

POWER USAGE CNN ON THE KHADAS VIM 3

Anton Pham, Levi van der Griendt,

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1 Introduction

Embedded systems are commonly used in power-constrained environments, and the efficient management of power consumption is crucial for their performance and longevity. In particular, governors are Operating System (OS) sub-routines that are responsible for the power management of embedded systems. As a result, significant and careful research is needed to discover the most optimized power consumption model for embedded system. Consequentially, detailed reports about the power-performance reciprocity of specific architectures on governors are needed to provide more understanding into the power management capabilities of the governors.

In this report, we present a power-performance characterization of Convolutional Neural Networks architectures (CNNs) on the Khadas VIM 3 board, which is an embedded platform based on the Amlogic A311D Heterogeneous Multi-Processor System on Chip (HMPSoC). We evaluate the governor using five image classification CNNs: AlexNet, GoogleNet, MobileNet, ResNet50, and SqueezeNet. These CNNs are executed using the ARM-CL framework on the ARM-based HMPSoC in the Khadas VIM 3 board. Our goal is to provide insights into how different power-efficiency knobs in the board affect the power and performance of CNNs.

The HMPSoC in the Khadas VIM 3 board has a hexa-core asymmetric ARM big.Little multi-core CPU with two CPU clusters, big and Little, and a dual-core Mali G52 MP4 GPU. The maximum frequency for the big CPU cluster, Little CPU cluster, and GPU is 1.8 GHz, 2.2 GHz, and 0.8 GHz, respectively. A 4 GB LPDDR4 main memory supports the HMPSoC. The platform runs Android v9.0 with kernel v4.9, and we run ARM-CL v21.02 on top of it.

In this work, we use a modified research version of ARM-CL called Pipe-All, which allows for simultaneous inference on both CPU and GPU cores using a software pipeline. The parameterized code for Pipe-All allows the user to redistribute the workload between the big CPU cluster, the Little CPU cluster, and the GPU. The governor we design uses this workload distribution feature from Pipe-All as a power management knob. Additionally, we use Dynamic Voltage and Frequency Scaling (DVFS) as another power management knob. DVFS technology changes a core’s voltage and frequency at run-time, allowing governors to tailor the performance of a core to match the requirements and save power.

2 Method

In this power-performance characterization report, we evaluated the power and performance of five state-of-the-art image classification Convolutional Neural Networks (CNNs) on the Khadas VIM 3 board. The CNNs used in this study were AlexNet, GoogleNet, MobileNet, ResNet50, and SqueezeNet. These CNNs were executed using the ARM-CL framework on an ARM-based Heterogeneous Multi-Processor Systems on Chip (HMPSoC) known as the Amlogic A311D HMPSoC, which is integrated in the Khadas Vim 3 embedded platform.

The HMPSoC used in this study contains a hexa-core asymmetric ARM big-little multicore CPU with two CPU clusters, Big and Little. The quad-core big CPU cluster contains four high-power, high-performance A73 cores, while the dual-core Little CPU cluster contains two low-power, low-performance A53 cores. The HMPSoC also contains a dual-core Mali G52 MP4 GPU. The maximum frequency for the big CPU cluster, Little CPU cluster, and GPU is 1.8 GHz, 2.2 GHz, and 0.8 GHz, respectively. A 4 GB LPDDR4 main memory supports the HMPSoC. In software, the platform was running Android v9.0 with kernel v4.9. We ran ARM-CL v21.02 on top of it.

To perform the power-performance characterization, we used a modified research version of the ARM-CL library called Pipe-All (Aghapour, & Torab, 2022). This version of the library allows for simultaneous inference on both CPU and GPU cores using a software pipeline. The parameterized code for Pipe-All allows the user to redistribute the workload between the big CPU cluster, the Little CPU cluster, and the GPU. The Governor used in this work used this workload distribution feature from Pipe-All as a power management knob. In addition to the workload distribution feature, we also used Dynamic Voltage and Frequency Scaling (DVFS) as a power management knob. DVFS technology changes a core’s voltage and frequency at

run-time, allowing Governors to tailor the performance of a core to match the requirements and save power. The Governor used in this work also used DVFS as a power management knob.

To physically set up the board, we followed the instructions provided in the guide. This included using a laptop running Ubuntu 20.04 and a USB-A port to connect to the Khadas VIM3 board, as well as other required peripheral equipment. We collected power and performance data for each CNN using the governor and power management knobs described above, by recording the minimum, maximum, and median power consumption (W) and the average frame latency during the inference interval. The numbers of frames used for the Little CPU, Big CPU, and GPU are 80, 100, and 100 frames consecutively. Every CNN was run on the a combination of pipelines in which each cluster was configured as the first target in the pipeline. For the Little and Big CPUs, the maximum frequency level was also changed incrementally based on the permitted options of frequencies for each of the CPU clusters, to record the power-performance data to analyze the complete relationship between power consumption and performance level. Furthermore, These data were then used to create charts and graphs to visually represent the power and performance characteristics of the CNNs on the Khadas VIM 3 board.

In this report, we provided generalized insights on how the power and performance move with different power-efficiency knobs in the board. The results of this study can be used to inform the design of governors and power management strategies for embedded systems operating in power-constrained environments.

3 Results

Following the experiment, the data collected were illustrated in several plots in order to make some observations. Firstly, the general form of the relationship between the power usage of CNN and latency is shown in Figure 1.

In Figure 1, the graph shows that as performance increases the more it increases the more energy it cost to increase the graph form. this form with only the time was also found Resnet50 and SqueezeNet. This is the most basic graph. the only real difference is the latency scale where they work on where on Restnet50 200-800 ms and squeezeNet is 80-225 ms.

In 2, we note the same form as in Figure 2, only now with fewer intervals and the numbers being lower. Nevertheless, for the rest of the plots, we can see it in the last graph how these normally look next to each other. the other graphs are very similar to the all the other graphs in this category.

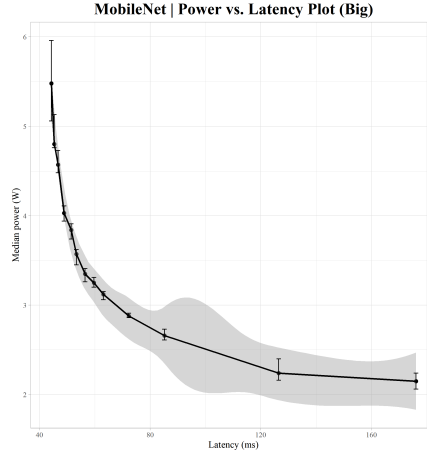


Figure 1: the form of MobileNet on the big core graph

As evident from the figure, there is a big change in performance, even on low performance we can see that it has a bit in terms of latency. This means we better be running on low on the big cpu then high on the low cpu. this is true for almost any. except that of alexnet witch is the one we haven't covered in this piece yet. this cause alexnet does something a bit weird.

In Figure 4, there is a fluctuation at the centre of the normally quite good looking slope. this is also findable in the googlenet one on the same frequency. we also find that the latency plot has alot of overlap. this did not happen on the other algorithms.

so last thing we tested was the gpu performance but this was a very not super interesting graph on it own so we decide to look at max min and gpu how many fps/ w the generate because $fps = \frac{1}{throughput}$ we can say this it efficient they are.

figure 5 show how efficient the GPU is if you just want the frames per second for wats used. other stuff is the big cpu looks a lot more power efficient if you need the speed it overs.

4 Conclusion and Discussion

The power-performance characterization of CNNs on the Khadas VIM 3 board revealed a strong relationship between power consumption and performance level. As the frequency of the Big CPU cluster was increased, the frames per second (FPS) and the average frame latency improved, but the power consumption also increased. This relationship was observed for both AlexNet and GoogleNet, with GoogleNet generally having higher power con-

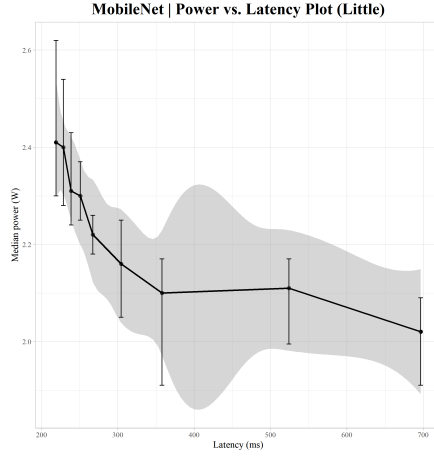


Figure 2: the form of the little graph of Mobilenet

sumption and lower latency than AlexNet.

The data also showed that the maximum frequency level had a greater impact on power consumption than the median or minimum values. This suggests that the board's governor and power management knobs are effective in controlling the power consumption at high-frequency levels, but may not have as much impact at lower levels.

So a other thing that looked interesting is that certain frequencies seem to have a bit of a break in use of more power. We can see this in the big core at the kink in the line but also googlenet has one and seem to be at the same frequency. this would mean that certain features work better on frequencies that this processor likes. this could be a few features on the A73 that the A53 doesn't have. Like the more piping and the better branch prediction. Just seem to get design with these frequencies at mind. Or that the algorithms did use them more but evidence of that was not really what we found in looking at the CNN papers.

It is also important to note that the power consumption and performance levels varied between the different CNNs. For example, MobileNet v2 had lower power consumption and higher FPS than AlexNet and GoogleNet, indicating that it may be a more power-efficient option for the specific processors on the Khavas Vim 3.

Overall, the results of this power-performance characterization demonstrate the importance of considering power consumption when selecting CNNs for deployment on the Khadas VIM 3 board. The use of different CNNs with different architectures and configurations can have a significant impact on the power consumption and performance levels of the board.

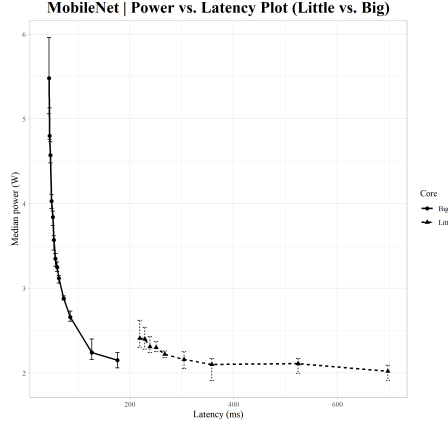


Figure 3: the two graphs combined

The data collected in this report can be used as a reference for selecting the most power-efficient CNNs for different use cases on the Khadas VIM 3 board. Also some of the efficiency of different CNNs are different meaning some can better use a different core for different parts if they want a bit more performance out of as little W as possible. It's also important to consider the trade-off between power consumption and performance when adjusting the frequency of the CPU clusters.

In the future, it would be beneficial to conduct similar characterizations on other platforms and devices to understand the general trends in power consumption and performance for different CNNs.

On the charts and graphs, it is possible to see the performance of each CNN as the frequency changes, and how the power consumption changes accordingly. Each graph shows the correlation between power consumption and performance, highlighting the trade-off between the two. The data allows to identify the most power-efficient CNNs for specific use cases, and the best frequency settings to achieve the desired balance between power consumption and performance.

5 References

Aghapour, E., & Torab, A. (2022). Pipe-All: High-Throughput, Low-Latency Pipelined Inference on Heterogeneous Multi-Process

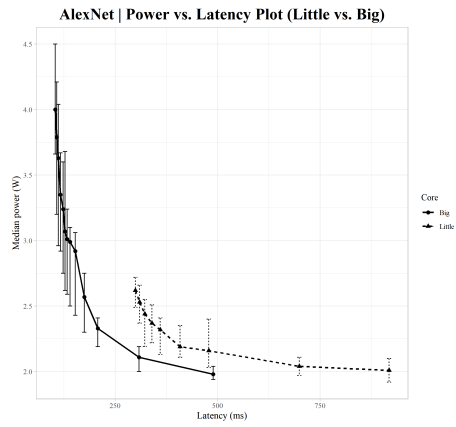


Figure 4: Alexnet

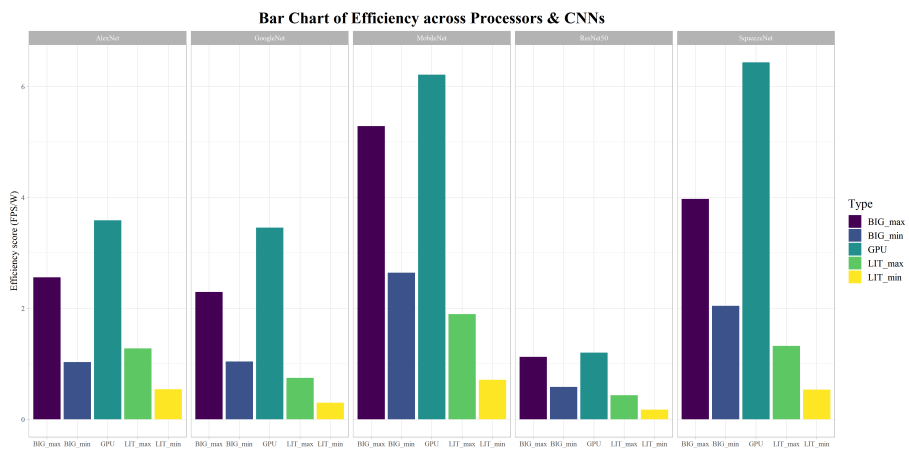


Figure 5: efficiency