## **Optimization Problems**

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$$\frac{\mathcal{E}_{x}}{\mathcal{O}}$$
 OLS:  $l_{i}(\beta) = (y_{i} - \chi_{i}^{T}\beta)^{T}$   
 $\mathcal{O} = \mathbb{R}^{P}$ 

logistic regression: 
$$y: \{10,1\}$$
  
 $l: |\beta| = y: \chi_i^{\dagger}\beta - log(1 + e^{\chi_i^{\dagger}\beta})$ 

lasso: 
$$L_i(\beta) = (y_i - x_i^{\mathsf{T}}\beta)^2$$

$$D = \{ \frac{2}{j-1} | \beta_j | \leq C \}$$

All take the form (general optimization)

# domain

subset selection:

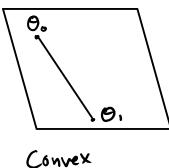
min - \frac{1}{n} \frac{1}{i=1} (y\_i - x\_i^T \beta)^2 sit. ||\beta||\_0 \le k

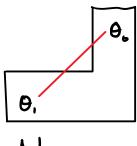
What makes this hard? non-convexity/discontinuous

#### Convexity

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Convex Set: C = RP is convex if YOO, O, EC then xOo+ (1-x)O, EC YOEXEL





Non-convex

Convex Function: 1:RP -> R s.t. dom (1) is

 $A(\angle \theta_0 + (1-\angle)\theta_1) \leq \angle A(\theta_0) + (1-\angle)A(\theta_1)$ for all O=x=1, 0.,0, E doin(f)





Convex Optimization & inequality constraints

min  $R(\beta)$  sit.  $g_i(\beta) \leq 0$ , i=1,...,m

hj(\$) = 0, j=1,...r

requality constraints

is convex if R, g; are convex Ex h; is affine (h; /3)=A; /3+b;)

Property: For convex functions, local minima are global minima

# local minima are global minima

A A A A

local minimum:  $\beta^{loc}_{s,t}$ . exists p>0 s.t.  $\forall \beta' \in O$  send  $||\beta^{loc}_{s,t}|| \leq p$  then  $R(\beta^{loc}) \leq R(\beta')$ 

global minimum:  $\beta \delta^{lo}$  s.l.  $\forall \beta' \in D$   $R(\beta \delta^{lo}) \leq R(\beta')$ 

### **Examples of Convex Functions**

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How do we know if a function is convex?

1st order characterization: 1 is differentiable

1(b) = 1(b) + 71(b) (B-Bo) VB, Bo ED

- 71(b)=0 => 1(b) = 1(bo)! Bo is global minimum

2nd order characterization: 1 is twice differentiable

721(p) > 0 (Positive Semi-definite: Azo

xTAx = 0 VX ER?

Examples

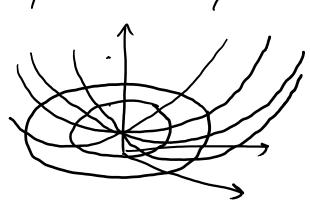
D linear 1/18= aTB+a.

> quadratic 1(B)= BTAB + aTB+a.

for PSD A'ZO

> log /1/5)= log(b)

D log-sum-exp



### Outline of Convex Optimization Methods

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Different optimization problems (unconstrained, linear, quadratic, linear constraints, equality constraints, etc.) have different methods.

#### First Order Methods:

- 1. Gradient descent: unconstrained smooth
- 2. Subgradient descent: unconstrained convex
- 3. Proximal gradient: unconstrained convex
- 4. Projected gradient: constrained smooth

#### Second Order Methods:

- 1. Newton method: unconstrained smooth
- 2. Barrier methods: constrained smooth
- 3. Primal-dual interior point: linear programs
- 4. Quasi-Newton methods: unconstrained smooth

Many more: stochastic gradient, coordinate descent, etc.