DFA for L includes 5 tuples $M = \left(Q\ ,\ \sum\ ,\ \delta\ ,\ q_0\ ,\ F\right)$

- **Set of all states** $Q = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7, q_8\}$
- **Input** $\sum = \{a, b, c, d, e, f, g, h, i, j, k, l, m, n, o, p, q, r, s, t, u, v, w, x, y, z, @,.\}$

  because $\psi = \{a, b, c,..., z\}$, $\Pi = \{.\}$, and $\phi = \{@\}$
- **Initial state** is denoted as q_0
- **Set of final states** $F = \{q_7\}$
- **Transition function** δ: $Q \times \sum \rightarrow Q$

	$\psi_{-g,o,v,r}$	@	.	g	o	v	r
→q_0	q_1	q_8	q_8	q_1	q_1	q_1	q_1
q_1	q_1	q_2	q_0	q_1	q_1	q_1	q_1
q_2	q_3	q_8	q_8	q_3	q_3	q_3	q_3
q_3	q_3	q_8	q_4	q_3	q_3	q_3	q_3
q_4	q_3	q_8	q_8	q_5	q_3	q_3	q_3
q_5	q_3	q_8	q_4	q_3	q_6	q_3	q_7
q_6	q_3	q_8	q_4	q_3	q_3	q_7	q_3
*q_7	q_3	q_8	q_4	q_3	q_3	q_3	q_3
q_8	q_8	q_8	q_8	q_8	q_8	q_8	q_8