

Geometric Discriminant Analysis

Predictive Modeling & Statistical Learning

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Introduction

Introduction

In these slides we discuss the approach originally proposed by Fisher. He formulated the classification problem in a geometric way. He sought to find the linear combination of the predictors such that the between-group variance was maximized relative to the within-group variance.

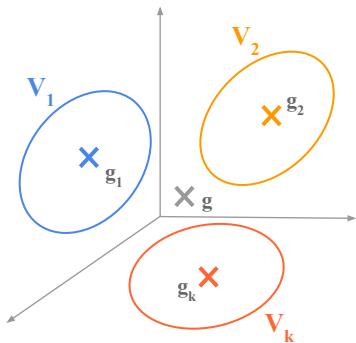
In other words, he wanted to find the combination of the predictors that gave maximum separation between the centroids of the data while at the same time minimizing the variation within each group of data.

Main Problem

How to find a representation of the objects which provides the best separation between groups (description emphasis)

How to find the rules for assigning the objects to their groups (prediction emphasis).

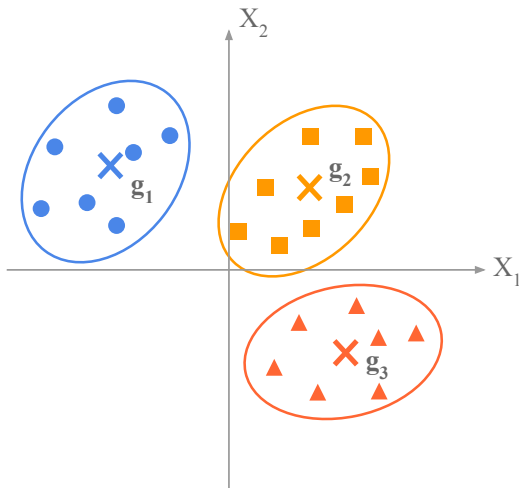
Between and Within Dispersion



Variances

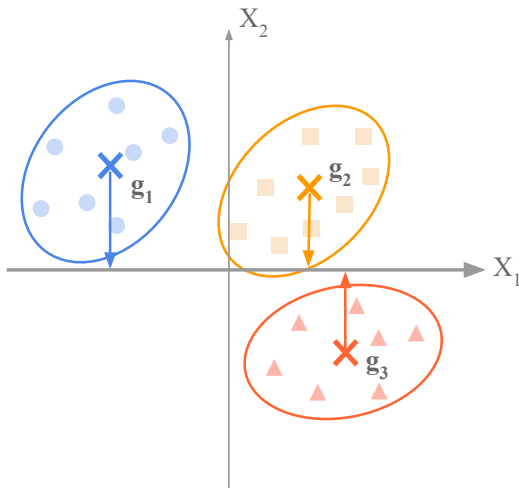
- ▶ Within-groups: W
- ▶ Between-groups: B
- ▶ Total: $V = W + B$

Say we have 3 classes in 2-dim space



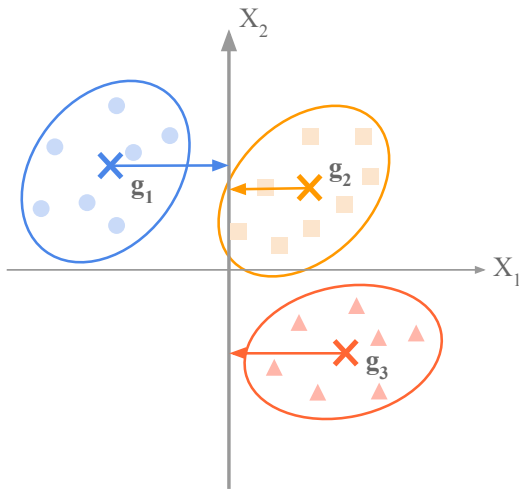
We look for the best representation separating the groups

Looking for optimal representation



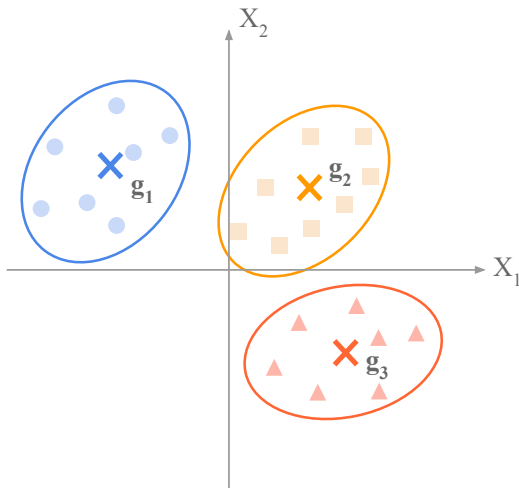
Axis X_1 separates group 1 from groups 2 and 3

Looking for optimal representation



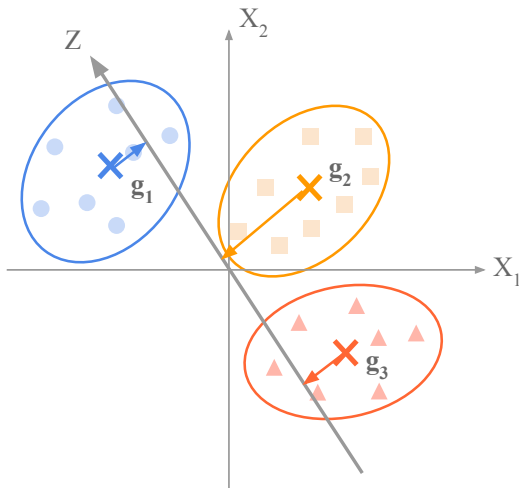
Axis X_2 separates group 3 from groups 1 and 2

Looking for optimal representation



Is there an axis that “best” separates the clouds?

Looking for a discriminant axis



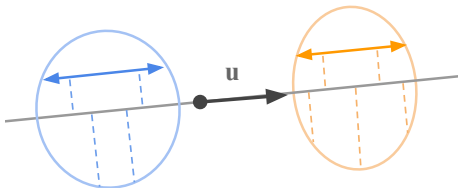
Axis $Z = a_1X_1 + a_2X_2$ separates all three groups

Main Problem

How to find a representation of the objects which provides the best separation between groups.

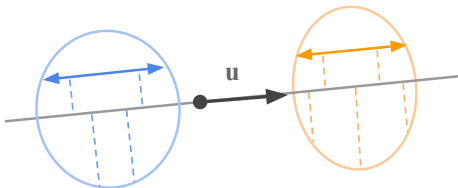
Two Goals

Minimize within-groups dispersion: $\min\{\mathbf{u}^T \mathbf{W} \mathbf{u}\}$

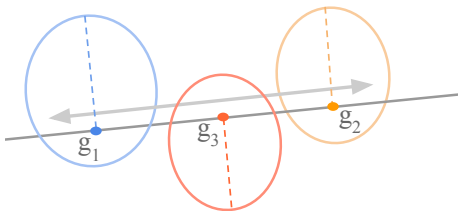


Two Goals

Minimize within-groups dispersion: $\min\{\mathbf{u}^T \mathbf{W} \mathbf{u}\}$



Maximize between-groups dispersion: $\max\{\mathbf{u}^T \mathbf{B} \mathbf{u}\}$



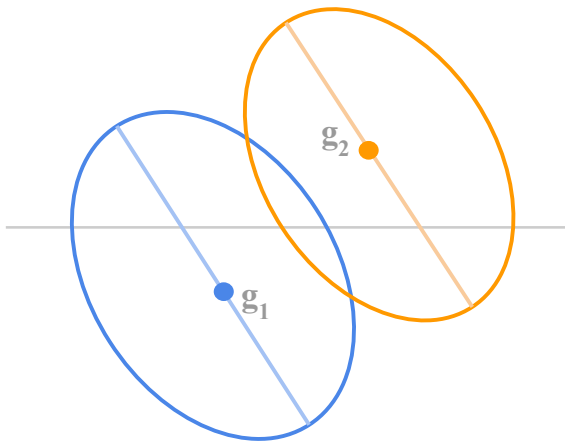
Two Incompatible Goals

It is generally impossible to find an axis u_1 which, in order to meet the objective of discriminant analysis, simultaneously:

- ▶ maximizes the between-groups variance
- ▶ minimizes the within-groups variance

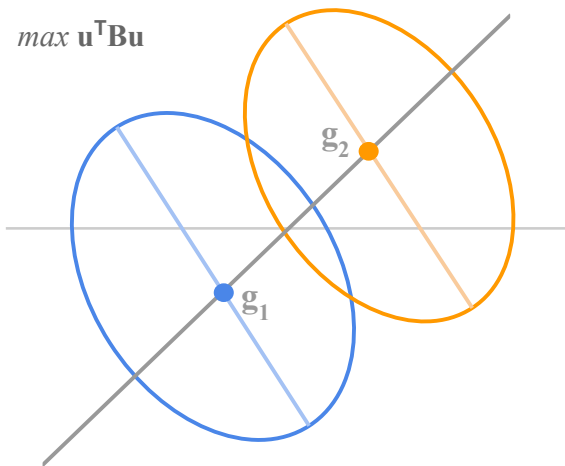
Let's see a picture of this issue

Double goal cartoon picture



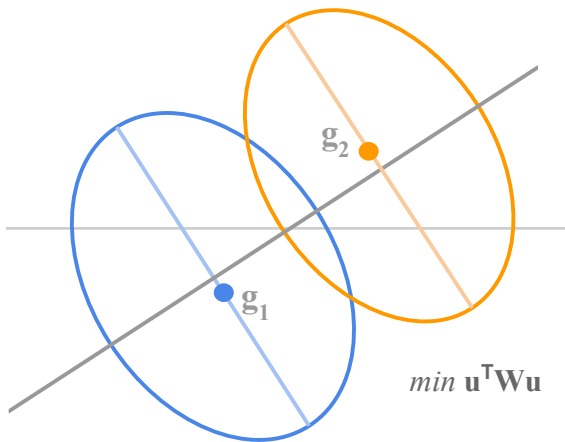
Double goal of discriminant analysis ... generally impossible

Double goal cartoon picture



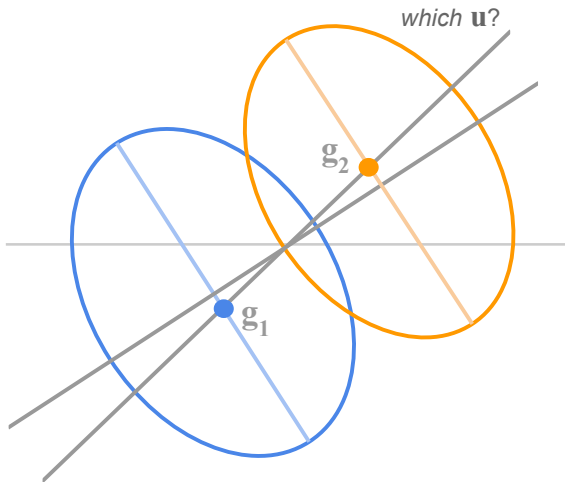
Double goal of discriminant analysis ... generally impossible

Double goal cartoon picture



Double goal of discriminant analysis ... generally impossible

Double goal cartoon picture



Double goal of discriminant analysis ... generally impossible

Double goal issue

If we are looking for the maximum between-groups dispersion, we will choose an axis \mathbf{u} parallel to the segment linking the centroids.

If we are looking for the minimum within-groups dispersion, we will choose an axis \mathbf{u} perpendicular to the principal axis of the ellipses.

Double goal issue

Impossible simultaneity:

$$\min\{\mathbf{u}^T \mathbf{W} \mathbf{u}\} \implies \mathbf{W} \mathbf{u} = \alpha \mathbf{u}$$

$$\max\{\mathbf{u}^T \mathbf{B} \mathbf{u}\} \implies \mathbf{B} \mathbf{u} = \beta \mathbf{u}$$

Main Problem

We should look then for a compromise. This is where the variance decomposition comes handy: $\mathbf{V} = \mathbf{W} + \mathbf{B}$

$$\mathbf{u}^T \mathbf{V} \mathbf{u} = \mathbf{u}^T \mathbf{W} \mathbf{u} + \mathbf{u}^T \mathbf{B} \mathbf{u}$$

Main Problem

We should look then for a compromise. This is where the variance decomposition comes handy: $\mathbf{V} = \mathbf{W} + \mathbf{B}$

$$\mathbf{u}^T \mathbf{V} \mathbf{u} = \underbrace{\mathbf{u}^T \mathbf{W} \mathbf{u}}_{\text{minimize}} + \underbrace{\mathbf{u}^T \mathbf{B} \mathbf{u}}_{\text{maximize}}$$

Main Problem

We have two options for the compromise:

$$\max \left\{ \frac{\mathbf{u}^\top \mathbf{B} \mathbf{u}}{\mathbf{u}^\top \mathbf{V} \mathbf{u}} \right\} \quad \text{OR} \quad \max \left\{ \frac{\mathbf{u}^\top \mathbf{B} \mathbf{u}}{\mathbf{u}^\top \mathbf{W} \mathbf{u}} \right\}$$

Solution

Instead of maximizing $\mathbf{u}^T \mathbf{B} \mathbf{u}$ or minimizing $\mathbf{u}^T \mathbf{W} \mathbf{u}$, we maximize $\mathbf{u}^T \mathbf{B} \mathbf{u} / \mathbf{u}^T \mathbf{V} \mathbf{u}$, which according to the Huygens theorem is equivalent to maximizing $\mathbf{u}^T \mathbf{B} \mathbf{u} / \mathbf{u}^T \mathbf{W} \mathbf{u}$

It can be shown that the solution \mathbf{u} is the eigenvector of $\mathbf{V}^{-1} \mathbf{B}$ associated with λ , the largest eigenvector of $\mathbf{V}^{-1} \mathbf{B}$.

Moreover, it turns out that \mathbf{u} is an eigenvector of $\mathbf{V}^{-1} \mathbf{B}$ if and only if \mathbf{u} is an eigenvector of $\mathbf{W}^{-1} \mathbf{B}$ with a corresponding eigenvalue of $\lambda / (1 - \lambda)$

Metrics

The metrics \mathbf{V}^{-1} and \mathbf{W}^{-1} are therefore called equivalent, but the metric \mathbf{W}^{-1} (the Mahalanobis metric) is used more widely by software developers.

With the Mahalanobis metric, the square of the distance between two points p_1 and p_2 is

$$d^2(p_1, p_2) = (\mathbf{p}_1 - \mathbf{p}_2)^\top \mathbf{W}^{-1} (\mathbf{p}_1 - \mathbf{p}_2)$$

A special PCA

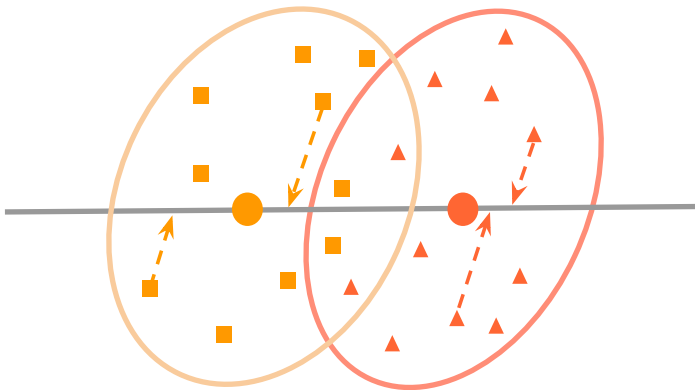
What do \mathbf{u} and \mathbf{W}^{-1} correspond in geometric terms?

\mathbf{u} is the axis from the PCA on the cloud of centroids \mathbf{g}_k , but it is an axis on which the points are projected obliquely, not orthogonally.

Without this obliqueness, corresponding to the equivalent metrics \mathbf{V}^{-1} and \mathbf{W}^{-1} , this would be a simple PCA, in which the groups would be less well separated.

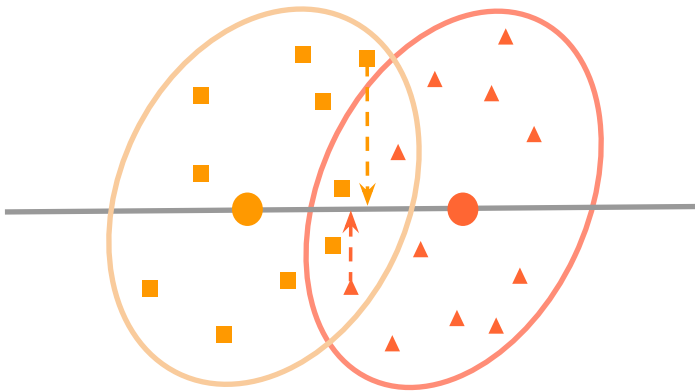
With \mathbf{W}^{-1} , the separation of two points depends not only on a Euclidean measurement, but also on the variance and correlation of the variables.

Oblique projection with \mathbf{W}^{-1}



Points are projected obliquely with \mathbf{W}^{-1}

Orthogonal projection without \mathbf{W}^{-1}



Without \mathbf{W}^{-1} , points would be orthogonally projected

Canonical Axes and Canonical Variables

- ▶ The axis \mathbf{u} is called a **canonical axis**
- ▶ When the first canonical axis has been determined, we search for a 2nd one
- ▶ The second axis should be the most discriminant and uncorrelated with the first one
- ▶ This procedure is repeated until the number of axis reaches the minimum of: $K - 1$ and p

In fact, it is not the canonical axes that are manipulated directly, but the *canonical variables* which are the coordinates of the individual points on the canonical axes.

Canonical Axes and Canonical Variables

In the case of two classes ($K = 2$), the canonical axis is unique and it turns out that is proportional to $\mathbf{W}^{-1}(\mathbf{g}_1 - \mathbf{g}_2)$

Iris Data Again

Example with Iris data

Fill in with R code!!!

Geometric Predictive Discriminant Analysis

Predictive Idea

Each observation x_i is classed in the group G_k for which the distance to the center \mathbf{g}_k is minimal, the distance being calculated using the Mahalanobis metric \mathbf{W}^{-1}

$$\begin{aligned} d^2(\mathbf{x}_i, \mathbf{g}_k) &= (\mathbf{x}_i - \mathbf{g}_k)^\top \mathbf{W}^{-1} (\mathbf{x}_i - \mathbf{g}_k) \\ &= \mathbf{x}_i^\top \mathbf{W}^{-1} \mathbf{x}_i - 2\mathbf{g}_k^\top \mathbf{W}^{-1} \mathbf{x}_i + \mathbf{g}_k^\top \mathbf{W}^{-1} \mathbf{g}_k \end{aligned}$$

Discriminant Functions

Note that minimizing $d^2(\mathbf{x}_i, \mathbf{g}_k)$ is equivalent to maximizing $2\mathbf{g}_k^T \mathbf{W}^{-1} \mathbf{x}_i + \mathbf{g}_k^T \mathbf{W}^{-1} \mathbf{g}_k$.

Let $\alpha_k = \mathbf{g}_k^T \mathbf{W}^{-1} \mathbf{g}_k$. Note that this a constant that does not depend on \mathbf{x}_i .

Thus, for each of the k groups we have a **discriminant linear function** that is found after inversion of the matrix \mathbf{W}

Mahalanobis D^2

Classification is based on the concept of distance from a point to a centroid.

An important quantity is the so-called Mahalanobis D^2 , which is the square of the distance between the two centroids:

$$D^2 = d^2(\mathbf{g}_1, \mathbf{g}_2) = (\mathbf{g}_1 - \mathbf{g}_2)^\top \mathbf{W}^{-1} (\mathbf{g}_1 - \mathbf{g}_2)$$

Mahalanobis D^2

The Mahalanobis D^2 measures the (square) distance between the two groups to be discriminated, and thus it also measures the quality of the discrimination: a higher value means better discrimination.

Geometric Classification Rule

The rule of classification of geometric discriminant analysis is a linear rule (which is why we speak of *linear discriminant analysis*).

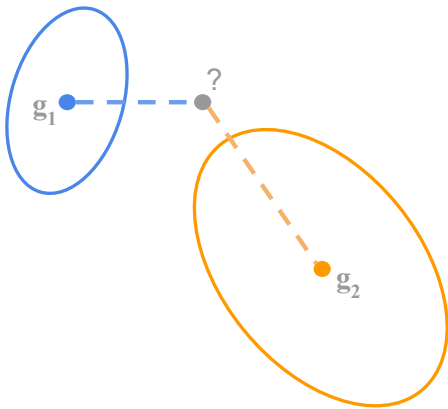
We assign each object to the group it is nearest to, using the \mathbf{W}^{-1} metric to calculate the distance of the object from the centroid of the group, in other words by carrying out an oblique projection of \mathbf{x}_i on the discriminant axis.

Geometric Classification Rule

Warning

The geometric rule of classification should not be used if the two groups have different *a priori* probabilities or variances.

Limitations of Geometric Classification



To which group should we assign the new object?

References

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