

## - Source Code

### DFS code

from collections import defaultdict  
# This collection represents a directed graph using adjacency list representation

class graph:

def \_\_init\_\_(self):

self.graph = defaultdict(list)

def addedge(self, u, v):

self.graph[u].append(v)

def DFSutil(self, v, visited):

visited.add(v)

print(v, end = ' ')

# Recur for all vertices adjacent to this vertex

for neighbour in self.graph[v]:

if neighbour not in visited:

self.DFSutil(neighbour, visited)

# The function to do DFS transversal using recursive DFS

```
def DFS(self, v):
```

```
    visited = set()
```

```
    self.DFSutil(v, visited)
```

# Driver code

# Create a graph in given above

```
g = graph()
```

```
g.addedge(0, 1)
```

```
g.addedge(0, 2)
```

```
g.addedge(1, 2)
```

```
g.addedge(2, 0)
```

```
g.addedge(2, 3)
```

```
g.addedge(3, 3)
```

```
print("The Following is in DFS for from vertex 2")
```

```
g.DFS(2)
```

- BFS code

```
from collections import defaultdict
```

```
class graph:
```

```
    # constructor
```

```
    def __init__(self):
```

```
        self.graph = defaultdict(list)
```

```
    def addEdge(self, u, v):
```

```
        self.graph[u].append(v)
```

```
    def BFS(self, s)
```

```
    # Mark all vertices as non visited
```

```
        visited = [False] * (max(self.graph) + 1)
```

```
    # create a queue for BFS
```

```
        queue = []
```



```
# Mark source node as visited & enqueue  
queue.append(s)  
visited[s] = True
```

```
while queue:  
    s = queue.pop(0)  
    print(s, end = ' ')
```

```
for i in self.graph[s]:  
    if visited[i] == False:
```

```
g = graph()  
g.addedge(0,1)  
g.addedge(0,2)  
g.addedge(1,2)  
g.addedge(2,0)  
g.addedge(2,3)  
print("Following is Breadth First starting from vertex  
2")  
g.BFS(2)
```

- DEID code

```
from collections import defaultdict
```

```
class graph:  
    def __init__(self, vertices):  
        self.v = vertices  
        self.graph = defaultdict(list)  
    def addEdge(self, u, v):  
        self.graph[u].append(v)
```



```
def DLS (self, src, target, maxDepth):  
    if src == target:  
        return true
```

```
    if maxDepth <= 0:  
        return false
```

```
    for i in self.graph[src]:  
        if (self.DLS (i, target, maxDepth - 1)):  
            return true  
    return false
```

```
def IDDFS (self, src, target, maxdepth):  
    for i in range (max depth):  
        if (self.BFS (src, target, i)):  
            return true  
    return false
```

```
def DFSutil (self, v, visited):  
    visited.add (v)
```

```
    print (v, end = ' ')
```

```
    for neighbour in self.graph[v]:  
        if neighbour not in visited:  
            self.DFSutil (neighbour, visited)
```

```
def BFS (self, s):
```

```
    visited = [False] * max (self)
```

```
    queue = []
```

```
    queue.append (s)
```

```
    visited [s] = true
```

```
    print ()
```



while queue:

```

s = queue.pop(0)
print(s, end = ' '):
for i in self.graph[s]:
    if visited[i] == False:
        queue.append(i)
        visited[i] = True

```

```

g = graph[7]:
g.addedge(0, 1)
g.addedge(0, 2)
g.addedge(0, 3)
g.addedge(1, 4)
g.addedge(2, 5)

```

```

target = 6
max_depth = 3
src = 0

```

if

```

print("Target is reachable from source" +
      " within max_Depth")

```

else:

```

print("Target is not reachable from source" +
      " within max_Depth")

```

```

g.DFS(0)
g.BFS(0)

```