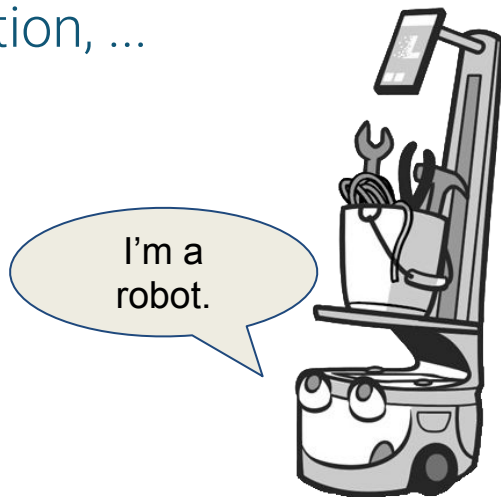
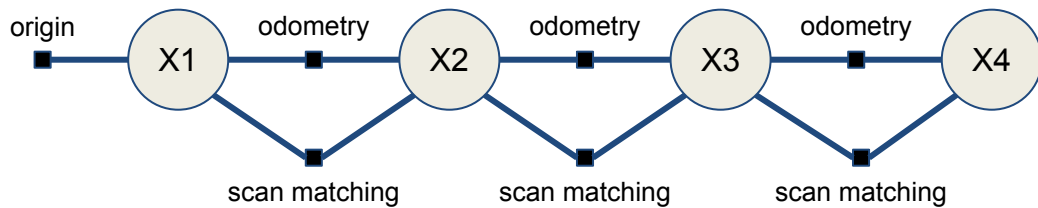
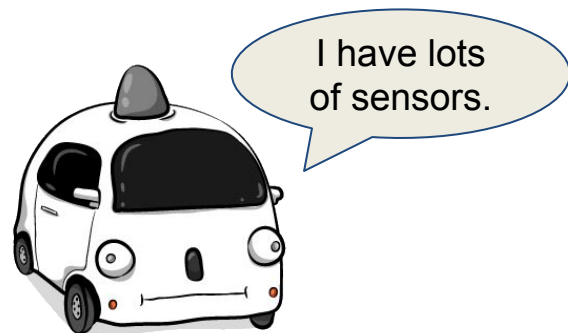
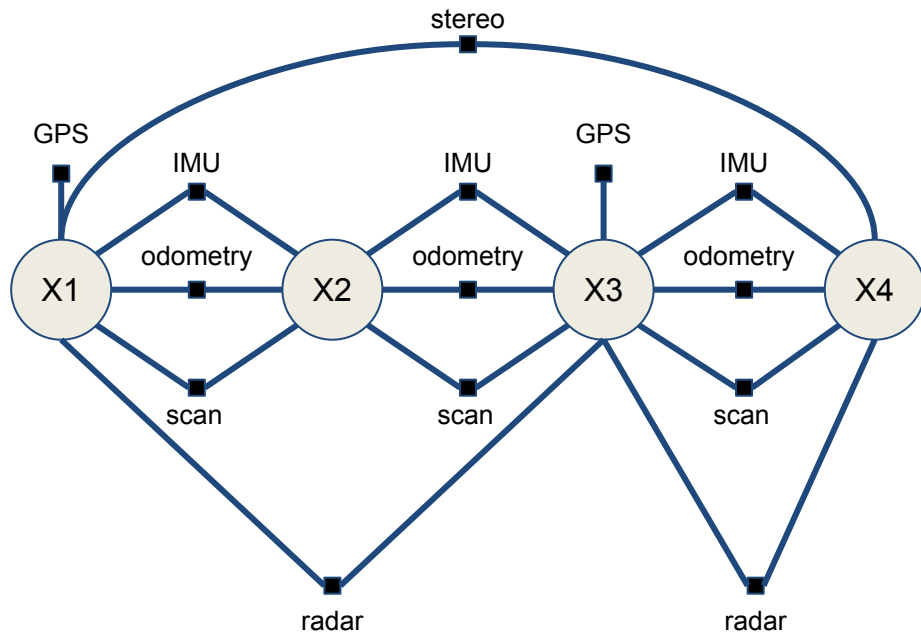


What is it?

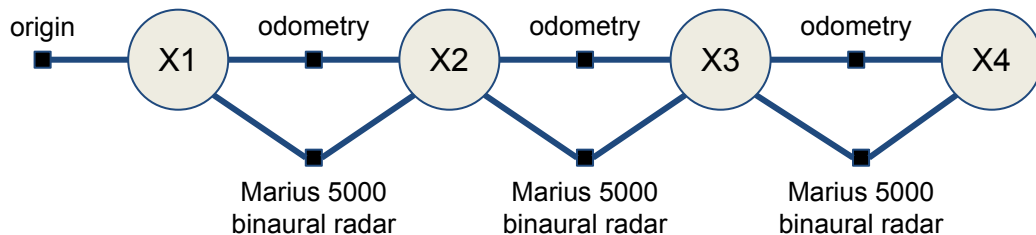
- Extensible sensor fusion framework
- Graph-based nonlinear least squares optimization
- Built on top of Google's Ceres inference engine
- Enables localization, mapping, calibration, ...



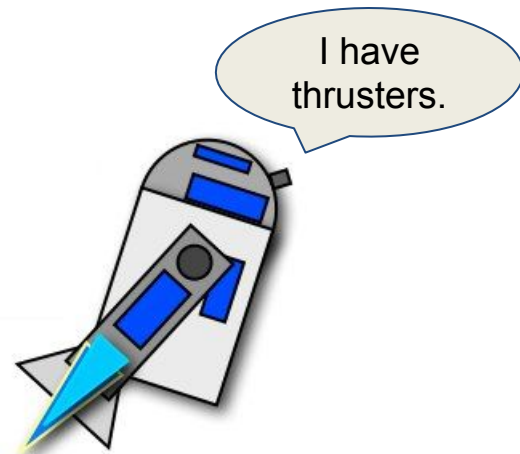
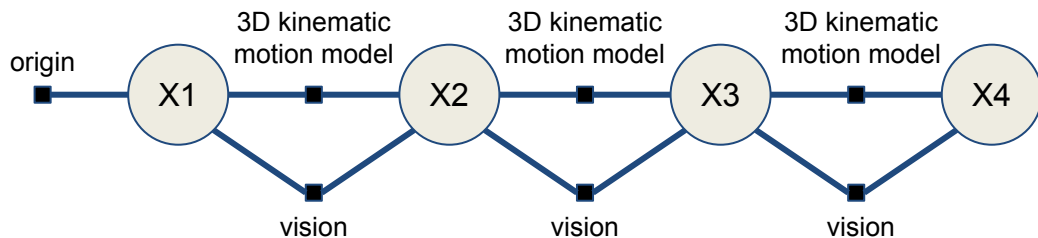
Configurable sensor suite



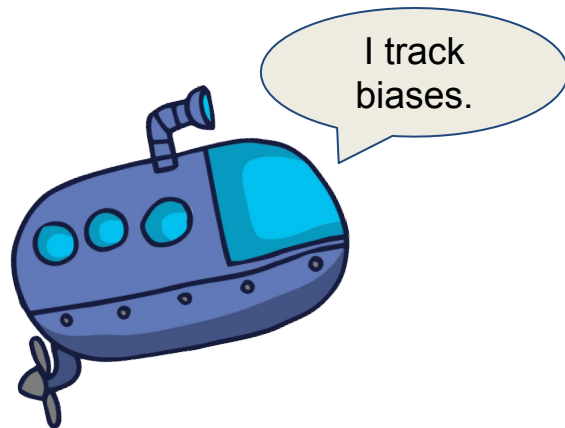
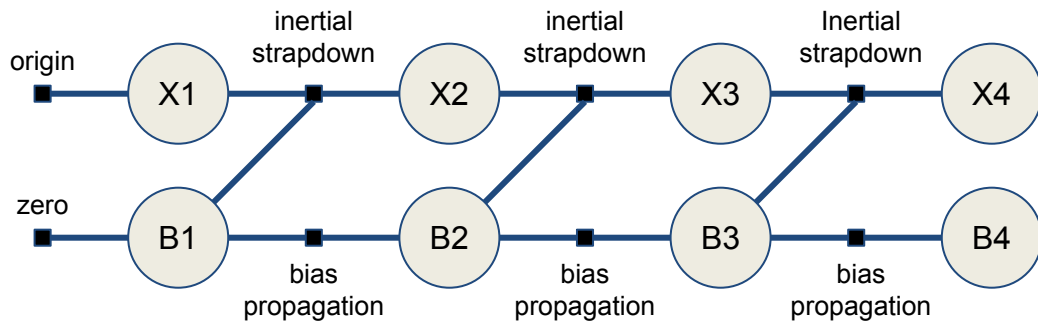
Extensible sensor models



Customizable motion models



Flexible state definitions



fuse

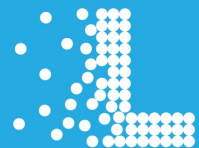
And so much more!



github.com/locusrobotics/fuse



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LocusRobotics.com/careers

