# Eigenvalue Decomposition

Predictive Modeling & Statistical Learning

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# Introduction

# Two Special Decompositions

Last time we talked about the Singular Value Decomposition (SVD).

In these slides, we'll talk about a closely related decomposition of SVD: the so-called Eigenvalue Decomposition (EVD) or Spectral Decomposition

# Recap

Matrix decompositions, also known as matrix factorizations

$$M = AB$$
 or  $M = ABC$ 

are a means of expressing a matrix as a product of usually two or three simpler matrices.

# Types of matrices

## Two types of matrices

We said that in data analysis we typically concentrate on two types of matrices:

- general rectangular matrices used to represent data tables.
- positive semi-definite matrices used to represent covariance matrices, correlation matrices, and any matrix that results from a crossproduct.

#### **EVD**

#### Eigenvalue Decomposition

- ► In contrast with SVD, the eigenvalue decomposition does NOT apply to any matrix.
- EVD applies to square matrices in general.
- A special type of square matrices are symmetric matrices.
- ▶ In data analysis methods, these matrices usually appear in the form of cross-product association matrices  $\mathbf{X}^\mathsf{T}\mathbf{X}$  and  $\mathbf{X}\mathbf{X}^\mathsf{T}$

### **EVD**

## Eigenvalue Decomposition

This decomposition applies to symmetric matrices such as the cross-product association matrices  $\mathbf{X}^\mathsf{T}\mathbf{X}$  and  $\mathbf{X}\mathbf{X}^\mathsf{T}$ 

## Symmetric Matrices

The attractive thing about EVD is that when applied to symmetric matrices the results have a "simple" nice structure.

# Eigen-Value Decomposition

#### **EVD**

An  $n \times n$  symmetric matrix M can be decomposed as:

$$\mathbf{M} = \mathbf{A} \mathbf{B} \mathbf{A}^\mathsf{T}$$

#### where

- $ightharpoonup {f A}$  is a n imes p column **orthonormal** matrix containing the eigen-vectors of  ${f M}$
- ightharpoonup B is a  $p \times p$  diagonal matrix containing the eigen-values of  ${f M}$

# Eigen-Value Decomposition

#### **EVD**

A more common notation for EVD is:

$$\mathbf{M} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^\mathsf{T}$$

#### where

- $lackbox{ U is a } n imes p$  column **orthonormal** matrix containing the eigen-vectors of  ${f M}$
- $\Lambda$  is a  $p \times p$  diagonal matrix containing the eigen-values of  ${\bf M}$

### **EVD**

$$\mathbf{M} = \mathbf{U} \boldsymbol{\Lambda} \mathbf{U}^\mathsf{T}$$

$$\mathbf{M} = \begin{bmatrix} u_{11} & \cdots & u_{1p} \\ u_{21} & \cdots & u_{2p} \\ \vdots & \ddots & \vdots \\ u_{n1} & \cdots & u_{np} \end{bmatrix} \begin{bmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_p \end{bmatrix} \begin{bmatrix} u_{11} & \cdots & u_{n1} \\ u_{12} & \cdots & u_{n2} \\ \vdots & \ddots & \vdots \\ u_{1p} & \cdots & u_{np} \end{bmatrix}$$

Vectors, which under a given transformation  $\mathbf{M}$  map into themselves or multiples of themselves, are called invariant vectors under that transformation. It follows that such vectors satisfy the relation:

$$\mathbf{M}\mathbf{x} = \lambda\mathbf{x}$$

where  $\lambda$  is a scalar.

The matrix equation:

$$\mathbf{M}\mathbf{x} = \lambda\mathbf{x}$$

can be rearranged as follows:

$$\mathbf{M}\mathbf{x} - \lambda\mathbf{x} = \mathbf{0}$$

Given

$$\mathbf{M}\mathbf{x} - \lambda\mathbf{x} = \mathbf{0}$$

We can factor out x

$$(\mathbf{M} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}$$

Obtaining the eigenstructure of a (square) matrix involves solving the **characteristic equation** 

$$det(\mathbf{M} - \lambda_i \mathbf{I}) = 0$$

If M is of order  $n \times n$ , then we can obtain n roots of the equation. These roots are called the **eigenvalues**.

# EVD in R

# eigen() in R

### eigen() function

R provides the function eigen() to perform an eigenvalue decomposition of a square matrix.

#### eigen() output

A list with the following components

- values a vector containing the eigenvalues
- vectors a matrix whose columns contain the eigenvectors

## EVD example in R

```
# X'X matrix
set.seed(22)
X <- as.matrix(USArrests)</p>
XtX <- t(X) %*% X
# eigenvalue decomposition
EVD = eigen(XtX)
# elements returned by eigen()
names (EVD)
## [1] "values" "vectors"
# vector of eigenvalues
(lambdas = EVD$values)
## [1] 2013735.2431 37957.1103 2084.9578
                                                  326.5089
```

# EVD example in R (con't)

```
# matrix of eigenvectors
(V <- EVD$vectors)

## [1,] [,2] [,3] [,4]

## [1,] -0.04239181  0.01616262  0.06588426  0.99679535

## [2,] -0.94395706  0.32068580 -0.06655170 -0.04094568

## [3,] -0.30842767 -0.93845891 -0.15496743  0.01234261

## [4,] -0.10963744 -0.12725666  0.98347101 -0.06760284
```

#### Relation between EVD and SVD

The EVD of the cross-product matrix of columns (or minor product moment)  $X^TX$  can be expressed as:

$$\mathbf{X}^\mathsf{T}\mathbf{X} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^\mathsf{T}$$

in terms of the SVD factorization of X:

$$\mathbf{X}^\mathsf{T}\mathbf{X} = \mathbf{V}\mathbf{D^2}\mathbf{V}^\mathsf{T}$$

#### Relation between EVD and SVD

The EVD of the cross-product matrix of rows (or major product moment)  $XX^T$  can be expressed as:

$$\mathbf{X}\mathbf{X}^\mathsf{T} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^\mathsf{T}$$

in terms of the SVD factorization of X:

$$\mathbf{X}\mathbf{X}^\mathsf{T} = \mathbf{U}\mathbf{D}^2\mathbf{U}^\mathsf{T}$$

# Power Method

#### About the Power Method

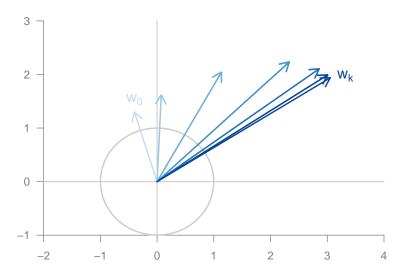
One of the basic procedures following a successive approximation approach is precisely the Power Method.

In its simplest form, the Power Method (PM) allows us to find **the largest** eigenvector and its corresponding eigenvalue.

#### About the Power Method

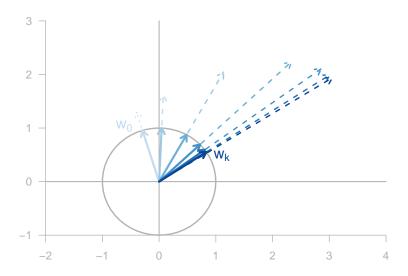
Choose an arbitrary vector  $\mathbf{w_0}$  to which we will apply the symmetric matrix  $\mathbf{S}$  repeatedly to form the following sequence:

$$\begin{split} w_1 &= Sw_0 \\ w_2 &= Sw_1 = S^2w_0 \\ w_3 &= Sw_2 = S^3w_0 \\ &\vdots \\ w_k &= Sw_{k-1} = S^kw_0 \end{split}$$



#### About the Power Method

- ▶ In practice, we must rescale the obtained vector  $\mathbf{w_k}$  at each step.
- ► The rescaling will allows us to judge whether the sequence is converging.
- $\blacktriangleright$  After some iterations, the vector  $w_{k-1}$  and  $w_k$  will be very similar
- ▶ Assuming a reasonable scaling strategy, the sequence will usually converge to the dominant eigenvector of S.



# Dominant Eigenvalue

The obtained vector is the dominant eigenvector. To get the corresponding eigenvalue we calculate the so-called **Rayleigh quotient** given by:

$$\lambda = \frac{\mathbf{w}_{\mathbf{k}}^{\mathsf{T}} \mathbf{S}^{\mathsf{T}} \mathbf{w}_{\mathbf{k}}}{\|\mathbf{w}_{\mathbf{k}}\|^2}$$

#### Remarks

Conditions for the power method to be succesfully used:

- ▶ The matrix must have a *dominant* eigenvalue.
- ▶ The starting vector  $\mathbf{w_0}$  must be nonzero.
- We need to scale each of the vectors w<sub>k</sub> otherwise the algorithm will "explode"

#### PM Pseudocode

#### Let's consider a more detailed version of the PM algorithm:

- 1. Start with an arbitraty initial vector w
- 2. Obtain product  $\tilde{\mathbf{w}} = \mathbf{S}\mathbf{w}$
- 3. Normalize  $\tilde{\mathbf{w}}$

e.g. 
$$\mathbf{w} = \frac{\tilde{\mathbf{w}}}{\|\tilde{\mathbf{w}}\|}$$

- 4. Compare w with its previous version
- 5. Repeat steps 2 till 4 until convergence

Assume that the matrix  $\mathbf{S}$  has p eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_p$ , and that they are ordered in decreasing way  $|\lambda_1| > |\lambda_2| \ge \dots \ge |\lambda_p|$ .

Note that the first eigenvalue is strictly greater than the second one. This is a very important assumption.

In the same way, we'll assume that the matrix S has p linearly independent vectors  $u_1, \ldots, u_p$  ordered in such a way that  $u_j$  corresponds to  $\lambda_j$ .

The initial vector  $\mathbf{w_0}$  may be expressed as a linear combination of  $\mathbf{u_1}, \dots, \mathbf{u_p}$ 

$$\mathbf{w_0} = a_1 \mathbf{u_1} + \dots + a_p \mathbf{u_p}$$

At every step of the iterative process the vector  $\mathbf{w}_{\mathbf{k}}$  is given by:

$$\mathbf{w_k} = a_1 \lambda_1^k \mathbf{u_1} + \dots + a_p \lambda_p^k \mathbf{u_p}$$

Since  $\lambda_1$  is the dominant eigenvalue, the component in the direction of  $\mathbf{u_1}$  becomes relatively greater than the other components as k increases. If we knew  $\lambda_1$  in advance, we could rescale at each step by dividing by it to get:

$$\left(\frac{1}{\lambda_1^k}\right)\mathbf{w_k} = a_1\mathbf{u_1} + \dots + a_p\left(\frac{\lambda_p^k}{\lambda_1^k}\right)\mathbf{u_p}$$

which converges to the eigenvector  $a_1\mathbf{u_1}$ , provided that  $a_1$  is nonzero.

Of course, in real life this scaling strategy is not possible—we don't know  $\lambda_1$ . Consequently, the eigenvector is determined only up to a constant multiple, which is not a concern since the really important thing is the *direction* not the length of the vector.

The speed of the convergence depends on how bigger  $\lambda_1$  is respect with to  $\lambda_2$ , and on the choice of the initial vector  $\mathbf{w_0}$ . If  $\lambda_1$  is not much larger than  $\lambda_2$ , then the convergence will be slow.

#### More Remarks

- ▶ The power method is a sequential method.
- $\blacktriangleright$  We can obtain  $w_1, w_2$ , and so on, step by step.
- ▶ If we only need the first *k* vectors, we can stop the procedure at the desired stage.

## Obtaining more eigenvectors?

Once we've obtained the first eigenvector  $\mathbf{w_1}$ , we can compute the second vector by reducing the matrix  $\mathbf{S}$  by the amount explained by the first eigenvector.

This operation of reduction is called **deflation** and the residual matrix is obtained as:

$$\mathbf{S}_1 = \mathbf{S} - \mathbf{w}_1 \mathbf{w}_1^\mathsf{T}$$

To get the second eigenvalue and its corresponding eigenvector, we operate on  $S_1$  in the same way as the operations on S.