

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & \cdots & a_{2n} \\ \vdots & \vdots & & & \vdots \\ a_{m1} & a_{m2} & \cdots & \cdots & a_{mn} \end{pmatrix} = (\vec{\beta}_1, \vec{\beta}_2, \cdots, \vec{\beta}_n)$$

$$\text{记 } \vec{\beta}_j = \begin{pmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{mj} \end{pmatrix}$$

## • 矩阵乘法的向量表示

$$AB = \begin{pmatrix} \vec{a}_1^T \\ \vec{a}_2^T \\ \vdots \\ \vec{a}_m^T \end{pmatrix} (\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n) = \begin{pmatrix} \vec{a}_1^T \vec{b}_1 & \vec{a}_1^T \vec{b}_2 & \cdots & \vec{a}_1^T \vec{b}_n \\ \vec{a}_2^T \vec{b}_1 & \vec{a}_2^T \vec{b}_2 & \cdots & \vec{a}_2^T \vec{b}_n \\ \vdots & \vdots & \ddots & \vdots \\ \vec{a}_m^T \vec{b}_1 & \vec{a}_m^T \vec{b}_2 & \cdots & \vec{a}_m^T \vec{b}_n \end{pmatrix}$$
$$= (c_{ij})_{m \times n}$$

$$c_{ij} = \vec{a}_i^T \vec{b}_j = (a_{i1}, a_{i2}, \dots, a_{in}) \begin{pmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{mj} \end{pmatrix}$$
$$= \sum_{k=1}^n a_{ik} b_{kj}$$

## • 矩阵与对角阵之积的特点

$\Lambda_m = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_m)$  左乘  $A_{m \times n}$

$$\Lambda_m A_{m \times n} = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_m \end{pmatrix} \begin{pmatrix} \vec{a}_1^T \\ \vec{a}_2^T \\ \vdots \\ \vec{a}_m^T \end{pmatrix} = \begin{pmatrix} \lambda_1 \vec{a}_1^T \\ \lambda_2 \vec{a}_2^T \\ \vdots \\ \lambda_m \vec{a}_m^T \end{pmatrix}$$

$\Lambda_n = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$  右乘  $A_{m \times n}$

$$A_{m \times n} \Lambda_n = (\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n) \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix} \\ = (\lambda_1 \vec{a}_1, \lambda_2 \vec{a}_2, \dots, \lambda_n \vec{a}_n)$$

**例3.** 设  $A^T A = O$ , 证明  $A = O$ .

**证:** 设  $A = (a_{ij})_{m \times n}$ , 按列分块:  $A = (\vec{a}_1, \vec{a}_2, \cdots, \vec{a}_n)$

$$A^T A = \begin{pmatrix} \vec{a}_1^T \\ \vec{a}_2^T \\ \vdots \\ \vec{a}_n^T \end{pmatrix} (\vec{a}_1, \vec{a}_2, \cdots, \vec{a}_n) = \begin{pmatrix} \vec{a}_1^T \vec{a}_1 & \vec{a}_1^T \vec{a}_2 & \cdots & \vec{a}_1^T \vec{a}_n \\ \vec{a}_2^T \vec{a}_1 & \vec{a}_2^T \vec{a}_2 & \cdots & \vec{a}_2^T \vec{a}_n \\ \vdots & \vdots & \ddots & \vdots \\ \vec{a}_n^T \vec{a}_1 & \vec{a}_n^T \vec{a}_2 & \cdots & \vec{a}_n^T \vec{a}_n \end{pmatrix}$$

$\because A^T A = O$ , 所以对角元均为 0, 即

$$a_j^T \vec{a}_j = (a_{1j}, a_{2j}, \cdots, a_{mj}) \begin{pmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{mj} \end{pmatrix} = \sum_{k=1}^m a_{kj}^2 = 0 \quad (j = 1, \cdots, n)$$

$$\therefore a_{kj} = 0 \quad (k = 1, \cdots, m; j = 1, \cdots, n)$$

## 四. 线性方程组的几种表示法

[illegible]

记  $A = \begin{pmatrix} a_{11} & a_{12} & \cdots & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & \cdots & a_{2n} \\ \vdots & \vdots & & & \vdots \\ a_{m1} & a_{m2} & \cdots & \cdots & a_{mn} \end{pmatrix}, \quad \vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ \vdots \\ x_n \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ \vdots \\ b_m \end{pmatrix}$

$$B = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{12} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{pmatrix}$$

$A$  称为系数矩阵,  
 $B$  称为增广矩阵.

$$\mathbf{B} = (\mathbf{A}:\vec{\mathbf{b}}) = (\mathbf{A}, \vec{\mathbf{b}}) = (\vec{\mathbf{a}}_1, \vec{\mathbf{a}}_2, \cdots, \vec{\mathbf{a}}_n, \vec{\mathbf{b}})$$

表示法1.  $A\vec{x} = \vec{b}$

表示法2. 
$$\begin{pmatrix} \vec{\alpha}_1^T \\ \vec{\alpha}_2^T \\ \vdots \\ \vec{\alpha}_m^T \end{pmatrix} \vec{x} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

相当于

$$\vec{\alpha}_i^T \vec{x} = b_i \\ (i = 1, 2, \dots, m)$$

表示法3. 
$$(\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \vec{b}$$

即 
$$x_1 \vec{a}_1 + x_2 \vec{a}_2 + \dots + x_n \vec{a}_n = \vec{b}$$





## 五. 克拉默法则的证明

## 克拉默法则：

[illegible]

**若其系数行列式  $D \neq 0$ , 则它有唯一解:**

$$x_j = \frac{D_j}{D} \quad (j = 1, 2, \dots, n)$$

$$D_j = \begin{vmatrix} a_{11} & \cdots & \mathbf{b_1} & \cdots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ a_{n1} & \cdots & \mathbf{b_n} & \cdots & a_{nn} \end{vmatrix}$$

**证:** 将 (1) 写成  $A\vec{x} = \vec{b}$

**因  $D \neq 0$ , 所以  $A$  可逆, 故得**

$$\vec{x} = A^{-1} \vec{b} = \frac{1}{|A|} A^* \vec{b} = \frac{1}{D} A^* \vec{b}$$

即

$$\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \frac{1}{D} \begin{pmatrix} A_{11} & A_{21} & \cdots & A_{n1} \\ A_{12} & A_{22} & \cdots & A_{n2} \\ \vdots & \vdots & & \vdots \\ A_{1n} & A_{2n} & \cdots & A_{nn} \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

故

$$x_j = \frac{1}{D} (b_1 A_{1j} + b_2 A_{2j} + \cdots + b_n A_{nj})$$

$$= \frac{D_j}{D} \quad (j = 1, 2, \cdots, n)$$

## 矩阵分块在行列式计算中的应用举例

设有3阶方阵  $A = (\vec{\alpha}, \vec{\beta}_1, \vec{\beta}_2)$ ,  $B = (\vec{\beta}, \vec{\beta}_1, \vec{\beta}_2)$ , 若  $|A| = 2$ ,  $|B| = \frac{1}{2}$ , 求  $|A + B|$ .

**解:**

$$\begin{aligned}|A + B| &= |\vec{\alpha} + \vec{\beta}, 2\vec{\beta}_1, 2\vec{\beta}_2| \\&= |\vec{\alpha}, 2\vec{\beta}_1, 2\vec{\beta}_2| + |\vec{\beta}, 2\vec{\beta}_1, 2\vec{\beta}_2| \\&= 2^2 |\vec{\alpha}, \vec{\beta}_1, \vec{\beta}_2| + 2^2 |\vec{\beta}, \vec{\beta}_1, \vec{\beta}_2| \\&= 8 + 2 = 10\end{aligned}$$



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# 作业

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25 (2) ; 26; 27; 28(1)