

Jungeun Lee

[✉ jungeunlee14@gmail.com](mailto:jungeunlee14@gmail.com) | [/github.com/2jungeuni](https://github.com/2jungeuni)

EDUCATION

- **Ulsan National Institute of Science and Technology (UNIST)** Aug. 2020 -
Ulsan, Republic of Korea
Combined Master's-Doctoral Program in Electrical Engineering
 - Focus: Multi-Agent Coordination, Reinforcement Learning, Optimization, Safe Control
 - GPA: 4.16/4.30
 - Advisor: Prof. Jeong hwan Jeon
- **Ulsan National Institute of Science and Technology (UNIST)** Mar. 2016 - Aug. 2020
Ulsan, Republic of Korea
B.S. in Electrical Engineering, Materials Science and Engineering
 - Honors: *Magna Cum Laude*
 - GPA: 3.71/4.30 (Major GPA: 3.82/4.30)

EXPERIENCE

- **CJ Corporation** Aug. 2025 - Jan. 2026
Seoul, Republic of Korea
Research Intern
 - Automated and optimized the logistics packing system using reinforcement learning.
 - Implemented a Gymnasium-based simulation reflecting real-world packing processes.
 - Reduced the total packing makespan compared to the conventional packing process through reinforcement learning and Gurobi-based mathematical optimization.

PUBLICATIONS

- [C6] **First author.** Manuscript under double-blind review at *The International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*, 2026.
- [C5] **Jungeun Lee***, Seongjae Lee*, Jeong hwan Jeon. "Safe Trajectory Planning with Bernstein Polynomials Under Control Barrier Function Constraints." Submitted to *American Control Conference (ACC)*, 2026.
- [C4] **Co-author.** Manuscript under double-blind review at *IEEE International Conference on Robotics and Automation (ICRA)*, 2026.
- [C3] Thi Thuy Ngan Duong, **Jungeun Lee**, Jeong hwan Jeon. "Cooperative Mission Planning for Heterogeneous Robots and Energy Constraints." *International Conference on Robot Intelligence Technology and Applications*, 2024.
- [J1] Cong Phat Vo, **Jungeun Lee**, Jeong hwan Jeon. "Robust Adaptive Path Tracking Control Scheme for Safe Autonomous Driving via Predicted Interval Algorithm." *IEEE Access*, 2022.
- [C2] **Jungeun Lee**, Hyeyoung Noh, Hyun Jong Yang. "Performance Analysis of Beamforming for Radar and Communications Coexisting Systems." *IEEE International Conference on Information and Communication Technology Convergence (ICTC)*, 2018.
- [C1] Hyeyoung Noh, **Jungeun Lee**, Hyun Jong Yang. "Beam Synthesis Under Feasible Scenarios for Radar and Communications Combined Systems." *IEEE International Conference on Information and Communication Technology Convergence (ICTC)*, 2018.

* Contributed equally

PATENTS AND SOFTWARE CERTIFICATIONS

- [S1] "Deep Reinforcement Learning and Demand Prediction Model for Mobility-on-Demand Systems." Tested and certified in accordance with *KS X ISO/IEC 25023:2016* by *TPR Co., Ltd. (KOLAS Accredited Testing Laboratory)*. Certification No. *TPR-SWT-2025-017*; issued on July 10, 2025.
- [P1] Hyun Jong Yang, Jonggyu Jang, Harim Lee, Yeongjun Kim, Hyeyoung Noh, **Jungeun Lee**, and Hyeonsu Lyu. "Simulator for a Radar-based Active Target Detection Drone Communication Base Station." *Korean Registered Patent No. C-2018-037076*.

PROJECTS (SELECTED)

- **Real-time dynamic routing technology based on prediction and simultaneous optimization of carbon emission and transport demand** *Apr. 2022 - Jun. 2025 (39 months)*

Agency: Ministry of SMEs and Startups, Republic of Korea



- Developed a routing algorithm to solve traffic congestion and the resulting environmental pollution in metropolitan areas.
- Designed a carbon emission model by capturing real-time vehicle sensor data on altitude, speed, and acceleration.
- Pioneered a deep reinforcement learning-based Autonomous Mobility-on-Demand (AMoD) system to reduce carbon emissions, moving beyond the limitations of classic optimization methods.

- **AI-based applications for multi-agent mobility operations**

May. 2024 - Nov. 2024 (7 months)

Agency: Electronics and Telecommunications Research Institute (ETRI)

- Developed and modularized C++ based algorithms for task assignment optimization and optimal routing in multi-agent mobility systems.
- Built a GUI-based simulation tool to validate algorithm performance under diverse environmental conditions and constraints.
- Designed the system with a ROS-compatible modular architecture to enhance scalability.

- **Development of AI technology for intelligent mobility-on-demand operations**

Apr. 2021 - Dec. 2022 (21 months)

Agency: Ministry of Science and ICT (MSIT), Republic of Korea



- Developed an optimal routing algorithm for demand-responsive mobility systems.
- Designed the system to adjust vehicle routes in real-time, reflecting new traffic demands from nearby locations.
- Formulated an optimization problem to minimize passenger travel delays and waiting times.
- An average travel delay of 2.52 minutes and an average wait time of 4 minutes for ride-sharing passengers.
- A service rate of 89.57% of the total demand.

- **AI Novatus Academia**

Agency: Gyeongsangnam-do Provincial Government, Republic of Korea



- Assisted in the reinforcement learning program.
- Provided theoretical lectures on reinforcement learning for employees of small and medium-sized enterprises (SMEs) in the Gyeongsangnam-do region.
- Conducted hands-on programming sessions to help participants apply reinforcement learning techniques to real-world applications.

SKILLS

- **Programming Languages:** Python, C++, Java, MATLAB
- **Machine Learning Frameworks:** PyTorch, TensorFlow
- **Optimization Solvers:** Gurobi, OR-Tools, IPOPT, CVX

HONORS AND AWARDS

- **KIIE & LG CNS Optimization Grand Challenge 2025**

Sep. 2025

Excellence Award (6th out of 343 Teams)



- Served as **team leader**.
- Awarded \$2,200 and employment benefits.
- Participants included researchers from leading universities (Imperial College London, Eindhoven University of Technology, SNU, KAIST, POSTECH) and major corporations (LG Display, Samsung Electronics, Hyundai Motor, KT).

- **Hyundai Motor Group Autonomous Driving Challenge**

Mar. 2025

3rd Place out of 16 Qualifiers



- Served as **team leader**.
- Awarded \$3,600.
- Recognized as Korea's first end-to-end autonomous driving challenge.

- Teams from leading universities such as KAIST, UNIST, GIST, Hanyang University, Korea University, Sungkyunkwan University.
- **Ulsan Public Data Utilization Startup Competition** *Aug. 2023*
3rd Place
- **National Science & Technology Scholarship** *Feb. 2016 - Aug. 2020*
- **Government-funded Scholarship (fully funded)** *Feb. 2016 -*