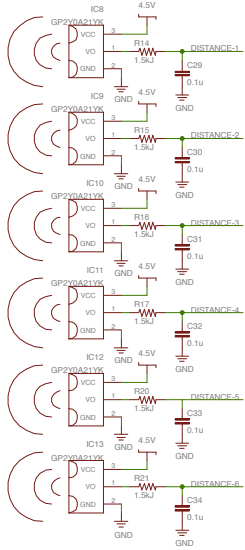
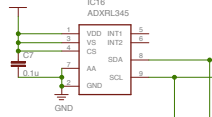


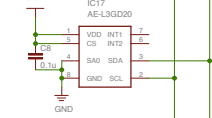
## Distance Sensor



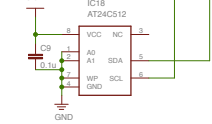
## Acceleration Sensor 3



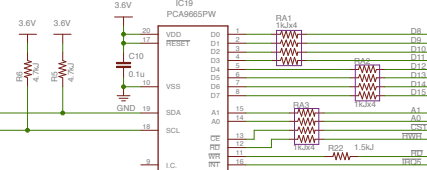
## Gyro Sensor 3



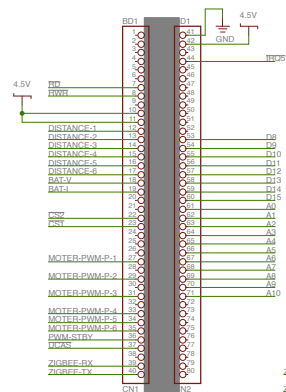
## EEP-ROM



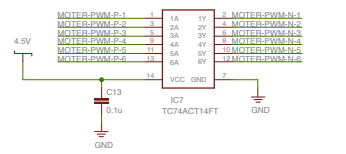
## I2C Bus Controller



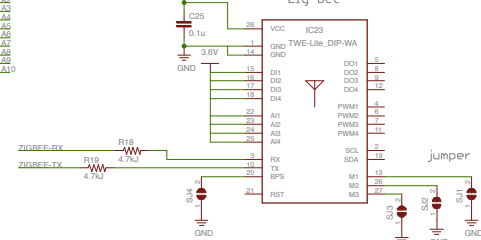
## U8 Pro Board



## Not Array(Motor Drive)

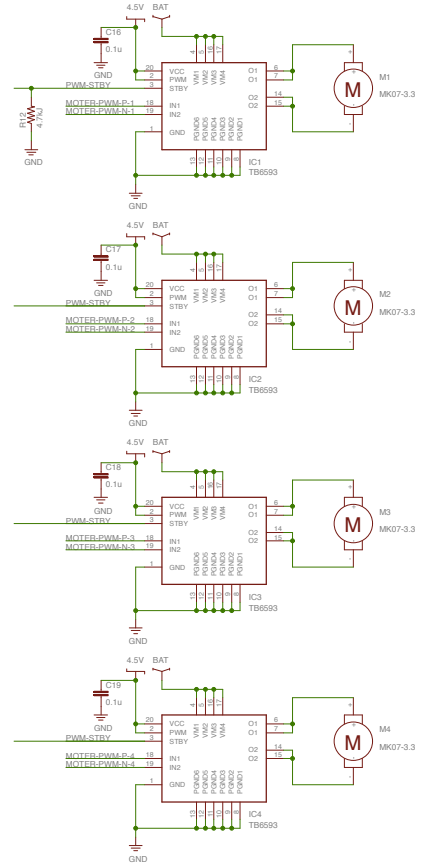


## Zig-Bee

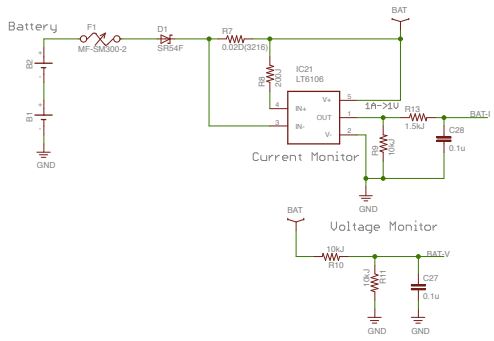


TODO: test RST pin floating  
TODO: fix bitrate

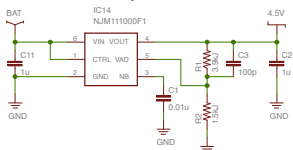
## Motor Drivers



## TODO: insert connector



## 4.5V Regulator



## 3.6V Regulator

